# CSE 421 Introduction to Algorithms

Lecture 16: Maxflow/MinCut

Ford-Fulkerson

#### **Announcements**

See EdStem Announcement/Email posted/sent on Sunday/Monday.

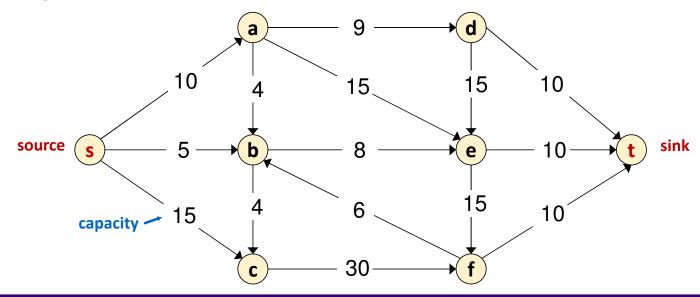
#### Midterm next Monday, November 4, 6:00 – 7:30 pm in this room

- Exam designed for a regular class time-slot but this includes extra time to finish.
- Coverage:
  - Up to the end of last Thursday's section on Dynamic Programming
- See important details in two Ed posts. Sample midterm for practice problems.
  - Includes 2-page "reference sheet" available to you on the midterm.
- Tomorrow's section will focus on review problems.
- Zoom review session for Q&A on Sunday Nov 3 at 4:45 pm.

#### **Last time: Flow Network**

#### Flow network:

- Abstraction for material *flowing* through the edges.
- G = (V, E) directed graph, no parallel edges.
- Two distinguished nodes: s = source, t = sink.
- c(e) = capacity of edge  $e \ge 0$ .

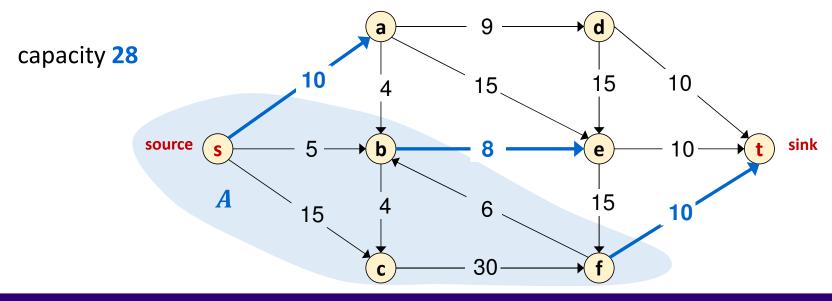


## **Last time: Minimum Cut Problem**

#### Minimum s-t cut problem:

**Given:** a flow network

Find: an s-t cut (A, B) of minimum capacity  $c(A, B) = \sum_{e \text{ out of } A} c(e)$ 



#### **Last time: Flows**

**Defn:** An s-t flow in a flow network is a function  $f: E \to \mathbb{R}$  that satisfies:

• For each  $e \in E$ :  $0 \le f(e) \le c(e)$ 

[capacity constraints]

• For each 
$$v \in V - \{s, t\}$$
: 
$$\sum_{e \text{ into } v} f(e) = \sum_{e \text{ out of } v} f(e)$$

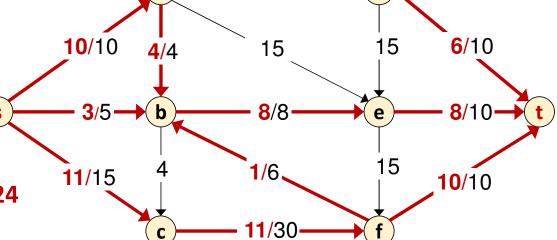
[flow conservation]

**Defn:** The value of flow f,

$$v(f) = \sum_{e \text{ out of } s} f(e)$$

Only show non-zero values of **f** 

value = 24

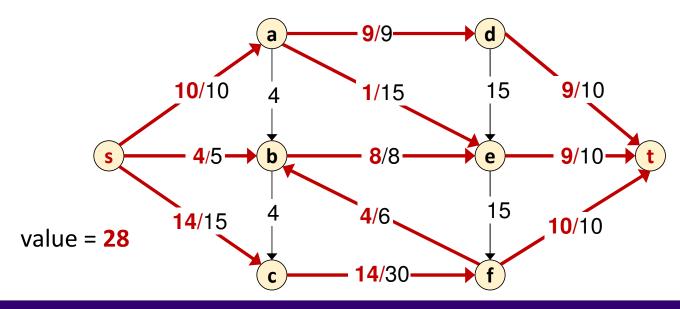


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#### **Last time: Maximum Flow Problem**

**Given:** a flow network

Find: an s-t flow of maximum value



## **Last time: Certificate of Optimality**

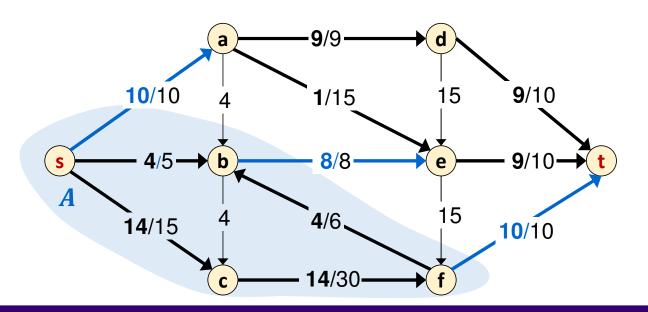
Corollary: Let f be any s-t flow and (A, B) be any s-t cut.

