

#### **Dynamic Programming**

Shayan Oveis Gharan

#### Q/A

- How to think, how to write?
  - Many cases it is better to spend more time on thinking than writing.
  - Try to write concise proofs for HW problems.
  - Make sure you use all assumptions of the problem.

# Sample Justification for Problem 1

Part (a): Every instance of stable matching has at least two stable matchings:

F BC every instance has at least 1 stable matching

F BC if we have one company and one applicant there is only one stable matching.

Part (c): If every vertex of G has even degree then every cut of G has even #edges.

T: BC every cycle has an even number of edges in every cut

T: BC we prove the contrapositive in HW2-P1.

# Sample Soln of Problem 2 Midterm

Alg: Use BFS (as in class) to find connected components. Say i-th connected comp has  $n_i$  vertices and  $m_i$  edges. If  $m_i \ge n_i$  for some i output yes. Otherwise output no.

**Runtime**: It takes O(m+n) to find connected components.

**Correctness**: First suppose that for some i, say i = 1, we have  $m_1 \ge n_1$ . Then, by in-class exercise this component has a cycle. So, if we remove an edge of the cycle we don't disconnect (as there is another path to connect endpoints). So, we should output yes.

O.w., suppose for every i,  $m_i < n_i$ . So every connected component must be a tree. And, we if we delete any edge of a tree we will disconnect it. So, we should output no.

# Sample Soln of Problem 3 Midterm

A(T) If T has 2 vertices color its edge arbitrarily and return O.w., Let v be a leaf and let T - v. Run A(T') to color edges of T'. Use same colors for T Let u be neighbor of v in T. Find a color {1,..,k} unused in edges neighbor of u in T' and color (u, v) with that.

**Runtime**: We make n function calls each runs in O(n). So  $O(n^2)$ .

**Correctness**: P(n)= For any tree *T* with n vertices s.t.,  $deg(v) \le k$  for all v, we properly color edges with k colors".

Base Case: P(2) holds since only one edge.

IH: Assume P(n-1) for some  $n \ge 2$ .

IS: Let T be arbitrary tree with n vertices s.t.,  $deg(v) \le k$  for all v. Let v be a leaf and T' = T - v. In class we showed T' is tree. Also degrees are still at most k. So, by IH we can color edges of T' with k colors. Let u be neighbor of v. Since  $deg(u) \le k$  in T, u has at most k-1 edges other than (u,v). So there is a color in  $\{1,...,k\}$  not used. Color (u,v) with that color and we get a proper 5 coloring of edges of T.

### **Dynamic Programming**

# Algorithmic Paradigm

**Greedy:** Build up a solution incrementally, myopically optimizing some local criterion.

Divide-and-conquer: Break up a problem into two sub-problems, solve each sub-problem independently, and combine solution to sub-problems to form solution to original problem.

Dynamic programming. Break up a problem into a series of overlapping sub-problems, and build up solutions to larger and larger sub-problems. Memorize the answers to obtain polynomial time ALG.

# **Dynamic Programming History**

Bellman. Pioneered the systematic study of dynamic programming in the 1950s.

Etymology.

Dynamic programming = planning over time.

Secretary of Defense was hostile to mathematical research.

Bellman sought an impressive name to avoid confrontation.

- "it's impossible to use dynamic in a pejorative sense"
- "something not even a Congressman could object to"

# **Dynamic Programming Applications**

#### Areas:

- Bioinformatics
- Control Theory
- Information Theory
- Operations Research
- Computer Science: Theory, Graphics, AI, ...

#### Some famous DP algorithms

- Viterbi for hidden Markov Model
- Unix diff for comparing two files.
- Smith-Waterman for sequence alignment.
- Bellman-Ford for shortest path routing in networks.
- Cocke-Kasami-Younger for parsing context free grammars.

# **Dynamic Programming**

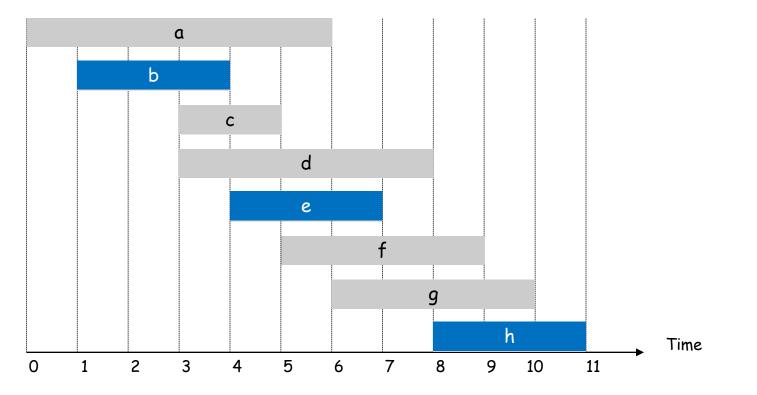
Dynamic programming is nothing but algorithm design by induction!

