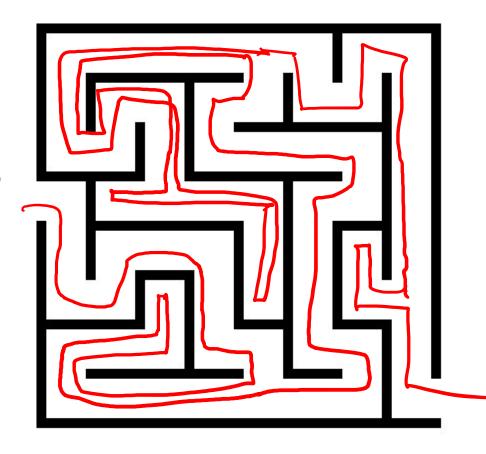
CSE 421

DFS / Topological Ordering

Shayan Oveis Gharan

Depth First Search

Follow the first path you find as far as you can go; back up to last unexplored edge when you reach a dead end, then go as far you can



Naturally implemented using recursive calls or a stack

DFS(s) – Recursive version

Global Initialization: mark all vertices undiscovered

```
DFS(v)
Mark v discovered

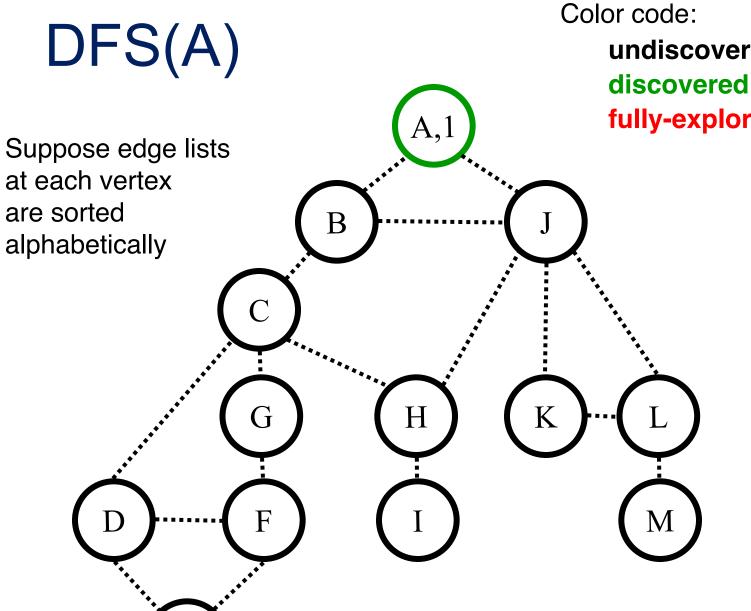
for each edge {v,x}

if (x is undiscovered)

Mark x discovered

DFS(x)
```

Mark v full-discovered

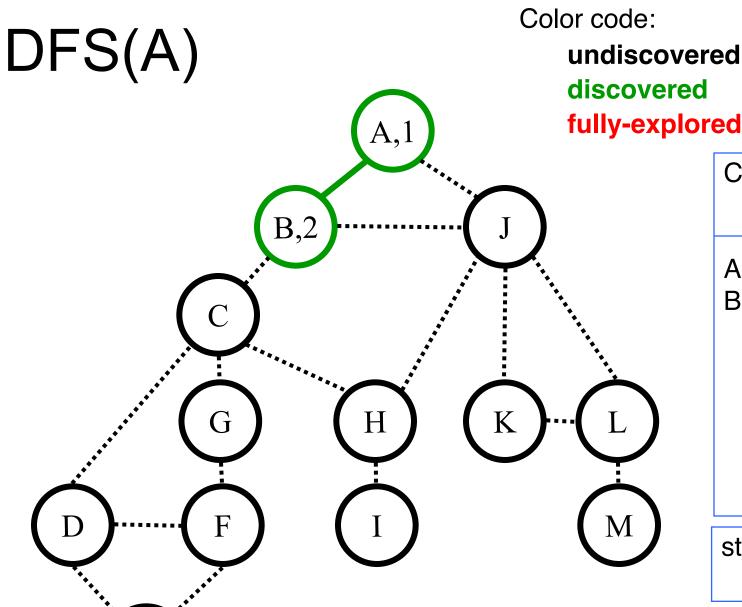


fully-explored

Call Stack (Edge list):

A (B,J)

st[] = **{1**}

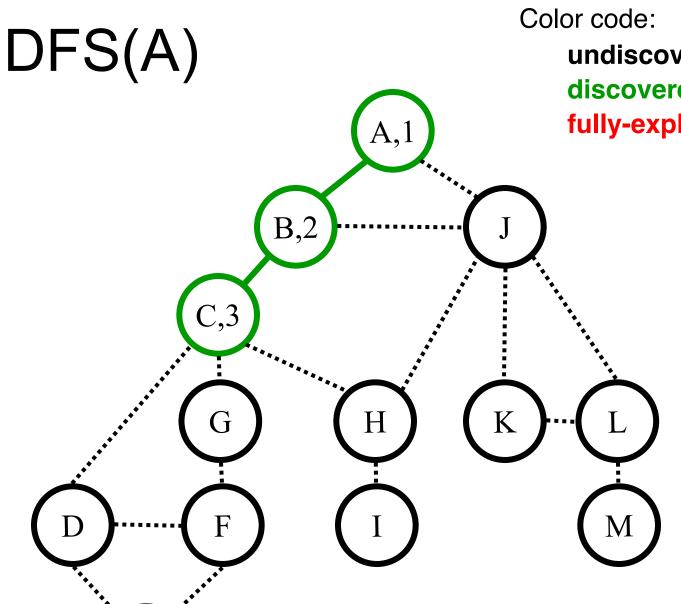


fully-explored

Call Stack: (Edge list)

A(P,J)B(A,C,J)

st[] = {1,2}



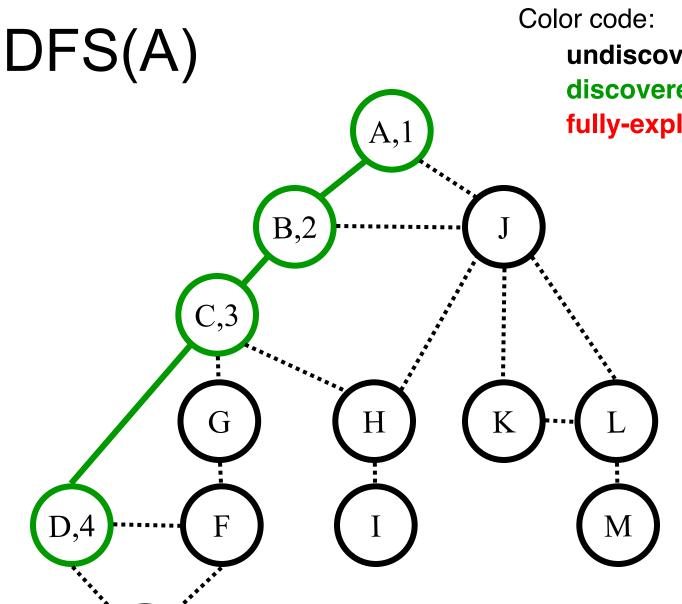
discovered

fully-explored

Call Stack: (Edge list)

A(P,J)B (**A**,**C**,J) C (B,D,G,H)

st[] = {1,2,3}



discovered

fully-explored

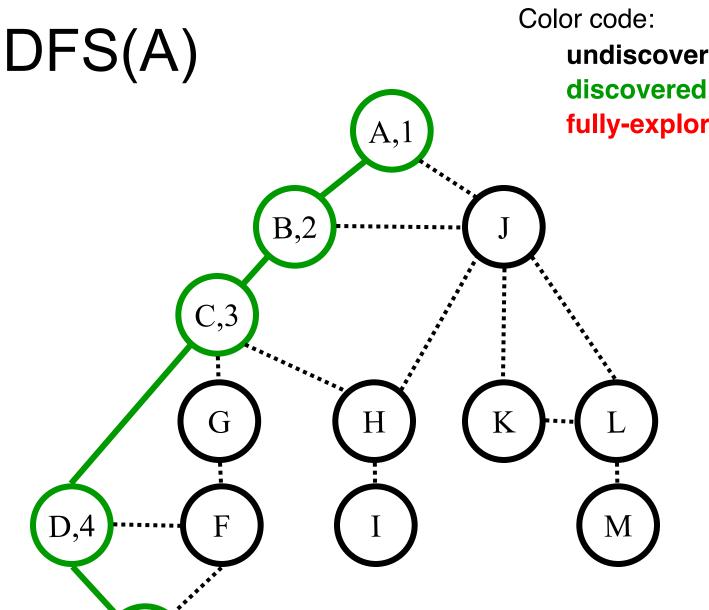
Call Stack: (Edge list)

