

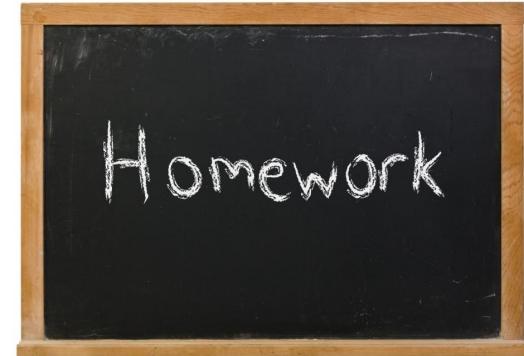
CSE 421: Introduction to Algorithms

Course Overview

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Administrativa Stuffs

HW1 is due Thursday April 08 at 11:59PM
Please submit to Gradescope



Late Submission: Fill out an extension request in edstem.

How to submit?

- **Double check** your submission before the deadline!!
- Please typeset your solution if possible

Guidelines:

- Always justify your answer
- You can collaborate, but you must write solutions on your own
- Your proofs should be clear, well-organized, and concise. Spell out main idea.
- Sanity Check: Spell out when you use assumptions of the problem

Induction: Intro 2

Prove that **every** instance of stable matchings with n companies and n applicants where some participant declare others as unacceptable has at most $n! = n(n - 1) \dots 2 \cdot 1$ many **perfect** matchings.