We just "remember" the subproblems that we have solved so far to avoid re-solving the same sub-problem many times.

## Weighted Interval Scheduling

## **Interval Scheduling**

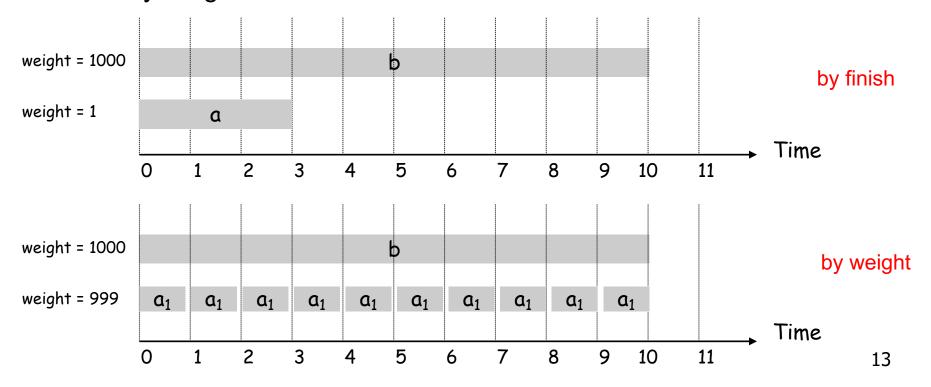
- Job j starts at s(j) and finishes at f(j) and has weight  $w_j$
- Two jobs compatible if they don't overlap.
- Goal: find maximum weight subset of mutually compatible jobs.



#### **Unweighted Interval Scheduling: Review**

Recall: Greedy algorithm works if all weights are 1:

- Consider jobs in ascending order of finishing time
- Add job to a subset if it is compatible with prev added jobs.
   OBS: Greedy ALG fails spectacularly (no approximation ratio) if arbitrary weights are allowed:



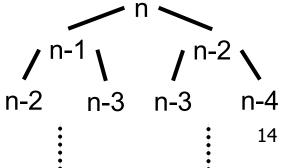
# Weighted Job Scheduling by Induction

Suppose 1, ..., *n* are all jobs. Let us use induction:

IH (strong ind): Suppose we can compute the optimum job scheduling for < n jobs.

IS: Goal: For any n jobs we can compute OPT. Case 1: Job n is not in OPT. -- Then, just return OPT of 1, ..., n - 1. Case 2: Job n is in OPT. -- Then, delete all jobs not compatible with n and recurse. Q: Are we done?

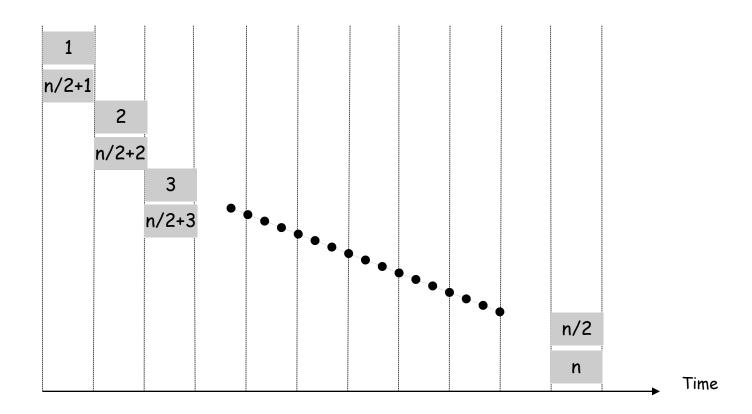
A: No, How many subproblems are there? Potentially  $2^n$  all possible subsets of jobs.



#### A Bad Example

Consider jobs n/2+1,...,n. These decisions have no impact on one another.

How many subproblems do we get?

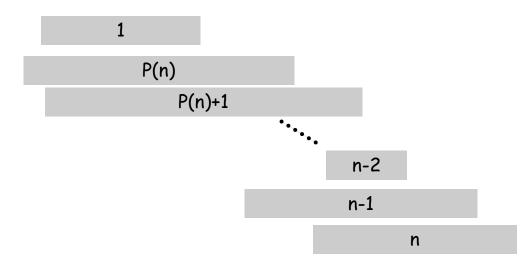


## Sorting to Reduce Subproblems

IS: For jobs 1,...,n we want to compute OPT Sorting Idea: Label jobs by finishing time  $f(1) \le \dots \le f(n)$ 

Case 1: Suppose OPT has job n.

