CSE 421: Introduction to Algorithms

Terminology: Complexity

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Administrativia Stuffs

HW1 is out. Please submit to Gradescope



Guidelines:

- You can collaborate, but you must write solutions on your own
- You CANNOT search the solution online
- See Ed for more guidelines.

Tips:

- Rewrite your proof.
- Make sure you use assumptions of the problem
- Make sure it is easy to understand

More

Algorithm:



Runtime:

Correctness:



Exceptions (not limited to):

- If possible, reduce the question into a solved problem, For example, for stable matching, explain
 - What "man" and "woman" are corresponding to
 - What their preference are.
 - How convert the stable matching to what we asked in the question.
- If the algorithm is similar to one in the class,
 Simply explain the difference.
 Make sure your description is not ambiguous.

Definition for Efficiency in This Course

Worst case complexity:

The worst case running time T(n) of an algorithm is max # steps algorithm takes on any input of size n.

Definition of 1 step in this course:

- only simple operations (+,*,-,=,if,call,...).
- each operation takes one time step.
- each memory access takes one time step.
- no fancy stuff (add two matrices, copy long string,...).

Definition of efficiency in this course:

An algorithm is efficient if it has polynomial worst case runtime.

Time Complexity on Worst Case Inputs



O-Notation

Given two positive functions f and g

- f(n) = O(g(n)) if there is a constant C > 0 and N st $f(n) \le Cg(n)$ for all n > N
- $f(n) = \Omega(g(n))$ if there is a constant C > 0 and N st $f(n) \ge Cg(n)$ for all n > N
- $f(n) = \Theta(g(n))$ if f(n) = O(g(n)) and $f(n) = \Omega(g(n))$, namely There is a constant $C_1, C_2 > 0$ and N st $C_1g(n) \le f(n) \le C_2g(n)$ for all n > N

Common Asymptotic Bounds

• Polynomials:

$$a_0 + a_1 n + \dots + a_d n^d$$
 is $O(n^d)$

• Logarithms:

 $\log_a n = O(\log_b n)$ for all constants a, b > 0

• Logarithms: log grows slower than every polynomial For all x > 0, $\log n = O(n^x)$

Running Time

An algorithm runs in polynomial time if $T(n) = n^{O(1)}$.

Equivalently, $T(n) = O(n^d)$ for some constant d.

Name 🔶	Complexity class \$	Running time $(T(n)) \Leftrightarrow$	Examples of running times \$	Example algorithms \$
constant time	Data Structures	O(1)	10	Finding the median value in a sorted array of numbers Calculating $(-1)^n$
inverse Ackermann time	CSE332	<i>Ο</i> (<i>α</i> (<i>n</i>))		Amortized time per operation using a disjoint set
iterated logarithmic time		O(log* n)		Distributed coloring of cycles
log-logarithmic		O(log log n)		Amortized time per operation using a bounded priority queue ^[2]
logarithmic time	DLOGTIME	<i>O</i> (log <i>n</i>)	$\log n$, $\log(n^2)$	Binary search
polylogarithmic time	Sublinger	poly(log n)	$(\log n)^2$	
fractional power	Sublinear Algorithms	$O(n^c)$ where $0 < c < 1$	$n^{1/2}, n^{2/3}$	Searching in a kd-tree
linear time	Aigonunins	<i>O</i> (<i>n</i>)	n, 2n + 5	Finding the smallest or largest item in an unsorted array, Kadane's algorithm, linear search
"n log-star n" time		$O(n \log^* n)$		Seidel's polygon triangulation algorithm.
linearithmic time	This	$O(n \log n)$	<i>n</i> log <i>n</i> , log <i>n</i> !	Fastest possible comparison sort; Fast Fourier transform.
quasilinear time	course 🚽	n poly(log n)		
quadratic time		<i>O</i> (<i>n</i> ²)	n ²	Bubble sort; Insertion sort; Direct convolution
cubic time		<i>O</i> (<i>n</i> ³)	n ³	Naive multiplication of two <i>n×n</i> matrices. Calculating partial correlation.
polynomial time	P	$2^{O(\log n)} = \operatorname{poly}(n)$	$n^2 + n, n^{10}$	Karmarkar's algorithm for linear programming; AKS primality test ^{[3][4]}
quasi-polynomial time	QP	2 ^{poly(log n)}	n ^{log log n} , n ^{log n}	Best-known $O(\log^2 n)$ -approximation algorithm for the directed Steiner tree problem.
sub-exponential time (first definition)	SUBEXP	$O(2^{n^{\varepsilon}})$ for all $\varepsilon > 0$		Contains BPP unless EXPTIME (see below) equals MA. ^[5]
sub-exponential time (second definition)		2 ^{o(n)}	2 ^{n^{1/3}}	Best-known algorithm for integer factorization; formerly-best algorithm for graph isomorphism
exponential time (with linear exponent)	E	2 ^{O(n)}	1.1 ⁿ , 10 ⁿ	Solving the traveling salesman problem using dynamic programming
exponential time	EXPTIME	2 ^{poly(n)}	2 ⁿ , 2 ^{n²}	Solving matrix chain multiplication via brute-force search
factorial time		O(n!)	<i>n</i> !	Solving the traveling salesman problem via brute-force search
double exponential time	2-EXPTIME	2 ^{2^{poly(n)}}	2 ^{2ⁿ}	Deciding the truth of a given statement in Presburger arithmetic