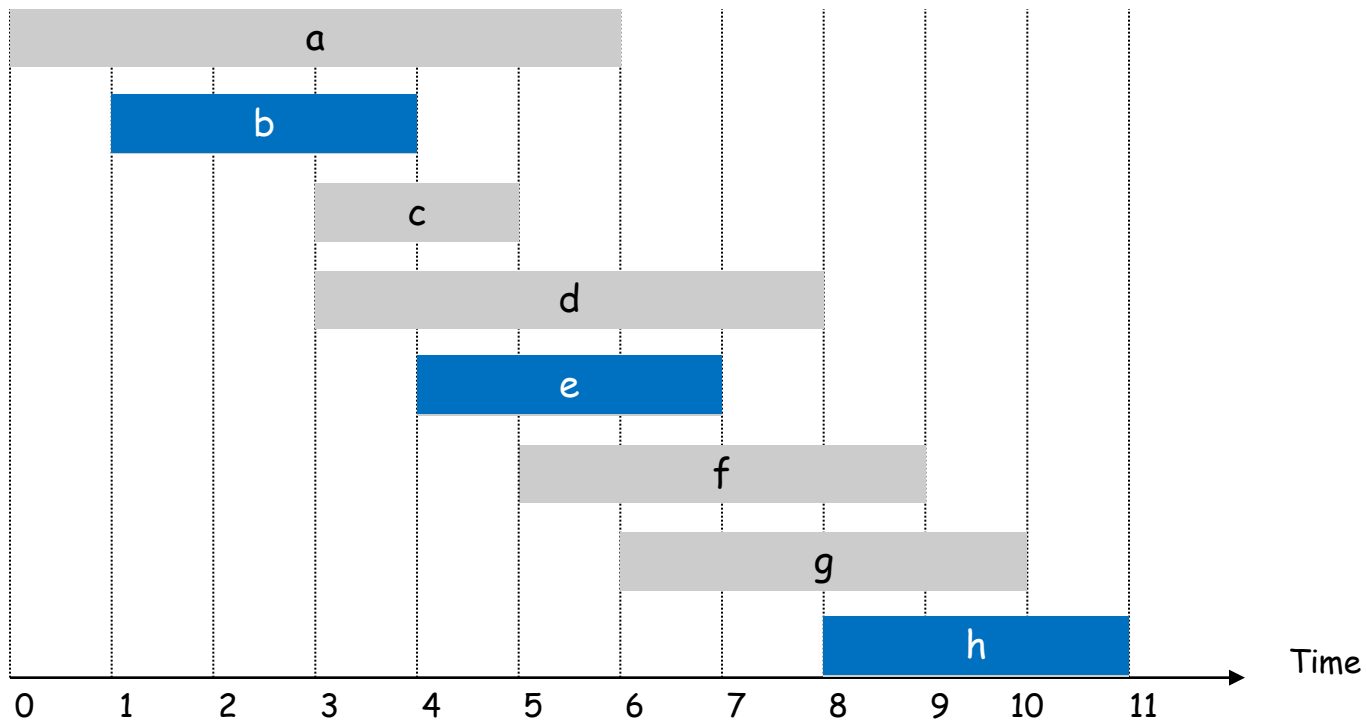
Five Representative Problems

1. Interval Scheduling
2. Weighted Interval Scheduling
3. Bipartite Matching
4. Independent Set Problem
5. Competitive Facility Location

Interval Scheduling

Input: Given a set of jobs with start/finish times

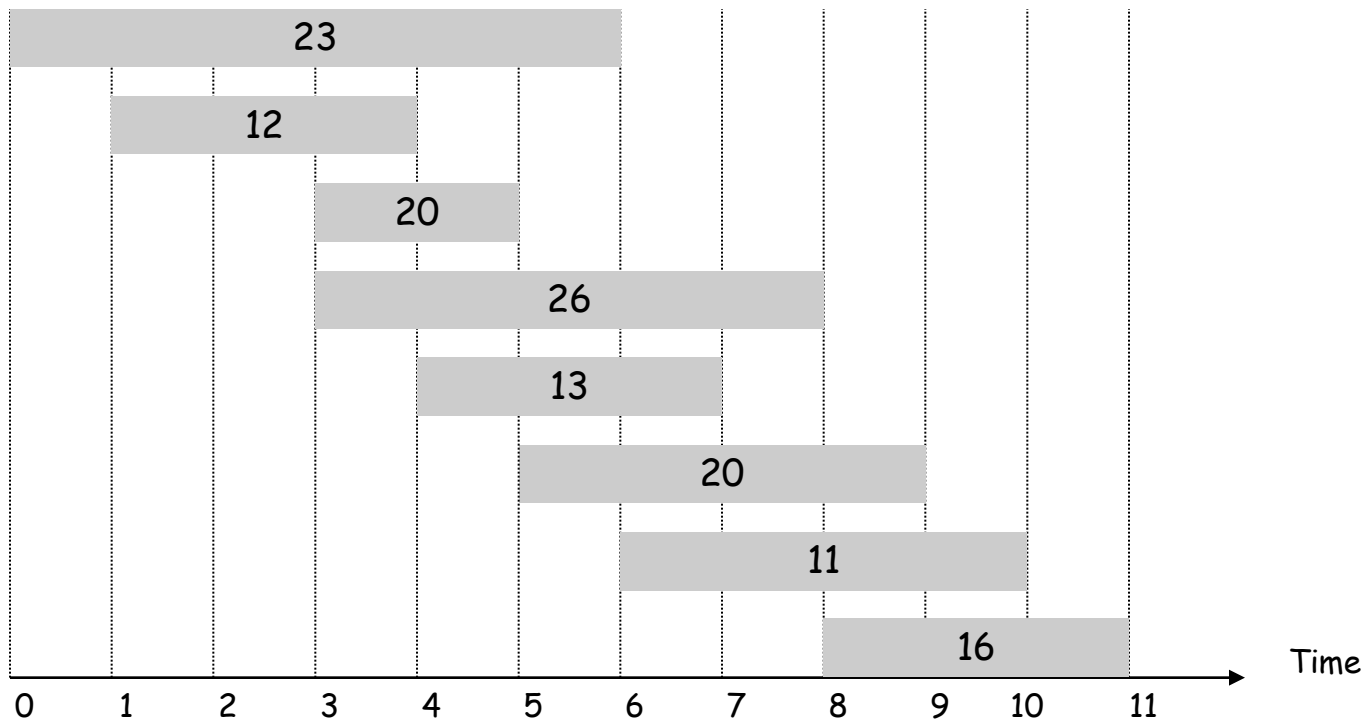
Goal: Find the **maximum cardinality** subset of jobs that can be run on a single machine.