- So, all jobs i that are not compatible with n are not OPT
- Let p(n) = largest index i < n such that job i is compatible with n.
- Then, we just need to find OPT of 1, ..., p(n)

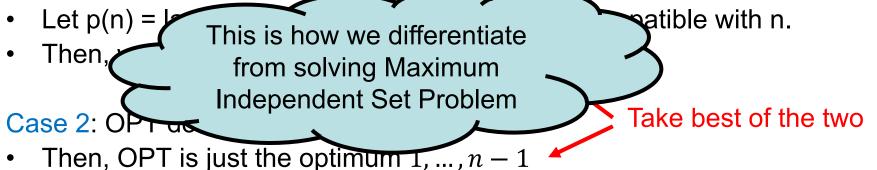


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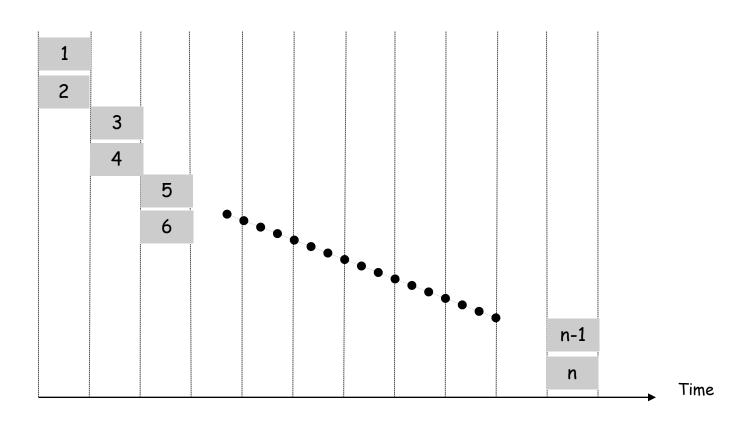
So, all jobs i that are not compatible with n are not OPT



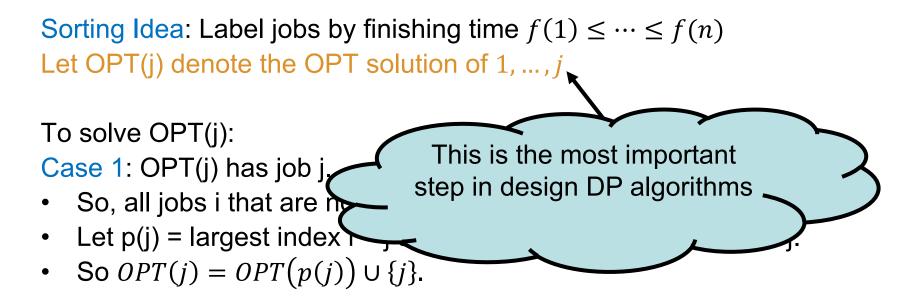
Q: Have we made any progress (still reducing to two subproblems)? A: Yes! This time every subproblem is of the form 1, ..., i for some iSo, at most n possible subproblems.

#### **Bad Example Review**

How many subproblems do we get in this sorted order?



# Weighted Job Scheduling by Induction



#### Case 2: OPT(j) does not select job j.

• Then, OPT(j) = OPT(j-1)

$$OPT(j) = \begin{cases} 0 & \text{if } j = 0 \\ \max\left(w_j + OPT(p(j)), OPT(j-1)\right) & \text{o.w.} \end{cases}$$

# Algorithm

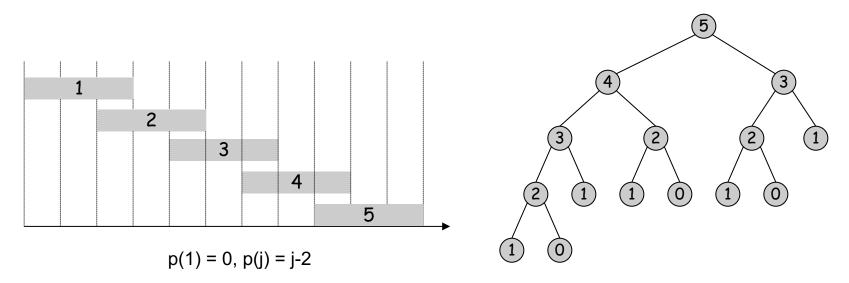
```
Input: n, s(1), \dots, s(n) and f(1), \dots, f(n) and w_1, \dots, w_n.
Sort jobs by finish times so that f(1) \leq f(2) \leq \cdots f(n).
Compute p(1), p(2), \dots, p(n)
Compute-Opt(j) {
    if (j = 0)
        return 0
    else
        return max(w<sub>j</sub> + Compute-Opt(p(j)), Compute-Opt(j-1))
}
```

## **Recursive Algorithm Fails**

Even though we have only n subproblems, we do not store the solution to the subproblems

 $\succ$  So, we may re-solve the same problem many many times.

