# CSE 421 Introduction to Algorithms

# Lecture 16: Ford-Fulkerson

**W** PAUL G. ALLEN SCHOOL of computer science & engineering

### Announcements

#### See EdStem Announcement/Email posted/sent yesterday.

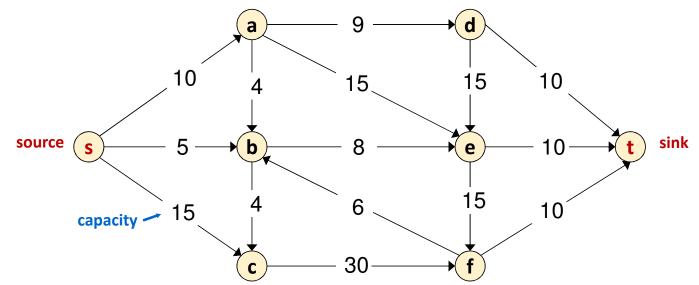
#### Midterm next Wednesday, November 8, 6:00 – 7:30 pm in this room

- Exam designed for a regular class time-slot but this includes extra time to finish.
- Coverage:
  - Up to the end of last Thursday's section on Dynamic Programming
- Sample midterm for practice problems and length coming later today.
  - Will include "reference sheet" available to you on the midterm.
- Tomorrow's section will focus on review problems.
- Zoom review session for Q&A on Tuesday Nov 7 at 4:30 pm.

## Last time: Flow Network

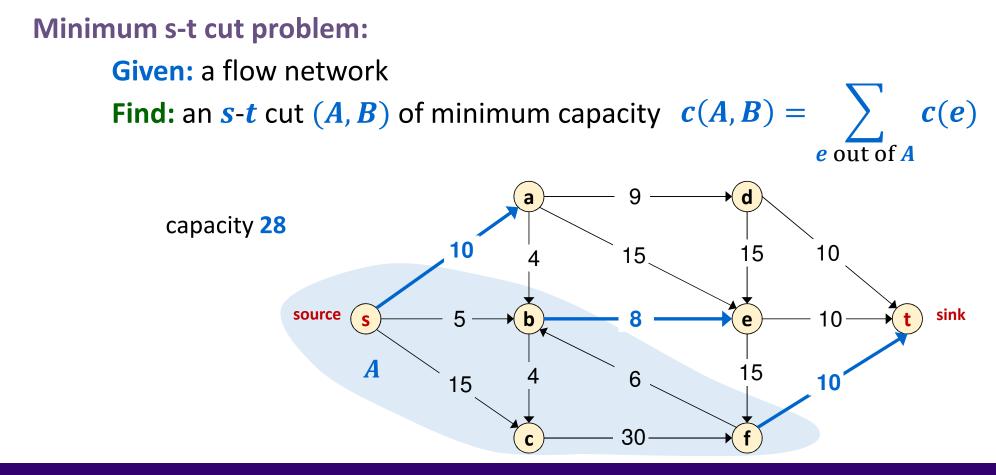
Flow network:

- Abstraction for material *flowing* through the edges.
- G = (V, E) directed graph, no parallel edges.
- Two distinguished nodes: **s** = source, **t** = sink.
- c(e) = capacity of edge  $e \ge 0$ .





#### Last time: Minimum Cut Problem

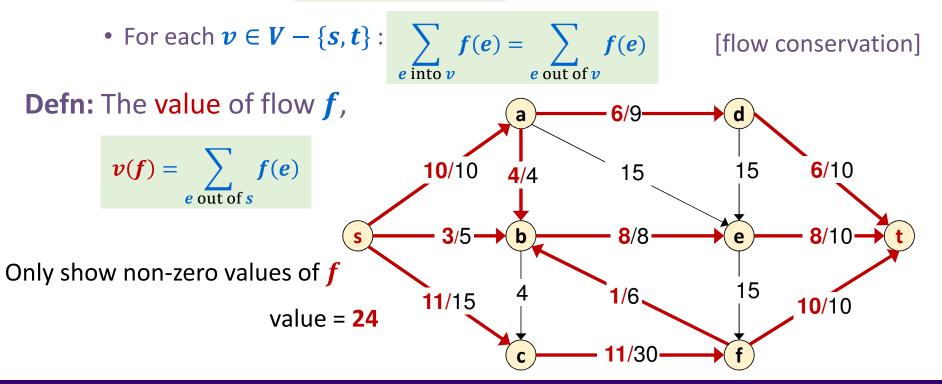


#### **Last time: Flows**

**Defn:** An *s*-*t* flow in a flow network is a function  $f: E \to \mathbb{R}$  that satisfies:

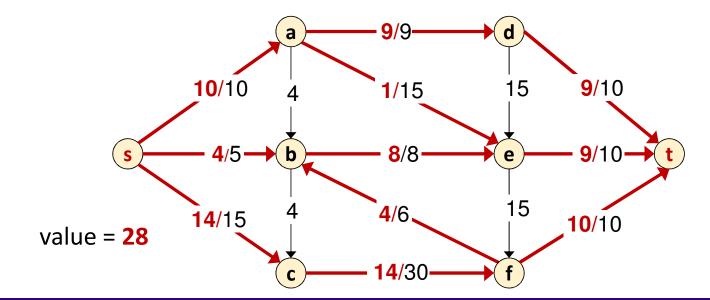
• For each  $e \in E$ :  $0 \leq f(e) \leq c(e)$ 

[capacity constraints]



### Last time: Maximum Flow Problem

**Given:** a flow network **Find:** an *s*-*t* flow of maximum value

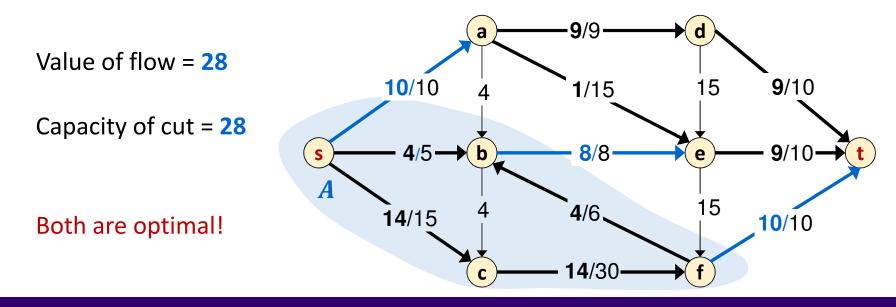




#### Last time: Certificate of Optimality

**Corollary:** Let **f** be any **s**-**t** flow and (**A**, **B**) be any **s**-**t** cut.

If v(f) = c(A, B) then f is a max flow and (A, B) is a min cut.



