

## Divide and Conquer: Integer Multiplication

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## Median

## Selecting k-th smallest

Problem: Given numbers  $x_1, ..., x_n$  and an integer  $1 \le k \le n$ output the *k*-th smallest number  $Sel(\{x_1, ..., x_n\}, k)$ 

A simple algorithm: Sort the numbers in time O(n log n) then return the k-th smallest in the array.

Can we do better?

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Yes, in time O(n) if k = 1 or k = 2.
```

Can we do O(n) for all possible values of k?

Assume all numbers are distinct for simplicity.

# An Idea

Choose a number w from  $x_1, \ldots, x_n$ 

Define

• 
$$S_{<}(w) = \{x_i : x_i < w\}$$

• 
$$S_{=}(w) = \{x_i : x_i = w\}$$

• 
$$S_{>}(w) = \{x_i : x_i > w\}$$

Solve the problem recursively as follows:

- If  $k \leq |S_{\leq}(w)|$ , output  $Sel(S_{\leq}(w), k)$
- Else if  $k \leq |S_{\leq}(w)| + |S_{=}(w)|$ , output w
- Else output  $Sel(S_{>}(w), k |S_{<}(w)| |S_{=}(w)|)$

Ideally want  $|S_{\leq}(w)|, |S_{\geq}(w)| \le n/2$ . In this case ALG runs in  $O(n) + O\left(\frac{n}{2}\right) + O\left(\frac{n}{4}\right) + \dots + O(1) = O(n)$ .

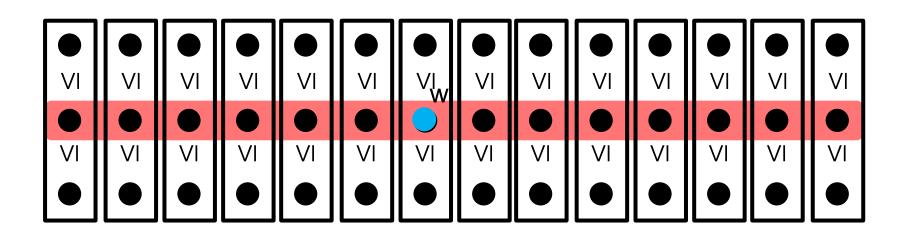
# How to choose w?

Suppose we choose w uniformly at random similar to the pivot in quicksort.

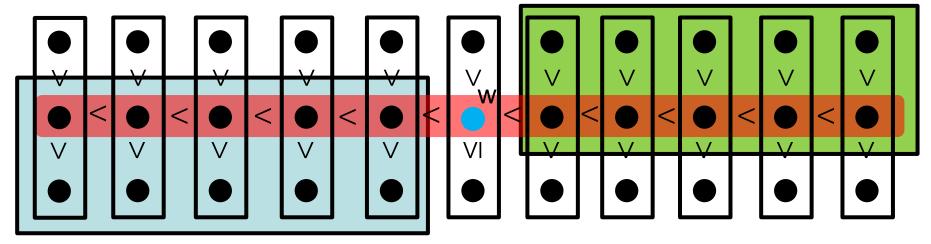
Then,  $\mathbb{E}[|S_{\leq}(w)|] = \mathbb{E}[|S_{>}(w)|] = n/2$ . Algorithm runs in O(n) in expectation.

Can we get O(n) running time deterministically?

- Partition numbers into sets of size 3.
- Sort each set (takes O(n))
- w = Sel(midpoints, n/6)



# How to lower bound $|S_{<}(w)|, |S_{>}(w)|$ ?

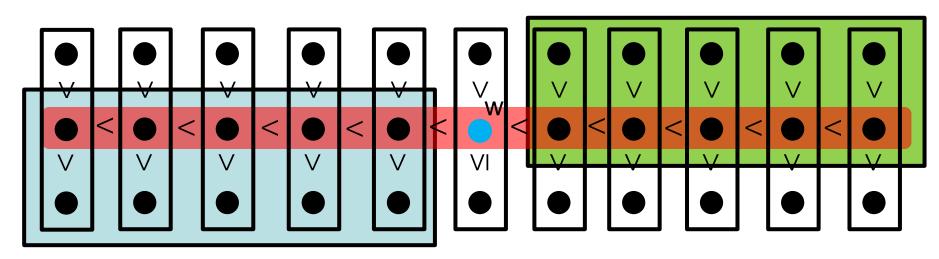


< **w** 

• 
$$|S_{<}(w)| \ge 2\left(\frac{n}{6}\right) = \frac{n}{3}$$
  
•  $|S_{>}(w)| \ge 2\left(\frac{n}{6}\right) = \frac{n}{3}$ .  
