

# **CSE 421: Introduction to Algorithms**



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## **Lecture 6**

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# Generic Graph Traversal Algorithm

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**Find:** set **R** of vertices reachable from  **$s \in V$**

Reachable(**s**):

**$R \leftarrow \{s\}$**

While there is a  **$(u,v) \in E$**  where  **$u \in R$**  and  **$v \notin R$**

    Add **v** to **R**

Return **R**



# Graph Traversal

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- Learn the basic structure of a graph
- Walk from a fixed starting vertex **s** to find all vertices reachable from **s**
  
- Three states of vertices
  - **unvisited**
  - **visited/discovered** (in **R**)
  - **fully-explored** (in **R** and all neighbors in **R**)



# Last time: Breadth-First Search

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- Completely explore the vertices in order of their distance from **s**
  
- Naturally implemented using a queue



# BFS(s)

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Global initialization: mark all vertices “unvisited”

BFS(s)

mark **s** “visited”;  $\mathbf{R} \leftarrow \{\mathbf{s}\}$ ; layer  $\mathbf{L}_0 \leftarrow \{\mathbf{s}\}$

while  $\mathbf{L}_i$  not empty

$\mathbf{L}_{i+1} \leftarrow \emptyset$

For each  $\mathbf{u} \in \mathbf{L}_i$

for each edge  $\{\mathbf{u}, \mathbf{v}\}$

if ( $\mathbf{v}$  is “unvisited”)

mark  $\mathbf{v}$  “visited”

Add  $\mathbf{v}$  to set  $\mathbf{R}$  and to layer  $\mathbf{L}_{i+1}$

mark  $\mathbf{u}$  “fully-explored”

$\mathbf{i} \leftarrow \mathbf{i}+1$



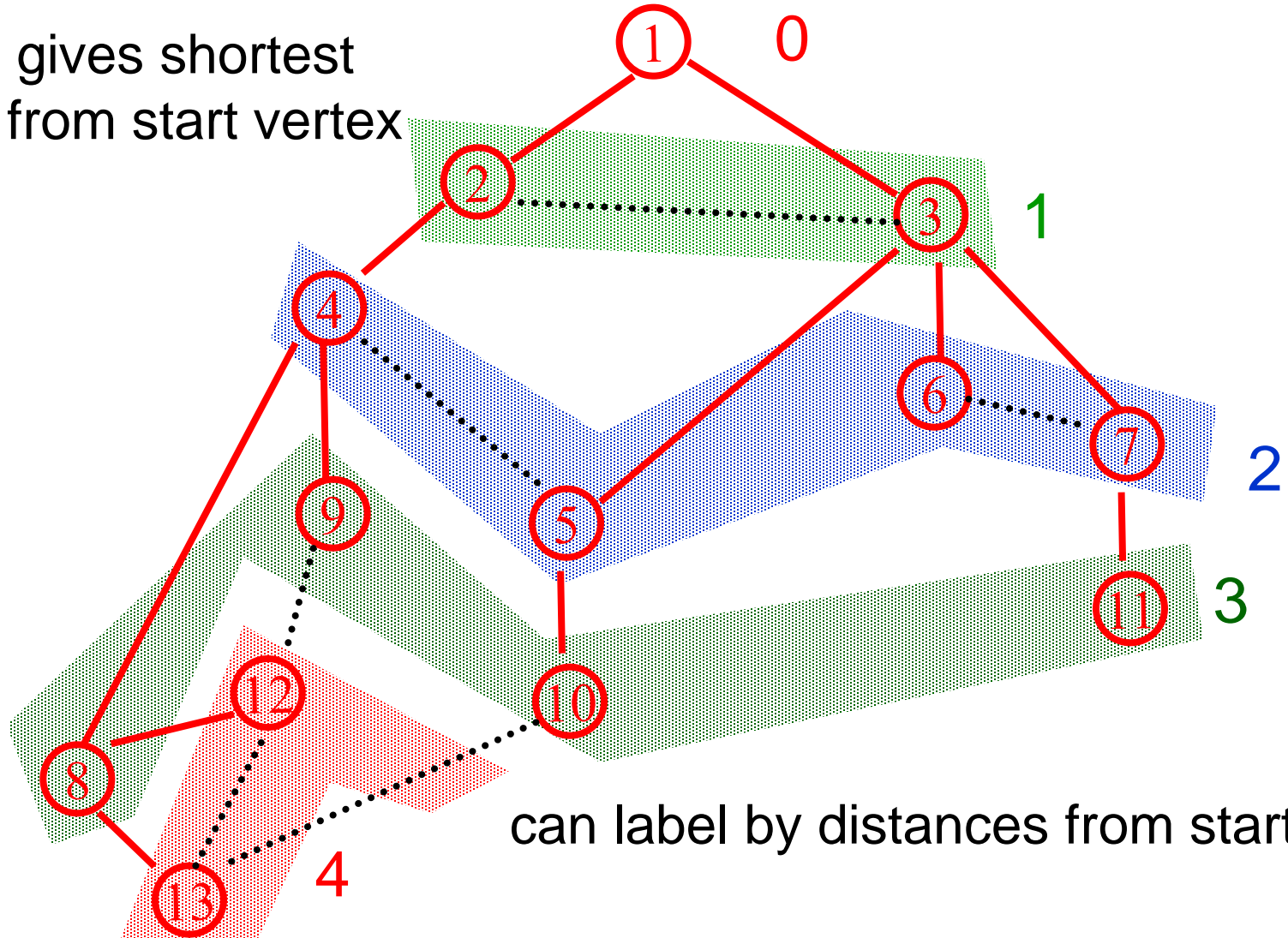
# Properties of BFS

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- BFS tree:
  - The rooted tree of edges followed when the BFS algorithm first discovers each vertex
  - Tree for BFS(**s**) gives the shortest paths (in # of hops) from **s** to each vertex reachable from **s**.
- On undirected graphs
  - All non-tree BFS edges join vertices on the same or adjacent layers

# BFS Application: Shortest Paths

Tree gives shortest paths from start vertex





# BFS gives Bipartiteness

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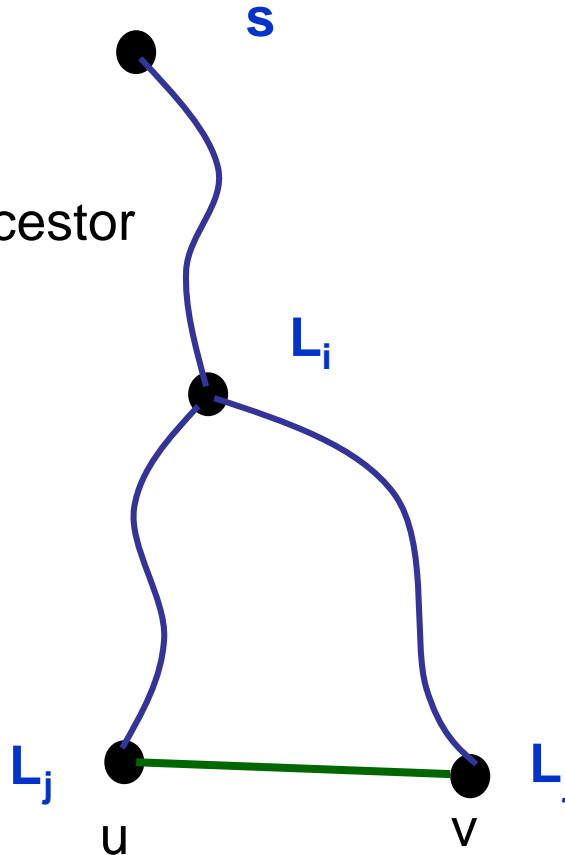
- Run BFS assigning all vertices from layer  $L_i$  the color  $i \bmod 2$ 
  - i.e. **red** if they are in an even layer, **blue** if in an odd layer
- If there is an edge joining two vertices  $u$  and  $v$  from the same layer then output “Not Bipartite”



# Why does it work?

$u$  and  $v$  have a common ancestor

Cycle length  $2(j-i)+1$



# Graph Search Application: Connected Components

- Want to answer questions of the form:
  - **Given:** vertices  $u$  and  $v$  in  $G$
  - Is there a path from  $u$  to  $v$ ?
- **Idea:** create array  $A$  such that
  - $A[u]$  = smallest numbered vertex that is connected to  $u$
  - question reduces to whether  $A[u]=A[v]$ ?

Q: Why not create an array  $Path[u,v]$ ?