If v(f) = c(A, B) then f is a max flow and (A, B) is a min cut.

Value of flow = 28

Capacity of cut = 28

Both are optimal!



## Last time: Towards a Max Flow Algorithm

What about the following greedy algorithm?

- Start with f(e) = 0 for all edges  $e \in E$ .
- While there is an s-t path P where each edge has f(e) < c(e).
  - "Augment" flow along P; that is:
    - Let  $\alpha = \min_{e \in P} (c(e) f(e))$
    - Add  $\alpha$  to flow on every edge e along path P. (Adds  $\alpha$  to v(f).)

But this can get stuck...

#### Flows and cuts so far

Let f be any s-t flow and (A, B) be any s-t cut:

Flow Value Lemma: The net value of the flow sent across (A, B) equals v(f).

$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$

Weak Duality: The value of the flow is at most the capacity of the cut;

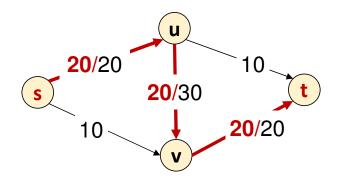
i.e., 
$$v(f) \le c(A, B)$$
. "Maxflow  $\le$  Mincut"

Corollary: If v(f) = c(A, B) then f is a maximum flow and (A, B) is a minimum cut.

Augmenting along paths using a greedy algorithm can get stuck.

**Today:** Ford-Fulkerson Algorithm, which applies greedy ideas to a "residual graph" that lets us reverse prior flow decisions from the basic greedy approach.

## **Greed Revisited: Residual Graph & Augmenting Paths**

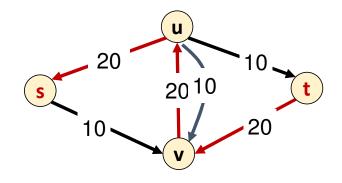


The only way we could route more flow from **s** to **t** would be to reduce the flow from **u** to **v** to make room for that amount of extra flow from **s** to **v**.

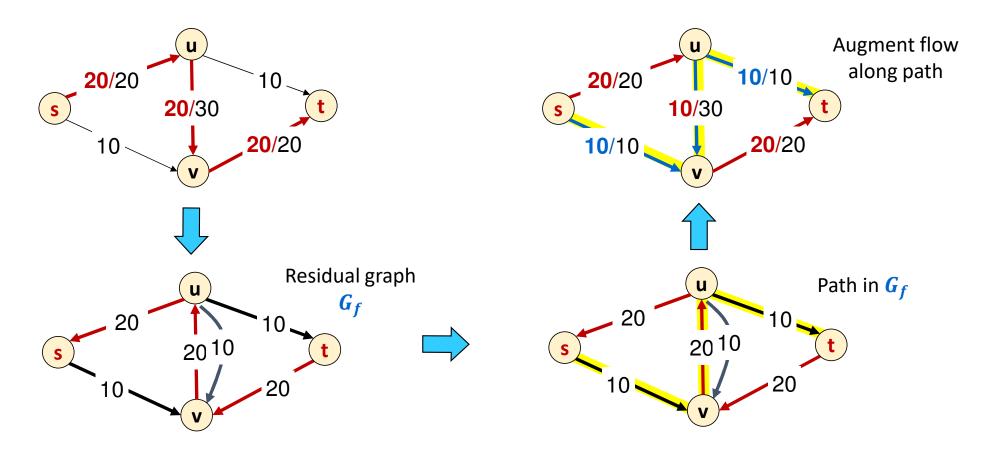
But to conserve flow we also would need to increase the flow from **u** to **t** by that same amount.

Suppose that we took this flow **f** as a baseline, what changes could each edge handle?

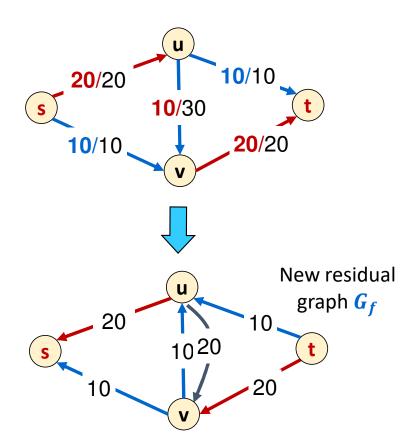
- We could add up to 10 units along sv or ut or uv
- We could reduce by up to 20 units from  $\mathbf{su}$  or  $\mathbf{uv}$  or  $\mathbf{vt}$  This gives us a residual graph  $G_f$  of possible changes where we draw reducing as "sending back".



## **Greed Revisited: Residual Graph & Augmenting Paths**



## **Greed Revisited: Residual Graph & Augmenting Paths**



No *s-t* path

BTW: Flow is optimal

## **Residual Graphs**

Original edge:  $e = (u, v) \in E$ .