# Last time: Towards a Max Flow Algorithm

What about the following greedy algorithm?

- Start with f(e) = 0 for all edges  $e \in E$ .
- While there is an s-t path P where each edge has f(e) < c(e).
  - "Augment" flow along **P**; that is:
    - Let  $\alpha = \min_{e \in P} (c(e) f(e))$
    - Add  $\alpha$  to flow on every edge *e* along path *P*. (Adds  $\alpha$  to v(f).)

But this can get stuck...

### Flows and cuts so far

Let **f** be any **s**-**t** flow and (**A**, **B**) be any **s**-**t** cut:

Flow Value Lemma: The net value of the flow sent across (A, B) equals v(f).  $v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$ 

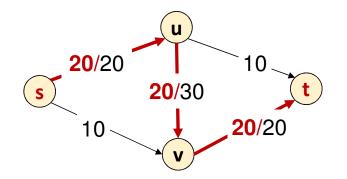
Weak Duality: The value of the flow is at most the capacity of the cut; i.e.,  $v(f) \le c(A, B)$ . "Maxflow  $\le$  Mincut"

**Corollary:** If v(f) = c(A, B) then f is a maximum flow and (A, B) is a minimum cut.

Augmenting along paths using a greedy algorithm can get stuck.

**Today:** Ford-Fulkerson Algorithm, which applies greedy ideas to a "residual graph" that lets us reverse prior flow decisions from the basic greedy approach.

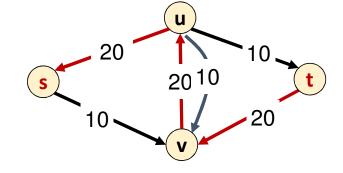
#### **Greed Revisited: Residual Graph & Augmenting Paths**



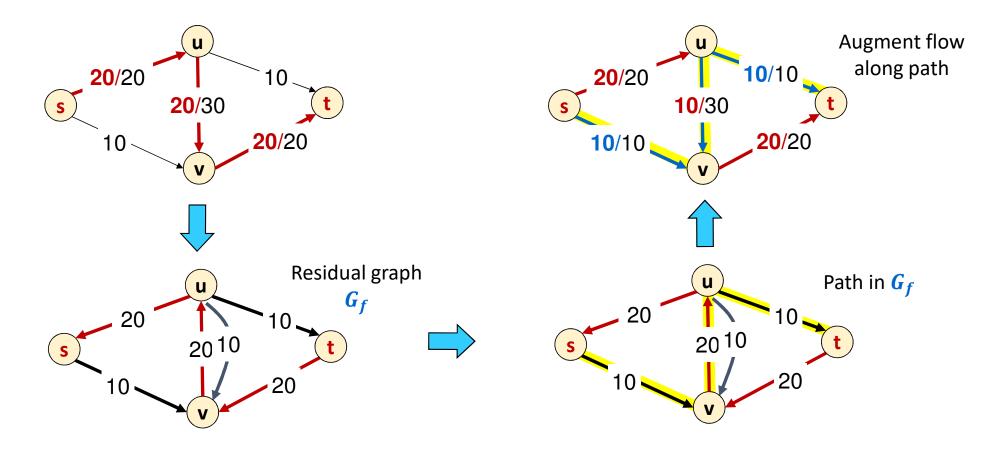
The only way we could route more flow from **s** to **t** would be to reduce the flow from **u** to **v** to make room for that amount of extra flow from **s** to **v**. But to conserve flow we also would need to increase the flow from **u** to **t** by that same amount.

Suppose that we took this flow **f** as a baseline, what changes could each edge handle?

- We could add up to 10 units along sv or ut or uv
- We could reduce by up to 20 units from **su** or **uv** or **vt** This gives us a residual graph  $G_f$  of possible changes where we draw reducing as "sending back".

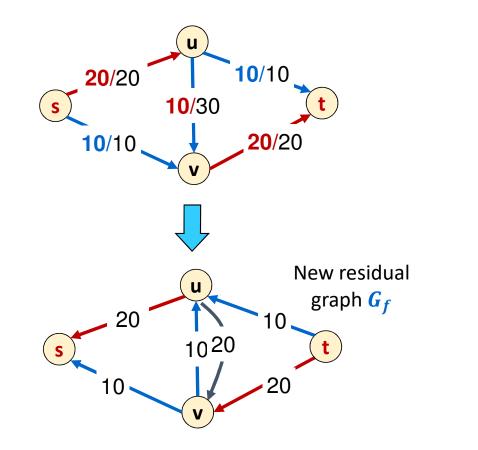


#### **Greed Revisited: Residual Graph & Augmenting Paths**





#### **Greed Revisited: Residual Graph & Augmenting Paths**



No *s*-*t* path

BTW: Flow is optimal



# **Residual Graphs**

Original edge:  $e = (u, v) \in E$ .

• Flow *f*(*e*), capacity *c*(*e*).

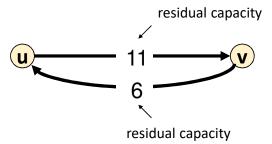


- Forward: e = (u, v) with capacity  $c_f(e) = c(e) f(e)$ 
  - Amount of extra flow we can add along e
- Backward:  $e^{R} = (v, u)$  with capacity  $c_{f}(e) = f(e)$ 
  - Amount we can reduce/undo flow along e

#### Residual graph: $G_f = (V, E_f)$ .

- Residual edges with residual capacity  $c_f(e) > 0$ .
- $E_f = \{e : f(e) < c(e)\} \cup \{e^{\mathbb{R}} : f(e) > 0\}.$





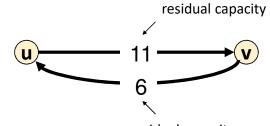
### **Residual Graphs and Augmenting Paths**

Residual edges of two kinds:

- Forward: e = (u, v) with capacity  $c_f(e) = c(e) f(e)$ 
  - Amount of extra flow we can add along e
- Backward:  $e^{R} = (v, u)$  with capacity  $c_{f}(e) = f(e)$ 
  - Amount we can reduce/undo flow along e

Residual graph:  $G_f = (V, E_f)$ .

