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# **CSE 421**

## **Network Flow/Linear Programming**

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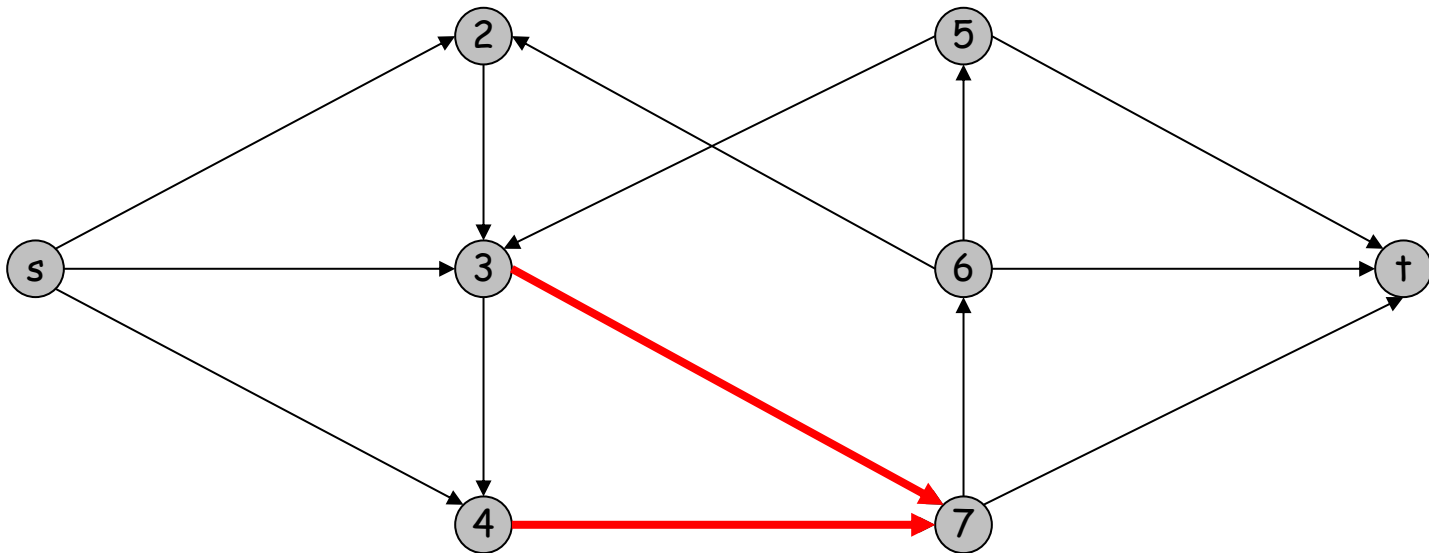
# Network Connectivity

# Network Connectivity

Given a digraph  $G = (V, E)$  and two nodes  $s$  and  $t$ , find min number of edges whose removal disconnects  $t$  from  $s$ .

**Def.** A set of edges  $F \subseteq E$  **disconnects  $t$  from  $s$**  if all  $s$ - $t$  paths uses at least one edge in  $F$ .

Ex: In testing network reliability

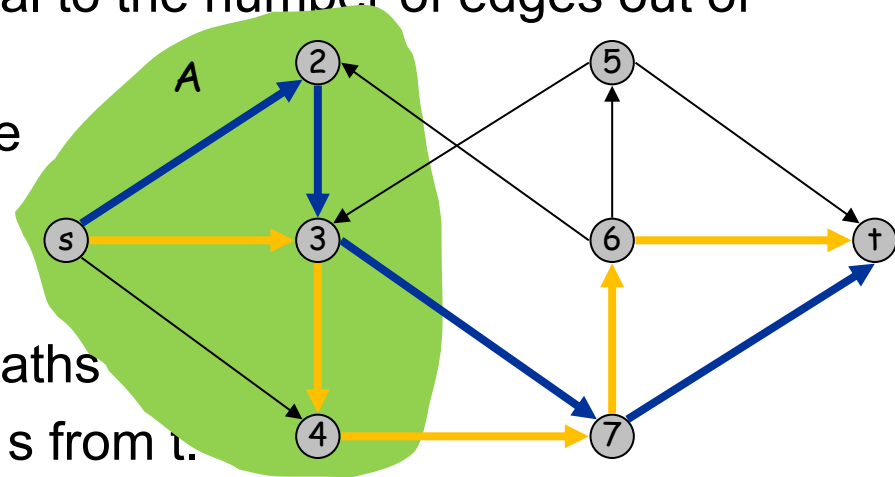


# Network Connectivity using Min Cut

**Thm. [Menger 1927]** The max number of edge-disjoint s-t paths is equal to the min number of edges whose removal disconnects t from s.