• Flow f(e), capacity c(e).

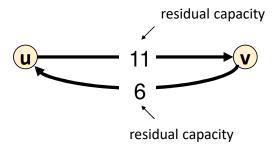


#### Residual edges of two kinds:

- Forward: e = (u, v) with capacity  $c_f(e) = c(e) f(e)$ 
  - Amount of extra flow we can add along e
- Backward:  $e^{R} = (v, u)$  with capacity  $c_{f}(e) = f(e)$ 
  - Amount we can reduce/undo flow along e

Residual graph:  $G_f = (V, E_f)$ .

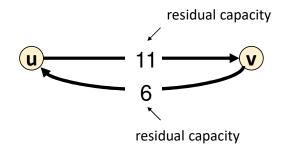
- Residual edges with residual capacity  $c_f(e) > 0$ .
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}.$



## **Residual Graphs and Augmenting Paths**

#### Residual edges of two kinds:

- Forward: e = (u, v) with capacity  $c_f(e) = c(e) f(e)$ 
  - Amount of extra flow we can add along e
- Backward:  $e^{R} = (v, u)$  with capacity  $c_{f}(e) = f(e)$ 
  - Amount we can reduce/undo flow along e

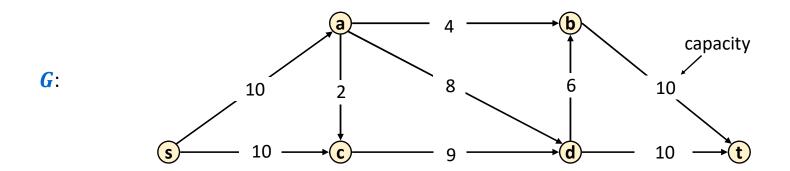


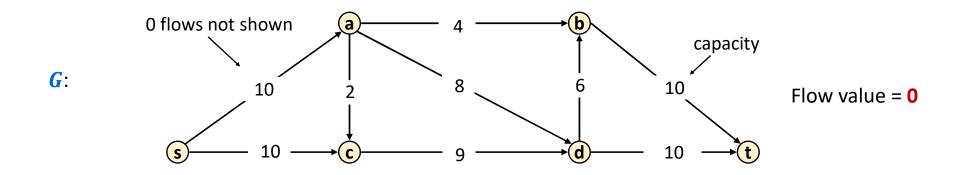
#### Residual graph: $G_f = (V, E_f)$ .

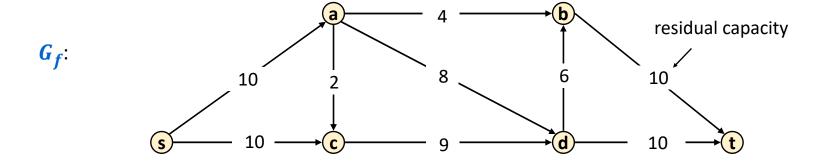
- Residual edges with residual capacity  $c_f(e) > 0$ .
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}.$

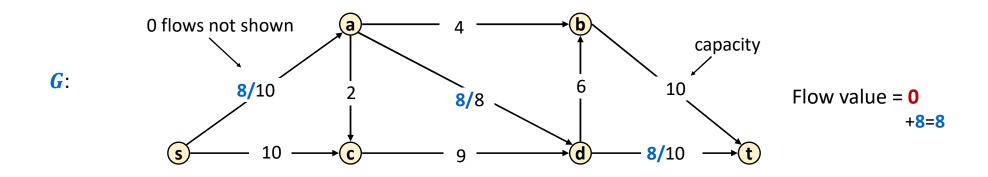
Augmenting Path: Any s-t path P in  $G_f$ . Let bottleneck(P)=  $\min_{e \in P} c_f(e)$ .

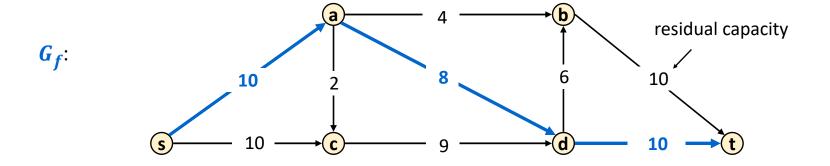
Ford-Fulkerson idea: Repeat "find an augmenting path P and increase flow by bottleneck(P)" until none left.