Interval Scheduling

Input: Given a set of jobs with start/finish times

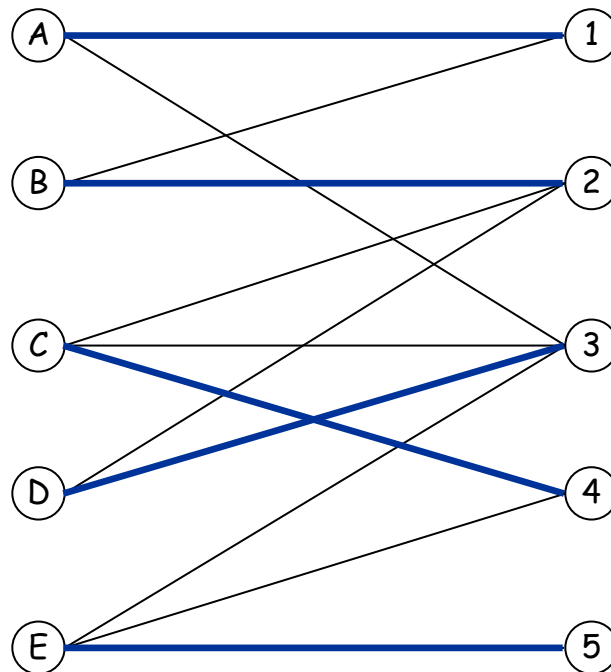
Goal: Find the **maximum weight** subset of jobs that can be run on a single machine.



Bipartite Matching

Input: Given a bipartite graph

Goal: Find the **maximum cardinality** matching

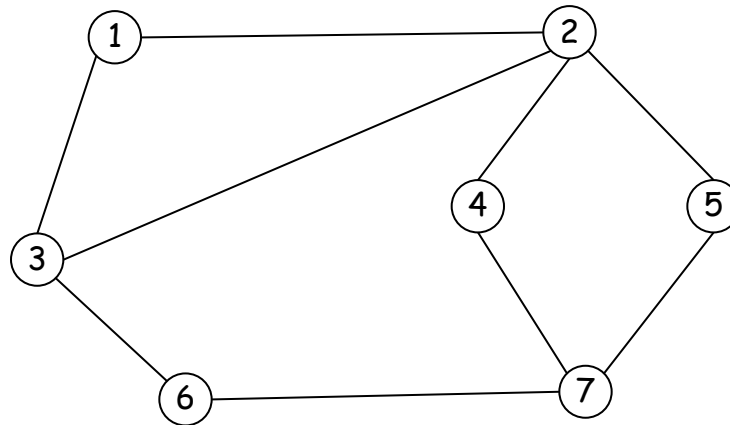


Independent Set

Input: A graph

Goal: Find the **maximum independent set**

Subset of nodes that no two joined by an edge

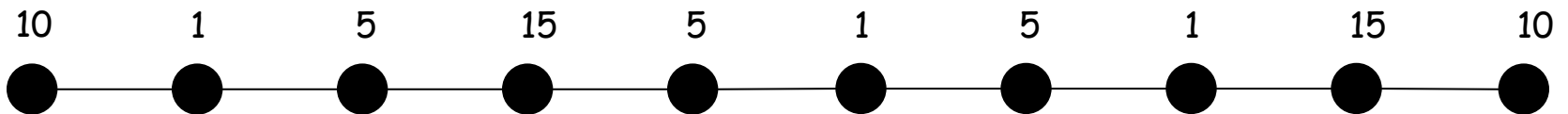


Competitive Facility Location

Input: Graph with weight on each node

Game: Two competing players alternate in selecting nodes. Not allowed to select a node if any of its neighbors have been selected.

Goal. Does player 2 have a strategy which guarantees a total value of V **no matter** what player 1 does?



Second player can guarantee 20, but not 25.