**Pf.**

- i) We showed that max number edge disjoint s-t paths = max flow.
- ii) Max-flow Min-cut theorem  $\Rightarrow$  min s-t cut = max-flow
- iii) For a s-t cut  $(A,B)$ ,  $\text{cap}(A,B)$  is equal to the number of edges out of A. In other words, every s-t cut  $(A,B)$  corresponds to  $\text{cap}(A,B)$  edges whose removal disconnects s from t.

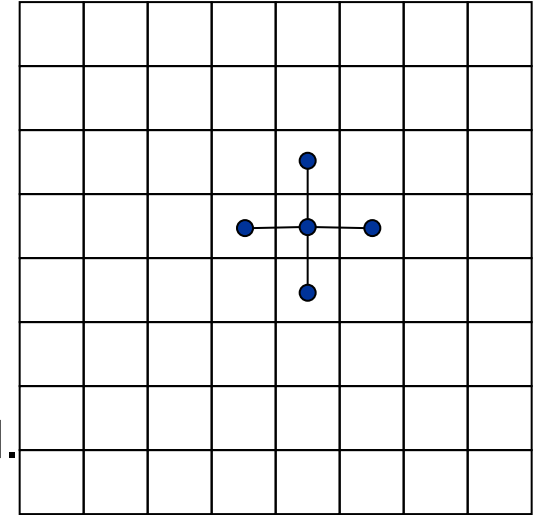


So, max number of edge disjoint s-t paths = min number of edges to disconnect s from t.

# Foreground / background segmentation

Label each pixel as foreground/background.

- $V$  = set of pixels,  $E$  = pairs of neighboring pixels.
- $a_i \geq 0$  is likelihood pixel  $i$  in foreground.
- $b_i \geq 0$  is likelihood pixel  $i$  in background.
- $p_{i,j} \geq 0$  is separation penalty for labeling one of  $i$  and  $j$  as foreground, and the other as background.



Goals.

**Accuracy:** if  $a_i > b_i$  in isolation, prefer to label  $i$  in foreground.

**Smoothness:** if many neighbors of  $i$  are labeled foreground, we should be inclined to label  $i$  as foreground.

Find partition  $(A, B)$  that **maximizes:**

$$\sum_{i \in A} a_i + \sum_{j \in B} b_j - \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

Foreground
Background

# Image Seg: Min Cut Formulation

## Difficulties:

- Maximization (as opposed to minimization)
- No source or sink
- Undirected graph

## Step 1: Turn into Minimization

Maximizing 
$$\sum_{i \in A} a_i + \sum_{j \in B} b_j - \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

Equivalent to minimizing 
$$+ \sum_{i \in V} a_i + \sum_{j \in V} b_j - \sum_{i \in A} a_i - \sum_{j \in B} b_j + \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

Equivalent to minimizing 
$$+ \sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

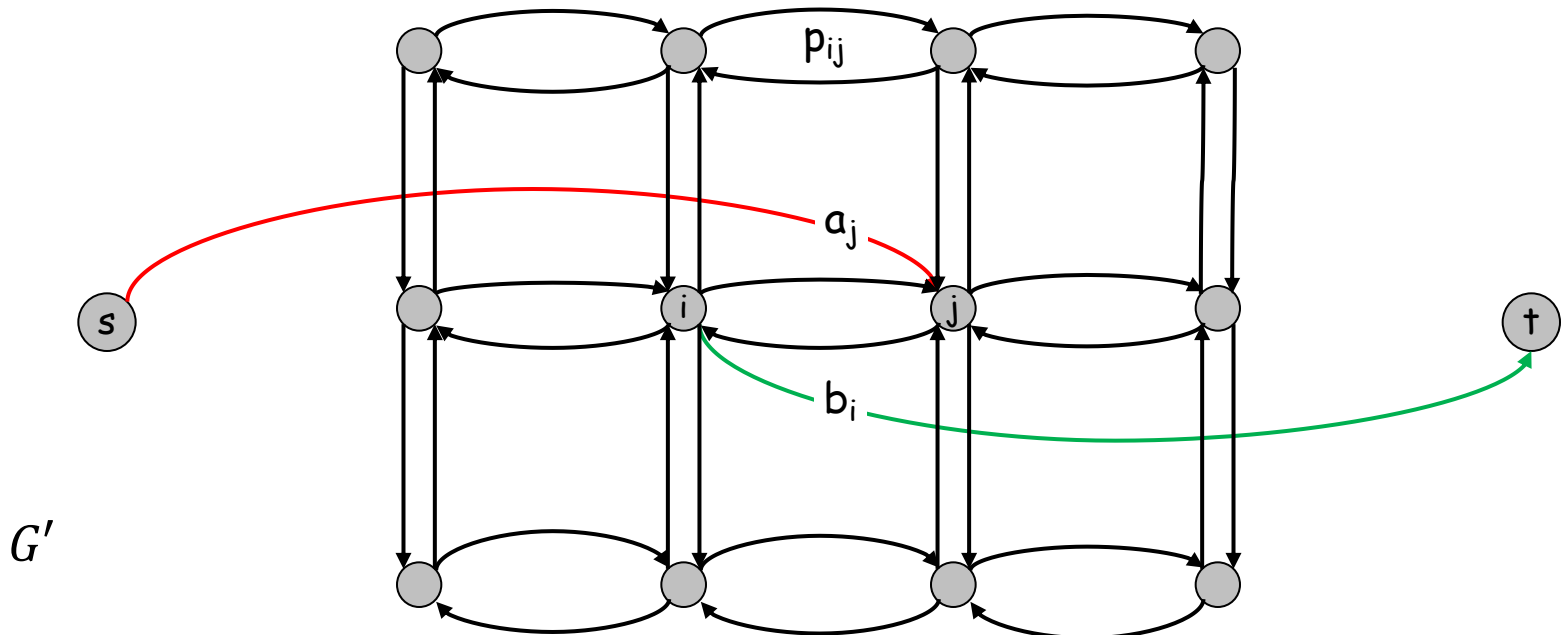
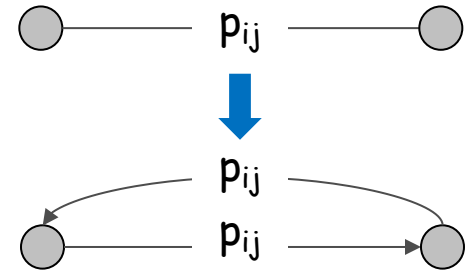
# Min cut Formulation (cont'd)

