CSE 421 Introduction to Algorithms

Lecture 8: Divide and Conquer

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Algorithm Design Techniques

Divide & Conquer

- Divide instance into subparts.
- Solve the parts recursively.
- Conquer by combining the answers

To truly fit Divide & Conquer

- each sub-part should be at most a constant fraction of the size of the original input instance
 - e.g. Mergesort, Binary Search, Quicksort (sort of), etc.

Binary search for roots (bisection method)



Given:

• Continuous function f and two points a < b with $f(a) \le 0$ and f(b) > 0

Find:

• Approximation within ε of c s.t. f(c) = 0 and a < c < b

Bisection method

```
Bisection(a, b, ɛ)
   if (b - a) \leq \varepsilon then
        return(a)
   else {
        c \leftarrow (a+b)/2
       if f(c) \leq 0 then
              return(Bisection(c, b, ɛ))
        else
            return(Bisection(a, c, ɛ))
   }
```

Time Analysis

At each step we halved the size of the interval

- It started at size b a
- It ended at size $\boldsymbol{\varepsilon}$

So # of calls to f is $\log_2((b-a)/\epsilon)$ # of hit of precim

Old Favorites

Binary search:

- One subproblem of half size plus one comparison
- Recurrence* for time in terms of # of comparisons
 - T(n) = T(n/2) + 1 for $n \ge 2$
 - $T(1) = 0^{-1}$
- Solving shows that $T(n) = \lceil \log_2 n \rceil + 1$

Mergesort:

- Two subproblems of half size plus merge cost of n-1 comparisons
- Recurrence* for time in terms of # of comparisons
 - $T(n) \le 2T(n/2) + n 1$ for $n \ge 2$
 - T(1) = 0
- Roughly *n* comparisons at each of $\log_2 n$ levels of recursion so T(n) is roughly $n \log_2 n$

*We will implicitly assume that every input to $T(\cdot)$ is rounded up to the nearest integer.

Find closest arin

Euclidean Closest Pair

Given:

• A sequence of *n* points p_1, \dots, p_n with real coordinates in *d* dimensions (\mathbb{R}^d)

Find:

• A pair of points p_i, p_j s.t. the Euclidean distance $d(p_i, p_j)$ is minimized

What is the first algorithm you can think of?

• Try all $\Theta(n^2)$ possible pairs

Can we do better if dimension d = 1?

Closest Pair in 1 Dimension



Algorithm:

- Sort points so $p_1 \leq p_2 \leq \cdots \leq p_n$
- Find closest adjacent pair p_i, p_{i+1} .

Running time: $O(n \log n)$

What about d = 2?



Sorting on 1st coordinate doesn't work

No single direction to sort points to guarantee success!

Let's try divide & conquer...

How might we divide the points so that each subpart is a constant factor smaller?



How might we divide the points so that each subpart is a constant factor smaller?

Split using median *x*-coordinate!

• each subpart has size n/2.

Conquer:

• Solve both size n/2 subproblems recursively

Recombine to get overall answer?

- Take the closer of the two answers?
 - works here but....



How might we divide the points so that each subpart is a constant factor smaller?

Split using median *x*-coordinate!

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Conquer:

Solve both size n/2 subproblems recursively

Recombine to get overall answer?

- Take the closer of the two answers?
 - ...but not always!



Need to worry about pairs across the split!

New idea to handle them

- Let δ be the distance of the closest pair in the 2 subparts
- This pair is a candidate
- Only need to check width δ band either side of the median Within that band ...
 - only need to compare each point with the other points in the rectangle of height δ above it.
 How many points can that be?



How many points can there be in that δ by 2δ rectangle?

Key idea: We know that no pair on either side is closer than δ apart so there can't be too many!

- Each of the 8 squares of side $\delta/2$ can contain at most 1 point!
 - Because diagonal has length $< \delta$
- So....only need to compare each point with the next 7 points above it to guarantee you'll find a partner closer than δ in the rectangle if there is one!

Fleshing out the algorithm:

Divide:

- At top level we need median x coordinate to split points $O(n \log n)$ total
- At next level down we'll need median x coordinate for each side
- Might as well sort all points by *x* coordinate up front to get all medians at once!