Ex. Number of recursive calls for family of "layered" instances grows like Fibonacci sequence



# Algorithm with Memoization

Memoization. Compute and Store the solution of each sub-problem in a cache the first time that you face it. lookup as needed.

```
Input: n, s(1), ..., s(n) and f(1), ..., f(n) and w_1, ..., w_n.
Sort jobs by finish times so that f(1) \le f(2) \le \cdots f(n).
Compute p(1), p(2), ..., p(n)
for j = 1 to n
   M[j] = empty
M[0] = 0
M-Compute-Opt(j) {
   if (M[j] is empty)
       M[j] = max(w_j + M-Compute-Opt(p(j)), M-Compute-Opt(j-1))
   return M[j]
}
```

# Bottom up Dynamic Programming

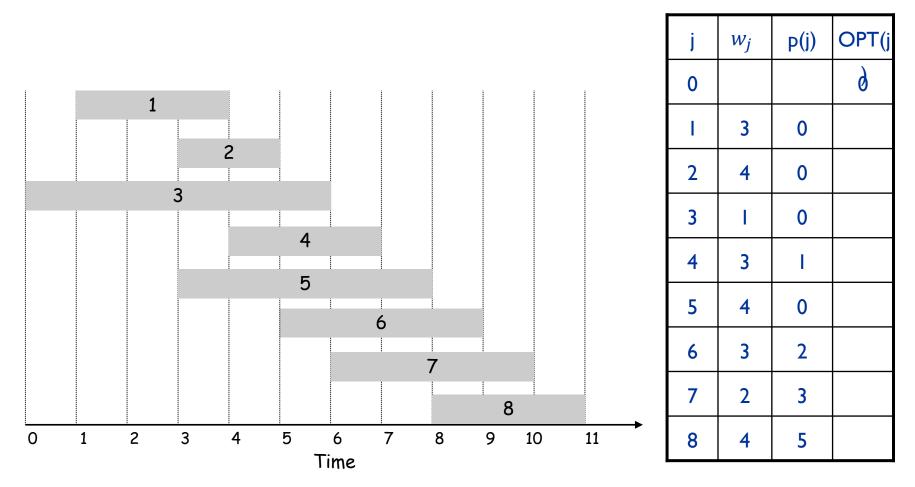
You can also avoid recusion

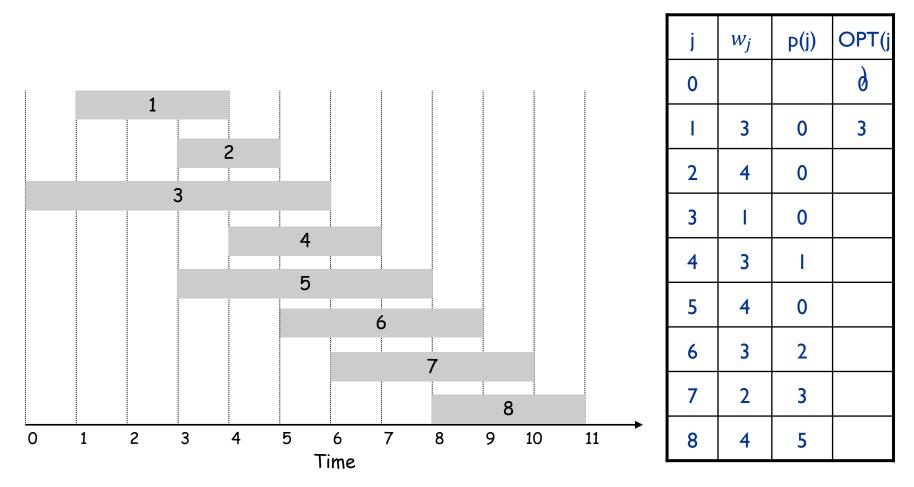
recursion may be easier conceptually when you use induction

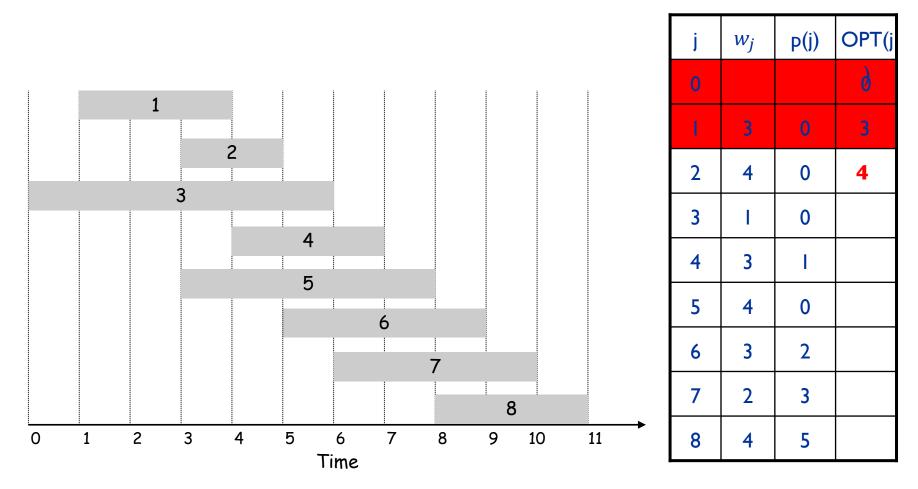
```
Input: n, s(1), ..., s(n) and f(1), ..., f(n) and w_1, ..., w_n.
Sort jobs by finish times so that f(1) \leq f(2) \leq \cdots f(n).
Compute p(1), p(2), ..., p(n)
Iterative-Compute-Opt {
    M[0] = 0
    for j = 1 to n
        M[j] = max(w<sub>j</sub> + M[p(j)], M[j-1])
}
```