 $\frac{n}{3} \le |S_{<}(w)|, |S_{>}(w)| \le \frac{2n}{3}$ 

So, what is the running time?

# Asymptotic Running Time?



- If  $k \leq |S_{\leq}(w)|$ , output  $Sel(S_{\leq}(w), k)$
- Else if  $k \le |S_{\le}(w)| + |S_{=}(w)|$ , output w
- Else output  $Sel(S_>(w), k S_<(w) S_=(w))$

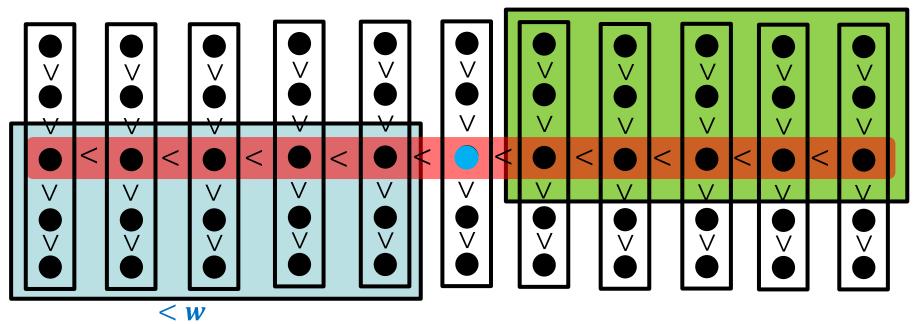
O(nlog n) again? So, what is the point?

Where 
$$\frac{n}{3} \le |S_{\le}(w)|, |S_{>}(w)| \le \frac{2n}{3}$$

$$T(n) = T\left(\frac{n}{3}\right) + T\left(\frac{2n}{3}\right) + O(n) \Rightarrow T(n) = O(n\log n)$$

# An Improved Idea

> w



Partition into n/5 sets. Sort each set and set w = Sel(midpoints, n/10)

•  $|S_{<}(w)| \ge 3\left(\frac{n}{10}\right) = \frac{3n}{10}$ •  $|S_{>}(w)| \ge 3\left(\frac{n}{10}\right) = \frac{3n}{10}$  $T(n) = T\left(\frac{n}{5}\right) + T\left(\frac{7n}{10}\right) + O(n) \Rightarrow T(n) = O(n)$ 

## An Improved Idea

```
Sel(S, k) {
   n \leftarrow |S|
   If (n < ??) return ??
   Partition S into n/5 sets of size 5
   Sort each set of size 5 and let M be the set of medians, so
|M|=n/5
   Let w=Sel(M,n/10)
                                             We can maintain each
   For i=1 to n{
      If x_i < w add x to S_<(w)
                                                 set in an array
      If x_i > w add x to S_>(w)
      If x_i = w add x to S_{=}(w)
   }
   If (k \leq |S_{\leq}(w)|)
      return Sel(S_{\leq}(w), k)
   else if (k \le |S_<(w)| + |S_=(w)|)
      return w;
   else
      return Sel (S_{>}(w), k - |S_{<}(w)| - |S_{=}(w)|)
```

}

# **D&C** Summary

Idea:

"Two halves are better than a whole"

- if the base algorithm has super-linear complexity.
- "If a little's good, then more's better"
  - repeat above, recursively
- Applications: Many.
  - Binary Search, Merge Sort, (Quicksort),
  - Root of a Function
  - Closest points,
  - Integer multiplication
  - Median
  - Matrix Multiplication

## **Approximation Algorithms**

# How to deal with NP-complete Problem

Many of the important problems in real world are NPcomplete. SAT, Set Cover, Graph Coloring, TSP, Max IND Set, Vertex Cover, ...

So, we cannot find optimum solutions in polynomial time. What to do instead?

- Find optimum solution of special cases (e.g., random inputs)
- Find near optimum solution in the worst case

# **Approximation Algorithm**

Polynomial-time Algorithms with a guaranteed approximation ratio.