$G' = (V', E')$ .

Add  $s$  to correspond to foreground;

Add  $t$  to correspond to background

Use two anti-parallel edges  
instead of undirected edge.

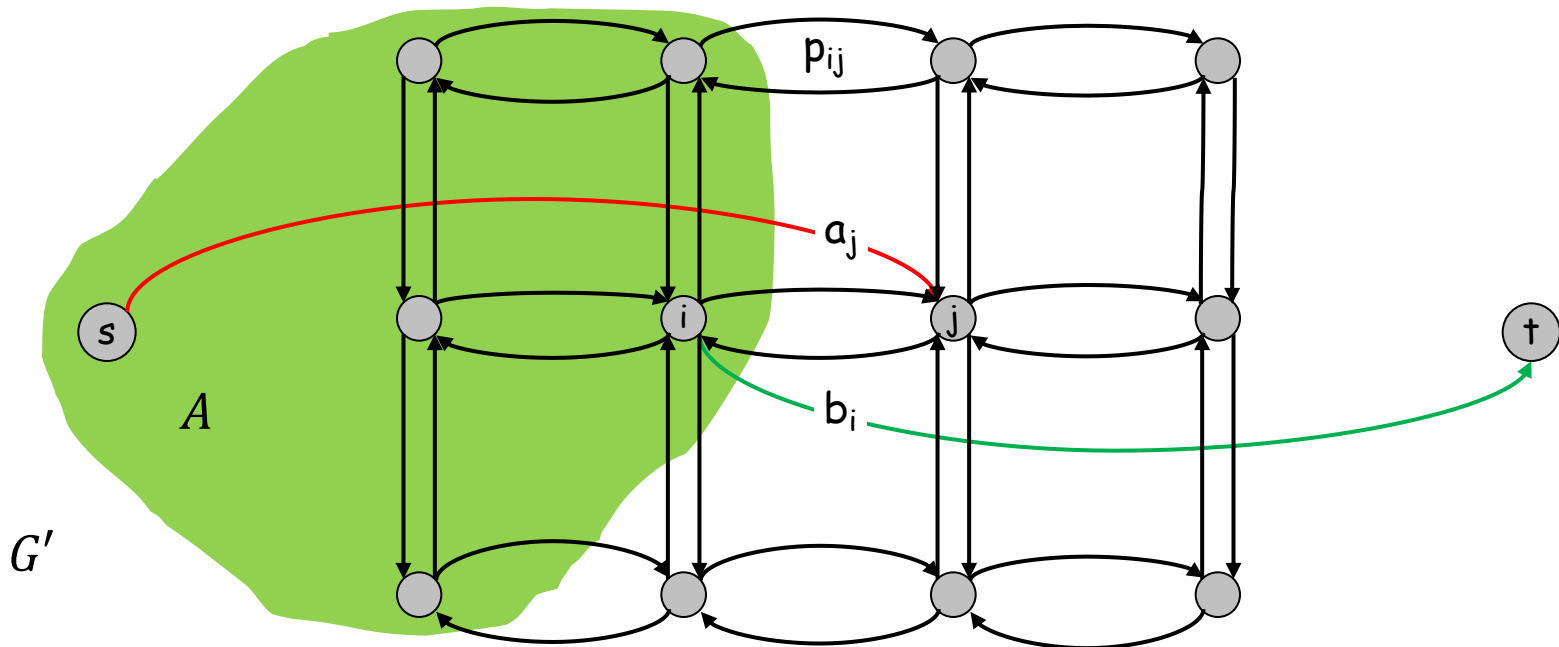


# Min cut Formulation (cont'd)

Consider min cut  $(A, B)$  in  $G'$ . ( $A$  = foreground.)

$$cap(A, B) = \sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{i,j}$$

Precisely the quantity we want to minimize.