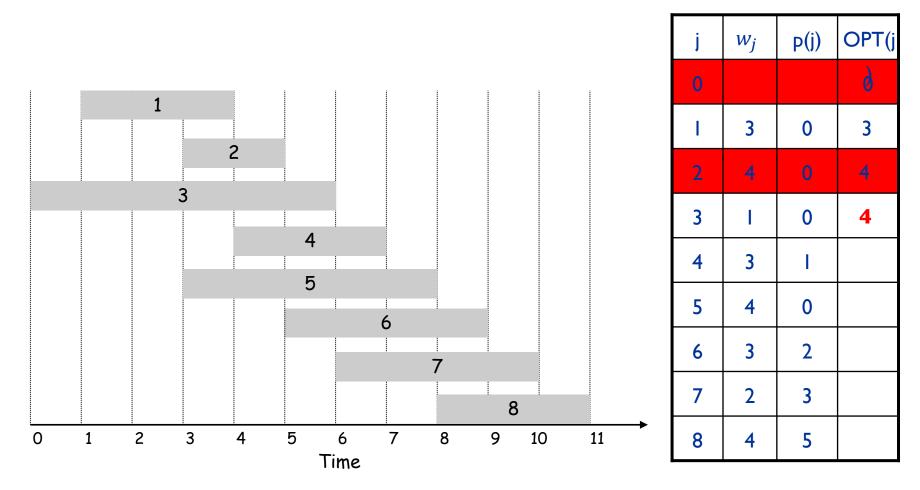
Output M[n]

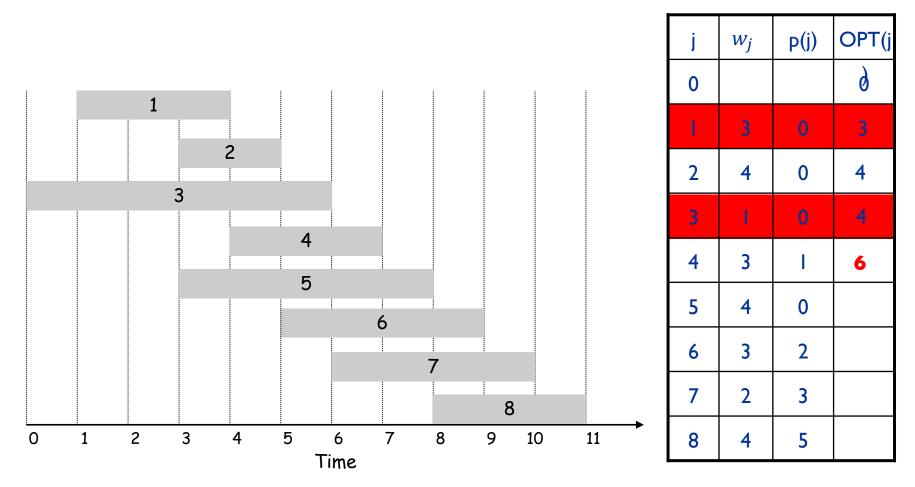
Claim: M[j] is value of OPT(j) Timing: Easy. Main loop is O(n); sorting is O(n log n)