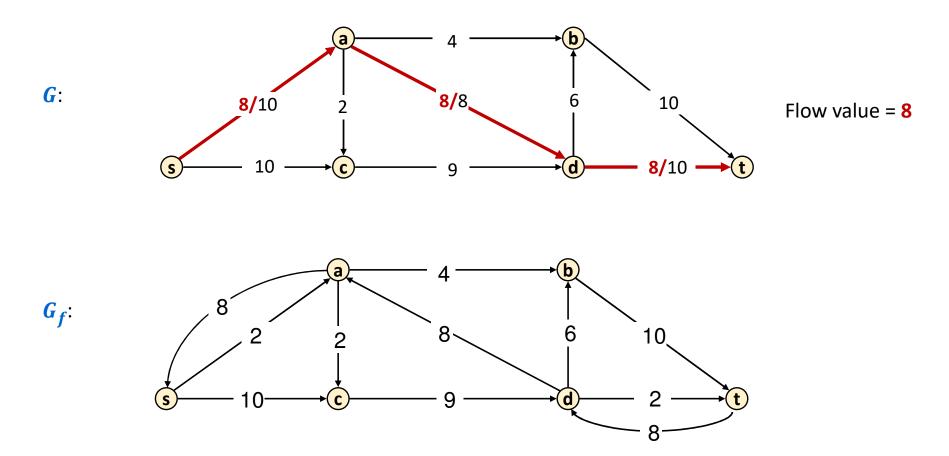


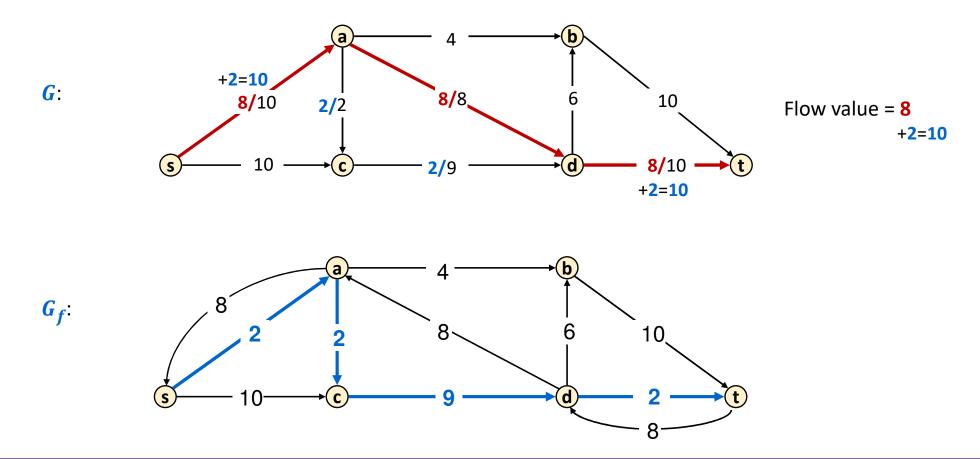


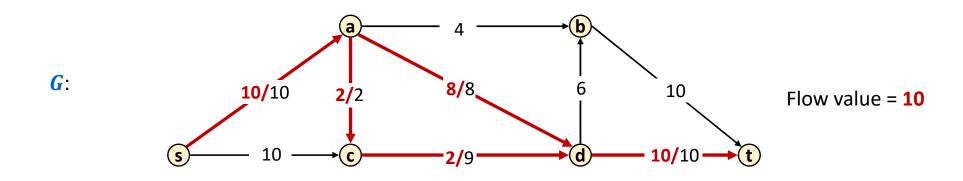


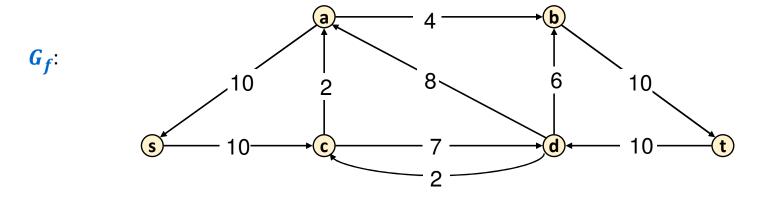


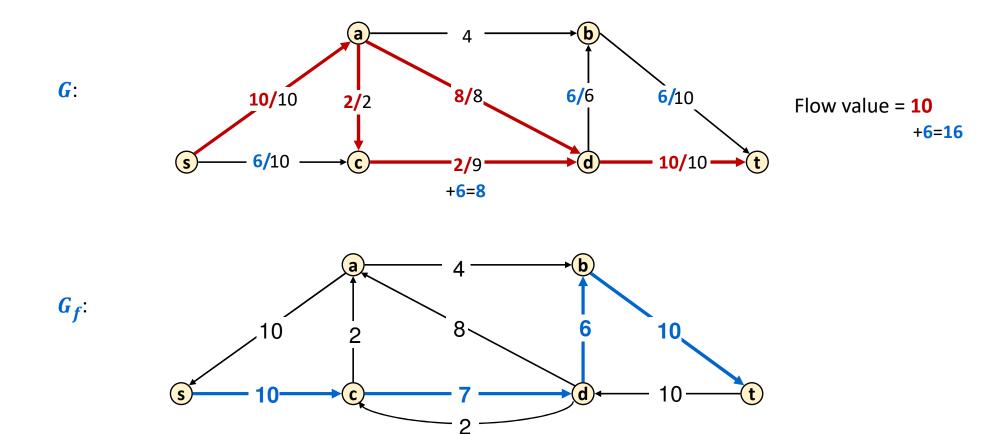


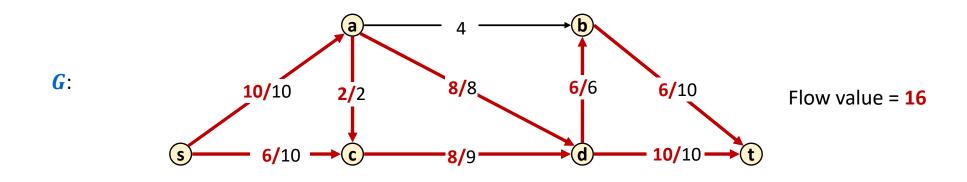


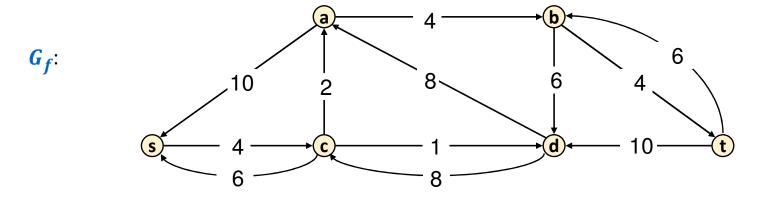


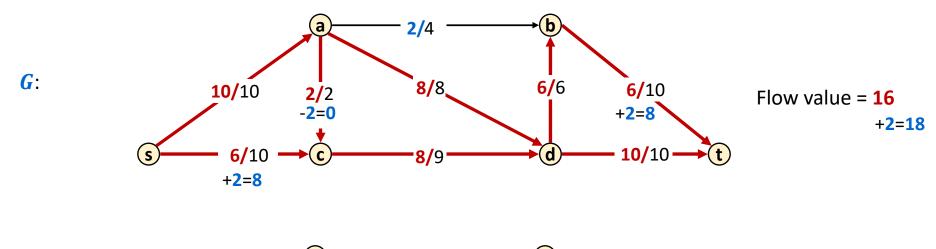


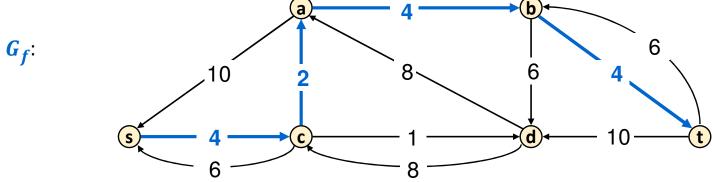


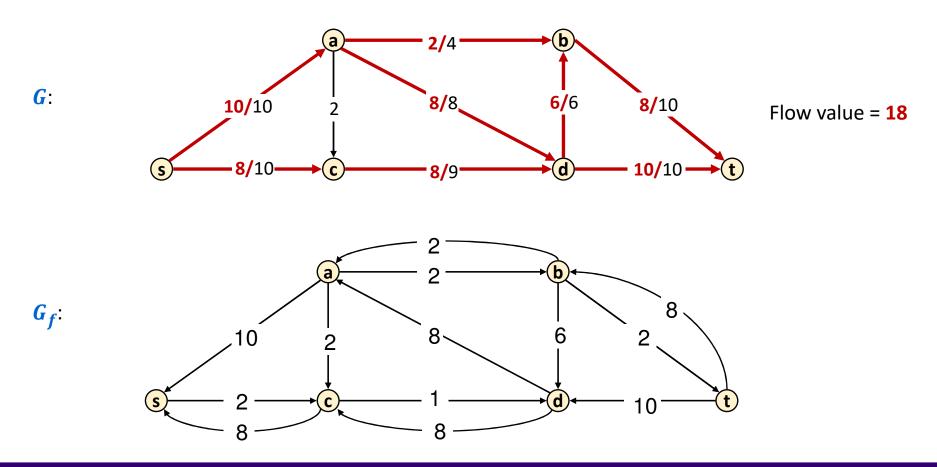


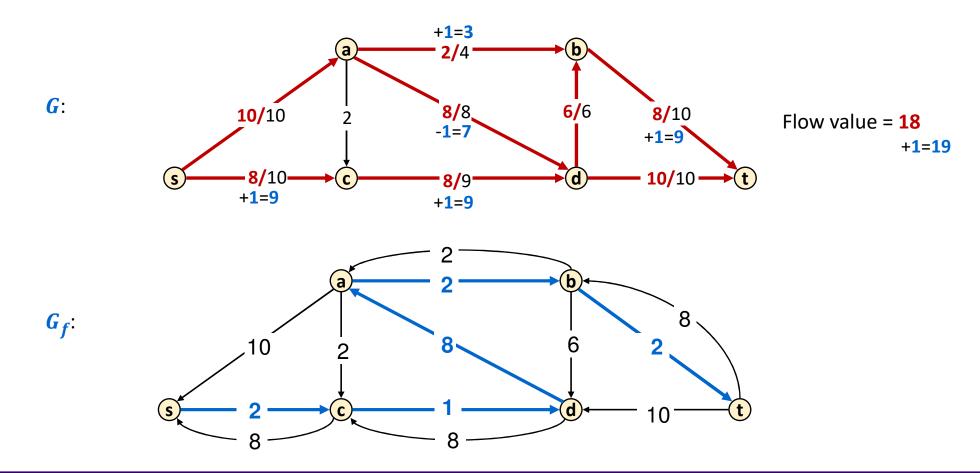


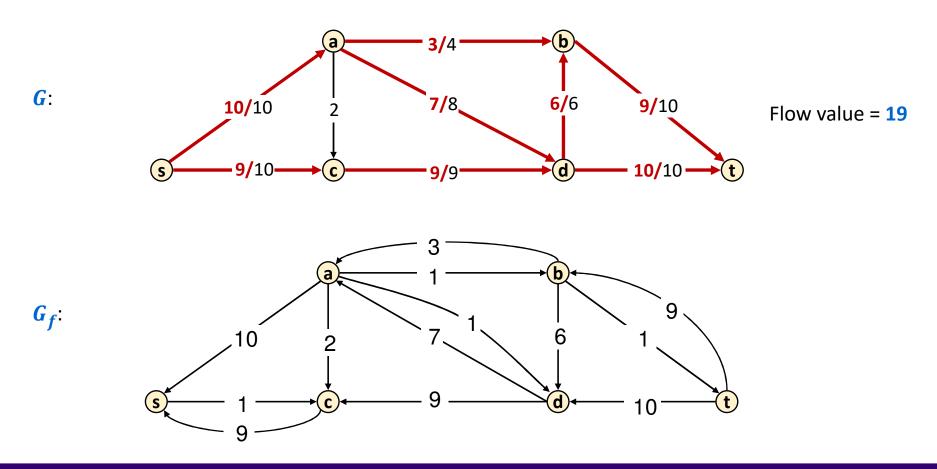


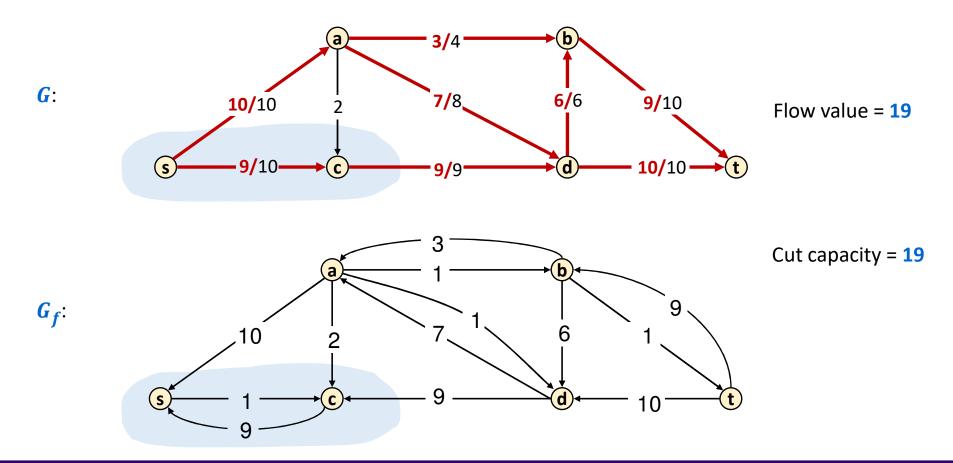












## **Augmenting Path Algorithm**

```