Five Representative Problems

Variation of a theme: Independent set Problem

1. Interval Scheduling
 $n \log n$ greedy algorithm
2. Weighted Interval Scheduling
 $n \log n$ dynamic programming algorithm
3. Bipartite Matching
 n^k maximum flow based algorithm
4. Independent Set Problem: NP-complete
5. Competitive Facility Location: PSPACE-complete

Main Objective: Design **Efficient** Algorithms
that finds optimum solutions in the **Worst Case**

Measuring Efficiency

Time \approx # of instructions executed in a **simple** programming language

only simple operations (+, *, -, =, if, call, ...)

each operation takes one time step

each memory access takes one time step

no fancy stuff (add these two matrices, copy this long string, ...) built in; write it/charge for it as above

Time Complexity

Problem: An algorithm can have different running time on different inputs

Solution: The complexity of an algorithm associates a number $T(N)$, the “time” the algorithm takes on problem size N .

On **which** inputs of size N ?

Mathematically,

T is a function that maps positive integers giving problem size to positive integers giving number of steps

Time Complexity (N)

Worst Case Complexity: **max** # steps algorithm takes on any input of size **N**

This Course

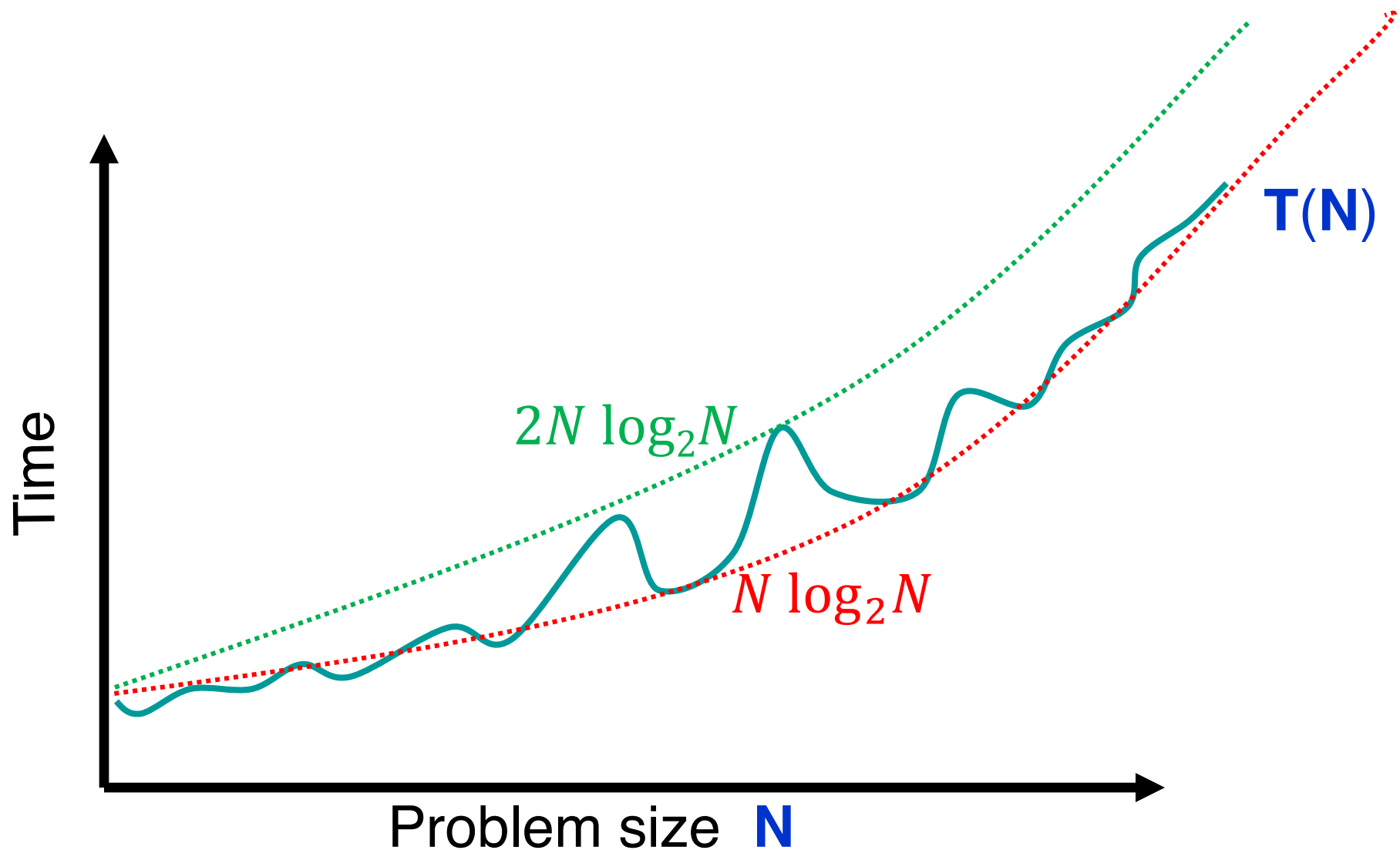
Average Case Complexity: **avg** # steps algorithm takes on inputs of size **N**