# Graph Search Application: Connected Components

- initial state: all  $v$  unvisited  
for  $s \leftarrow 1$  to  $n$  do
  - if  $\text{state}(s) \neq \text{"fully-explored"}$  then
    - BFS( $s$ ): setting  $A[u] \leftarrow s$  for each  $u$  found  
(and marking  $u$  visited/fully-explored)endif  
endfor
- Total cost:  **$O(n+m)$** 
  - each vertex is touched once in this outer procedure and the edges examined in the different BFS runs are disjoint
  - works also with "Depth First Search"



# DFS(**u**) – Recursive version

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Global Initialization: mark all vertices "unvisited"

DFS(**u**)

mark **u** "visited" and add **u** to **R**

for each edge {**u**,**v**}

if (**v** is "unvisited")

DFS(**v**)

end for

mark **u** "fully-explored"



# Properties of DFS(s)

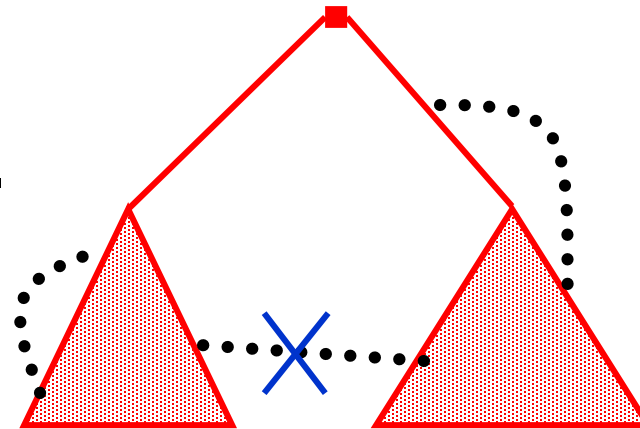
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- Like BFS(s):
  - DFS(s) visits  $x$  if and only if there is a path in  $G$  from  $s$  to  $x$
  - Edges into undiscovered vertices define a "depth first spanning tree" of  $G$
- Unlike the BFS tree:
  - the DFS spanning tree isn't minimum depth
  - its levels don't reflect min distance from the root
  - non-tree edges never join vertices on the same or adjacent levels
- BUT...

# Non-tree edges

- All non-tree edges join a vertex and one of its descendants/ancestors in the DFS tree

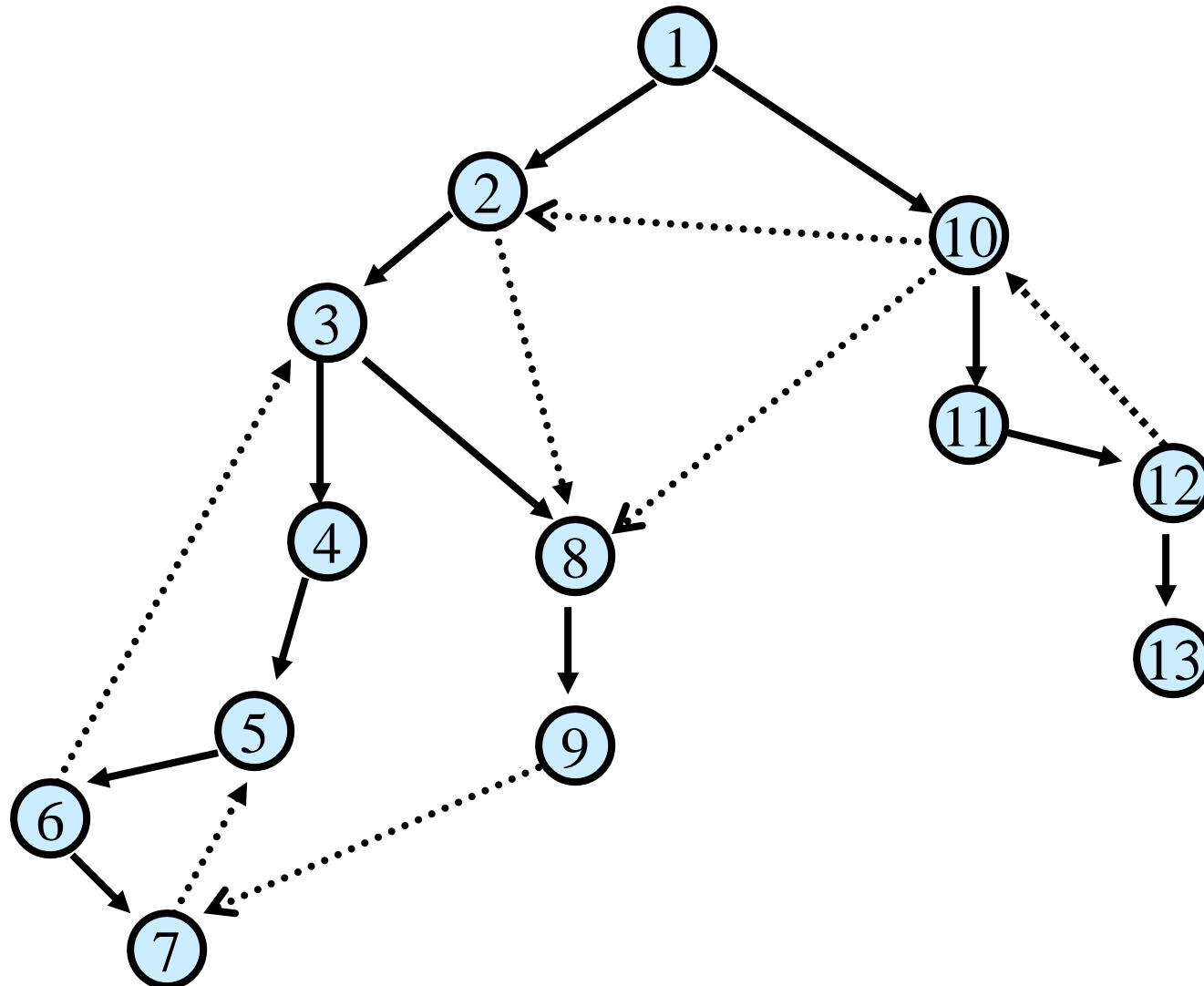
- No cross edges.



# No cross edges in DFS on undirected graphs

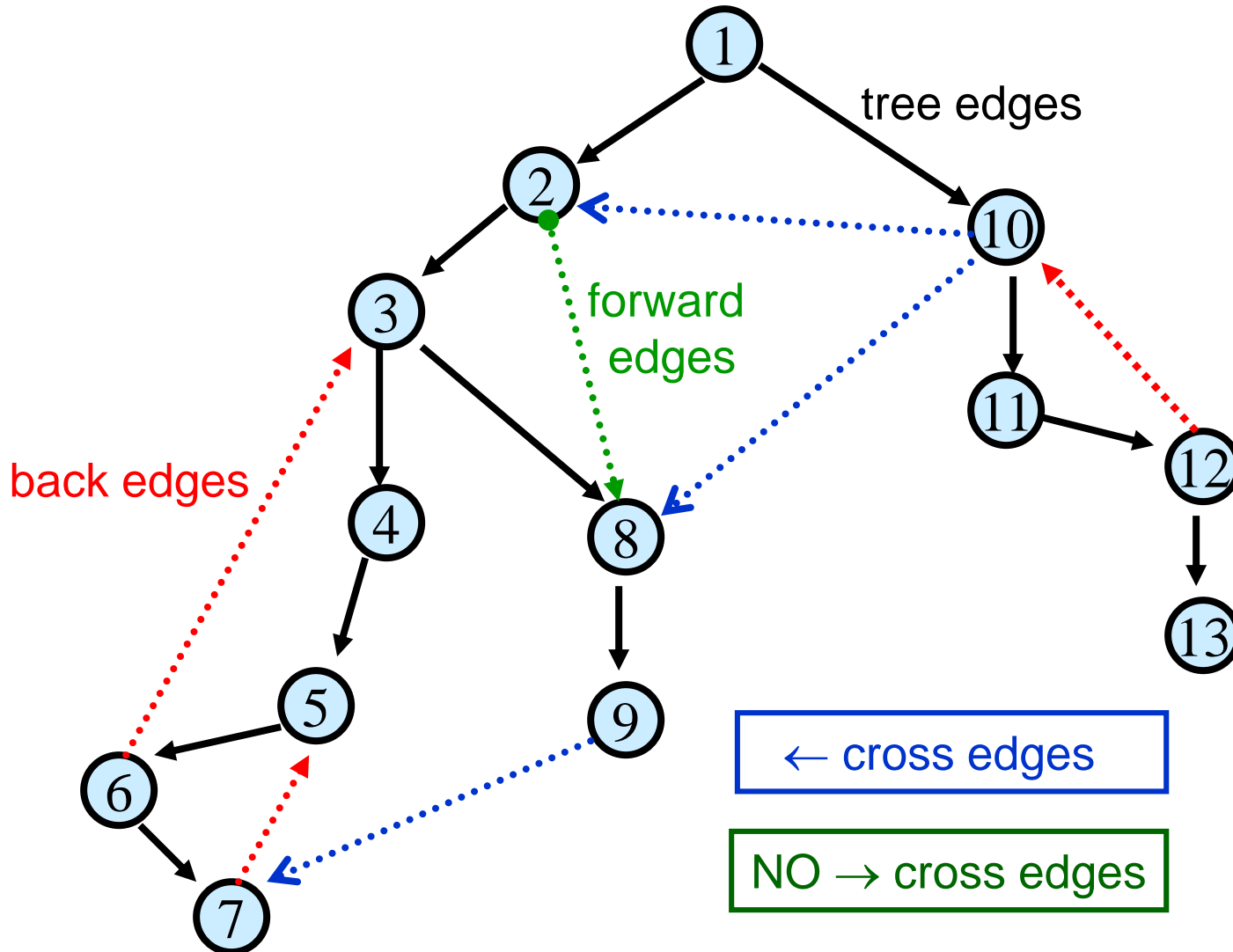
- **Claim:** During **DFS(x)** every vertex marked visited is a descendant of **x** in the DFS tree **T**
- **Claim:** For every **x,y** in the DFS tree **T**, if **(x,y)** is an edge not in **T** then one of **x** or **y** is an ancestor of the other in **T**
- **Proof:**
  - One of **x** or **y** is visited first, suppose WLOG that **x** is visited first and therefore **DFS(x)** was called before **DFS(y)**
    - During **DFS(x)**, the edge **(x,y)** is examined
  - Since **(x,y)** is not an edge of **T**, **y** was visited when the edge **(x,y)** was examined during **DFS(x)**
  - Therefore **y** was visited during the call to **DFS(x)** so **y** is a descendant of **x**.