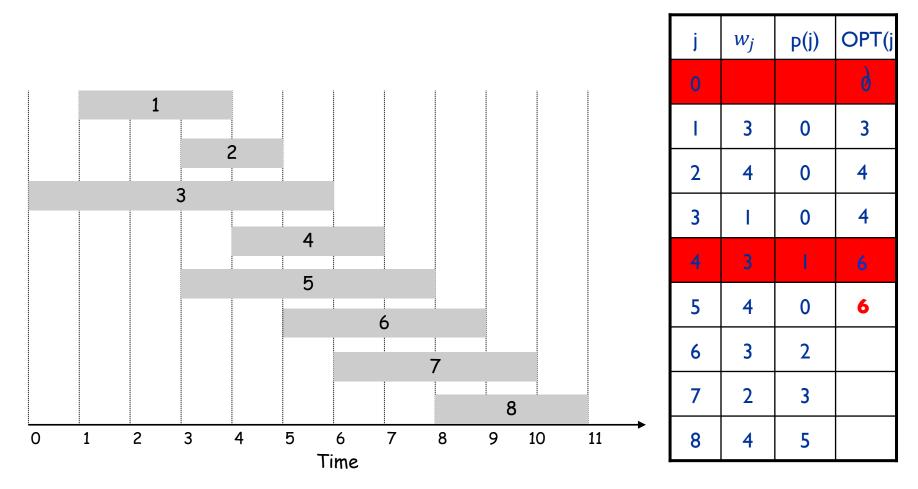


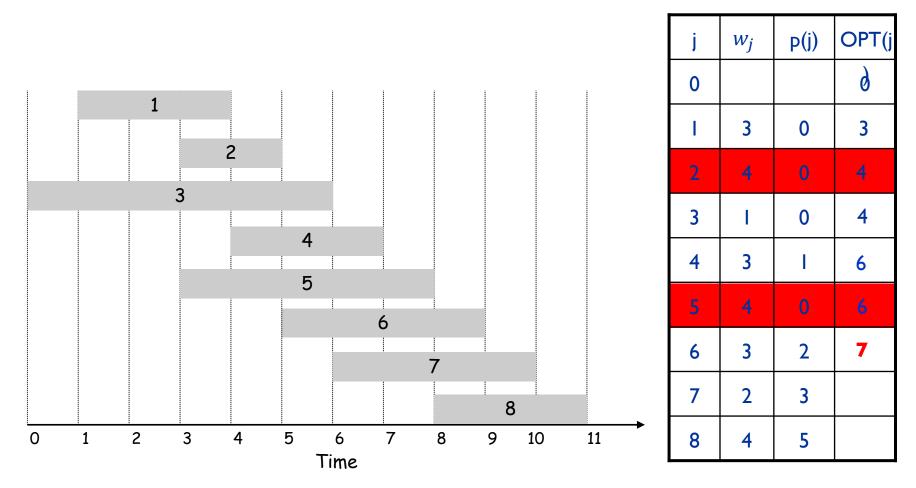


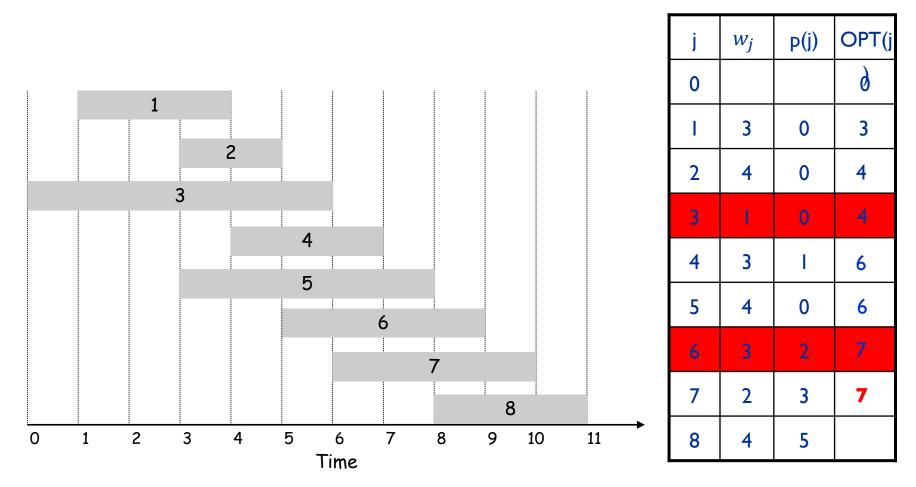


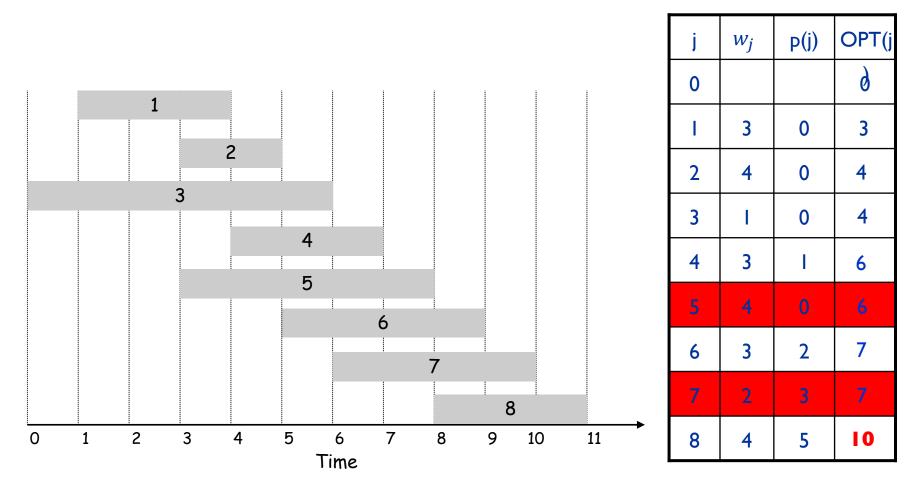


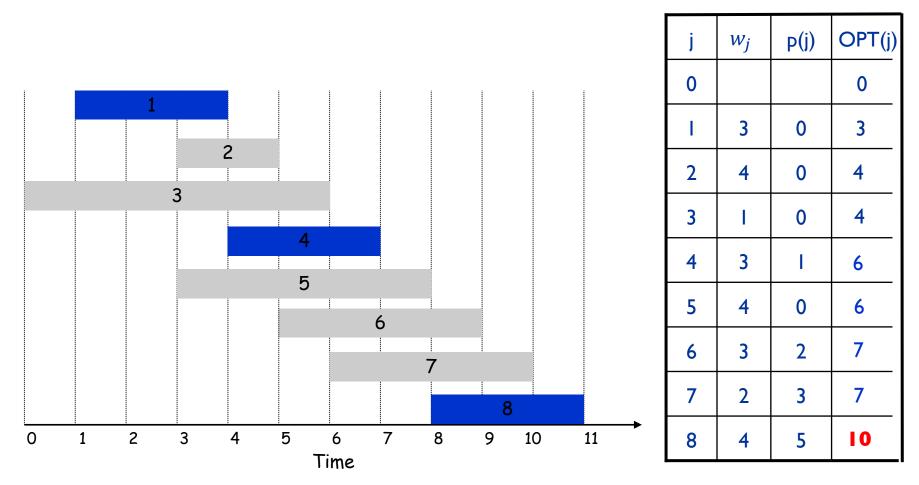












#### **Knapsack Problem**

### **Knapsack Problem**

Given *n* objects and a "knapsack."

Item *i* weighs  $w_i > 0$  kilograms (an integer) and value  $v_i \ge 0$ .

Knapsack has capacity of *W* kilograms.

Goal: fill knapsack so as to maximize total value.

	Item	Value	Weight
Ex: OPT is $\{3, 4\}$ with (weight 10) and value 36.	1	1	2
VV = 11	2	5	3
	3	14	4
	4	22	6
	5	30	8

Greedy: repeatedly add item with maximum ratio  $v_i / w_i$ .

**Ex**: { 5, 2 } achieves only value =  $35 \implies$  greedy not optimal.

# **Dynamic Programming: First Attempt**

Let OPT(i)=Max value of subsets of items 1, ..., i of weight  $\leq W$ .

Case 1: OPT(i) does not select item i

- In this case OPT(i) = OPT(i-1)

Case 2: OPT(i) selects item i

- In this case, item *i* does not immediately imply we have to reject other items
- The problem does not reduce to OPT(i-1) because we now want to pack as much value into box of weight  $\leq W w_i$