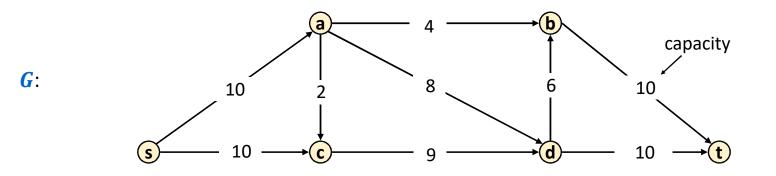
- Residual edges with residual capacity  $c_f(e) > 0$ .
- $E_f = \{e : f(e) < c(e)\} \cup \{e^{\mathbb{R}} : f(e) > 0\}.$



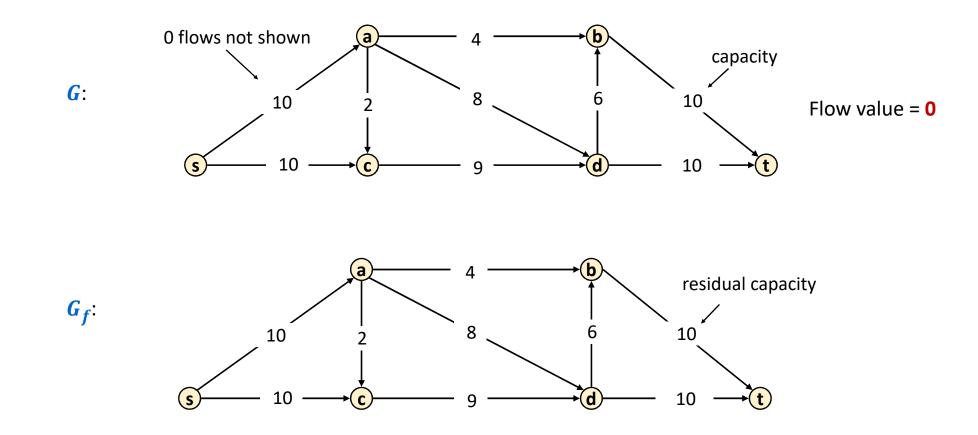
residual capacity

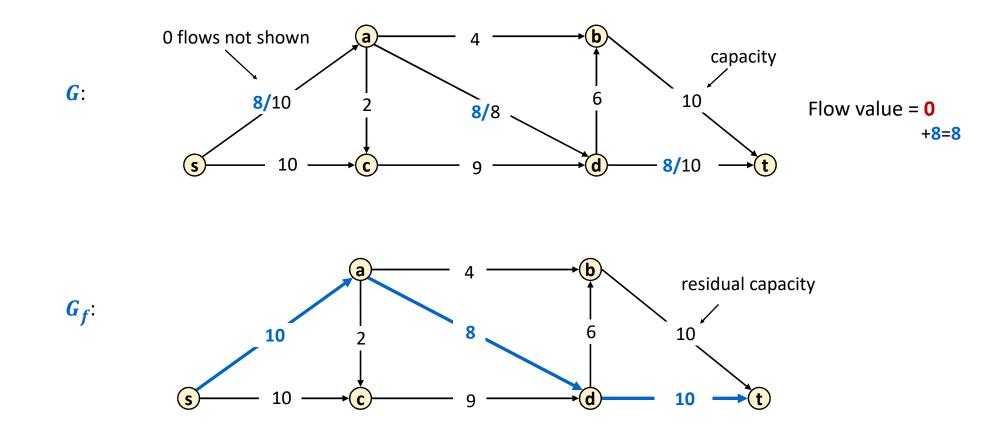
Augmenting Path: Any *s*-*t* path *P* in  $G_f$ . Let bottleneck(*P*) =  $\min_{e \in P} c_f(e)$ .

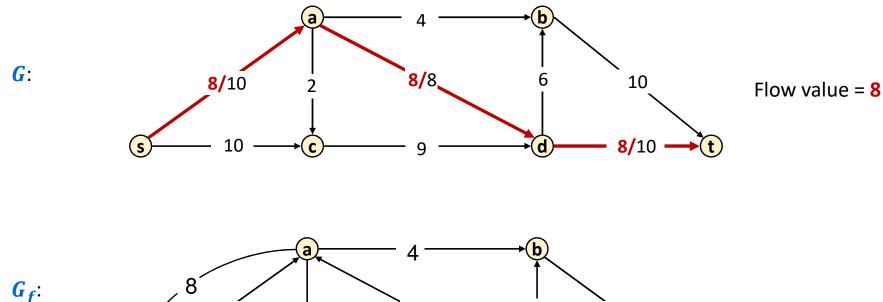
Ford-Fulkerson idea: Repeat "find an augmenting path *P* and increase flow by bottleneck(*P*)" until none left.

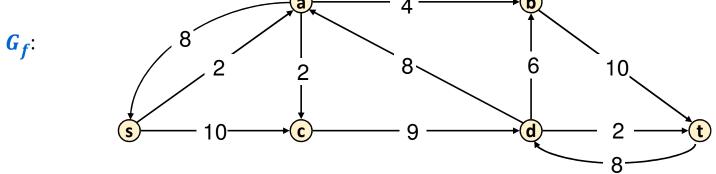


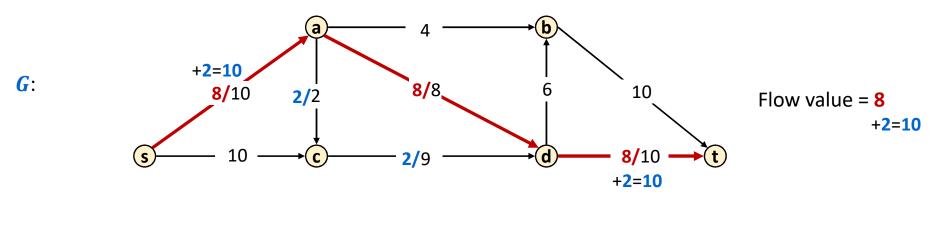
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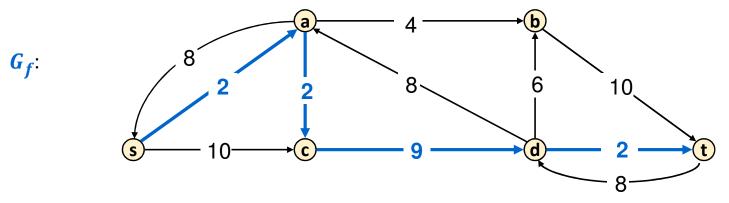