A(B,J)

B (**A**,**C**,J) C (**B**,**D**,G,H)

D(C,E,F)

st[] = {1,2,3,4}



fully-explored

Call Stack: (Edge list)

A(B,J)

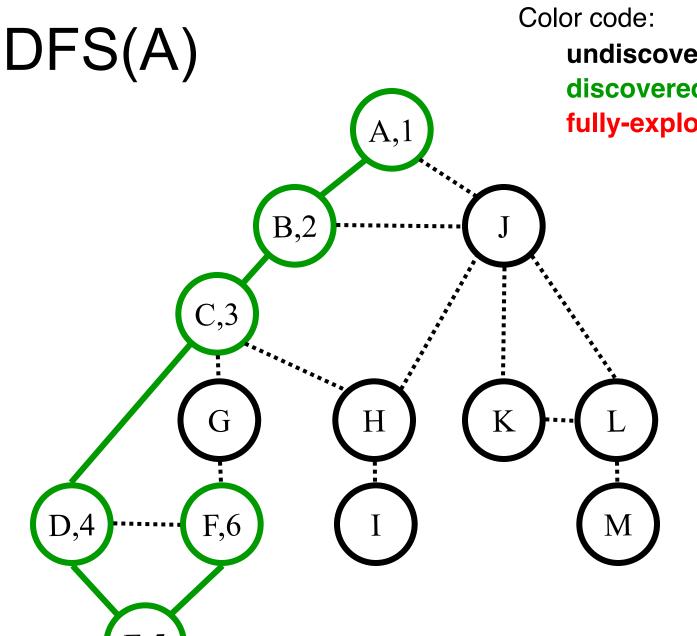
 $B(\cancel{K},\cancel{C},J)$

C (**B**,**D**,**G**,**H**)

D (**%**,**F**,F)

E(D,F)

st[] = {1,2,3,4,5}



discovered

fully-explored

Call Stack: (Edge list)

A(B,J)

 $B(\cancel{K},\cancel{C},J)$

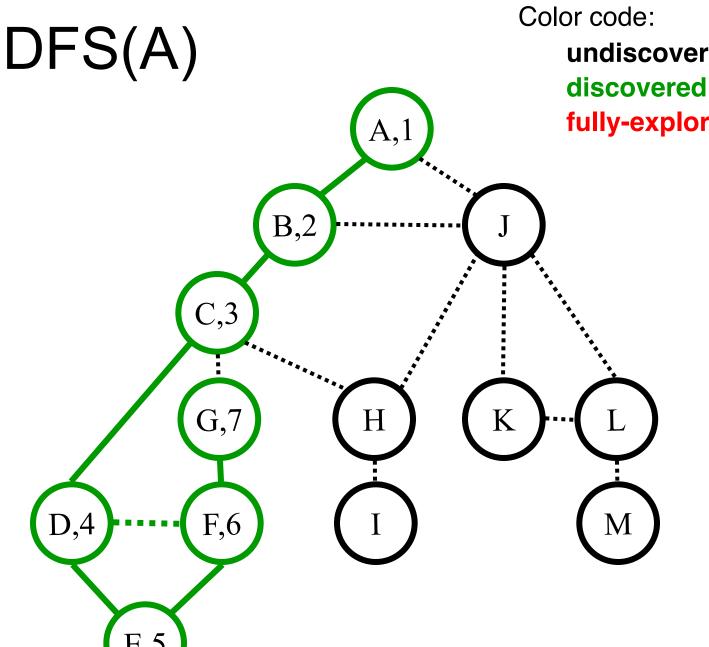
C (**p**,**p**,G,H)

D (**∅**,**万**,F)

 $E(\vec{p},\vec{r})$

F (D,E,G)

st[] = {1,2,3,4,5, 6}



fully-explored

Call Stack: (Edge list)

A(B,J)

 $B(\cancel{K},\cancel{C},J)$

C (**p**,**p**,G,H)

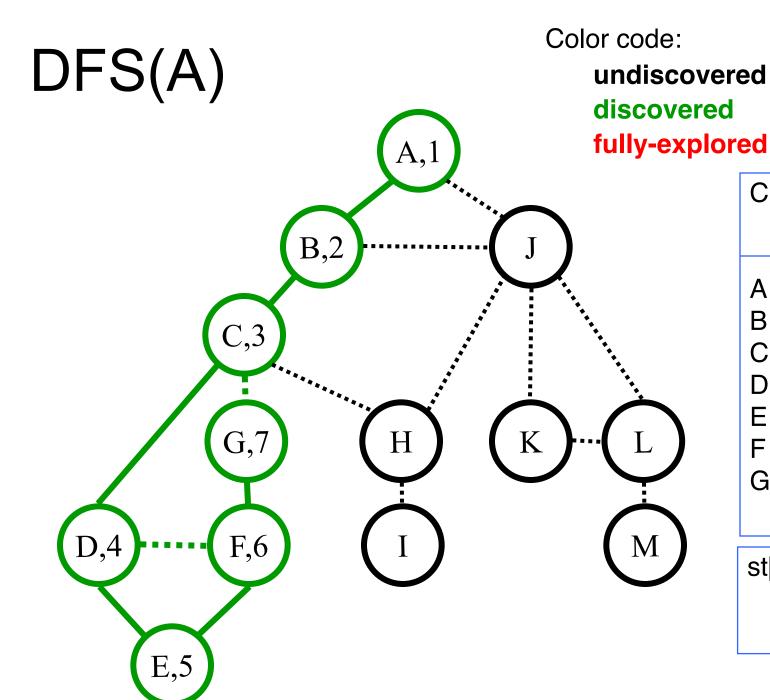
D (**∅**,**万**,F)

 $E(\vec{p},\vec{r})$

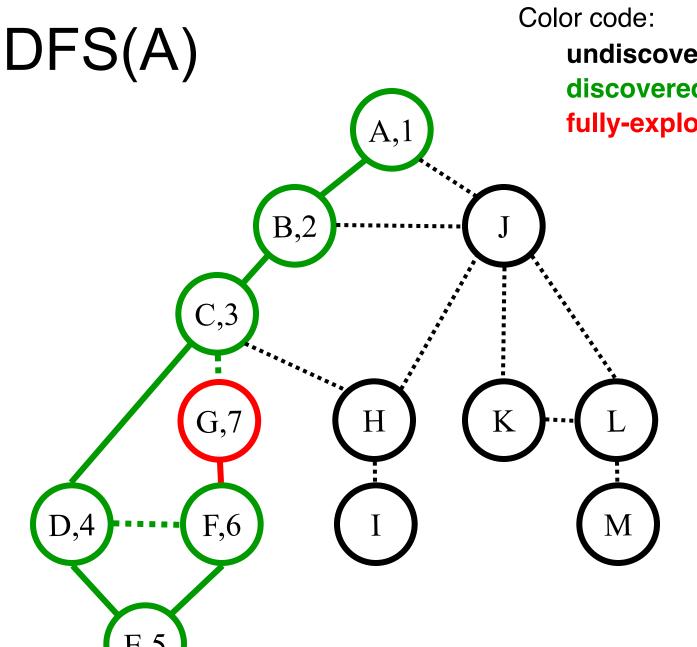
F (D,E,G)

G(C,F)

st[] = {1,2,3,4,5, 6,7}



A (**p**,J) B (**p**,**p**,G,J) C (**p**,**p**,G,H) D (**p**,**p**,F) E (**p**,**p**) F (**p**,**p**,E,**p**) G (**p**,**p**)



discovered

fully-explored

Call Stack: (Edge list)

A(B,J)