Best Case Complexity: **min** # steps algorithm takes on any input of size **N**

Why Worst-case Inputs?

- Analysis is typically easier
- Useful in real-time applications
e.g., space shuttle, nuclear reactors)
- Worst-case instances kick in when an algorithm is run as a module many times
e.g., geometry or linear algebra library
- Useful when running competitions
e.g., airline prices
- Unlike average-case no debate about the right definition

Time Complexity on Worst Case Inputs



O-Notation

Given two positive functions **f** and **g**

- **f(N)** is **O(g(N))** iff there is a constant **c > 0** s.t.,
f(N) is eventually always $\leq c g(N)$
- **f(N)** is **$\Omega(g(N))$** iff there is a constant **$\varepsilon > 0$** s.t.,
f(N) is $\geq \varepsilon g(N)$ for infinitely
- **f(N)** is **$\Theta(g(N))$** iff there are constants $c_1, c_2 > 0$ so that
eventually always $c_1 g(N) \leq f(N) \leq c_2 g(N)$

Asymptotic Bounds for common fns

- **Polynomials:**

$$a_0 + a_1n + \cdots + a_d n^d \text{ is } O(n^d)$$

- **Logarithms:**

$$\log_a n = O(\log_b n) \text{ for all constants } a, b > 0$$

- **Logarithms:** log grows slower than every polynomial

$$\text{For all } x > 0, \log n = O(n^x)$$

- $n \log n = O(n^{1.01})$

Efficient = Polynomial Time

An algorithm runs in polynomial time if $T(n) = O(n^d)$ for some constant d independent of the input size n .

Why Polynomial time?

If problem size grows by at most a constant factor then so does the running time

- E.g. $T(2N) \leq c(2N)^k \leq 2^k(cN^k)$
- Polynomial-time is exactly the set of running times that have this property

Typical running times are small degree polynomials, mostly less than N^3 , at worst N^6 , not N^{100}

Why it matters?

- #atoms in universe $< 2^{240}$
- Life of the universe $< 2^{54}$ seconds
- A CPU does $< 2^{30}$ operations a second

If every atom is a CPU, a 2^n time ALG cannot solve $n=350$ if we start at Big-Bang.

	n	$n \log_2 n$	n^2	n^3	1.5^n	2^n	$n!$
$n = 10$	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	4 sec
$n = 30$	< 1 sec	< 1 sec	< 1 sec	< 1 sec	< 1 sec	18 min	10^{25} years
$n = 50$	< 1 sec	< 1 sec	< 1 sec	< 1 sec	11 min	36 years	very long
$n = 100$	< 1 sec	< 1 sec	< 1 sec	1 sec	12,892 years	10^{17} years	very long
$n = 1,000$	< 1 sec	< 1 sec	1 sec	18 min	very long	very long	very long
$n = 10,000$	< 1 sec	< 1 sec	2 min	12 days	very long	very long	very long
$n = 100,000$	< 1 sec	2 sec	3 hours	32 years	very long	very long	very long
$n = 1,000,000$	1 sec	20 sec	12 days	31,710 years	very long	very long	very long

not only get very big, but do so *abruptly*, which likely yields erratic performance on small instances