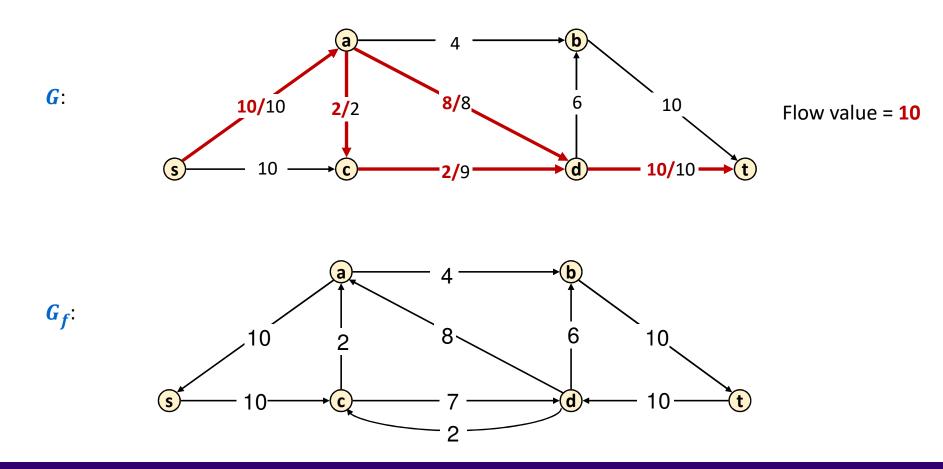




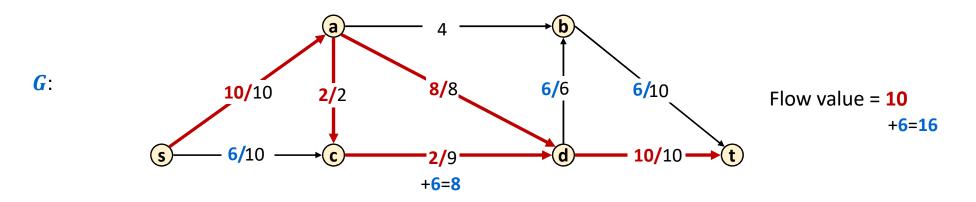


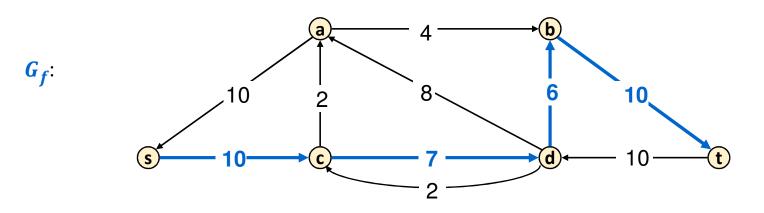


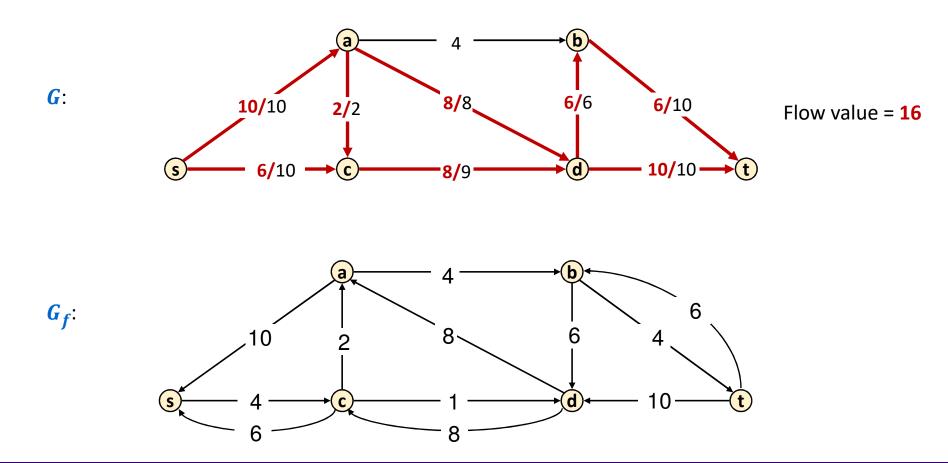




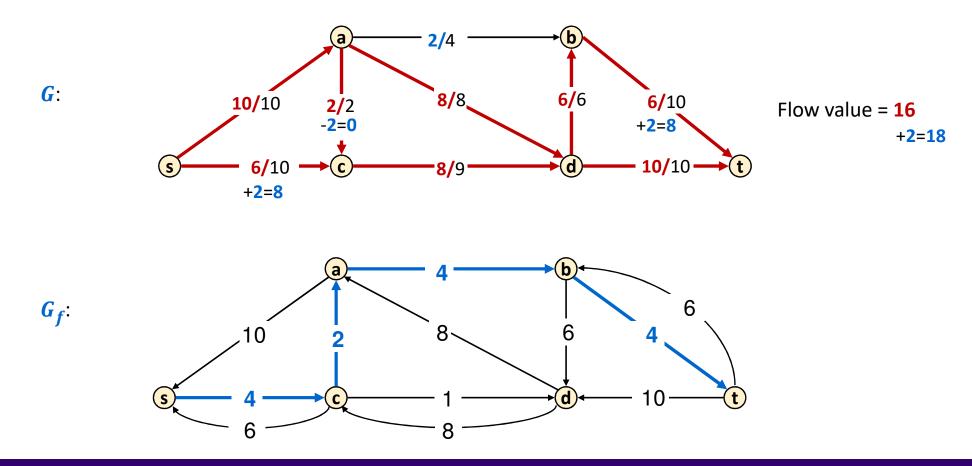
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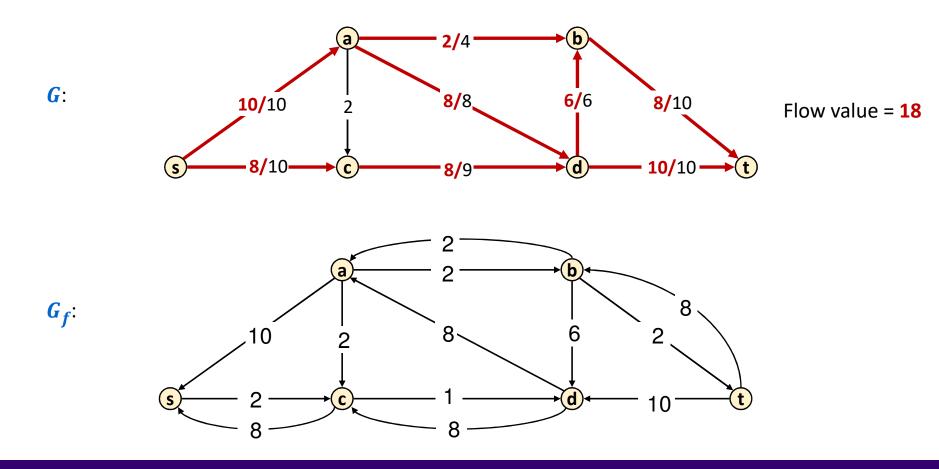




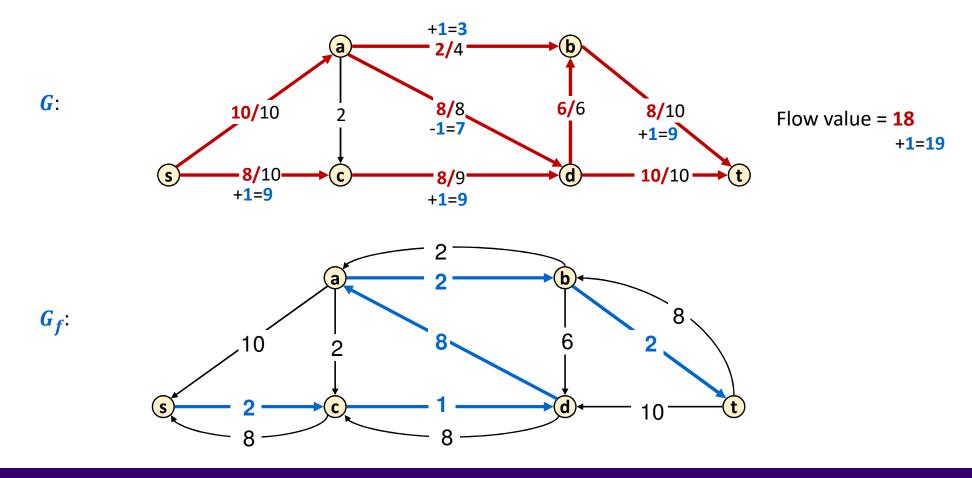
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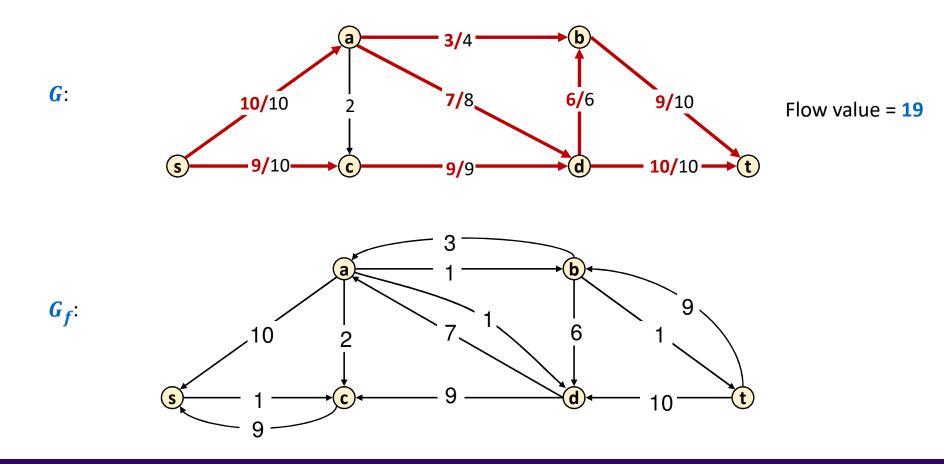
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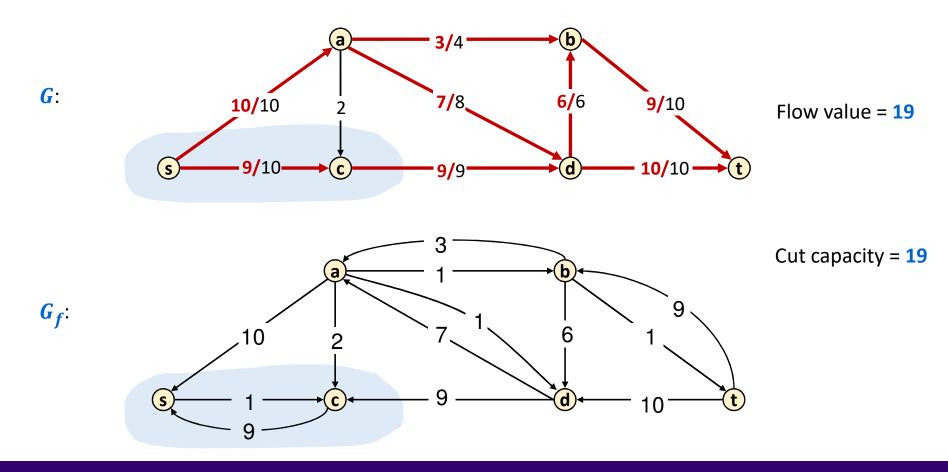
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#### **Augmenting Path Algorithm**

```
Ford-Fulkerson(G, s, t, c) {
   foreach e \in E f(e) \leftarrow 0
   G<sub>f</sub> \leftarrow residual graph
   while (G<sub>f</sub> has an s-t path P) {
      f \leftarrow Augment(f, c, P)
      update G<sub>f</sub>
   }
   return f
}
```

```
Augment(f, c, P) {

    b \leftarrow bottleneck(P)

    foreach e \in P {

        if (e \in E) f(e) \leftarrow f(e) + b

        else f(e<sup>R</sup>) \leftarrow f(e<sup>R</sup>) - b

    }

    return f

}
```