# DFS(v) for a directed graph





# DFS(v)



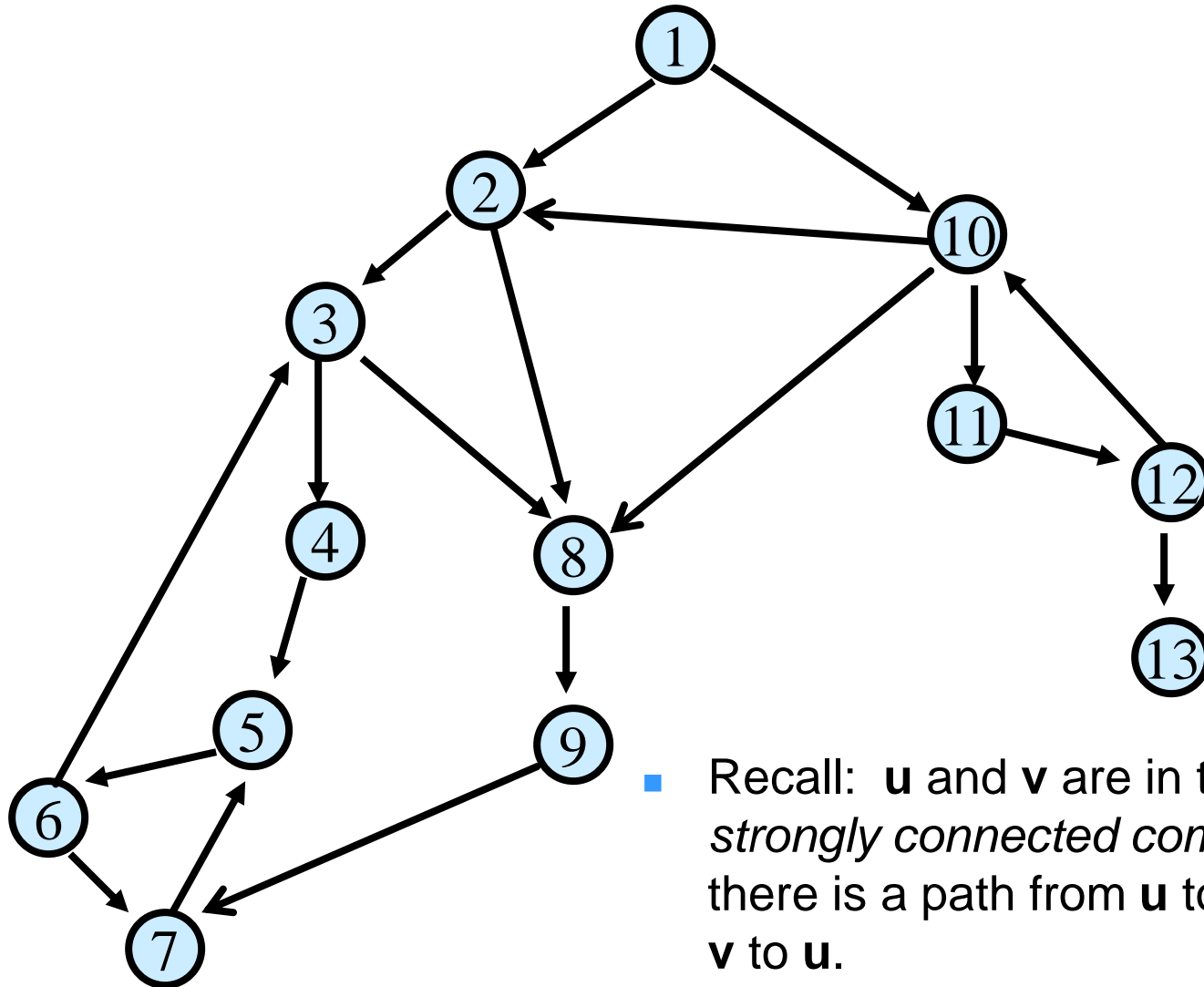


# Properties of Directed DFS

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- Before  $DFS(s)$  returns, it visits all previously unvisited vertices reachable via directed paths from  $s$
- Every cycle contains a back edge in the DFS tree

# Identify the Strongly Connected Components



- Recall:  $u$  and  $v$  are in the same *strongly connected component* iff there is a path from  $u$  to  $v$  and from  $v$  to  $u$ .

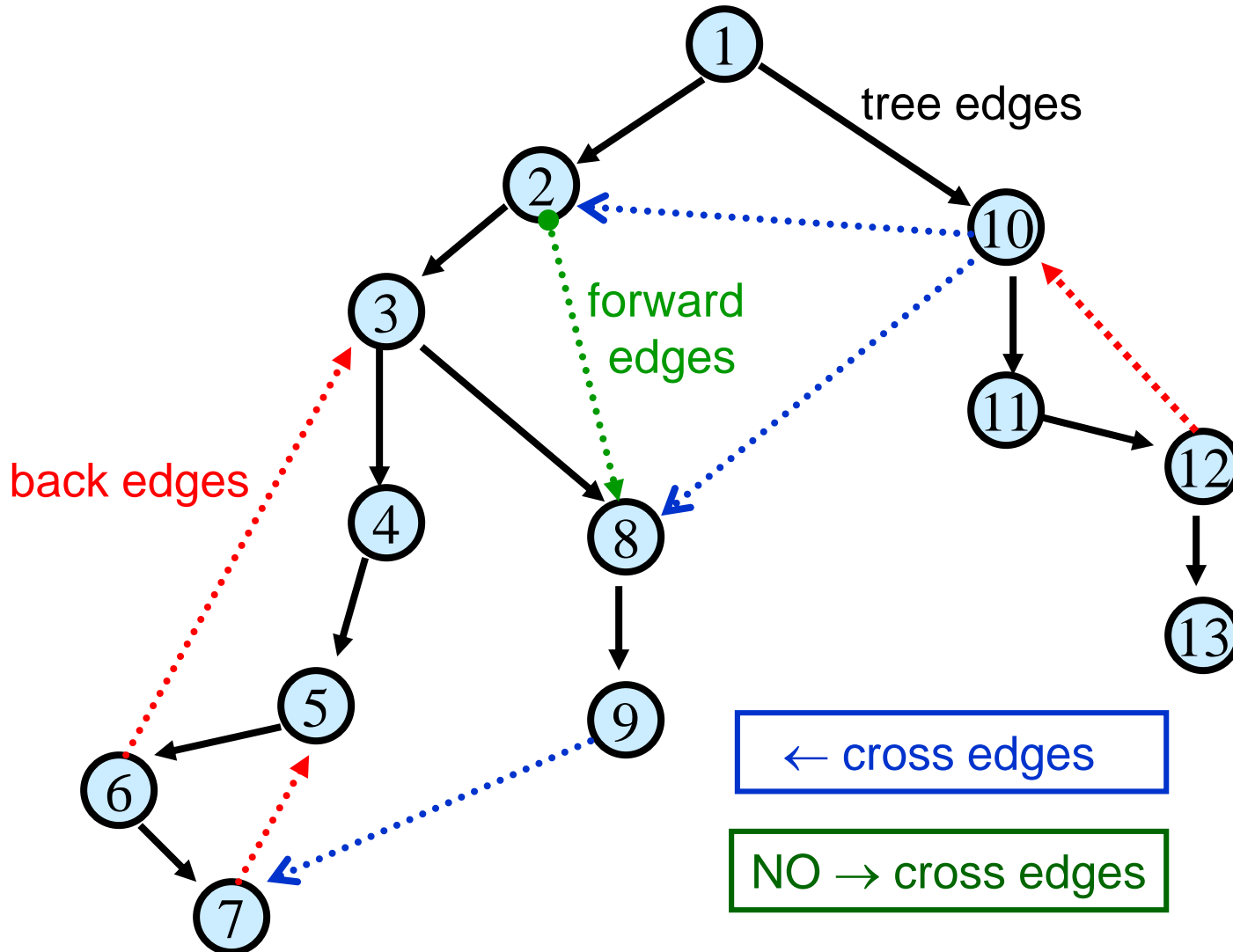


# Strongly connected components can be found in $O(n+m)$ time

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- But it's tricky!
- Simpler problem: given a vertex  $v$ , compute the vertices in  $v$ 's scc in  $O(n+m)$  time