# Linear Programming

# System of Linear Equations

Find a solution to

$$x_3 - x_1 = 4$$

$$x_3 - 2x_2 = 3$$

$$x_1 + 2x_2 + x_3 = 7$$

Can be solved by Gaussian elimination method in  $O(n^3)$   
when we have  $n$  variables/ $n$  constraints

# Linear Algebra Premier

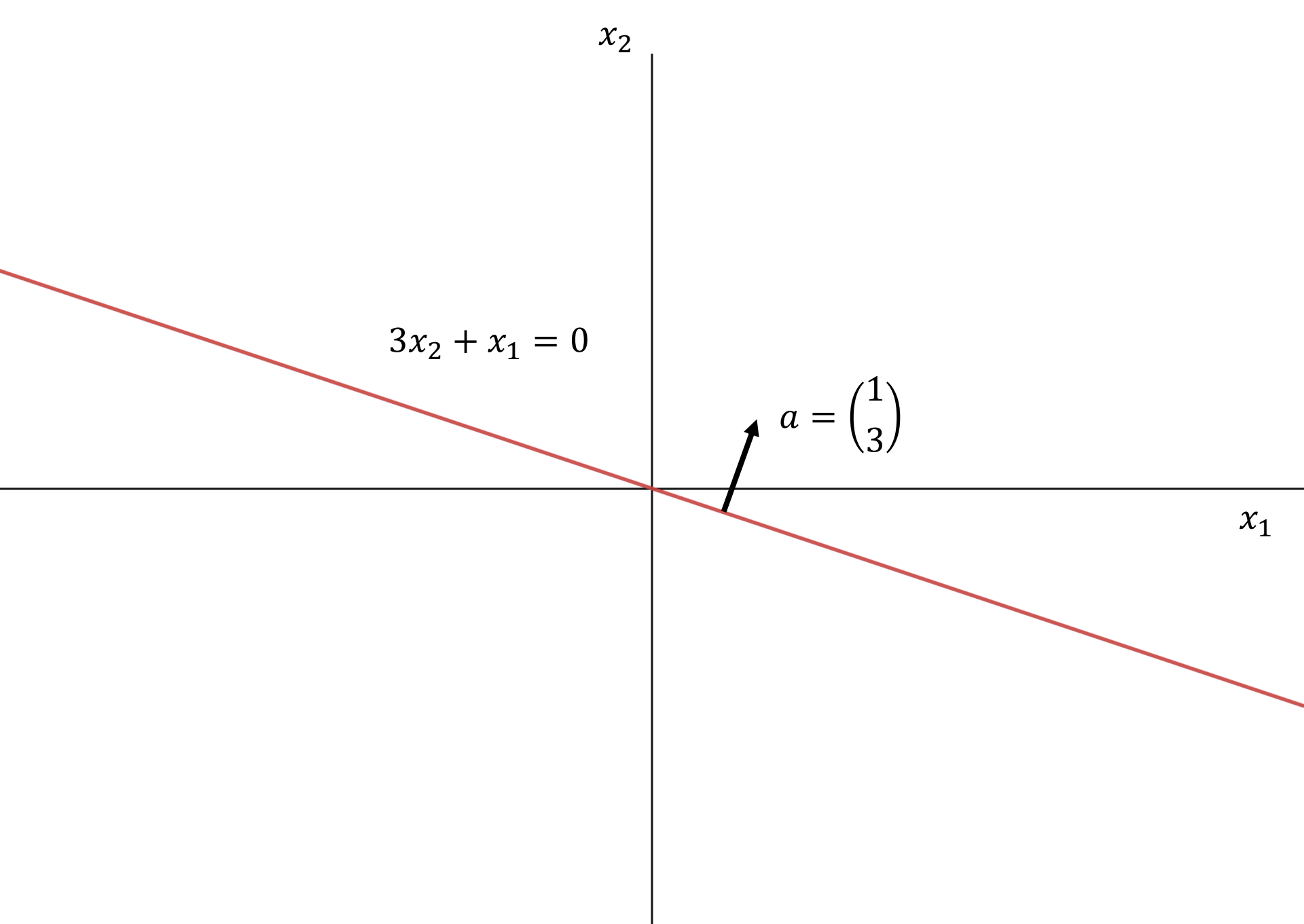
Let  $a$  be a column vector in  $\mathbb{R}^d$  and  $x$  a column vector of  $d$  variables.