# **Max-Flow Min-Cut Theorem**

#### Augmenting Path Theorem: Flow f is a max flow $\Leftrightarrow$ there are no augmenting paths wrt f

Max-Flow Min-Cut Theorem: The value of the max flow equals the value of the min cut. [Elias-Feinstein-Shannon 1956, Ford-Fulkerson 1956] "Maxflow = Mincut"

**Proof:** We prove both together by showing that all of these are equivalent:

- (i) There is a cut (A, B) such that v(f) = c(A, B).
- (ii) Flow **f** is a max flow.
- (iii) There is no augmenting path w.r.t. *f*.

 $(i) \Rightarrow (ii)$ : We already know this by the corollary to weak duality lemma.

Only  $(iii) \Rightarrow (i)$  remaining

 $(ii) \Rightarrow (iii): (by contradiction)$ If there is an augmenting path w.r.t. flow **f** then we can improve **f**. Therefore **f** is not a max flow.

#### $\underline{(iii)} \Rightarrow \underline{(i):}$

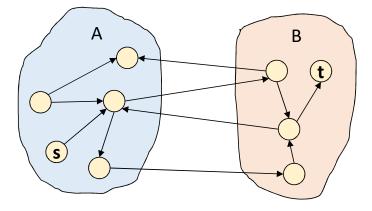
**Claim:** If there is no augmenting path w.r.t. f, there is a cut (A, B) s.t. v(f) = c(A, B).

**Proof of Claim:** Let *f* be a flow with no augmenting paths.

Let A be the set of vertices reachable from s in residual graph  $G_f$ .

- By definition of  $A, s \in A$ .
- Since no augmenting path (s-t path in  $G_f$ ),  $t \notin A$ .

Then  $v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$ 



original network

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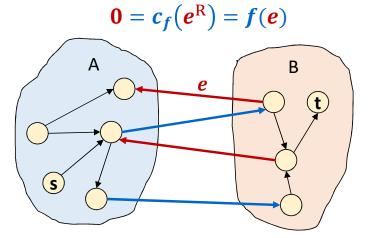
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Then 
$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$
  
=  $\sum_{e \text{ out of } A} f(e)$ 





original network

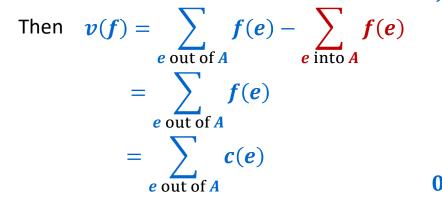
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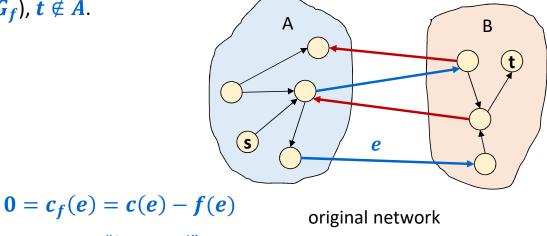
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"Saturated"

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#### $\underline{(iii)} \Rightarrow \underline{(i):}$

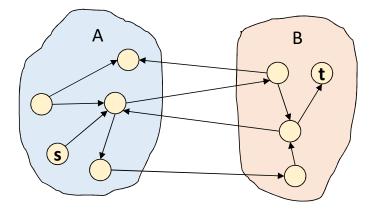
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Let A be the set of vertices reachable from s in residual graph  $G_f$ .

- By definition of  $A, s \in A$ .
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Then 
$$v(f) = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$
  
$$= \sum_{e \text{ out of } A} f(e)$$
$$= \sum_{e \text{ out of } A} c(e) = c(A, B)$$



original network

# **Running Time**

- Computing first  $G_f$  takes O(n + m) time. (Can ignore disconnected bits so  $m \ge n 1$ .)
- Finding each augmenting path (graph search in  $G_f$ ) takes O(m) time.
- Updating f and  $G_f$  takes O(n) time.

Total O(m) per iteration.

Assumption: All capacities are integers between 1 and C.

Ford-Fulkerson Invariant: Every flow value f(e) and every residual capacity  $c_f(e)$  remains an integer throughout the algorithm. So there is a maximum flow with only integer flows.

**Theorem:** The Ford-Fulkerson algorithm terminates in  $\leq$  Maxflow < nC iterations.

**Proof:** Capacity of cut with  $A = \{s\}$  is  $\leq (n - 1)C$ . Each augmentation increases flow value by at least 1.

**Corollary:** If C = 1, Ford-Fulkerson runs in O(mn) time.

# **Bipartite Matching**

A graph G = (V, E) is bipartite iff

- Set **V** of vertices has two disjoint parts **X** and **Y**
- Every edge in *E* joins a vertex from *X* and a vertex from *Y*

Set  $M \subseteq E$  is a matching in G iff no two edges in M share a vertex

**Goal:** Find a matching *M* in *G* of maximum size.

Differences from stable matching

- limited set of possible partners for each vertex
- sides may not be the same size
- no notion of stability; matching everything may be impossible.