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Why "Polynomial"?

Point is not that n^{2000} is a practical bound, or that the differences among n and 2n and n^2 are negligible.

- "My problem is in P" is a starting point for a more detailed analysis
- "My problem is not in P" may suggest that you need to shift to a more tractable variant



Other Complexities

Average Case Complexity:

avg # steps algorithm takes

Communication Complexity:

max # communication algorithm send between servers

Space Complexity:

max # space algorithm needs

Parallel Complexity:

max length of the longest series of operations that have to be performed sequentially due to data dependencies

CSE 351 Quiz

What is the cost of following operations? (in terms of cycle for CPU with 1 core)

Compute a*b+c where a,b,c are float (throughput)

~1/16 cycles

Cost of unpredictable if (latency)
~20 cycles

Life is simple in 421. Everything is O(1)

- Cost of reading 1 byte from a random location in memory (latency)
 ~300 cycles
- Cost of reading 1 byte from a random location in a M.2 SSD (latency) ~100k cycles
- Cost of reading 1 byte from a random location in a 7200RPM harddisk (latency) ~10M cycles
- Cost of Elon posting a Twitter from Mars (latency) ~10T cycles

Warning

In real world, not all operations take same amount of time.

ithare.com	Operation Cost in CPU Cycles	10 °	10¹	10²	10 ³	10⁴	10⁵	10
"Simple"	register-register op (ADD,OR,etc.)	<1						
	Memory write	~1						
	Bypass delay: switch between							
	integer and floating-point units	0-3						
	"Right" branch of "if"	1-2						
	Floating-point/vector addition	1-3						
	Multiplication (integer/float/vector)	1-7						
	Return error and check	1-7						
	L1 read		3-4					
	TLB miss		7-21					
	L2 read		10-12					
"Wrong" b	ranch of "if" (branch misprediction)		10-20					
0	Floating-point division		10-40					
	128-bit vector division		10-70					
	Atomics/CAS		15-30					
	C function direct call		15-30					
	Integer division		15-40					
	C function indirect call		20-5	0				
	C++ virtual function call		30	-60				
	L3 read		30	-70				
	Main RAM read			100-150				
NU	JMA: different-socket atomics/CAS				_			
	(guesstimate)			100-300				
	NUMA: different-socket L3 read			100-300				
Allocatio	on+deallocation pair (small objects)			200-50	00			
NUM	A: different-socket main RAM read			300	-500			
	Kernel call				1000-150	D		
Т	hread context switch (direct costs)				2000			
	C++ Exception thrown+caught				500	00-10000		
	Thread context switch (total costs,							
	including cache invalidation)					10000 - 1	million	

Not all CPU operations are created equal



Distance which light travels while the operation is performed

Warning

In real world, not all memory accesses take same amount of time.

Latency Numbers Every Programmer Should Know

↔ lat	ency.txt						
1	Latency Comparison Numbers (~2012)						
2							
3	L1 cache reference	0.5	ns				
4	Branch mispredict	5	ns				
5	L2 cache reference	7	ns				14x L1 cache
6	Mutex lock/unlock	25	ns				
7	Main memory reference	100	ns				20x L2 cache, 200x L1 cache
8	Compress 1K bytes with Zippy	3,000	ns	3 u	S		
9	Send 1K bytes over 1 Gbps network	10,000	ns	10 u	S		
10	Read 4K randomly from SSD*	150,000	ns	150 u	S		~1GB/sec SSD
11	Read 1 MB sequentially from memory	250,000	ns	250 u	S		
12	Round trip within same datacenter	500,000	ns	500 u	S		
13	Read 1 MB sequentially from SSD st	1,000,000	ns	1,000 u	s 1	ms	~1GB/sec SSD, 4X memory
14	Disk seek	10,000,000	ns	10,000 u	s 10	ms	20x datacenter roundtrip
15	Read 1 MB sequentially from disk	20,000,000	ns	20,000 u	s 20	ms	80x memory, 20X SSD
16	Send packet CA->Netherlands->CA	150,000,000	ns	150,000 u	s 150	ms	