$$\langle a, x \rangle = a^T x = a_1 x_1 + a_2 x_2 + \cdots + a_d x_d$$

**Hyperplane:** A hyperplane is the set of points  $x$  such that  $\langle a, x \rangle = b$  for some  $b \in \mathbb{R}$

**Halfspace:** A halfspace is the set of points on one side of a hyperplane.

$$\{x: \langle a, x \rangle \leq b\} \quad \text{or} \quad \{x: \langle a, x \rangle \geq b\}$$

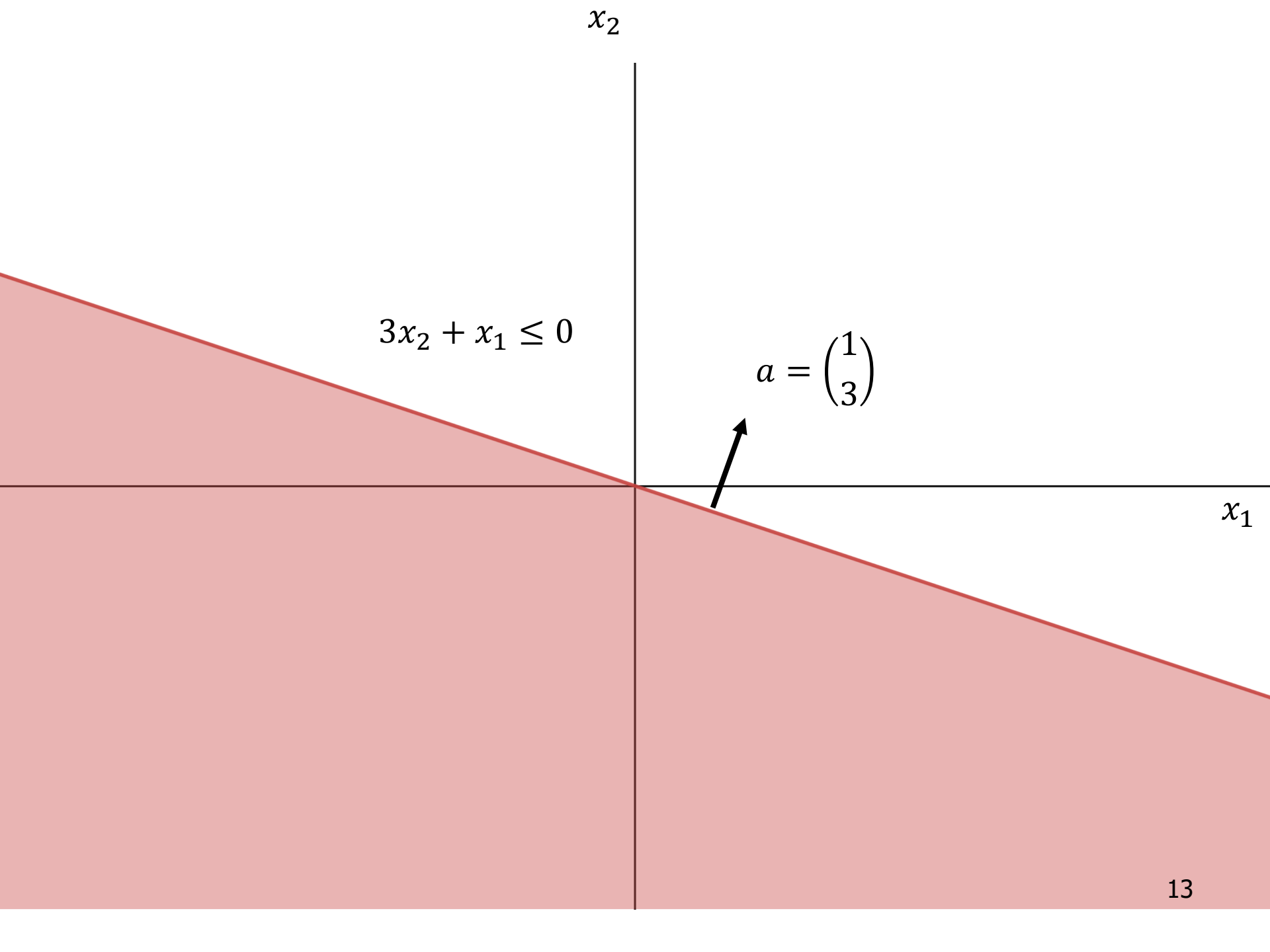


$x_2$

$$3x_2 + x_1 \leq 0$$

$$a = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$x_1$



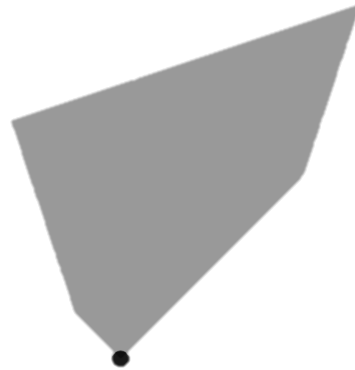
$x_2$

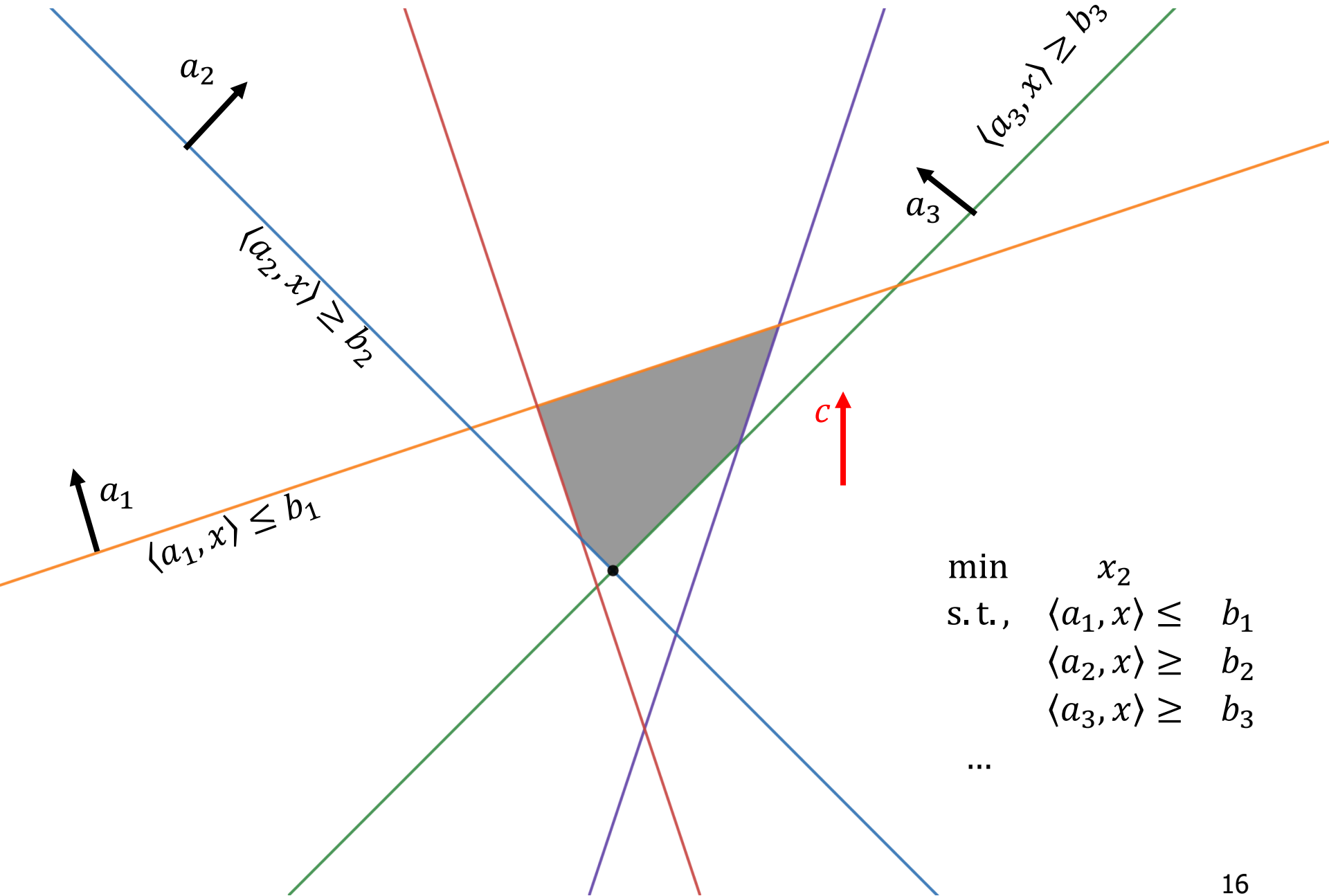
$$3x_2 + x_1 \leq -3$$

$x_1$

$a = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$

# Find the smallest point in a polytope







# Linear Programming

Optimize a linear function subject to linear inequalities

$$\begin{aligned} \max \quad & 3x_1 - 4x_3 \\ \text{s.t.}, \quad & x_1 + x_2 \leq 5 \\ & x_3 - x_1 = 4 \\ & x_3 - x_2 \geq -5 \\ & x_1, x_2, x_3 \geq 0 \end{aligned}$$

- We can have equalities and inequalities,
- We can have a linear objective functions

# Linear Algebra Premier

Let  $a$  be a column vector in  $\mathbb{R}^d$  and  $x$  a column vector of  $d$  variables.