# Strongly Connected Components





# Directed Acyclic Graphs

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- A directed graph  $G=(V,E)$  is **acyclic** if it has no directed cycles
- **Terminology:** A **directed acyclic graph** is also called a **DAG**

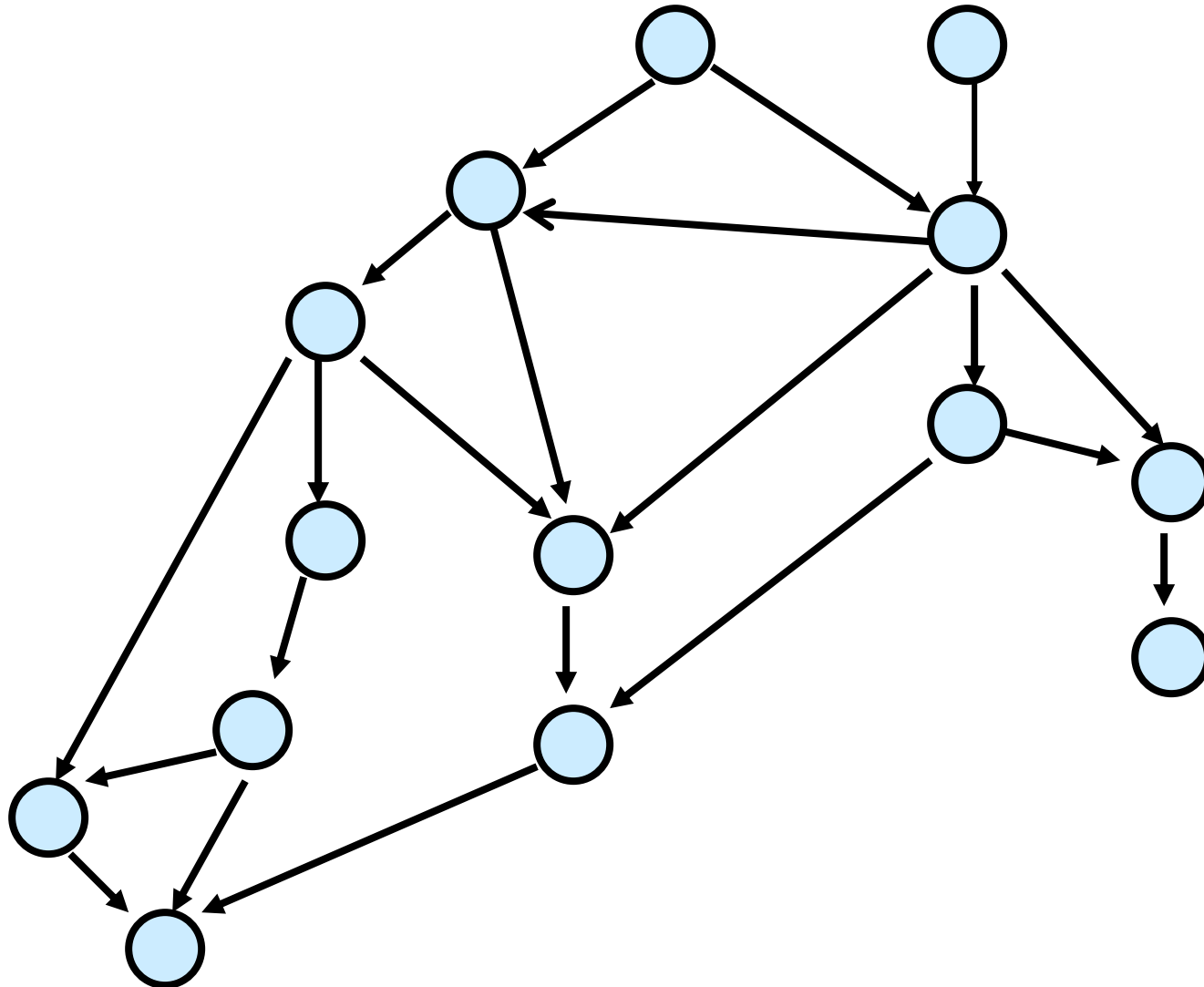


# Topological Sort

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- **Given:** a directed acyclic graph (DAG)  $G=(V,E)$
- **Output:** numbering of the vertices of  $G$  with distinct numbers from 1 to  $n$  so edges only go from lower number to higher numbered vertices
- Applications
  - nodes represent tasks
  - edges represent precedence between tasks
  - topological sort gives a sequential schedule for solving them

# Directed Acyclic Graph







# In-degree 0 vertices

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- Every DAG has a vertex of in-degree 0
- **Proof:** By contradiction
  - Suppose every vertex has some incoming edge
  - Consider following procedure:
    - while (true) do
      - $v \leftarrow$  some predecessor of  $v$
  - After  $n+1$  steps where  $n=|V|$  there will be a repeated vertex
    - This yields a cycle, contradicting that it is a DAG