<u>Conquer:</u> Solve the two sub-problems to get two candidate pairs

Recombine:

- Choose closer candidate pair and let its distance be δ O(1)
- Select **B** = all points in band with x coordinates within δ of median
- Sort *B* by *y* coordinate May involve repeated work for different calls
- Compare each point in **B** with next 7 points and update if closer pair found. O(n)

over all calls

2T(n/2)

 $O(n \log n)$

 $O(\mathbf{n})$

Fleshing out the algorithm: A better version:

| <u>Preprocess</u> : Compute sorted list <i>X</i> of points by <i>x</i> coordinate • Subparts will be defined by two indices into this list | $O(n \log n)$ |
|---|---------------------------------------|
| Compute sorted list \mathbf{Y} of points by \mathbf{y} coordinate | $O(\boldsymbol{n}\log\boldsymbol{n})$ |
| <u>Divide</u> : Use median in X to get X_L and X_R and filter points of Y to produce sorted sublists Y_L and Y_R | 0(n) |
| <u>Conquer:</u> Solve the two sub-problems to get two candidate pairs | 2 T(n/2) |
| <u>Recombine:</u> | |
| Choose closer candidate pair and let its distance be δ | 0(1) |
| • Filter Y to get B = points in band w/ x coordinates within δ of median | $O(\boldsymbol{n})$ |
| • Compare each point in B with next 7 points and update if closer pair found. $O(n)$ | |

Total runtime = Preprocessing time + Divide and Conquer time

Let T(n) be Divide and Conquer time:

Recurrence:

• $T(n) \le 2 T(n/2) + O(n)$ for $n \ge 3$ • T(2) = 1

Solution: T(n) is $O(n \log n)$.

With preprocessing, total runtime is $O(n \log n)$.

Sometimes two sub-problems aren't enough

More general divide and conquer

- You've broken the problem into a different sub-problems
- Each has size at most n/b
- The cost of break-up and recombining sub-problem solutions is $O(n^k)$
 - "cost at the top level"

Recurrence

- $T(n) = a \cdot T(n/b) + O(n^k)$ for $n \ge b$
- *T* is constant for inputs < *b*.
 - For solutions correct up to constant factors no need for exact base case

Solving Divide and Conquer Recurrence

Master Theorem: Suppose that $T(n) = a \cdot T(n/b) + O(n^k)$ for n > b.

- If $a < b^k$ then T(n) is $O(n^k)$
 - Cost is dominated by work at top level of recursion
 - If $a = b^k$ then T(n) is $O(n^k \log n)$
 - Total cost is the same for all $\log_b n$ levels of recursion
 - If $a > b^k$ then T(n) is $O(n^{\log_b a})$
 - Note that $\log_b a > k$ in this case
 - Cost is dominated by total work at lowest level of recursion

Binary search: a = 1, b = 2, k = 0 so $a = b^k$: Solution: $O(n^0 \log n) = O(\log n)$

Mergesort: a = 2, b = 2, k = 1 so $a = b^k$: Solution: $O(n^1 \log n) = O(n \log n)$

Proving Master Theorem for $T(n) = a \cdot T(n/b) + c \cdot n^k$

Write $d = [\log_b n]$ so $n \le b^d$





Proving Master Theorem for $T(n) = a \cdot T(n/b) + c \cdot n^k$

total work/level n^k biggest

 $(a/b^k) \cdot n^k$

 $(a/b^k)^2 \cdot n^k$

. . .

 $a^{\log_b n}$

total work

If $a < b^k$ sum of geometric series with biggest term $O(n^k)$

If $a = b^k$ sum of $O(\log n)$ terms each $O(n^k)$

If $a > b^k$ sum of geometric series with biggest term $O(a^{\log_b n})$ Claim: $a^{\log_b n} = n^{\log_b a}$

Proof: Take log_b of both sides

Write $d = [\log_b n]$ so $n \le b^d$

level work/problem

 n^k

 n^k/b^k

 n^k/b^{2k}

b^k

1

of problems

1

a

 a^2

 a^{d-1}

 a^d