 $B(\cancel{K},\cancel{C},J)$

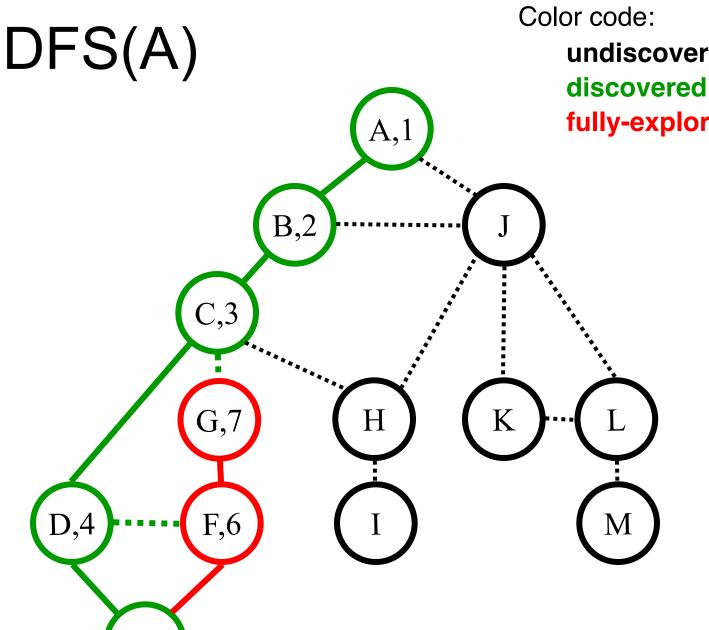
C (**p**,**p**,G,H)

D (**%**,**F**,F)

 $E(\vec{p},\vec{r})$

F (D,E,G)

st[] = {1,2,3,4,5, 6}



fully-explored

Call Stack: (Edge list)

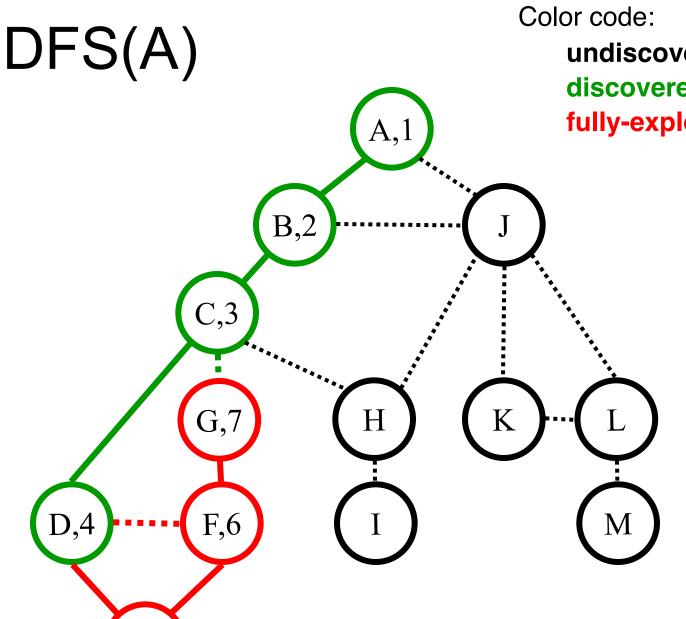
A(B,J)

B (**A**,**C**,J) C (**B**,**D**,G,H)

D (**%**,**F**,F)

 $E(\mathcal{D},\mathcal{F})$

st[] = {1,2,3,4,5}



discovered

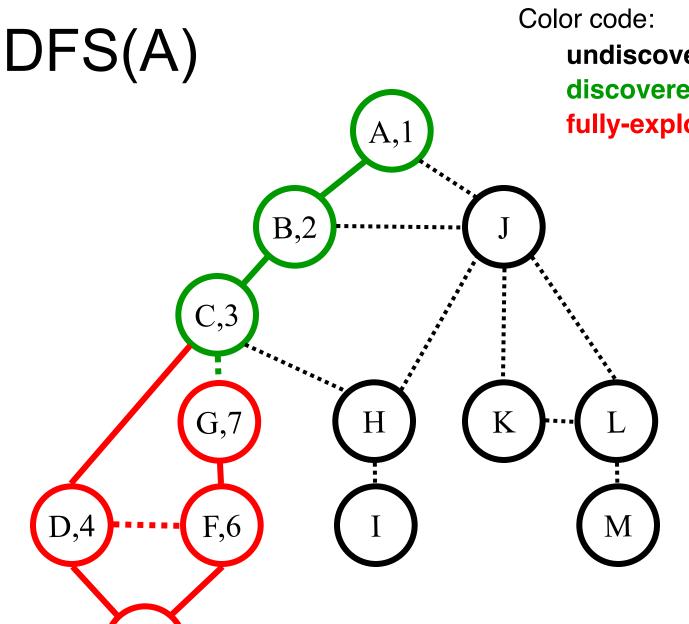
fully-explored

Call Stack: (Edge list)

A(B,J)

B (**A**,**C**,J) C (**B**,**D**,G,H) D (**C**,**E**,**F**)

st[] = {1,2,3,4}



discovered

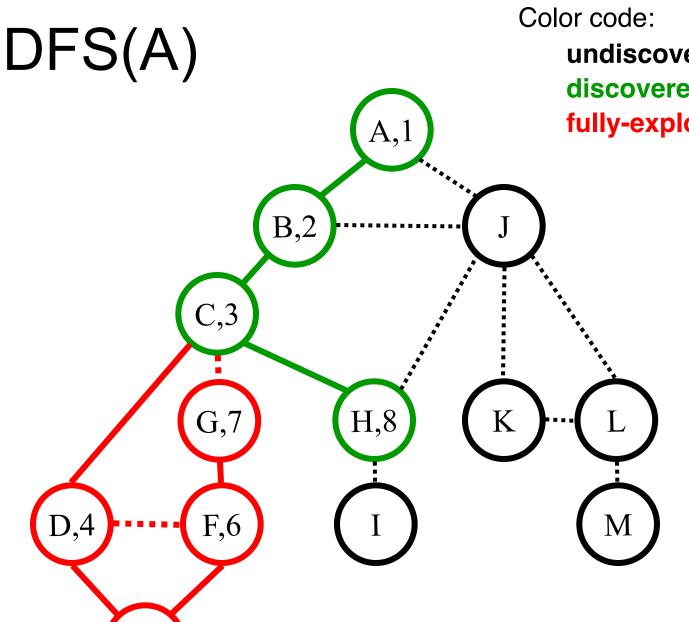
fully-explored

Call Stack: (Edge list)

A(B,J)

B (**A**,**C**,J) C (**B**,**D**,G,H)

st[] = {1,2,3}



discovered

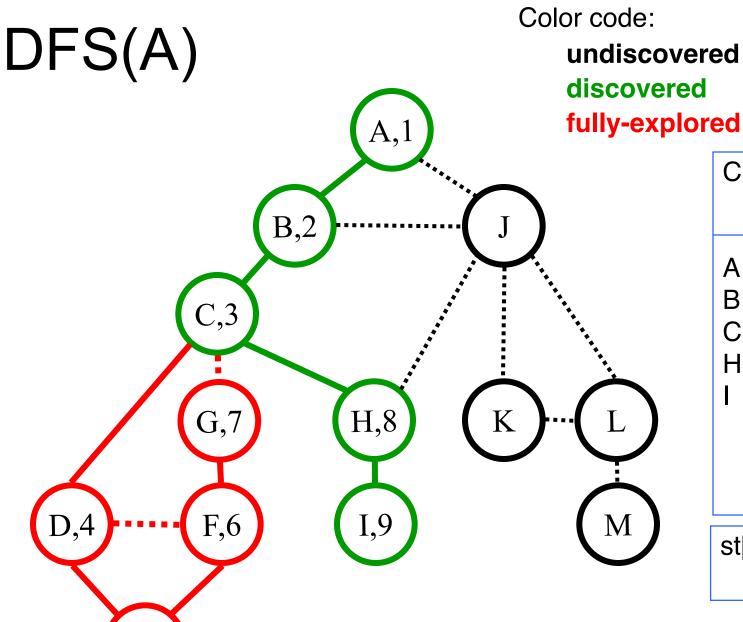
fully-explored

Call Stack: (Edge list)

A(B,J)B (**A**,**C**,**J**) C (**B**,**D**,**C**,**H**)