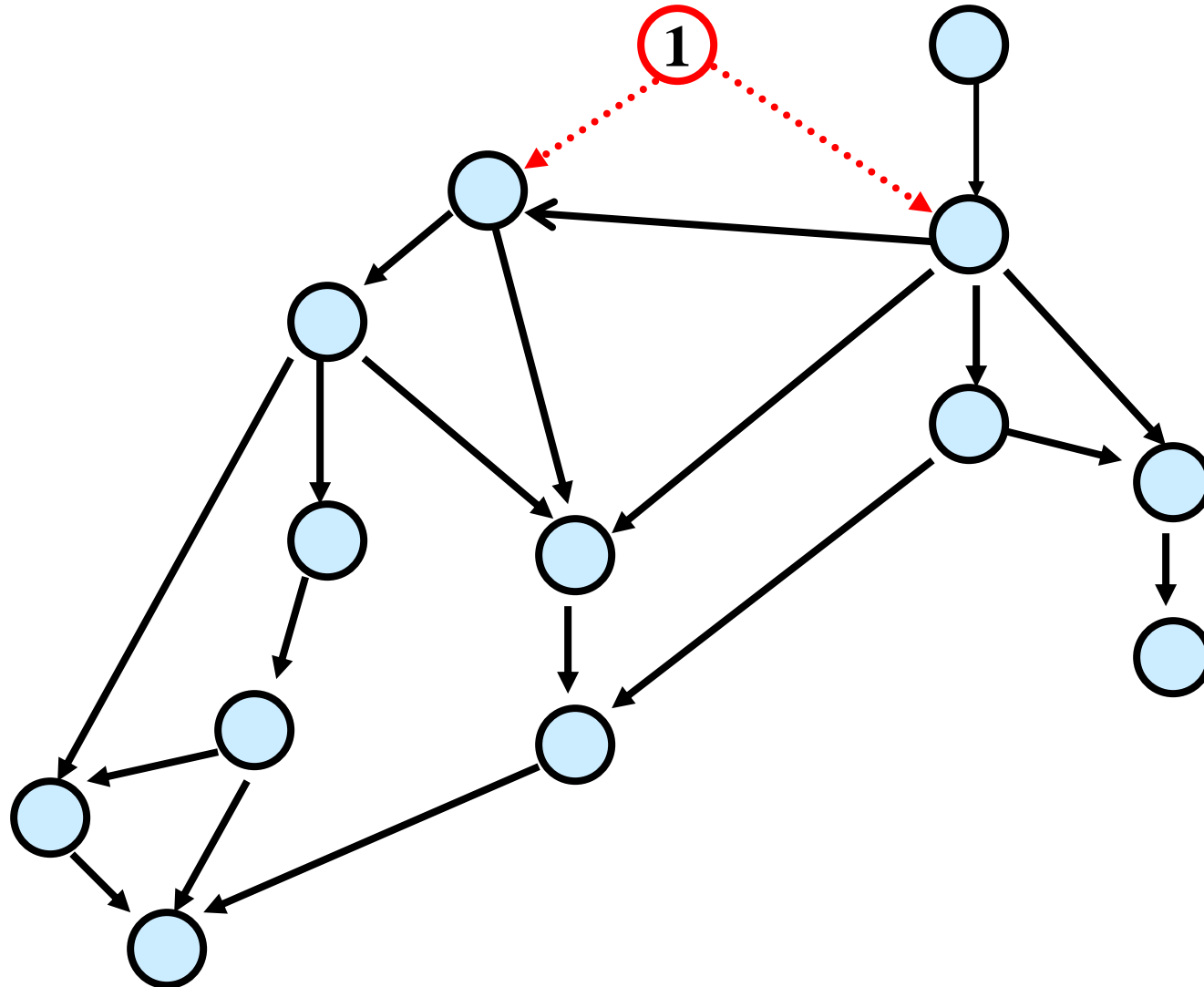


# Topological Sort

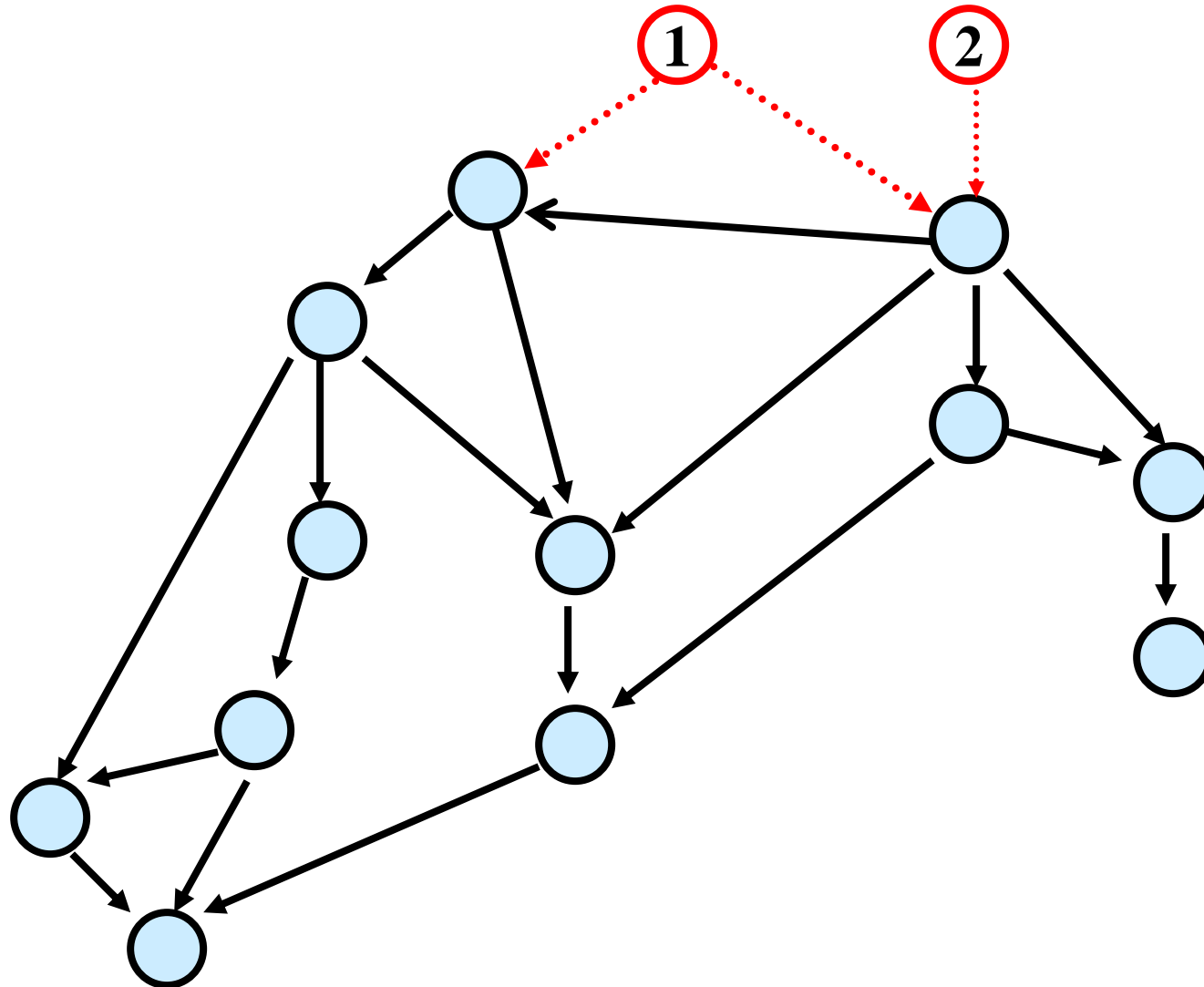
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- Can do using DFS
- Alternative simpler idea:
  - Any vertex of in-degree 0 can be given number 1 to start
  - Remove it from the graph and then give a vertex of in-degree 0 number 2, etc.