\label{eq:ford-Fulkerson} \begin{split} &\text{Ford-Fulkerson}(G,\ s,\ t,\ c)\ \{\\ &\text{foreach}\ e\in E\ f(e)\leftarrow 0\\ &G_f\leftarrow G \end{split} \label{eq:while} \begin{aligned} &\text{while}\ (G_f\ has\ an\ s-t\ path\ P)\ \{\\ &f\leftarrow Augment(f,\ c,\ P)\\ &update\ G_f \end{aligned} \label{eq:has-ham} \\ &\text{return}\ f \end{split}
```

```
Augment(f, c, P) {
   b \leftarrow bottleneck(P)
   foreach e \in P {
      if (e \in E) f(e) \leftarrow f(e) + b
      else      f(e^R) \leftarrow f(e^R) - b
   }
  return f
}
```

#### **Max-Flow Min-Cut Theorem**

Augmenting Path Theorem: Flow f is a max flow  $\Leftrightarrow$  there are no augmenting paths wrt f

Max-Flow Min-Cut Theorem: The value of the max flow equals the value of the min cut.

[Elias-Feinstein-Shannon 1956, Ford-Fulkerson 1956] "Maxflow = Mincut"

- (i) There is a cut (A, B) such that v(f) = c(A, B).
  - (ii) Flow f is a max flow.
- (iii) There is no augmenting path w.r.t. f.
- $(i) \Rightarrow (ii)$ : We already know this by the corollary to weak duality lemma.

**Proof:** We prove both together by showing that all of these are equivalent:

Only  $\underline{\text{(iii)}} \Rightarrow \underline{\text{(i)}}$  remaining

 $(ii) \Rightarrow (iii)$ : (by contradiction)

If there is an augmenting path w.r.t. flow f then we can improve f. Therefore f is not a max flow.