H(C,I,J)

st[] = {1,2,3,8}



E,5

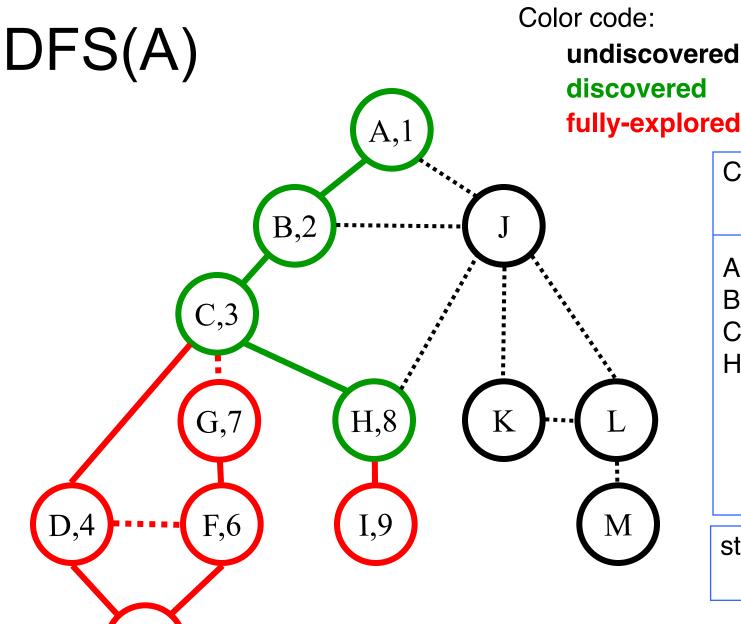
undiscovered

Call Stack: (Edge list)

A(B,J) $B(\cancel{R},\cancel{Q},J)$ $C(\cancel{R},\cancel{Q},\cancel{M},\cancel{M})$ H (**%**,**/**,**J**)

I (H)

st[] = {1,2,3,8,9}

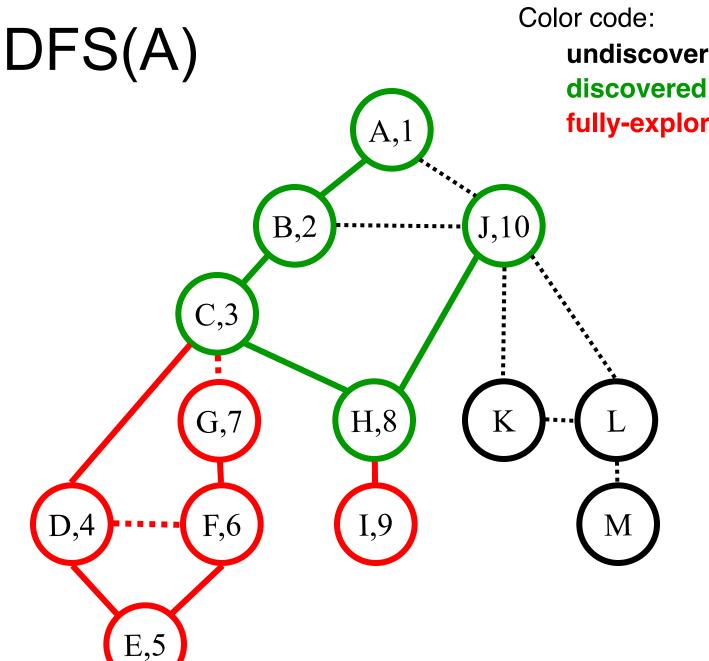


fully-explored

Call Stack: (Edge list)

A(B,J)B (**A**,**C**,**J**) C (**B**,**D**,**C**,**H**) H (**C**,**Y**,**J**)

st[] = {1,2,3,8}

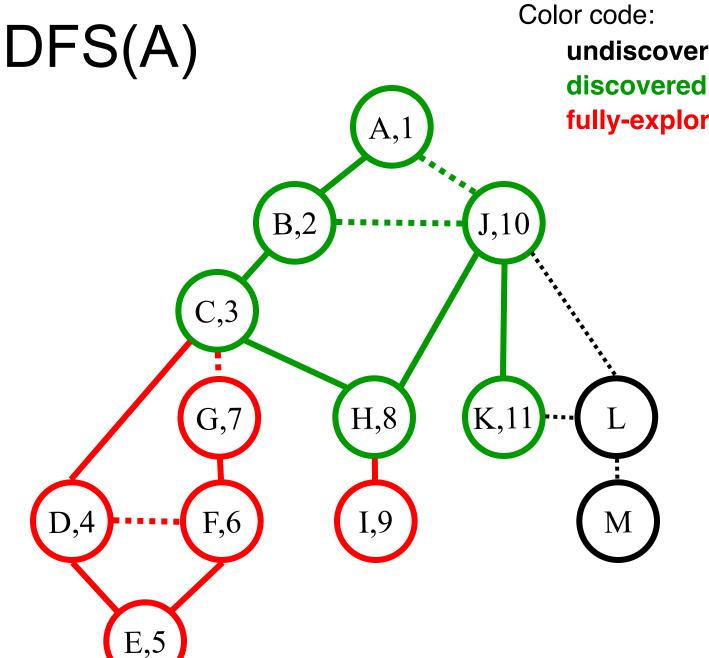


fully-explored

Call Stack: (Edge list)

A(B,J)B (A, C, J) C (B, D, A, H) H (2,1,1) J(A,B,H,K,L)

st[] = {1,2,3,8, 10}



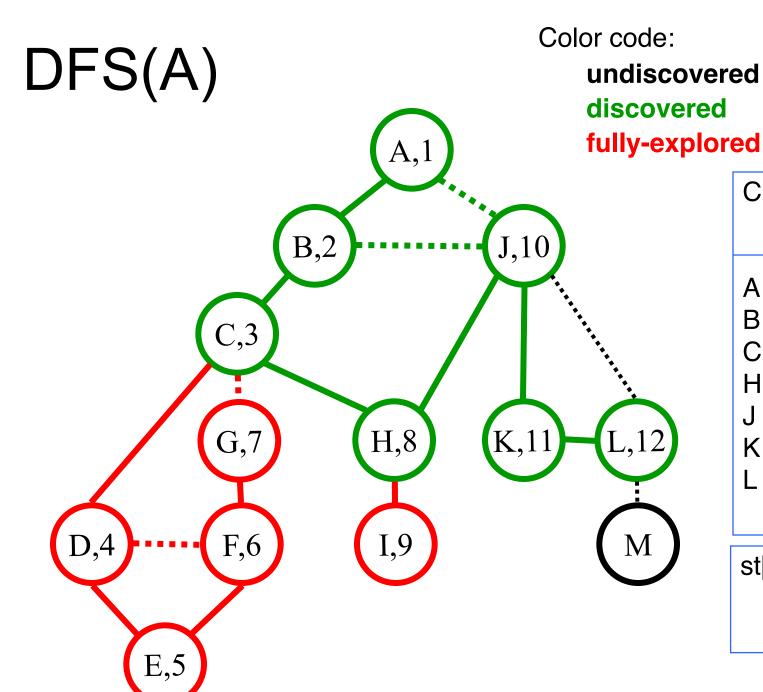
fully-explored

Call Stack: (Edge list)

A(B,J)B (**A**,**C**,J) C (**B**,**D**,**C**,**H**) $H(\mathcal{C},\mathcal{V},\mathcal{Y})$ J(A,B,H,K,L)

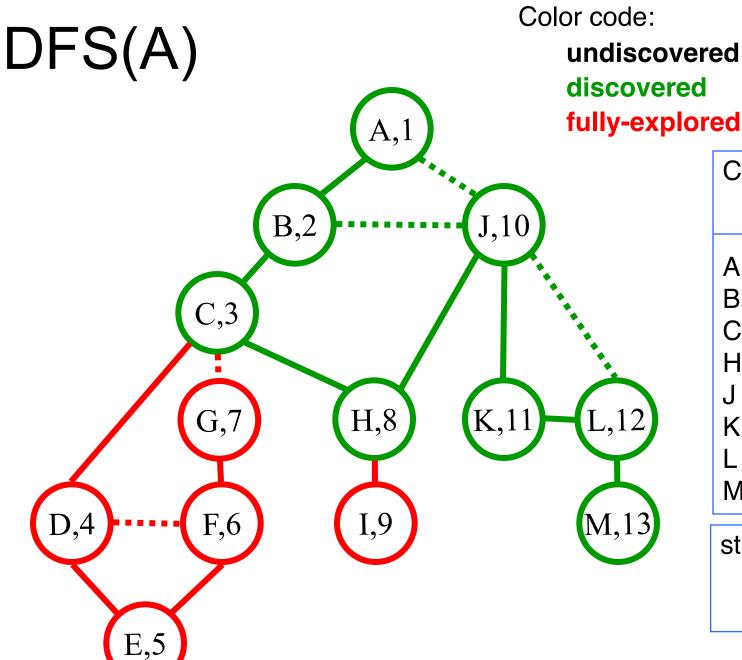
K(J,L)