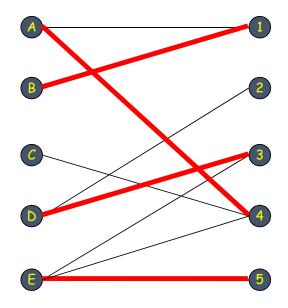
# **Bipartite Matching**

- Models assignment problems
  - X represents customers, Y represents salespeople
  - X represents professors, Y represents courses
- If |X| = |Y| = n
  - G has perfect matching iff maximum matching has size n

## **Bipartite Matching**

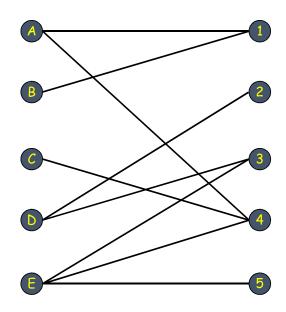
Input: Bipartite graph

**Goal:** Find maximum size matching.



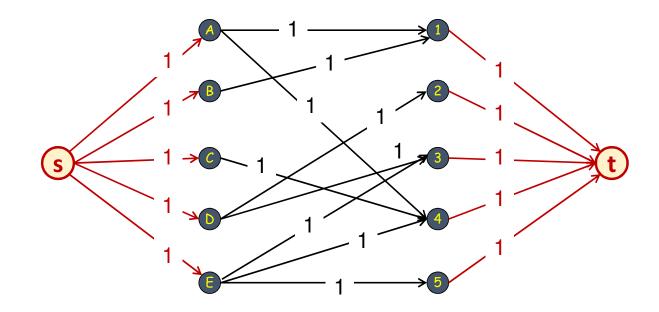


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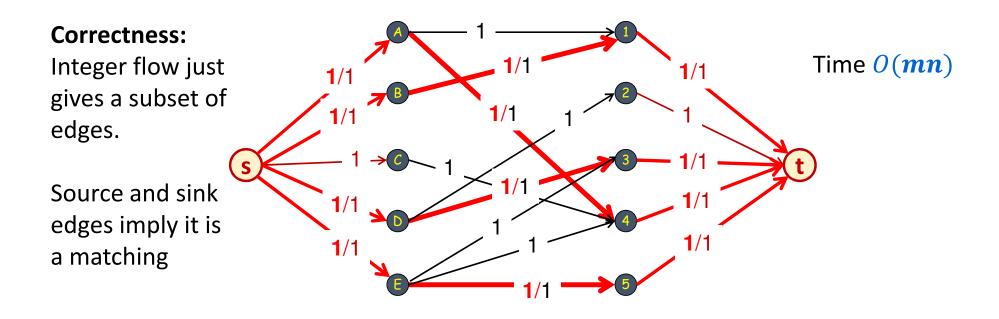




Add new source **s** pointing to left set, new sink **t** pointed to by right set. Direct all edges from left to right with capacity 1. Compute MaxFlow.



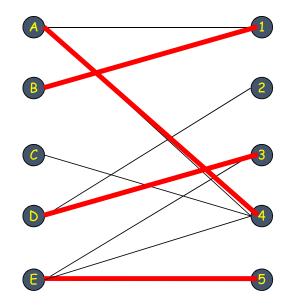
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## **Bipartite Matching**

Input: Bipartite graph

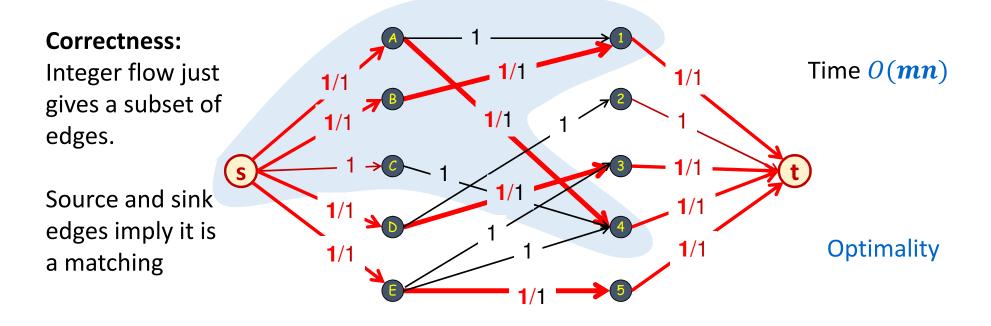
**Goal:** Find maximum size matching.



Optimality



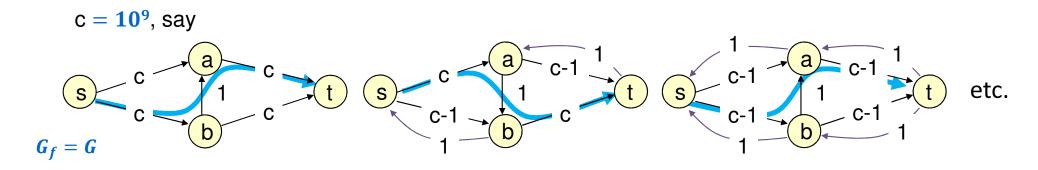
Add new source **s** pointing to left set, new sink **t** pointed to by right set. Direct all edges from left to right with capacity 1. Compute MaxFlow.



## **Ford-Fulkerson Efficiency**

Worst case runtime O(mnC) with integer capacities  $\leq C$ .

- O(m) time per iteration.
- At most *nC* iterations.
- This is "pseudo-polynomial" running time.
- May take exponential time, even with integer capacities:



# Choosing Good Augmenting Paths

## **Choosing Good Augmenting Paths**

Use care when selecting augmenting paths.

- Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- If capacities are irrational, algorithm not guaranteed to terminate!

**Goal:** Choose augmenting paths so that:

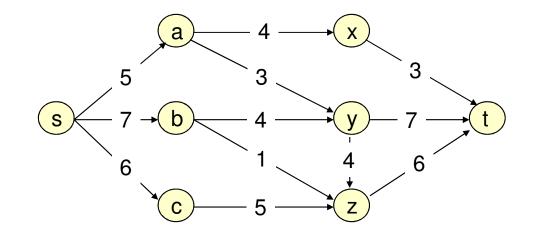
- Can find augmenting paths efficiently.
- Few iterations.
- Choose augmenting paths with: [Edmonds-Karp 1972, Dinitz 1970]
  - Max bottleneck capacity.
  - Sufficiently large bottleneck capacity.
  - Fewest number of edges.