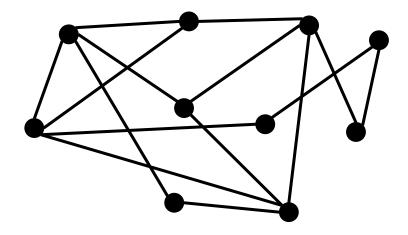
$$\alpha = \frac{\text{Cost of computed solution}}{\text{Cost of the optimum}}$$

worst case over all instances.

Goal: For each NP-hard problem find an approximation algorithm with the best possible approximation ratio.

#### Vertex Cover

Given a graph G=(V,E), Find smallest set of vertices touching every edge

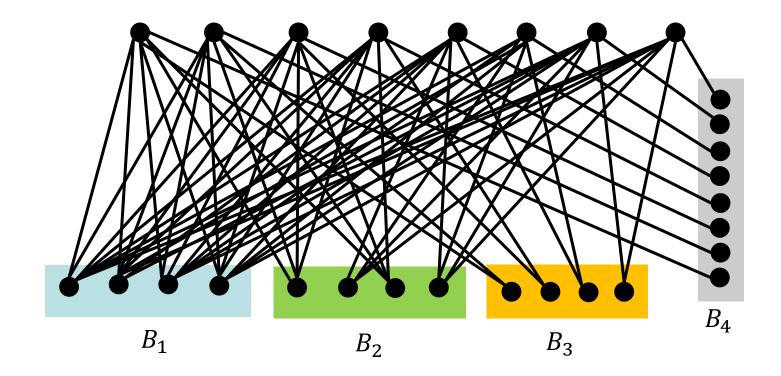


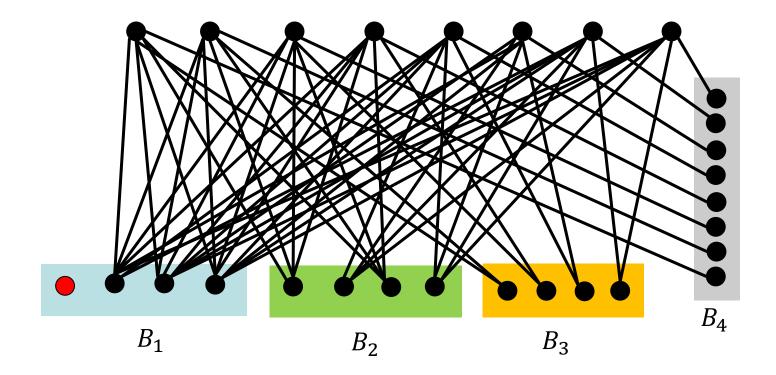
# Greedy Algorithm?

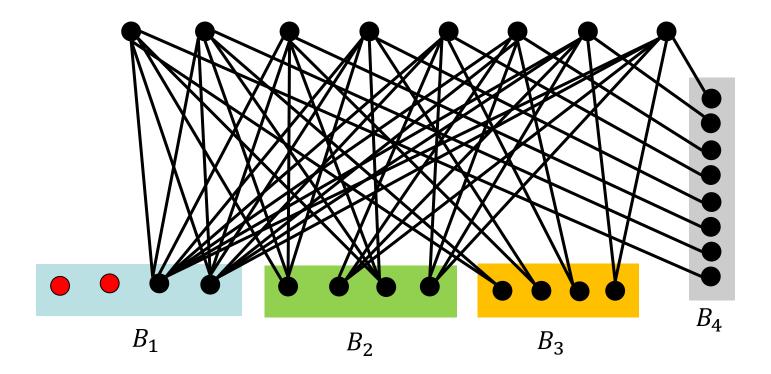
Greedy algorithms are typically used in practice to find a (good) solution to NP-hard problems

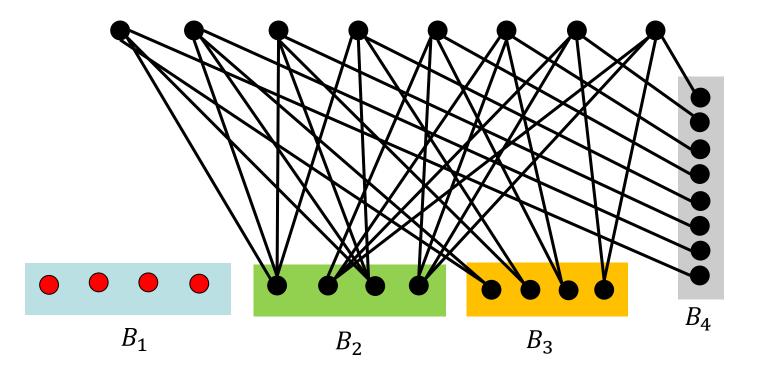