st[] = {1,2,3,8,10 ,11}



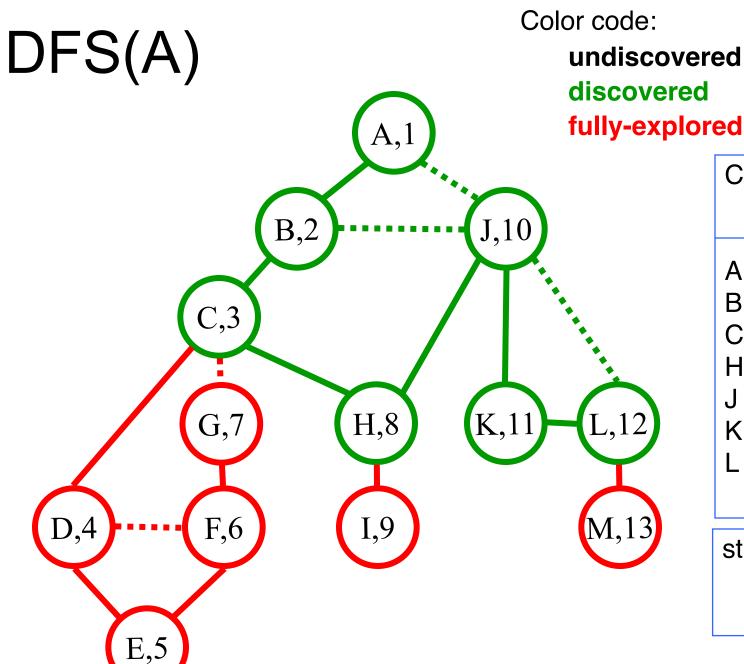
A (**B**',**J**)
B (**A**',**C**',**J**)
C (**B**',**D**',**C**',**H**')
H (**C**',**J**',**J**')
J (**A**',**B**',**H**',**K**,**L**)
K (**J**',**L**)'
L (**J**,**K**,**M**)

st[] = {1,2,3,8,10 ,11,12}



A (\$\beta, \beta, \beta

st[] = {1,2,3,8,10 ,11,12,13}



A (₱,J) B (♠,Ø,J) C (₱,₱,Ø,₩)

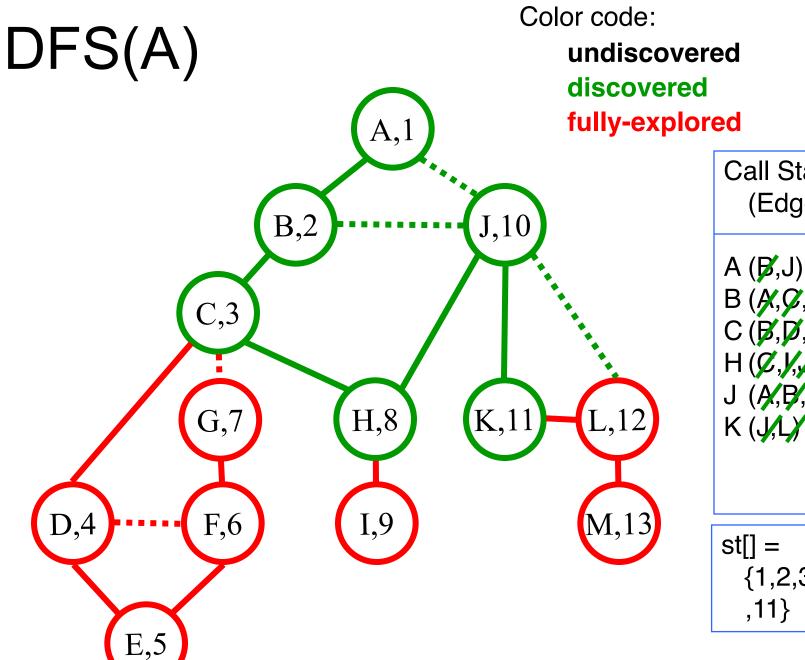
H (Ø, /, /)

J (**A**,**B**,**H**,**K**,L)

K (J,L)

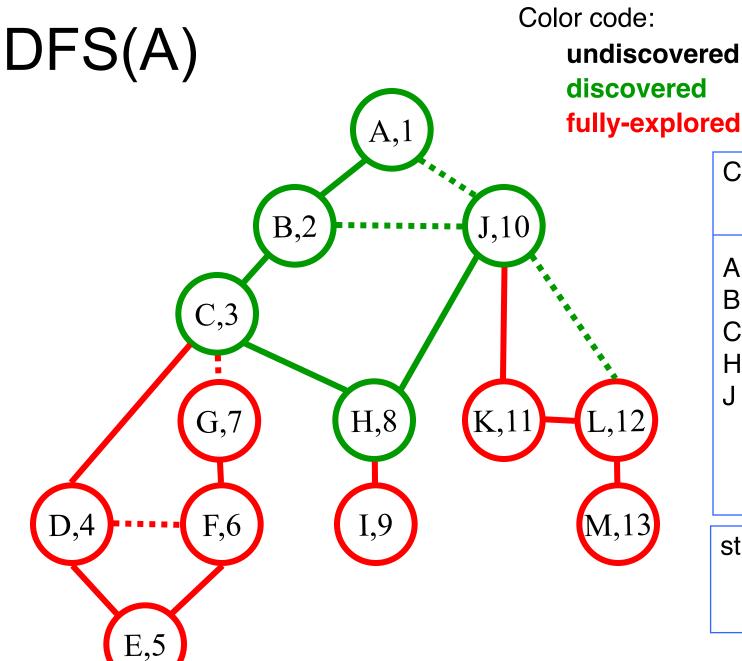
L (J,K,1)/1)

st[] = {1,2,3,8,10 ,11,12}



B (**A**,**C**,J) C (**B**,**D**,**C**,**H**) $H(\mathcal{C},\mathcal{V},\mathcal{Y})$ J(A,B,H,K,L)K (J,L)

{1,2,3,8,10

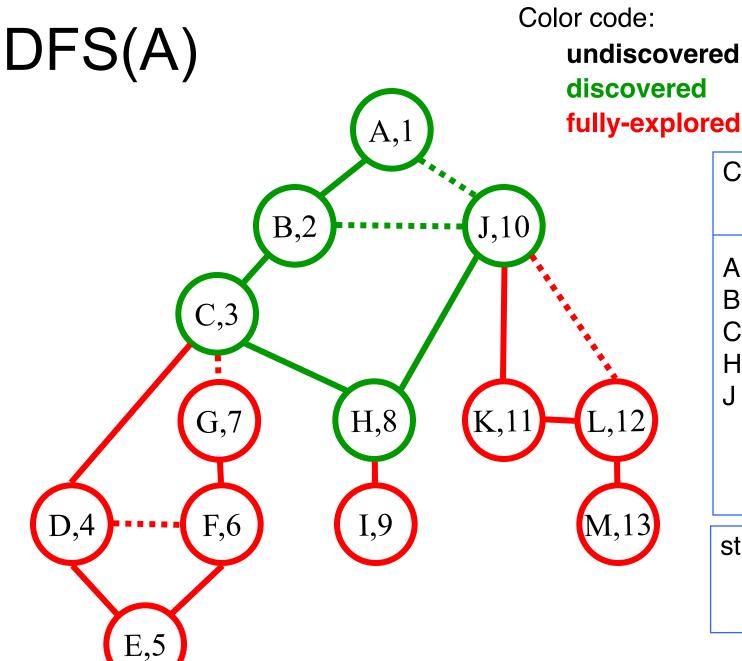


undiscovered discovered

> Call Stack: (Edge list)

A(B,J)B (**A**,**C**,**J**) C (**B**,**D**,**C**,**H**) H (Z, Y, Y) J(A,B,H,K,L)

st[] = {1,2,3,8, 10}



undiscovered discovered

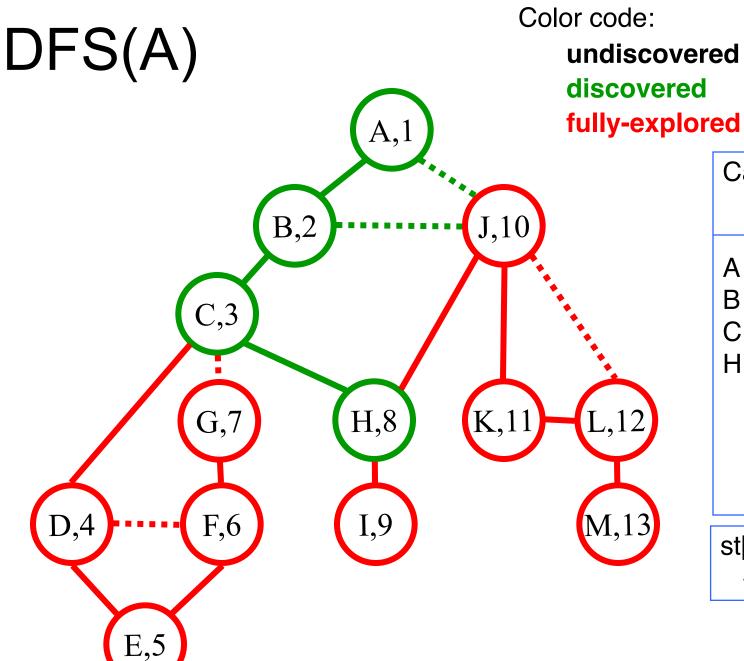
> Call Stack: (Edge list)