Conclusion: We need more subproblems, we need to strengthen IH.

# Stronger DP (Strengthenning Hypothesis)

Let OPT(i, w) = Max value subset of items 1, ..., *i* of weight  $\leq w$  where  $0 \leq i \leq n$  and  $0 \leq w \leq W$ .

Case 1: OPT(i, w) selects item *i* 

• In this case,  $OPT(i, w) = v_i + OPT(i - 1, w - w_i)$ 

Case 2: OPT(i, w) does not select item i

• In this case, OPT(i, w) = OPT(i - 1, w).

#### Therefore,

$$OPT(i,w) = \begin{cases} 0 & \text{If } i = 0\\ OPT(i-1,w) & \text{If } w_i > w\\ \max(OPT(i-1,w), v_i + OPT(i-1,w-w_i) & \text{o.w.}, \end{cases}$$

Take best of the two

```
Compute-OPT(i,w)
if M[i,w] == empty
if (i==0)
    M[i,w]=0
    recursive
else if (w<sub>i</sub> > w)
    M[i,w]=Comp-OPT(i-1,w)
    else
        M[i,w]= max {Comp-OPT(i-1,w), v<sub>i</sub> + Comp-OPT(i-1,w-w<sub>i</sub>)}
    return M[i, w]
```

```
for w = 0 to W
    M[0, w] = 0
for i = 1 to n
    for w = 1 to W
    if (w<sub>i</sub> > w)
        M[i, w] = M[i-1, w]
    else
        M[i, w] = max {M[i-1, w], v<sub>i</sub> + M[i-1, w-w<sub>i</sub>]}
```