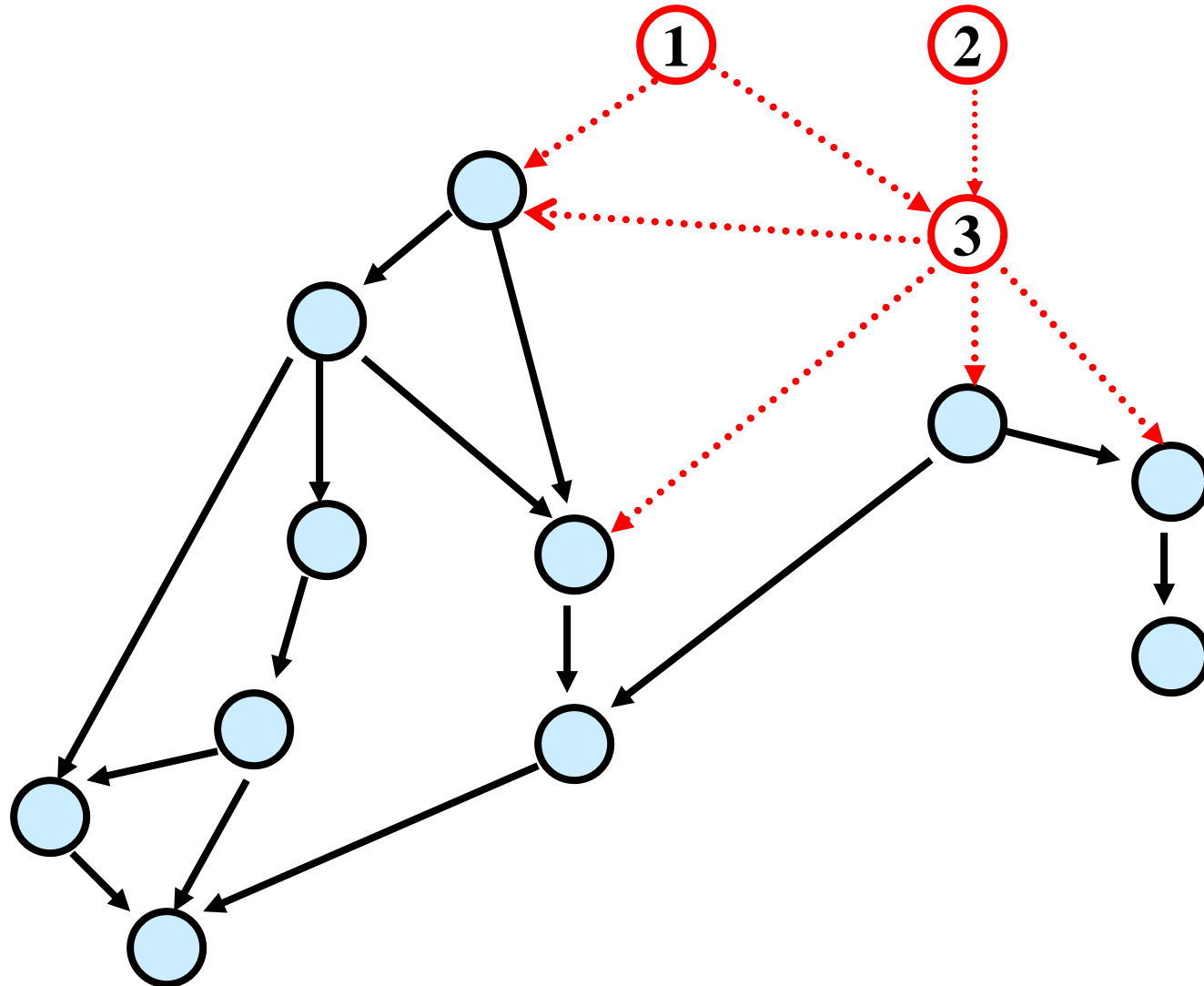
# Topological Sort



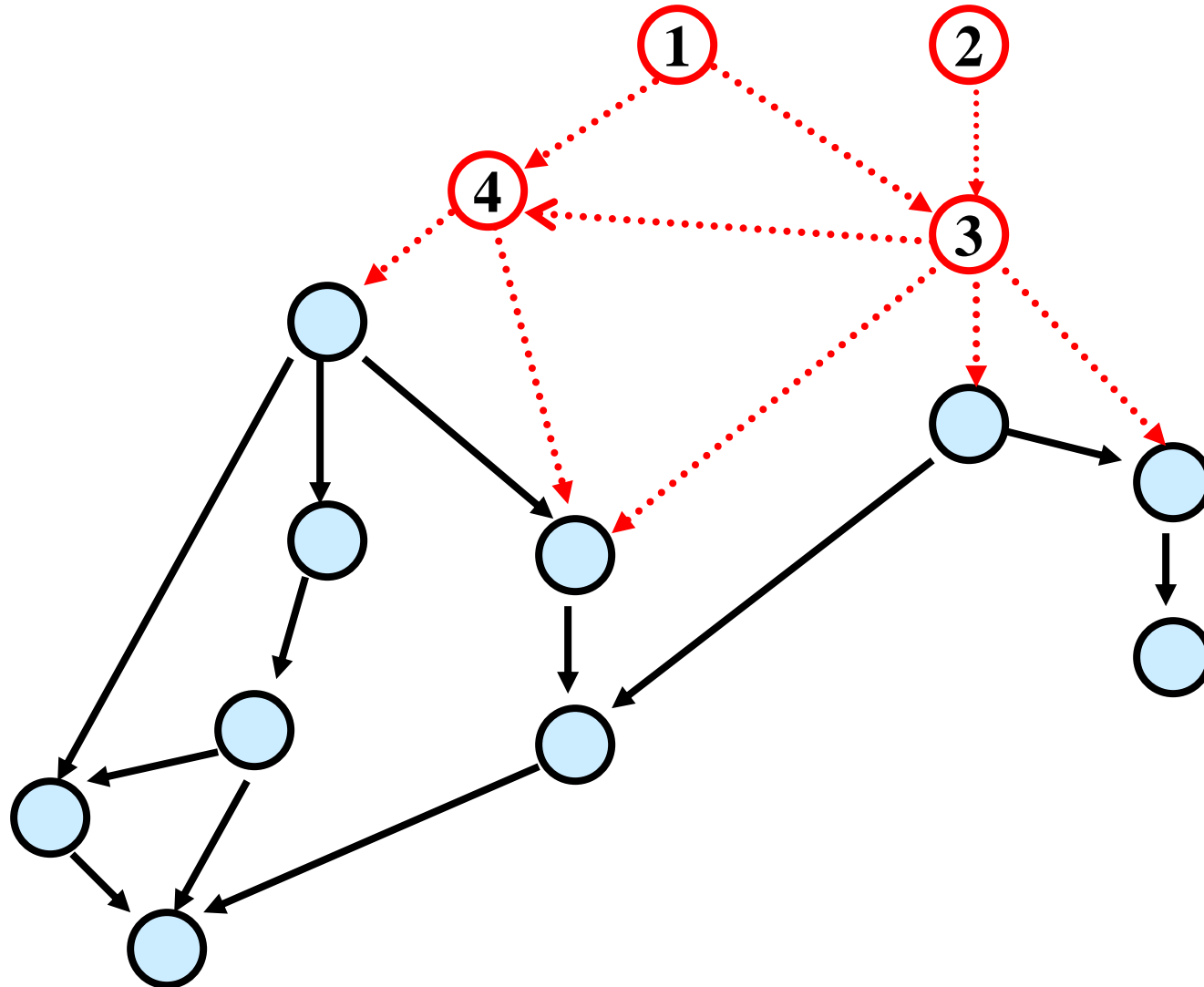
# Topological Sort



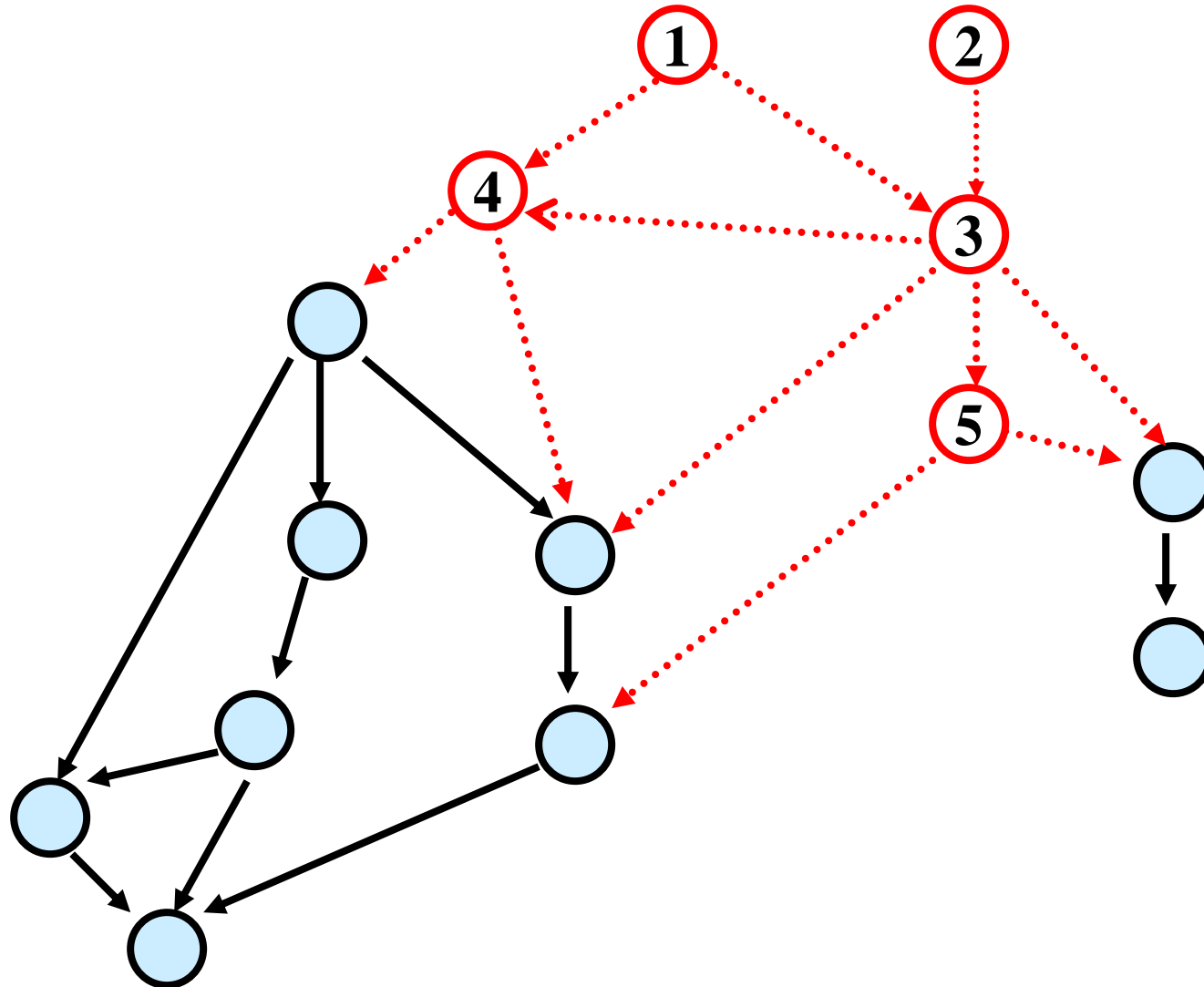
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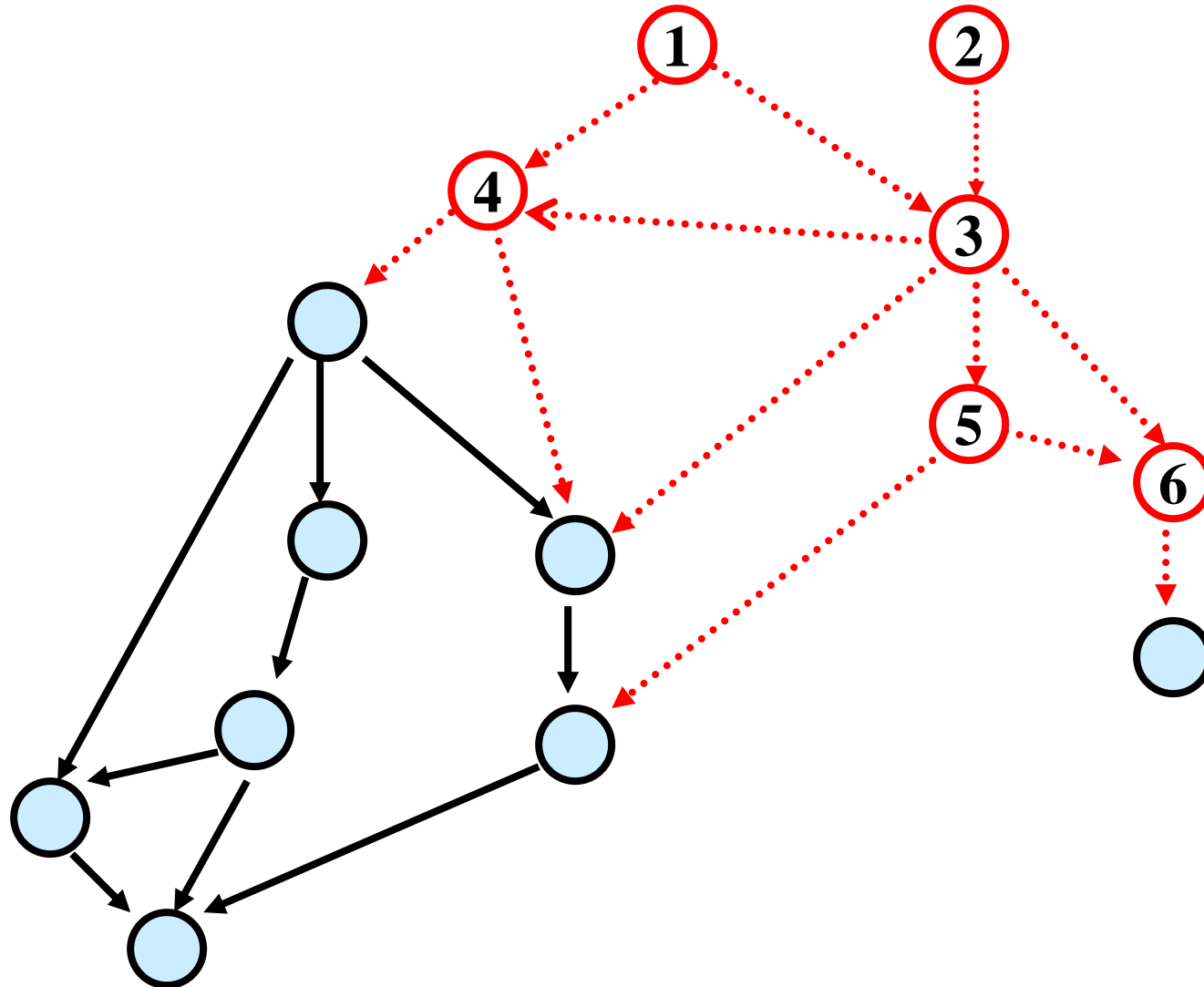
# Topological Sort