$$\langle a, x \rangle = a^T x = a_1 x_1 + a_2 x_2 + \cdots + a_d x_d$$

$$A = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_m^T \end{bmatrix} \quad \longrightarrow \quad Ax = \begin{pmatrix} \langle a_1, x \rangle \\ \langle a_2, x \rangle \\ \vdots \\ \langle a_m, x \rangle \end{pmatrix}$$

$$Ax \leq b \quad \longrightarrow \quad \begin{array}{l} \langle a_1, x \rangle \leq b_1 \\ \langle a_2, x \rangle \leq b_2 \\ \vdots \\ \langle a_m, x \rangle \leq b_m \end{array}$$

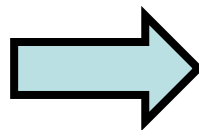
# Linear Programming Standard Form

$$\begin{aligned} \max \quad & \langle c, x \rangle \\ \text{s.t.}, \quad & Ax \leq b \\ & x \geq 0 \end{aligned}$$

Any linear program can be translated into the standard form.

$$\begin{aligned} \min \quad & y_1 - 2y_2 \\ \text{s.t.}, \quad & y_1 + 2y_2 = 3 \\ & y_1 - y_2 \geq 1 \\ & y_1 \geq 0 \end{aligned}$$

Replace  $y_2$   
with  $z_2 - z'_2$



$$\begin{aligned} \max \quad & -y_1 + 2(z_2 - z'_2) \\ \text{s.t.}, \quad & y_1 + 2(z_2 - z'_2) \leq 3 \\ & -(y_1 + 2(z_2 - z'_2)) \leq -3 \\ & -(y_1 - (z_2 - z'_2)) \leq -1 \\ & y_1, z_2, z'_2 \geq 0 \end{aligned}$$

# Applications of Linear Programming

**Generalizes:**  $Ax=b$ , 2-person zero-sum games, shortest path, max-flow, matching, multicommodity flow, MST, min weighted arborescence, ...

## Why significant?

- We can solve linear programming in polynomial time.
- Useful for approximation algorithms
- We can model many practical problems with a linear model and solve it with linear programming

## Linear Programming in Practice:

- There are very fast implementations: IBM CPLEX, Gorubi in Python, CVX in Matlab, ....
- CPLEX can solve LPs with millions of variables/constraints in minutes

# Example 1: Diet Problem

Suppose you want to schedule a diet for yourself. There are four category of food: veggies, meat, fruits, and dairy. Each category has its own (p)rice, (c)alory and (h)appiness per pound:

	veggies	meat	fruits	dairy
price	$p_v$	$p_m$	$p_f$	$p_d$
calorie	$c_v$	$c_m$	$c_f$	$c_d$
happiness	$h_v$	$h_m$	$h_f$	$h_d$

**Linear Modeling:** Consider a linear model: If we eat 0.5lb of meat, 0.2lb of fruits we will be  $0.5 h_m + 0.2 h_f$  happy

- You should eat 1500 calories to be healthy
- You can spend 20 dollars a day on food.

**Goal:** Maximize happiness?

# Diet Problem by LP

- You should eat 1500 calories to be healthy
- You can spend 20 dollars a day on food.

**Goal:** Maximize happiness?

	veggies	meat	fruits	dairy
price	$p_v$	$p_m$	$p_f$	$p_d$
calorie	$c_v$	$c_m$	$c_f$	$c_d$
happiness	$h_v$	$h_m$	$h_f$	$h_d$

$$\begin{aligned} \max \quad & x_v h_v + x_m h_m + x_f h_f + x_d h_d \\ \text{s. t.} \quad & x_v p_v + x_m p_m + x_f p_f + x_d p_d \leq 20 \\ & x_v c_v + x_m c_m + x_f c_f + x_d c_d \leq 1500 \\ & x_v, x_m, x_f, x_d \geq 0 \end{aligned}$$

#pounds of veggies, meat, fruits, dairy to eat per day

# Components of a Linear Program

- Set of variables
- Bounding constraints on variables,
  - Are they nonnegative?
- Objective function
- Is it a minimization or a maximization problem
- LP Constraints, make sure they are linear
  - Is it an equality or an inequality?

# Example 2: Max Flow

Define the set of variables

- For every edge  $e$  let  $x_e$  be the flow on the edge  $e$

Put bounding constraints on your variables

- $x_e \geq 0$  for all edge  $e$  (The flow is nonnegative)

Write down the constraints

- $x_e \leq c(e)$  for every edge  $e$ , (Capacity constraints)
- $\sum_{e \text{ out of } v} x_e = \sum_{e \text{ in to } v} x_e \quad \forall v \neq s, t$  (Conservation constraints)

Write down the objective function

- $\sum_{e \text{ out of } s} x_e$

Decide if it is a minimize/maximization problem

- **max**



# Example 2: Max Flow

$$\begin{aligned} \max \quad & \sum_{e \text{ out of } s} x_e \\ \text{s.t.} \quad & \sum_{e \text{ out of } v} x_e = \sum_{e \text{ in to } v} x_e \quad \forall v \neq s, t \\ & x_e \leq c(e) \quad \forall e \\ & x_e \geq 0 \quad \forall e \end{aligned}$$

Q: Do we get exactly the same properties as Ford Fulkerson?