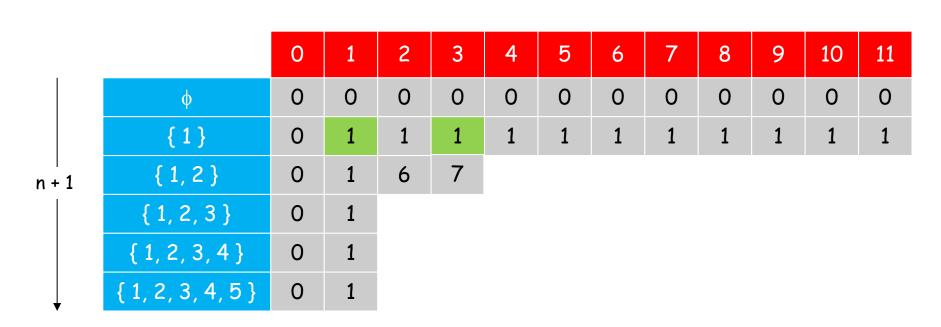
```
return M[n, W]
```

		0	1	2	3	4	5	6	7	8	9	10	11
	φ	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0											
 n + 1	{ 1, 2 }	0											
	{ 1, 2, 3 }	0											
	{ 1, 2, 3, 4 }	0											
↓ ▼	{1,2,3,4,5}	0											

	Item	Value	Weight
W = 11	1	1	1
if $(w_i > w)$	2	6	2
M[i, w] = M[i-1, w] 👉 else	3	18	5
$M[i, w] = \max \{M[i-1, w], v_i + M[i-1, w-w_i]\}$	4	22	6
	5	28	7

		0	1	2	3	4	5	6	7	8	9	10	11
	φ	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0	1	1	1	1	1	1	1	1	1	1	1
n + 1	{ 1, 2 }	0											
	{ 1, 2, 3 }	0											
	{ 1, 2, 3, 4 }	0											
Ļ	{1,2,3,4,5}	0											

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OPT: { 4, 3 } value = 22 + 18 = 40		Item	Value	Weight
	W = 11	1	1	1
if $(w_i > w)$		2	6	2
M[i, w] = M[i-1, w] else		3	18	5
M[i, w] = max {M[i-1, w], $v_i$ + M[i-1,	w-w <sub>i</sub> ]}	4	22	6
		5	28	7

		0	1	2	3	4	5	6	7	8	9	10	11
	φ	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0	1	1	1	1	1	1	1	1	1	1	1
n + 1	{ 1, 2 }	0	1	6	7	7	7	7	7	7	7	7	7
	{ 1, 2, 3 }	0	1	6	7	7	18	19					
	{ 1, 2, 3, 4 }	0	1										
Ļ	{1,2,3,4,5}	0	1										

OPT: { 4, 3 } value = 22 + 18 = 40	14/ 14	Item	Value	Weight
	W = 11	1	1	1
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M[i, w] = M[i-1, w] else		3	18	5
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		0	1	2	3	4	5	6	7	8	9	10	11
	φ	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0	1	1	1	1	1	1	1	1	1	1	1
 n + 1	{ 1, 2 }	0	1	6	7	7	7	7	7	7	7	7	7
	{ 1, 2, 3 }	0	1	6	7	7	18	19	24	25	25	25	25
	{ 1, 2, 3, 4 }	0	1	6	7	7	18	22	24	28	29		
↓ ↓	{1,2,3,4,5}	0	1										

OPT: { 4, 3 } value = 22 + 18 = 40	N4/ 11	Item	Value	Weight
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if $(w_i > w)$		2	6	2
M[i, w] = M[i-1, w] else		3	18	5
M[i, w] = max {M[i-1, w], $v_i$ + M[i-1	, w-w <sub>i</sub> ]}	4	22	6
		5	28	7

		0	1	2	3	4	5	6	7	8	9	10	11
	φ	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0	1	1	1	1	1	1	1	1	1	1	1
 n + 1	{ 1, 2 }	0	1	6	7	7	7	7	7	7	7	7	7
	{ 1, 2, 3 }	0	1	6	7	7	18	19	24	25	25	25	25
	{ 1, 2, 3, 4 }	0	1	6	7	7	18	22	24	28	29	29	40
↓ ▼	{1,2,3,4,5}	0	1	6	7	7	18	22	28	29	34	34	40

OPT: { 4, 3 } value = 22 + 18 = 40		Item	Value	Weight
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		5	28	7

# Knapsack Problem: Running Time

#### Running time: $\Theta(n \cdot W)$

- Not polynomial in input size!
- "Pseudo-polynomial."
- Decision version of Knapsack is NP-complete.

#### Knapsack approximation algorithm:

There exists a polynomial algorithm that produces a feasible solution that has value within 0.01% of optimum in time Poly(n, log W).

#### DP Ideas so far

- You may have to define an ordering to decrease #subproblems
- OPT(i,w) is exactly the predicate of induction
- You may have to strengthen DP, equivalently the induction, i.e., you have may have to carry more information to find the Optimum.
- This means that sometimes we may have to use two dimensional or three dimensional induction