

CSE 421 Algorithms

Winter 2019
Lecture 10
Minimum Spanning Trees

Announcement

- CSE 421 Midterm
 - Wednesday, February 13
 - In class, closed book, no notes
 - All material covered in lecture
 - KT 1.1 – KT 5.5

Edge costs are assumed to be non-negative

Dijkstra's Algorithm Implementation and Runtime

$S = \{ \}; d[s] = 0; d[v] = \text{infinity for } v \neq s$

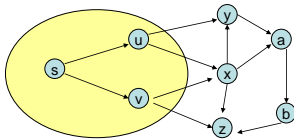
While $S \neq V$

Choose v in $V-S$ with minimum $d[v]$

Add v to S

For each w in the neighborhood of v

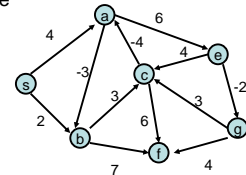
$d[w] = \min(d[w], d[v] + c(v, w))$



HEAP OPERATIONS
n Extract Mins
m Heap Updates

Shortest Paths

- Negative Cost Edges
 - Dijkstra's algorithm assumes positive cost edges
 - For some applications, negative cost edges make sense
 - Shortest path not well defined if a graph has a negative cost cycle

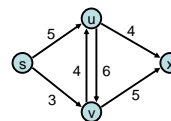


Negative Cost Edge Preview

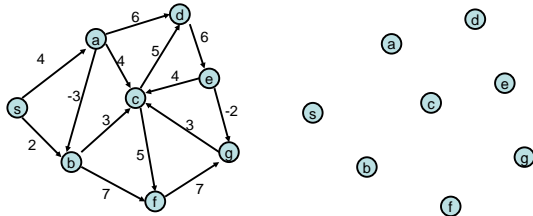
- Topological Sort can be used for solving the shortest path problem in directed acyclic graphs
- Bellman-Ford algorithm finds shortest paths in a graph with negative cost edges (or reports the existence of a negative cost cycle).

Bottleneck Shortest Path

- Define the bottleneck distance for a path to be the maximum cost edge along the path



Compute the bottleneck shortest paths



Dijkstra's Algorithm for Bottleneck Shortest Paths

$S = \{ \}$; $d[s] = \text{negative infinity}$; $d[v] = \text{infinity}$ for $v \neq s$

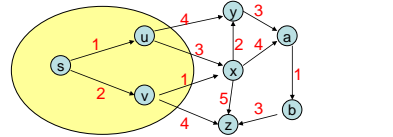
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Add v to S

For each w in the neighborhood of v

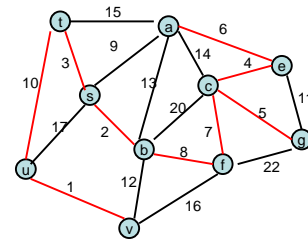
$d[w] = \min(d[w], \max(d[v], c(v, w)))$



Minimum Spanning Tree

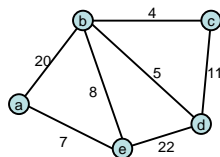
- Introduce Problem
- Demonstrate three different greedy algorithms
- Provide proofs that the algorithms work

Minimum Spanning Tree



Greedy Algorithms for Minimum Spanning Tree

- Extend a tree by including the cheapest outgoing edge
- Add the cheapest edge that joins disjoint components
- Delete the most expensive edge that does not disconnect the graph

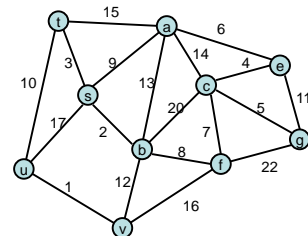


Greedy Algorithm 1 Prim's Algorithm

- Extend a tree by including the cheapest outgoing edge

Construct the MST with Prim's algorithm starting from vertex a

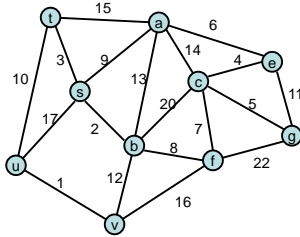
Label the edges in order of insertion



Greedy Algorithm 2 Kruskal's Algorithm

- Add the cheapest edge that joins disjoint components

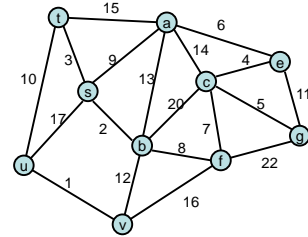
Construct the MST with Kruskal's algorithm
Label the edges in order of insertion



Greedy Algorithm 3 Reverse-Delete Algorithm

- Delete the most expensive edge that does not disconnect the graph

Construct the MST with the reverse-delete algorithm
Label the edges in order of removal



Dijkstra's Algorithm for Minimum Spanning Trees

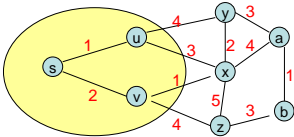
$S = \{ \}$; $d[s] = 0$; $d[v] = \text{infinity}$ for $v \neq s$
While $S \neq V$

Choose v in $V-S$ with minimum $d[v]$

Add v to S

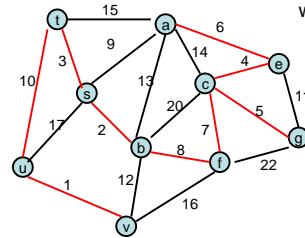
For each w in the neighborhood of v

$d[w] = \min(d[w], c(v, w))$



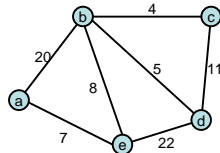
Minimum Spanning Tree

Undirected Graph
 $G=(V,E)$ with edge weights



Greedy Algorithms for Minimum Spanning Tree

- **[Prim]** Extend a tree by including the cheapest outgoing edge
- **[Kruskal]** Add the cheapest edge that joins disjoint components
- **[ReverseDelete]** Delete the most expensive edge that does not disconnect the graph

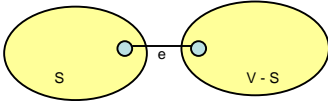


Why do the greedy algorithms work?

- For simplicity, assume all edge costs are distinct

Edge inclusion lemma

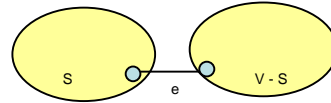
- Let S be a subset of V , and suppose $e = (u, v)$ is the minimum cost edge of E , with u in S and v in $V-S$
- e is in every minimum spanning tree of G
 - Or equivalently, if e is not in T , then T is not a minimum spanning tree



e is the minimum cost edge between S and $V-S$

Proof

- Suppose T is a spanning tree that does not contain e
- Add e to T , this creates a cycle
- The cycle must have some edge $e_1 = (u_1, v_1)$ with u_1 in S and v_1 in $V-S$



- $T_1 = T - \{e_1\} + \{e\}$ is a spanning tree with lower cost
- Hence, T is not a minimum spanning tree