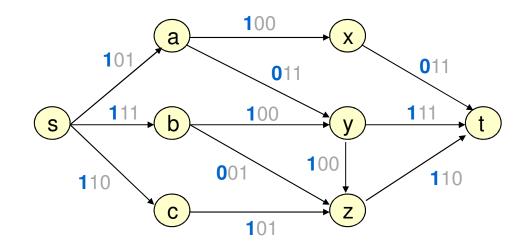
# **Capacity Scaling**

General idea:

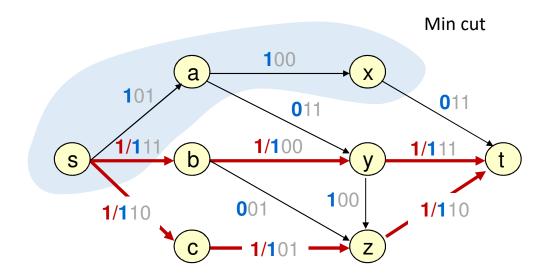
- Choose augmenting paths **P** with 'large' capacity.
- Can augment flows along a path P by any amount < bottleneck(P)</li>
  - Ford-Fulkerson still works
- Get a flow that is maximum for the high-order bits first and then add more bits later

**Capacity Scaling** 



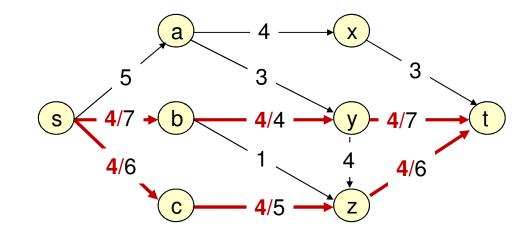


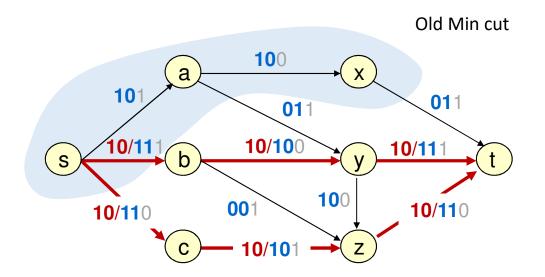
Solve flow problem with capacities with just the high-order bit:



Solve flow problem with capacities with just the high-order bit:

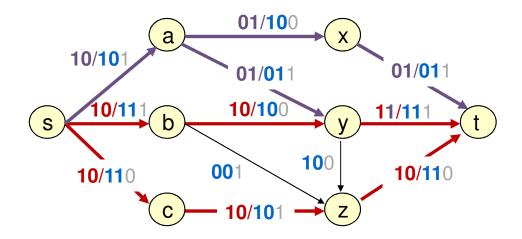
- Each edge has "capacity"  $\leq 1$  (equivalent to 4 here)
- Time *0*(*mn*)





Solve flow problem with capacities with the **2** high-order bits:

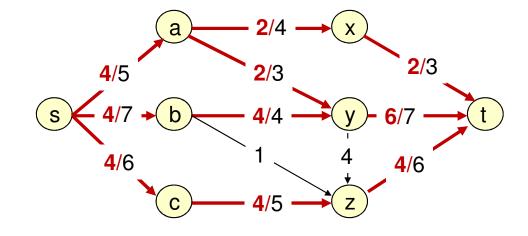
 Capacity of old min cut goes up by < 1 per edge (equivalent to 2 here) for a total residual capacity < m.</li>

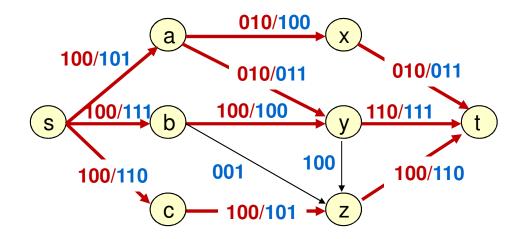


Solve flow problem with capacities with the **2** high-order bits:

- Capacity of old min cut goes up by < 1 per edge (equivalent to 2 here) for a total residual capacity < m.</li>
- Time  $O(m^2)$  for  $\leq m$  iterations.

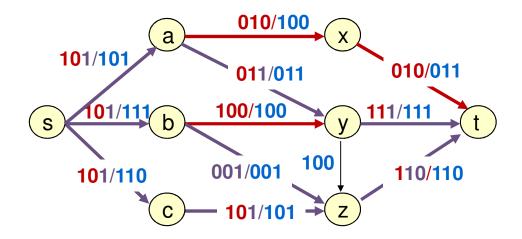
## **Capacity Scaling Bits 1 and 2**





Solve flow problem with capacities with all 3 bits:

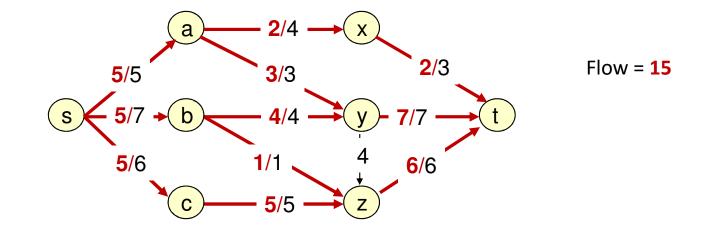
Capacity of old min cut goes up by ≤ 1 per edge for a total residual capacity ≤ m.



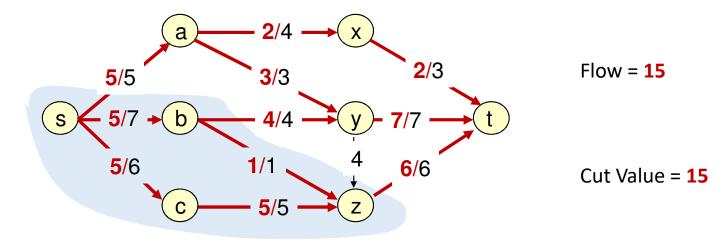
Solve flow problem with capacities with all 3 bits:

- Capacity of old min cut goes up by ≤ 1 per edge for a total residual capacity ≤ m.
- Time  $O(m^2)$  for  $\leq m$  iterations.

## **Capacity Scaling All Bits**



#### **Capacity Scaling All Bits**



Flow is a MaxFlow



## **Total time for capacity scaling**

- Number of rounds =  $[log_2 C]$  where C is the largest capacity
- Time per round  $O(m^2)$ 
  - At most *m* augmentations per round
  - O(m) time per augmentation

Total time  $O(m^2 \log C)$