A(B,J)B (**A**,**C**,**J**) C (**B**,**D**,**C**,**H**)

H (Z, Y, Y)

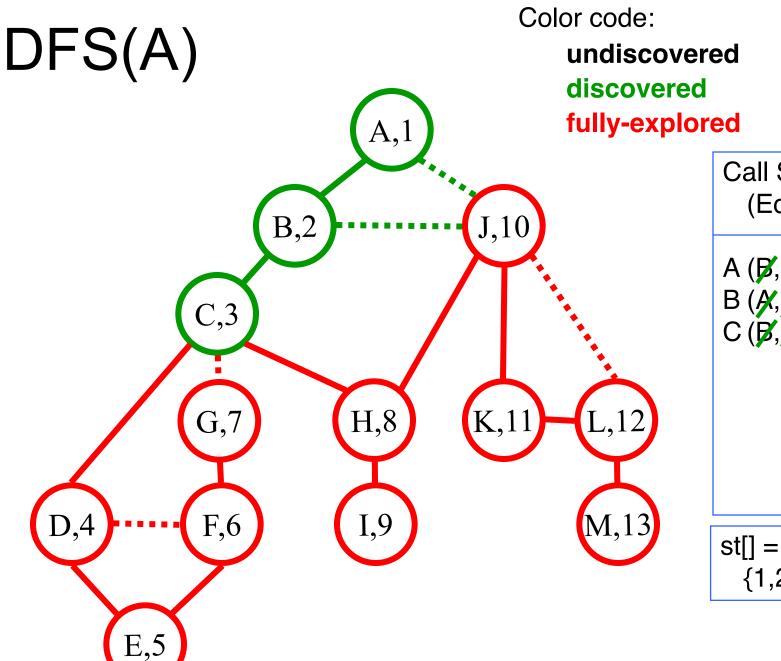
J (A,B,H,K,K)

st[] = {1,2,3,8, 10}



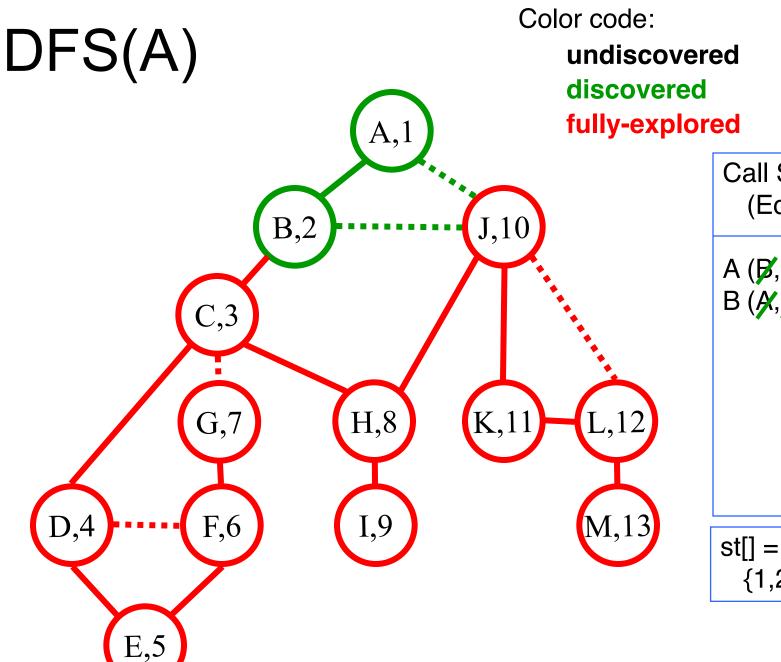
A (**B**',J) B (**A**',**C**',J) C (**B**',**D**',**C**',**H**') H (**C**',**Y**,**Y**')

 $st[] = {1,2,3,8}$



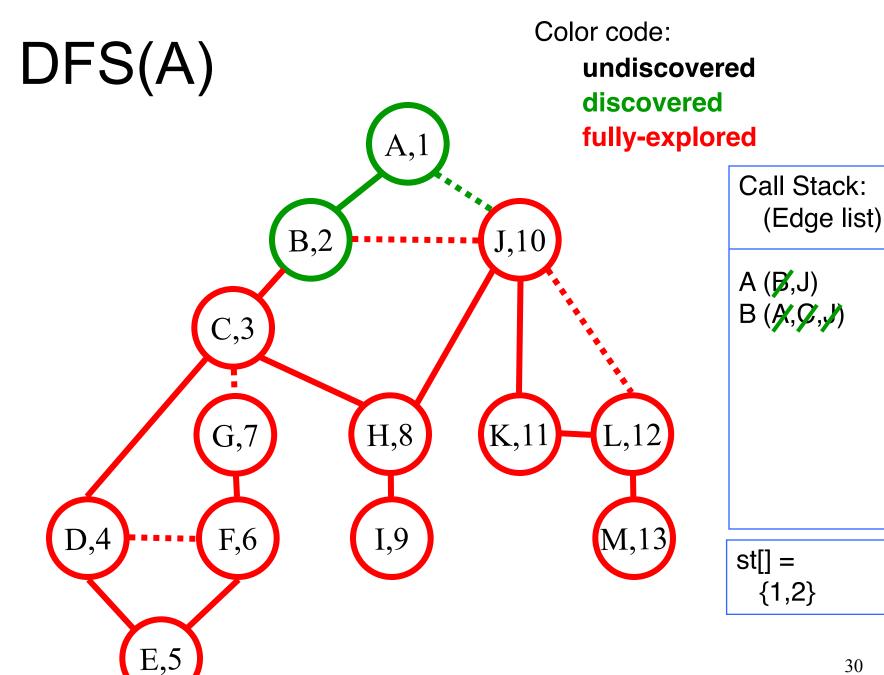
A (**B**',**J**) B (**A**',**G**',**J**) C (**B**',**D**',**G**',**H**')