A: Not necessarily, the max-flow **may not be integral**

# Example 3: Min Cost Max Flow

Suppose we can route 100 gallons of water from  $s$  to  $t$ .  
But for every pipe edge  $e$  we have to pay  $p(e)$   
for each gallon of water that we send through  $e$ .

**Goal:** Send 100 gallons of water from  $s$  to  $t$  with minimum possible cost

$$\begin{array}{ll} \min & \sum_{e \in E} p(e) \cdot x_e \\ \text{s. t.} & \sum_{e \text{ out of } v} x_e = \sum_{e \text{ in to } v} x_e \quad \forall v \neq s, t \\ & \sum_{e \text{ out of } s} x_e = 100 \\ & x_e \leq c(e) \quad \forall e \\ & x_e \geq 0 \quad \forall e \end{array}$$

# Linear Programming and Approximation Algorithms

# Integer Program for Vertex Cover

Given a graph  $G=(V,E)$  with costs  $c_v$  on the vertices. Find a vertex cover of  $G$  with minimum cost, i.e.,  $\min \sum_{v \in S} c_v$

Write LP with Integrality Constraint:

- Variables: One variable  $x_v$  for each vertex  $v$
- Bound:  $x_v \in \{0,1\}$
- Edge cover Constraints:  $x_u + x_v \geq 1$  for every edge  $(u, v) \in E$
- Obj:  $\min \sum_v c_v x_v$

# IP for Vertex Cover

$$\begin{aligned} \min \quad & \sum_v c_v x_v \\ \text{s.t.}, \quad & x_v + x_u \geq 1 \quad \forall (u, v) \in E \\ & x_v \in \{0, 1\} \quad \forall v \in V \end{aligned}$$

IP is NP-complete general!  
But there are fast algorithms in  
practice that often work

Fact:

min vertex cover.

Pf:

- First, any vertex cover  $S$ ,  $x_v = \begin{cases} 1 & \text{if } v \in S \\ 0 & \text{o.w.} \end{cases}$  is feasible
- For any feasible solution  $x$ , the  $S = \{v: x_v = 1\}$  is a vertex cover

# LP Relaxation Vertex Cover

$$\begin{aligned} \min \quad & \sum_v c_v x_v \\ \text{s.t.}, \quad & x_v + x_u \geq 1 \quad \forall (u, v) \in E \\ & 0 \leq x_v \leq 1 \quad \forall v \in V \end{aligned}$$

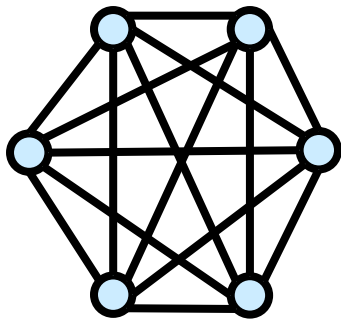
**Fact:** OPT-LP  $\leq$  Min Vertex Cover

**Pf:** Min vertex cover is a feasible solution of the LP

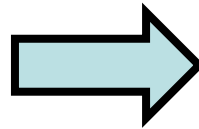
**Q:** Can we hope to get an integer solution?

# Bad Optimum solutions

$$\begin{aligned} \min \quad & \sum_v c_v x_v \\ \text{s.t.}, \quad & x_v + x_u \geq 1 \quad \forall (u, v) \in E \\ & 0 \leq x_v \leq 1 \quad \forall v \in V \end{aligned}$$



$K_n$  complete graph



A feasible solution:  
Set  $x_v = 0.5$  for all  $v$   
in the complete graph

If  $c_v = 1$  for all  $v$ , then  
Min vertex cover =  $n - 1$   
But OPT LP =  $n/2$ .

# Approximation Alg for Vertex Cover

Given a graph  $G=(V,E)$  with costs  $c_v$  on the edges. Find a vertex cover of  $G$  with minimum cost, i.e.,  $\min \sum_{v \in S} c_v$

**Thm:** There is a 2-approximation Alg for **weighted** vertex cover.

**ALG:** Solve LP. Let  $S = \{v: x_v \geq 0.5\}$ . Output  $S$ .

**Pf:** First, for every edge  $(u, v)$ ,  $x_u + x_v \geq 1$  So at least one is in  $S$ . So,  $S$  is a vertex cover.

Second,

$$\sum_{v \in S} c_v \leq \sum_{v \in S} c_v (2x_v) \leq 2 \text{OPTLP} \leq \text{Min Vertex Cov}$$