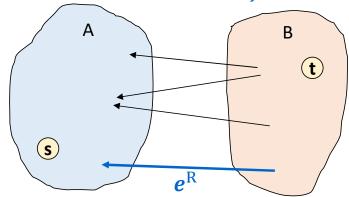
 $(iii) \Rightarrow (i)$ :

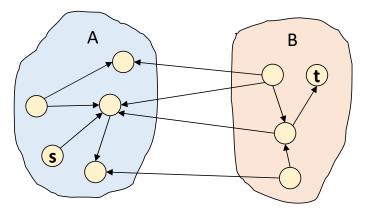
Claim: If there is no augmenting path w.r.t. f, there is a cut (A, B) s.t. v(f) = c(A, B).

**Proof of Claim:** Let **f** be a flow with no augmenting paths.

Let A be the set of vertices reachable from s in residual graph  $G_f$ .

- By definition of A,  $s \in A$ .
- Since no augmenting path (s-t path in  $G_f$ ),  $t \notin A$ .





residual graph

 $(iii) \Rightarrow (i)$ :

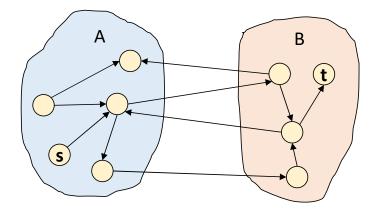
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Then 
$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$



original network

No edge  $e^R$  in

 $(iii) \Rightarrow (i)$ :

Claim: If there is no augmenting path w.r.t. f, there is a cut (A, B) s.t. v(f) = c(A, B).

No edge  $e^{R}$  in residual graph

**Proof of Claim:** Let **f** be a flow with no augmenting paths.

Let A be the set of vertices reachable from s in residual graph  $G_f$ .

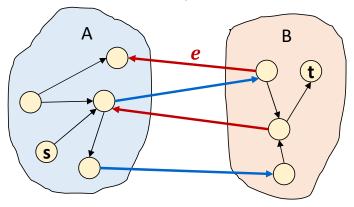
So no flow on  $oldsymbol{e}$ 

- By definition of A,  $s \in A$ .
- Since no augmenting path (s-t path in  $G_f$ ),  $t \notin A$ .

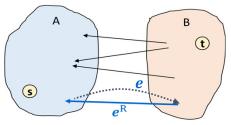
Then 
$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$

$$= \sum_{e \text{ out of } A} f(e)$$

$$f(e) = c_f(e^{R}) = 0$$



original network



 $(iii) \Rightarrow (i)$ :

Claim: If there is no augmenting path w.r.t. f, there is a cut (A, B) s.t. v(f) = c(A, B).

No edge *e* in residual graph

**Proof of Claim:** Let **f** be a flow with no augmenting paths.

Let A be the set of vertices reachable from s in residual graph  $G_f$ .

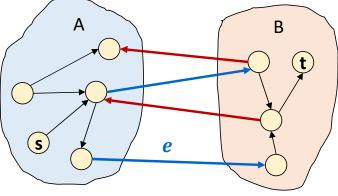
- By definition of A,  $s \in A$ .
- Since no augmenting path (s-t path in  $G_f$ ),  $t \notin A$ .

Then 
$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$

$$= \sum_{e \text{ out of } A} f(e)$$

$$= \sum_{e \text{ out of } A} c(e)$$

No unused capacity on  $oldsymbol{e}$   $oldsymbol{0} = oldsymbol{c}_f(oldsymbol{e}) = oldsymbol{c}(oldsymbol{e}) - oldsymbol{f}(oldsymbol{e})$ 



f(e) = c(e) original network

 $(iii) \Rightarrow (i)$ :

Claim: If there is no augmenting path w.r.t. f, there is a cut (A, B) s.t. v(f) = c(A, B).

**Proof of Claim:** Let **f** be a flow with no augmenting paths.

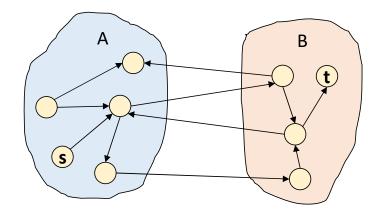
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Then 
$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$

$$= \sum_{e \text{ out of } A} f(e)$$

$$= \sum_{e \text{ out of } A} c(e) = c(A, B)$$



original network

## **Running Time**

- Computing first  $G_f$  takes O(n+m) time. (Can ignore disconnected bits so  $m \ge n-1$ .)
- Finding each augmenting path (graph search in  $G_f$ ) takes O(m) time.
- Updating f and  $G_f$  takes O(n) time.

Total O(m) per iteration.

**Assumption:** All capacities are integers between 1 and C.

Ford-Fulkerson Invariant: Every flow value f(e) and every residual capacity  $c_f(e)$  remains an integer throughout the algorithm. So there is a maximum flow with only integer flows.

**Theorem:** The Ford-Fulkerson algorithm terminates in  $\leq$  Maxflow < nC iterations.

**Proof:** Capacity of cut with  $A = \{s\}$  is  $\leq (n-1)C$ . Each augmentation increases flow value by at least 1.

Corollary: If C = 1, Ford-Fulkerson runs in O(mn) time.