Strategy (1): Iteratively, include a vertex that covers most new edges

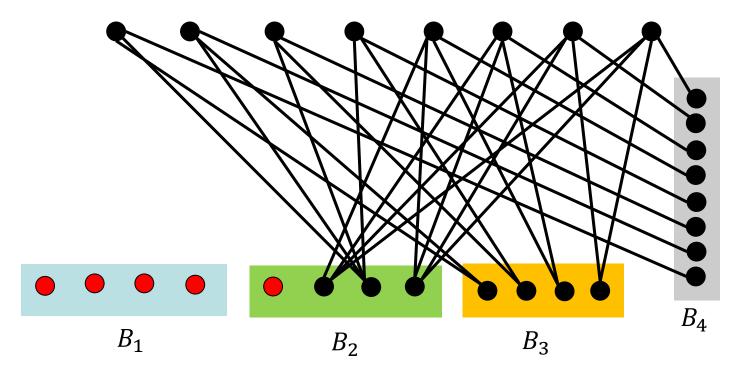
Q:Does this give an optimum solution? A: No,

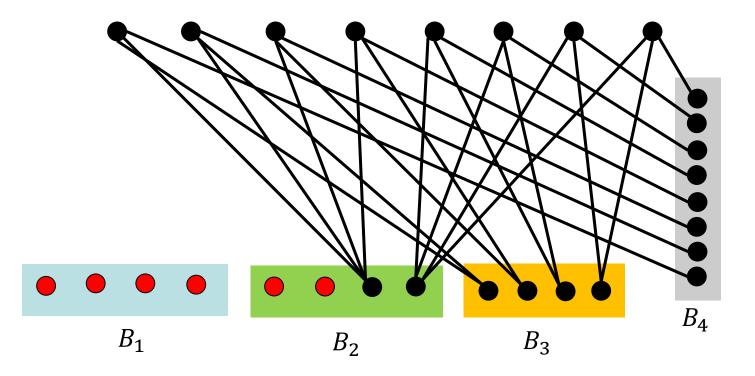


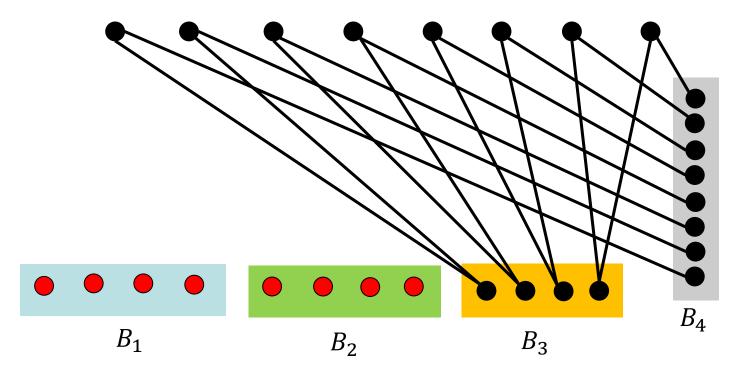


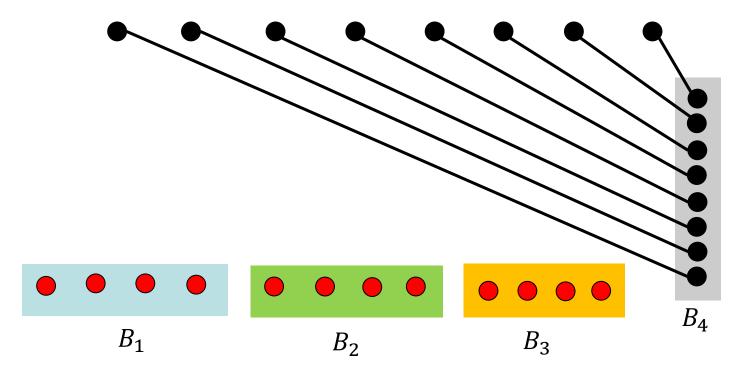


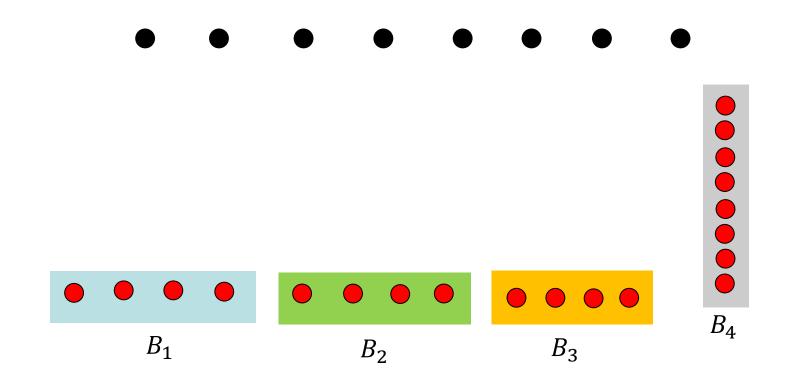


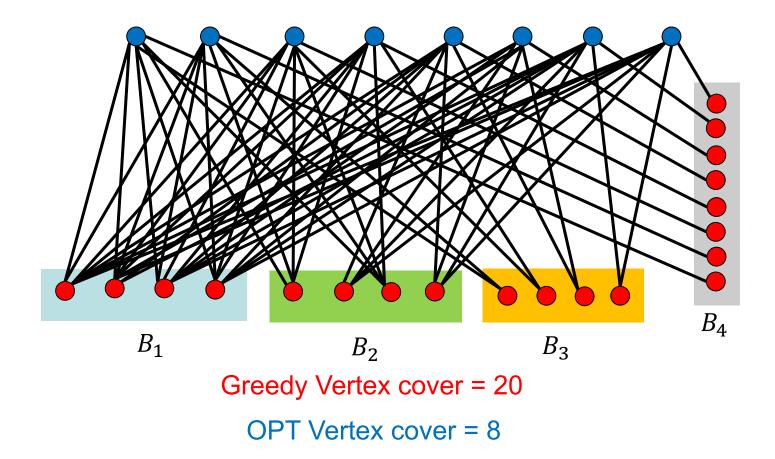






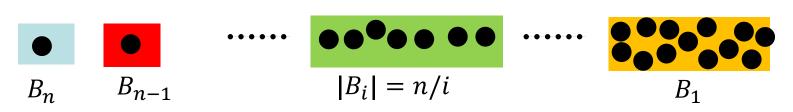






n vertices. Each vertex has one edge into each  $B_i$ 





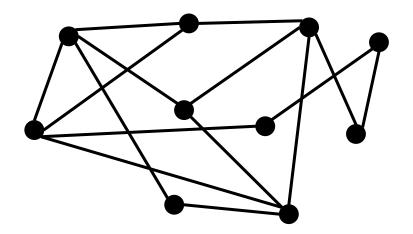
Each vertex in  $B_i$  has *i* edges to top

Greedy pick bottom vertices =  $n + \frac{n}{2} + \frac{n}{3} + \dots + 1 \approx n \ln n$ OPT pick top vertices = n