Example:

Improving Google CPU usage by 0.5% via a better hash table https://www.youtube.com/watch?v=ncHmEUmJZf4

CSE 421: Introduction to Algorithms

Terminology: Graph

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Graphs



Examples:

- Transportation networks
- Communication networks
- Internet
- Social networks
- Dependency networks

Undirected Graphs G=(V,E)



Graphs don't Live in Flat Land

Geometrical drawing is mentally convenient, but mathematically irrelevant:

4 drawings of a single graph:



Directed Graphs



Terminology

• Degree of a vertex: # edges that touch that vertex



- Connected: Graph is connected if there is a path between every two vertices
- Connected component: Maximal set of connected vertices

Terminology (cont'd)

Path: A sequence of distinct vertices
 s.t. each vertex is connected
 to the next vertex with an edge

 Cycle: Path of length > 2 that has the same start and end

Tree: A connected graph with no cycles





Exercise: Degree 1 vertices

Claim: If G has no cycle, then it has a vertex of degree ≤ 1 (Every tree has a leaf)

Proof: (By contradiction)

Suppose every vertex has degree ≥ 2 .

Start from a vertex v_1 and follow a path, $v_1, ..., v_i$ when we are at v_i we choose the next vertex to be different from v_{i-1} . We can do so because $\deg(v_i) \ge 2$.

The first time that we see a repeated vertex ($v_j = v_i$) we get a cycle.

We always get a repeated vertex because *G* has finitely many vertices



Exercise: Trees and Induction

Claim: Every tree with n vertices has n - 1 edges.

Proof: (Induction on *n*.)

Base: n = 1, the tree has no edge

Induction: Let T be a tree with n vertices.

So, T has a vertex v of degree 1.

Remove v and the neighboring edge, and let T' be the new graph.

We claim T' is a tree: It has no cycle, and it must be connected.

So, T' has n - 2 edges and T has n - 1 edges.

Exercise: Degree Sum

Claim: In any undirected graph, the number of edges is equal to $(1/2) \sum_{\text{vertex } v} \deg(v)$

Pf: $\sum_{\text{vertex } v} \deg(v)$ counts every edge of the graph exactly twice; once from each end of the edge.



Exercise: Odd Degree Vertices

Claim: In any undirected graph, the number of odd degree vertices is even

Pf: In previous claim we showed sum of all vertex degrees is even. So there must be even number of odd degree vertices, because sum of odd number of odd numbers is odd.



Exercise: #edges

Let G = (V, E) be a graph with n = |V| vertices and m = |E| edges.

Claim:
$$0 \le m \le {n \choose 2} = \frac{n(n-1)}{2} = O(n^2)$$

Pf: Since every edge connects two distinct vertices (i.e., G has no loops)

and no two edges connect the same pair of vertices (i.e., G has no multi-edges)

It has at most $\binom{n}{2}$ edges.

Sparse Graphs

A graph is called sparse if $m \ll n^2$ and it is called dense otherwise.

Sparse graphs are very common in practice

- Friendships in social network
- Planar graphs
- Web graph

O(n+m) is usually much better runtime than $O(n^2)$.

Vertex set $V = \{v_1, ..., v_n\}.$

Adjacency Matrix: A

- For all, i, j, A[i, j] = 1 iff $(v_i, v_j) \in E$
- Storage: n^2 bits

Advantage:

• O(1) test for presence or absence of edges

Disadvantage:

 Inefficient for sparse graphs both in storage and edgeaccess



Storing Graphs Adjacency List: O(n+m) words 3 Compact for sparse 2 3

3

4

Easily see all edges •

Disadvantage

Advantage

 \bullet

- Bad memory access •
- Not good for parallel algorithms. ullet

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Adjacency Array: O(n + m) words

Advantage

- Compact for sparse
- Easily see all edges
- Better for memory access
- Better for parallel algorithms.

Disadvantage

Difficult to update the graph





Implicit Representation:

f(v) outputs an iterator of neighbor of v. Aka, f(v)->next()->next()->next()

Advantage

No space is required

Disadvantage

Mainly work for abstractly defined graph



2,125,922,464,947,725,402,112,000 states.

In practice, pick the representation according to the algorithm (depends how we want to access the graph).

In this course, we focus on asymptotic runtime. We can simply do this:

- For each vertex, use a hash table to store its neighbors
- This gives O(1) time for many operations Insert, Delete, Find, Next, ...