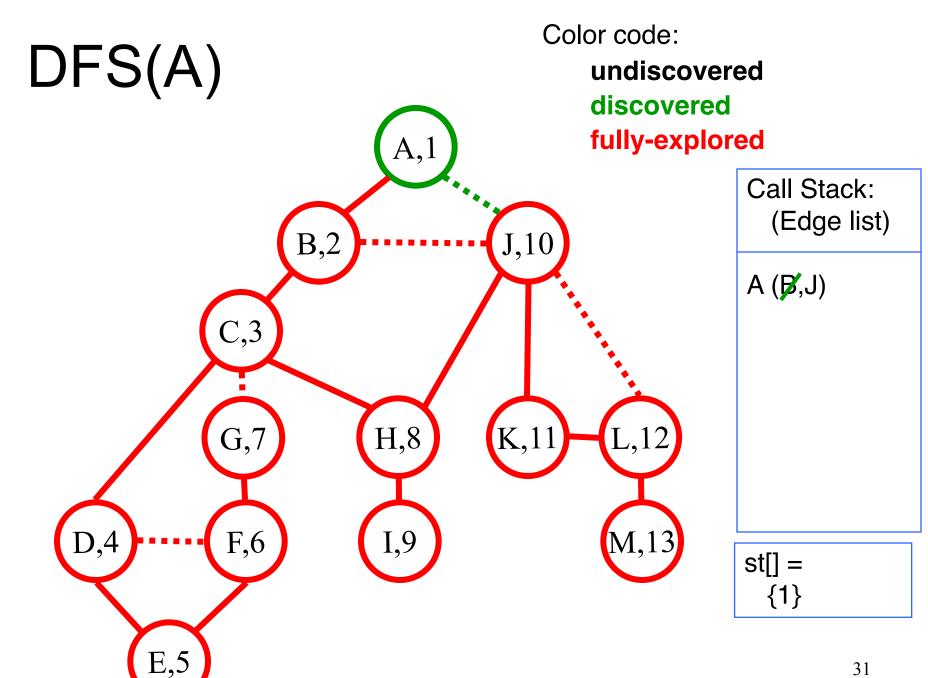
st[] = {1,2,3}

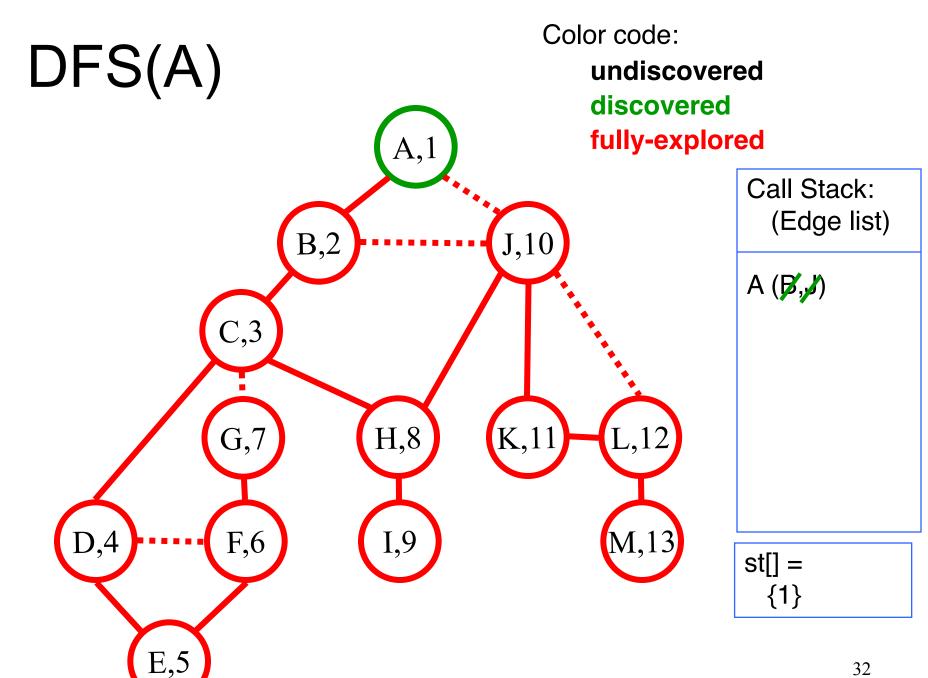


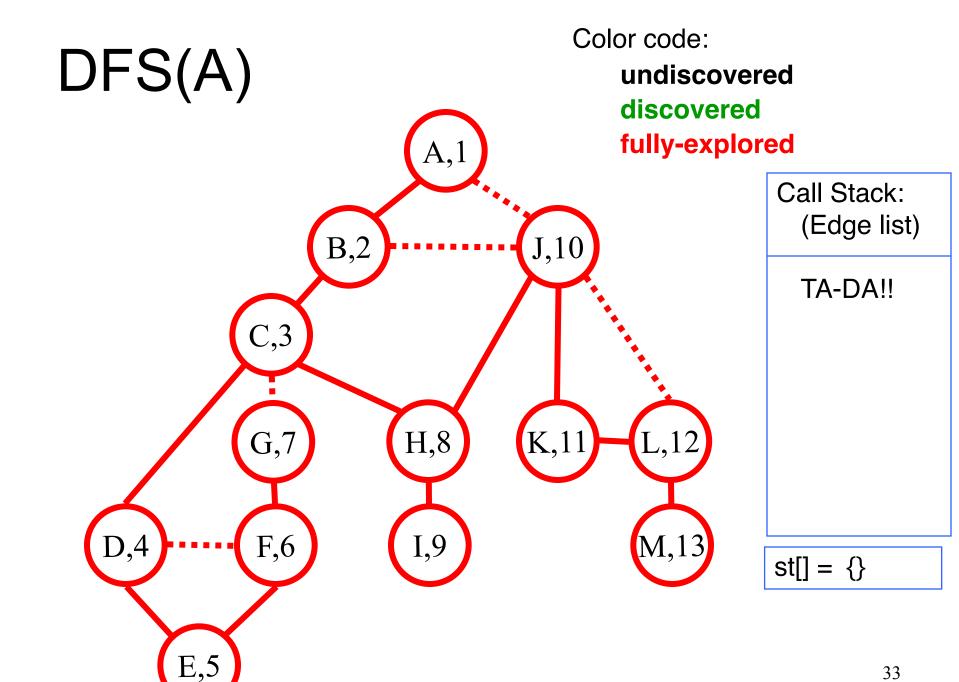
 $A(\beta,J)$ B (A,Q,J)

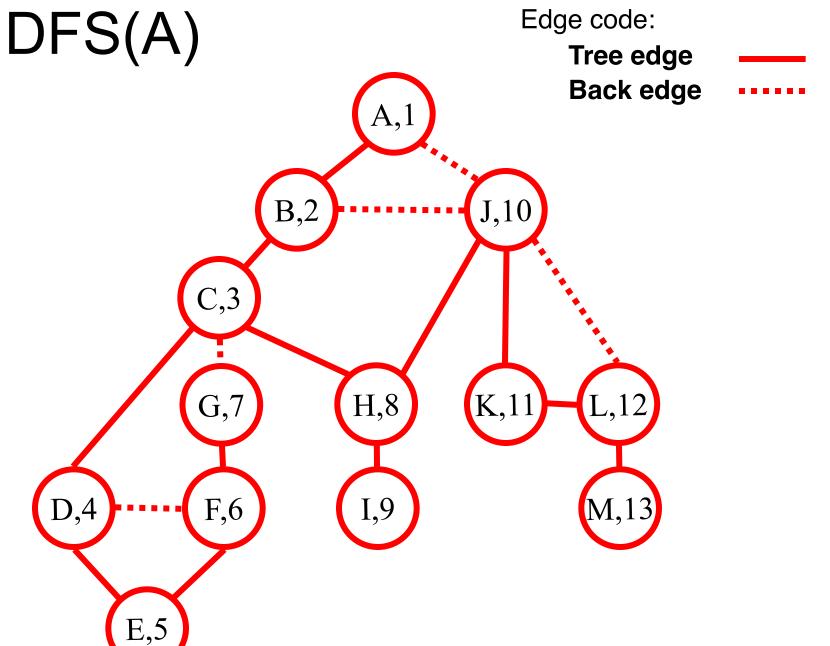
{1,2}

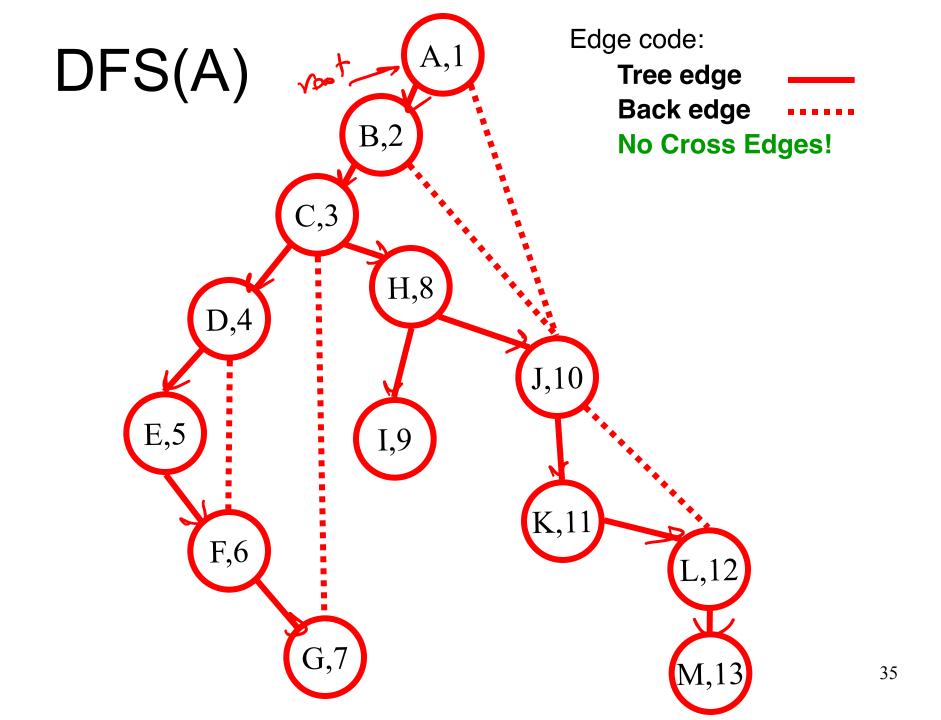












Properties of (undirected) DFS

Like BFS(s):

- DFS(s) visits x iff there is a path in G from s to x
 So, we can use DFS to find connected components
- Edges into then-undiscovered vertices define a tree the "depth first spanning tree" of G

Unlike the BFS tree:

- The DF spanning tree isn't minimum depth
- Its levels don't reflect min distance from the root
- Non-tree edges never join vertices on the same or adjacent levels

Non-Tree Edges in DFS

All non-tree edges join a vertex and one of its descendents/ancestors in the DFS tree

BFS tree ≠ DFS tree, but, as with BFS, DFS has found a tree in the graph s.t. non-tree edges are "simple" – only

descendant/ancestor

Non-Tree Edges in DFS

Obs: During DFS(x) every vertex marked visited is a descendant of x in the DFS tree

Lemma: For every edge $\{x, y\}$, if $\{x, y\}$ is not in DFS tree, then one of x or y is an ancestor of the other in the tree.