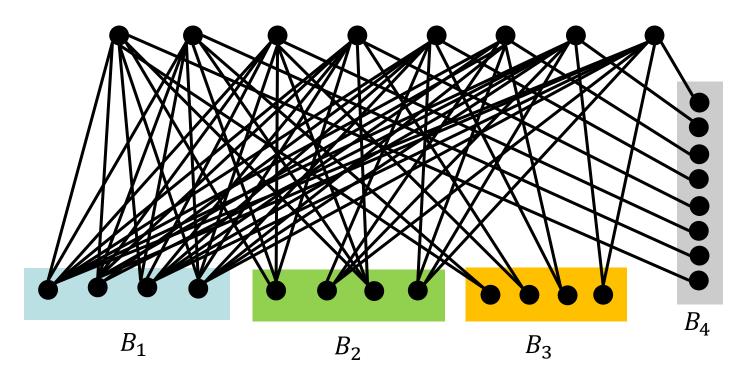
## A Different Greedy Rule

Greedy 2: Iteratively, pick both endpoints of an uncovered edge.

Vertex cover = 6



## Greedy 2: Pick Both endpoints of an uncovered edge



Greedy vertex cover = 16

OPT vertex cover = 8

# Greedy (2) gives 2-approximation

Thm: Size of greedy (2) vertex cover is at most twice as big as size of optimal cover

Pf: Suppose Greedy (2) picks endpoints of edges  $e_1, ..., e_k$ . Since these edges do not touch, every valid cover must pick one vertex from each of these edges!

i.e.,  $OPT \ge k$ .

But the size of greedy cover is 2k. So, Greedy is a 2-approximation.