A graph G = (V, E) is bipartite iff

- Set V of vertices has two disjoint parts X and Y
- Every edge in E joins a vertex from X and a vertex from Y

Set  $M \subseteq E$  is a matching in G iff no two edges in M share a vertex

**Goal:** Find a matching M in G of maximum size.

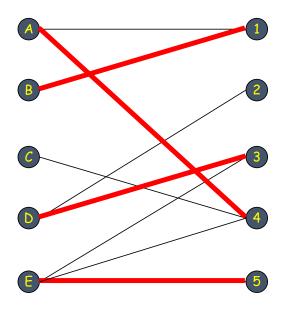
Differences from stable matching

- limited set of possible partners for each vertex
- sides may not be the same size
- no notion of stability; matching everything may be impossible.

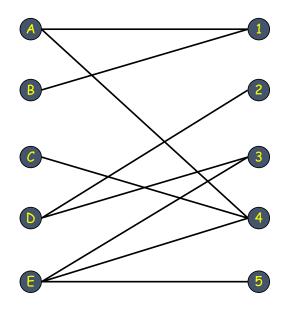
- Models assignment problems
  - X represents customers, Y represents salespeople
  - X represents professors, Y represents courses
- If |X| = |Y| = n
  - G has perfect matching iff maximum matching has size n

**Input:** Bipartite graph

Goal: Find maximum size matching.

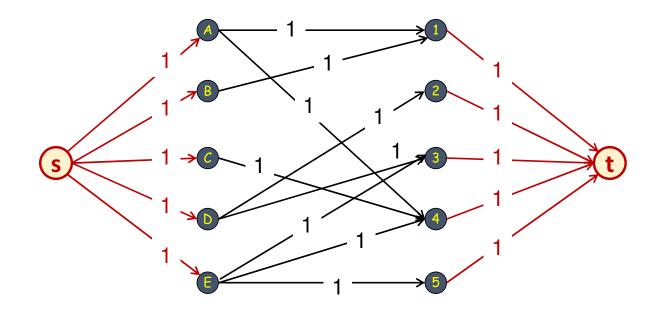


**Input:** Bipartite graph



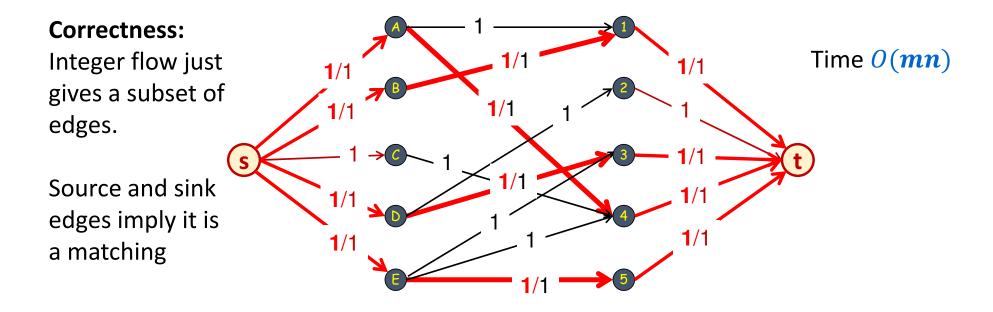
Add new source **s** pointing to left set, new sink **t** pointed to by right set.

Direct all edges from left to right with capacity 1. Compute MaxFlow.



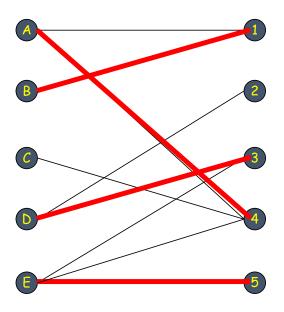
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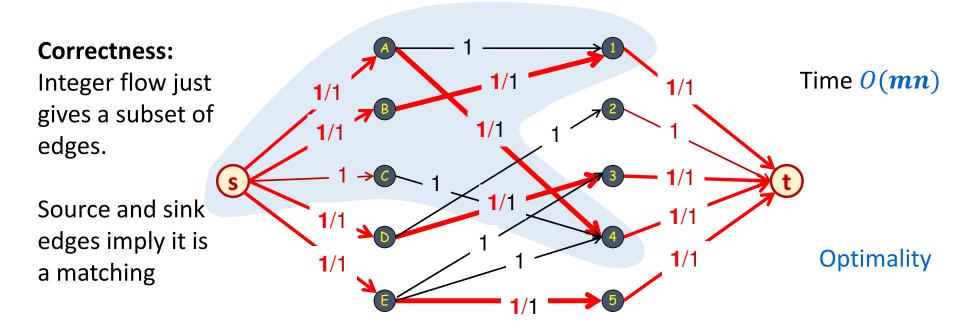
**Input:** Bipartite graph

Goal: Find maximum size matching.



**Optimality** 

Add new source s pointing to left set, new sink t pointed to by right set. Direct all edges from left to right with capacity 1. Compute MaxFlow.



## Ford-Fulkerson Efficiency

Worst case runtime O(mnC) with integer capacities  $\leq C$ .

- O(m) time per iteration.
- At most **nC** iterations.
- This is "pseudo-polynomial" running time.
- May take exponential time, even with integer capacities:

$$c = 10^9$$
, say
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, say