Proof:

One of x or y is visited first, suppose WLOG that x is visited first and therefore DFS(x) was called before DFS(y)

Since $\{x, y\}$ is not in DFS tree, y was visited when the edge $\{x,y\}$ was examined during DFS(x)

Therefore y was visited during the call to DFS(x) so y is a descendant of x.

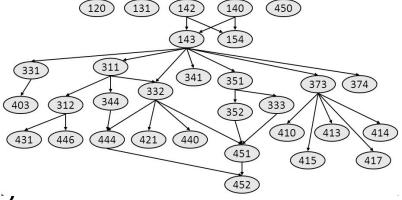
DAGs and Topological Ordering

Precedence Constraints

In a directed graph, an edge (i, j) means task i must occur before task j.

Applications

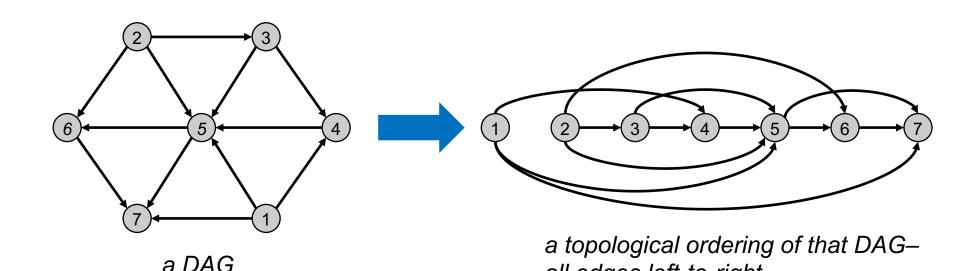
- Course prerequisite:
 course i must be taken before j
- Compilation:
 must compile module i before.
- Computing overflow:
 output of job i is part of input to job j
- Manufacturing or assembly: sand it before paint it



Directed Acyclic Graphs (DAG)

A DAG is a directed acyclic graph, i.e., one that contains no directed cycles.

Def: A topological order of a directed graph G = (V, E) is an ordering of its nodes as $v_1, v_2, ..., v_n$ so that for every edge (v_i, v_j) we have i < j.



all edges left-to-right

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DAGs: A Sufficient Condition

Lemma: If G has a topological order, then G is a DAG.

Pf. (by contradiction)

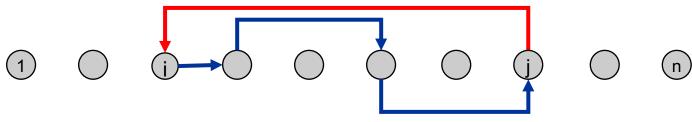
Suppose that G has a topological order 1,2,...,n and that G also has a directed cycle C.

Let i be the lowest-indexed node in C, and let j be the node just before i; thus (j, i) is an (directed) edge.

By our choice of i, we have i < j.

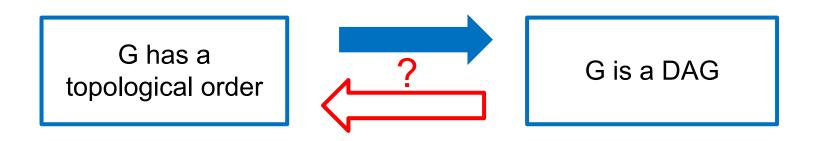
On the other hand, since (j, i) is an edge and 1, ..., n is a topological order, we must have j < i, a contradiction





the supposed topological order: 1,2,...,n

DAGs: A Sufficient Condition



Every DAG has a source node

Lemma: If G is a DAG, then G has a node with no incoming edges (i.e., a source).

Pf. (by contradiction)

Suppose that G is a DAG and and it has no source

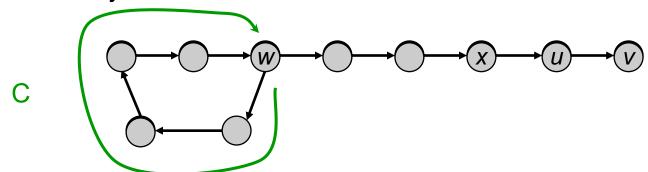
Pick any node v, and begin following edges backward from v. Since v has at least one incoming edge (u, v) we can walk backward to u.

Then, since u has at least one incoming edge (x, u), we can walk backward to x.

Is this similar to a

Repeat until we visit a node, say w, twice.

Let C be the sequence of nodes encountered between successive visits to w. C is a cycle.



previous proof?

DAG => Topological Order

Lemma: If G is a DAG, then G has a topological order

Pf. (by induction on n)

Base case: true if n = 1.

IH: Every DAG with n-1 vertices has a topological ordering.

IS: Given DAG with n > 1 nodes, find a source node v.

 $G - \{v\}$ is a DAG, since deleting v cannot create cycles.

Reminder: Always remove vertices/edges to use IH

By IH, $G - \{v\}$ has a topological ordering.

Place v first in topological ordering; then append nodes of G - { v } in topological order. This is valid since v has no incoming edges.

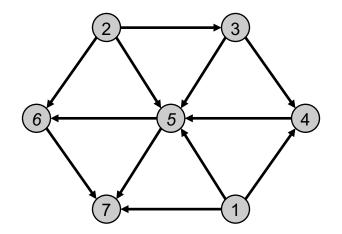
A Characterization of DAGs

G has a topological order

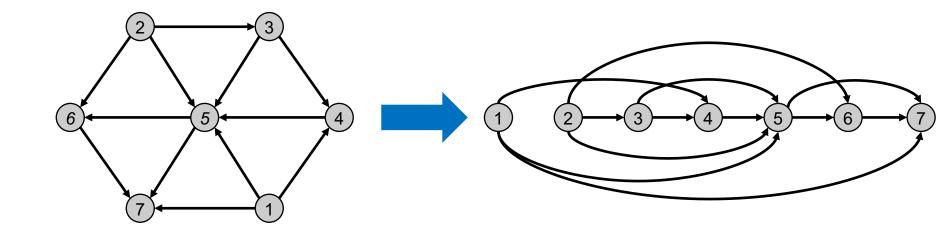


G is a DAG

Topological Order Algorithm: Example



Topological Order Algorithm: Example



Topological order: 1, 2, 3, 4, 5, 6, 7

Topological Sorting Algorithm

Maintain the following:

```
count[w] = (remaining) number of incoming edges to node w
S = set of (remaining) nodes with no incoming edges
```

Initialization:

```
count[w] = 0 for all w
count[w]++ for all edges (v,w) O(m + n)
```

Main loop:

while S not empty

- remove some v from S
- make v next in topo order
 O(1) per node
- for all edges from v to some w
 O(1) per edge
 - -decrement count[w]
 - -add w to S if count[w] hits 0

 $S = S \cup \{w\}$ for all w with count[w]=0

Correctness: clear, I hope

Time: O(m + n) (assuming edge-list representation of graph)

Summary

- Graphs: abstract relationships among pairs of objects
- Terminology: node/vertex/vertices, edges, paths, multi-edges, self-loops, connected
- Representation: Adjacency list, adjacency matrix
- Nodes vs Edges: $m = O(n^2)$, often less
- BFS: Layers, queue, shortest paths, all edges go to same or adjacent layer
- DFS: recursion/stack; all edges ancestor/descendant
- Algorithms: Connected Comp, bipartiteness, topological sort