# Topological Sort

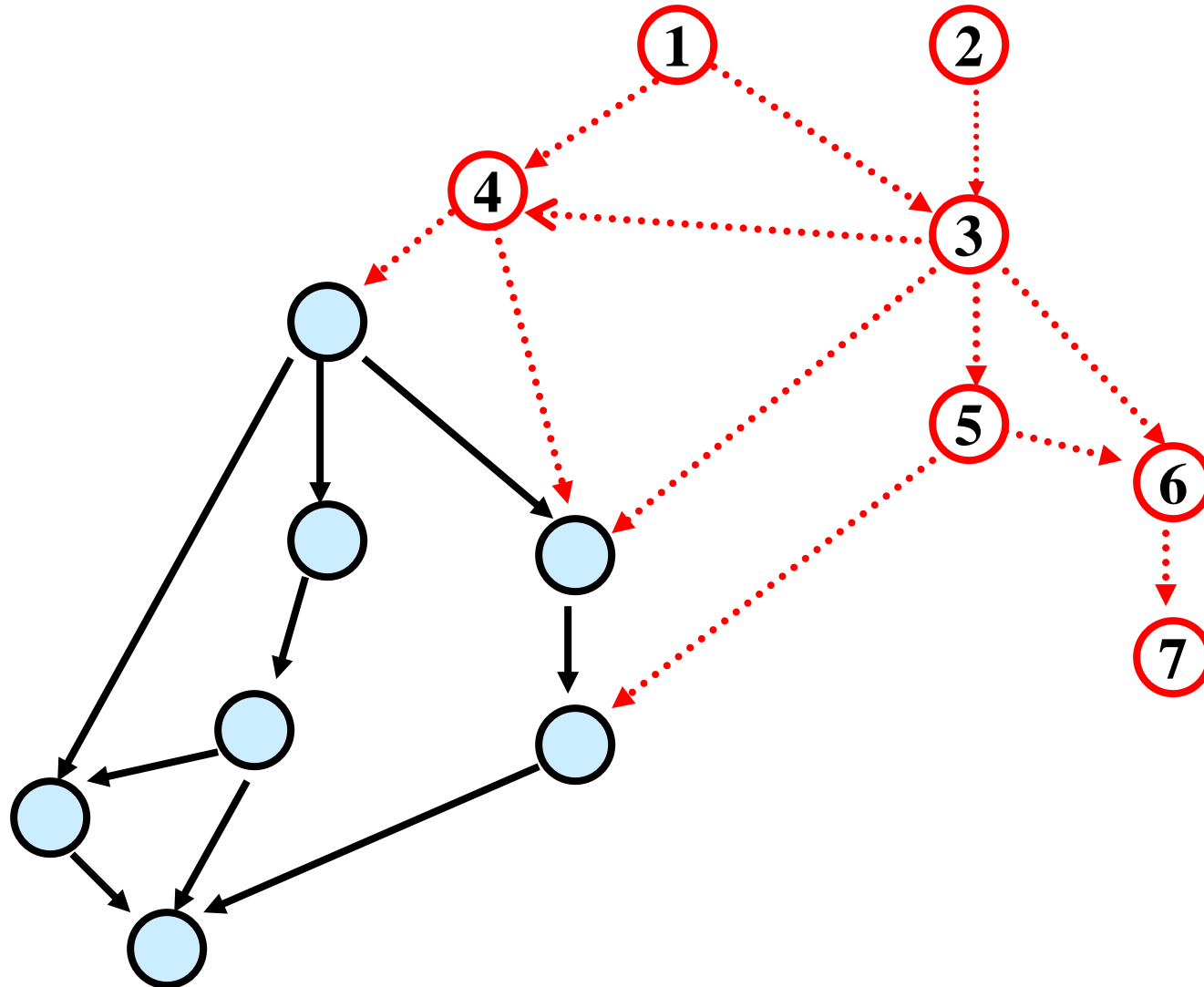


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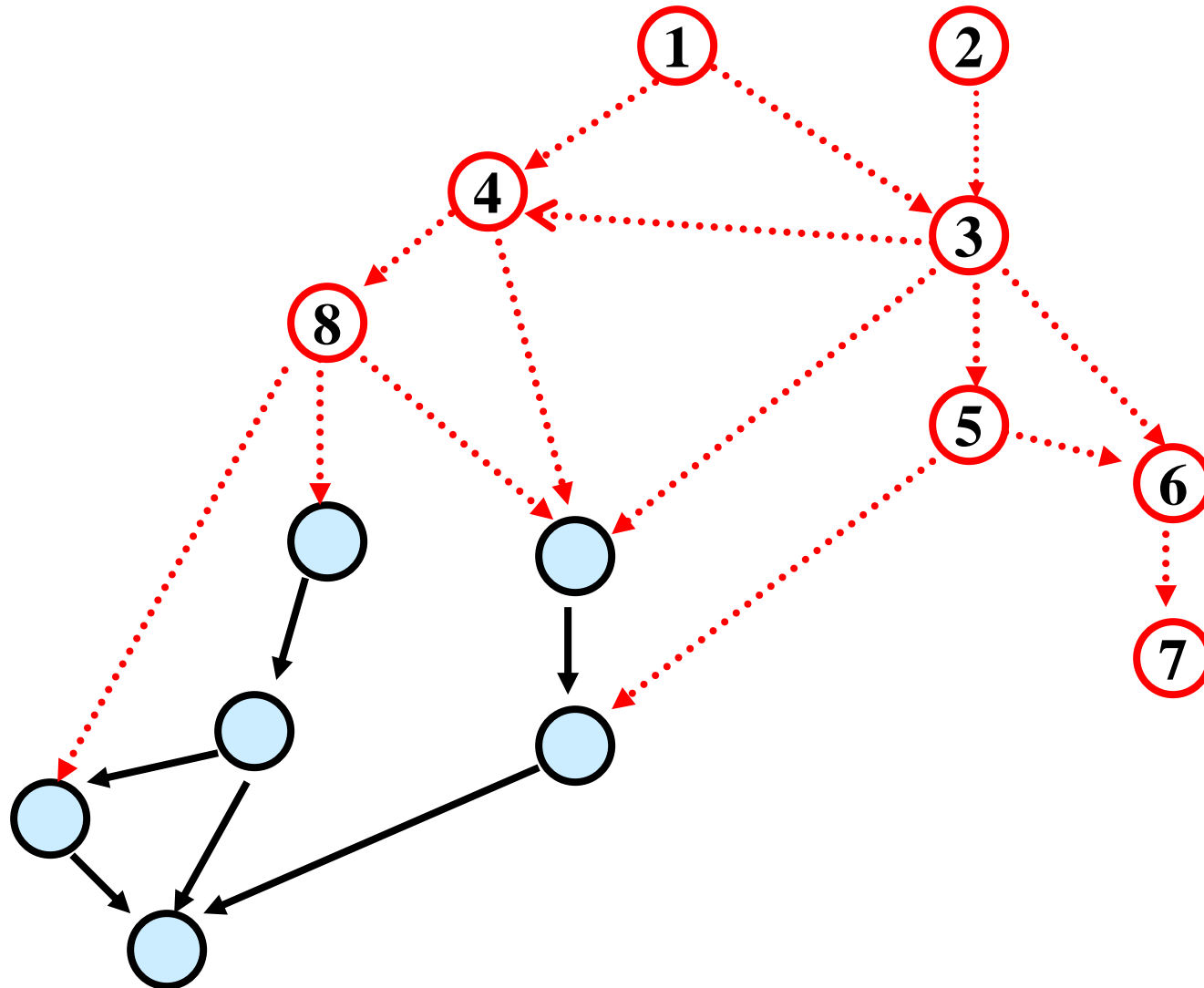




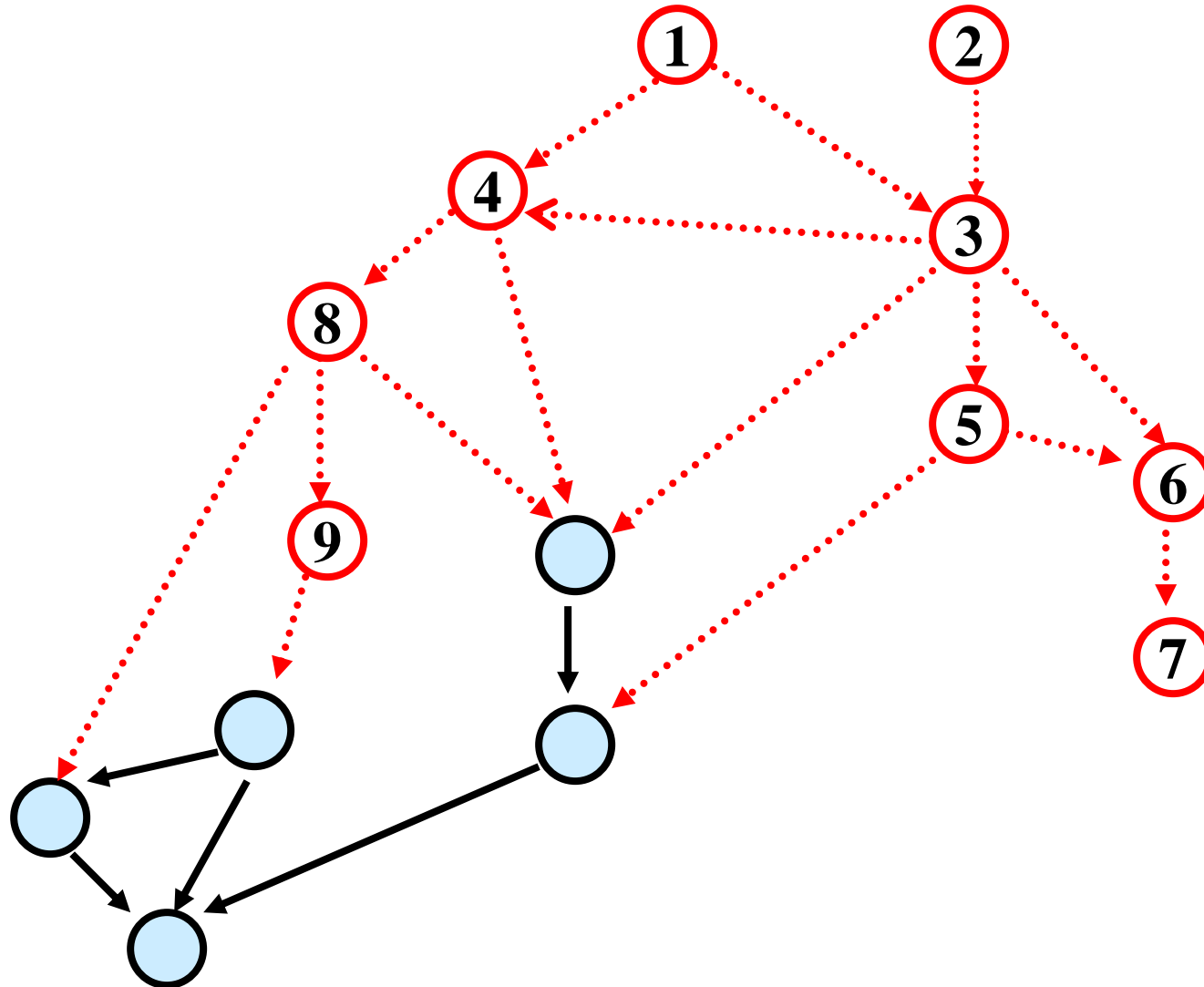
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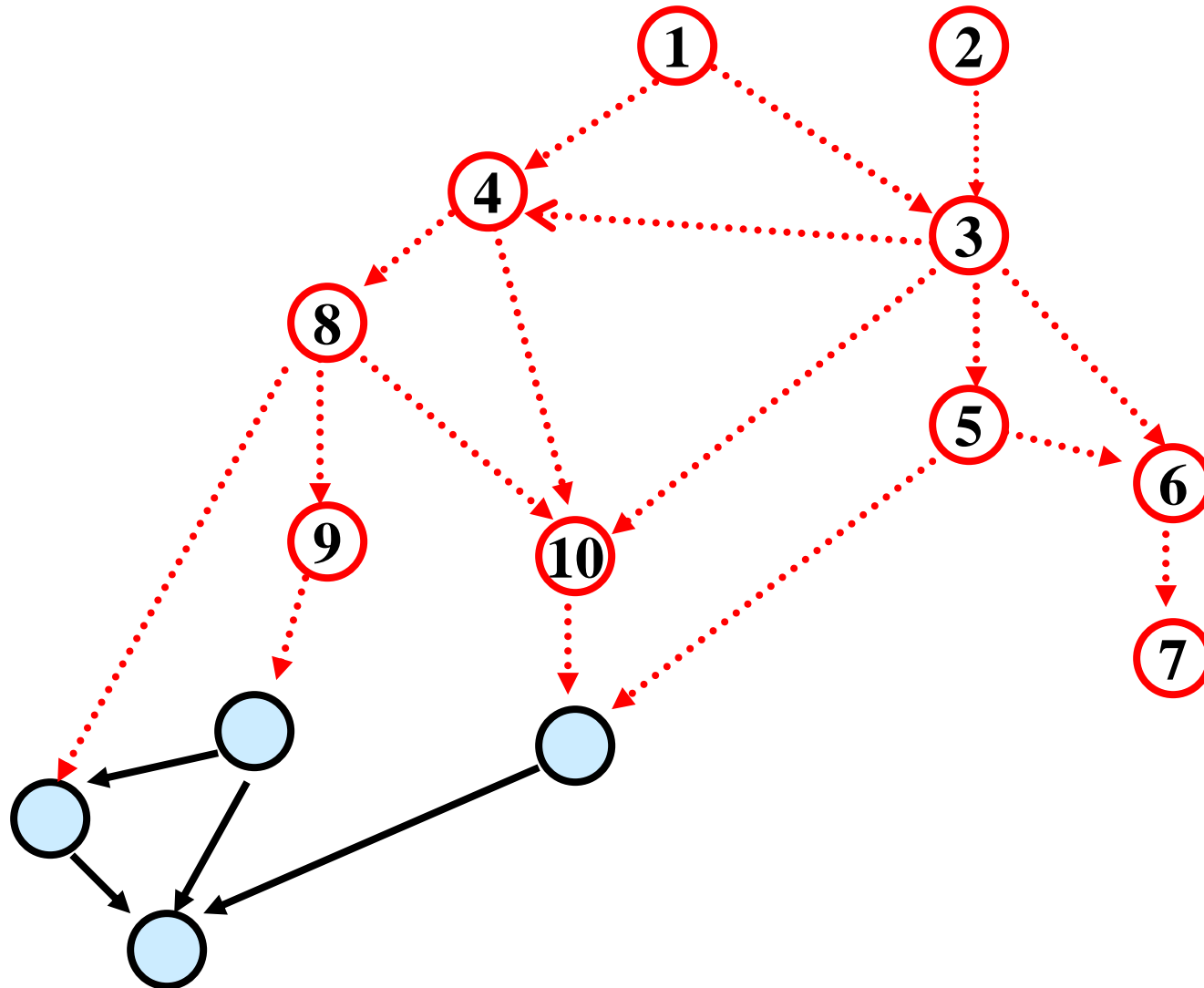
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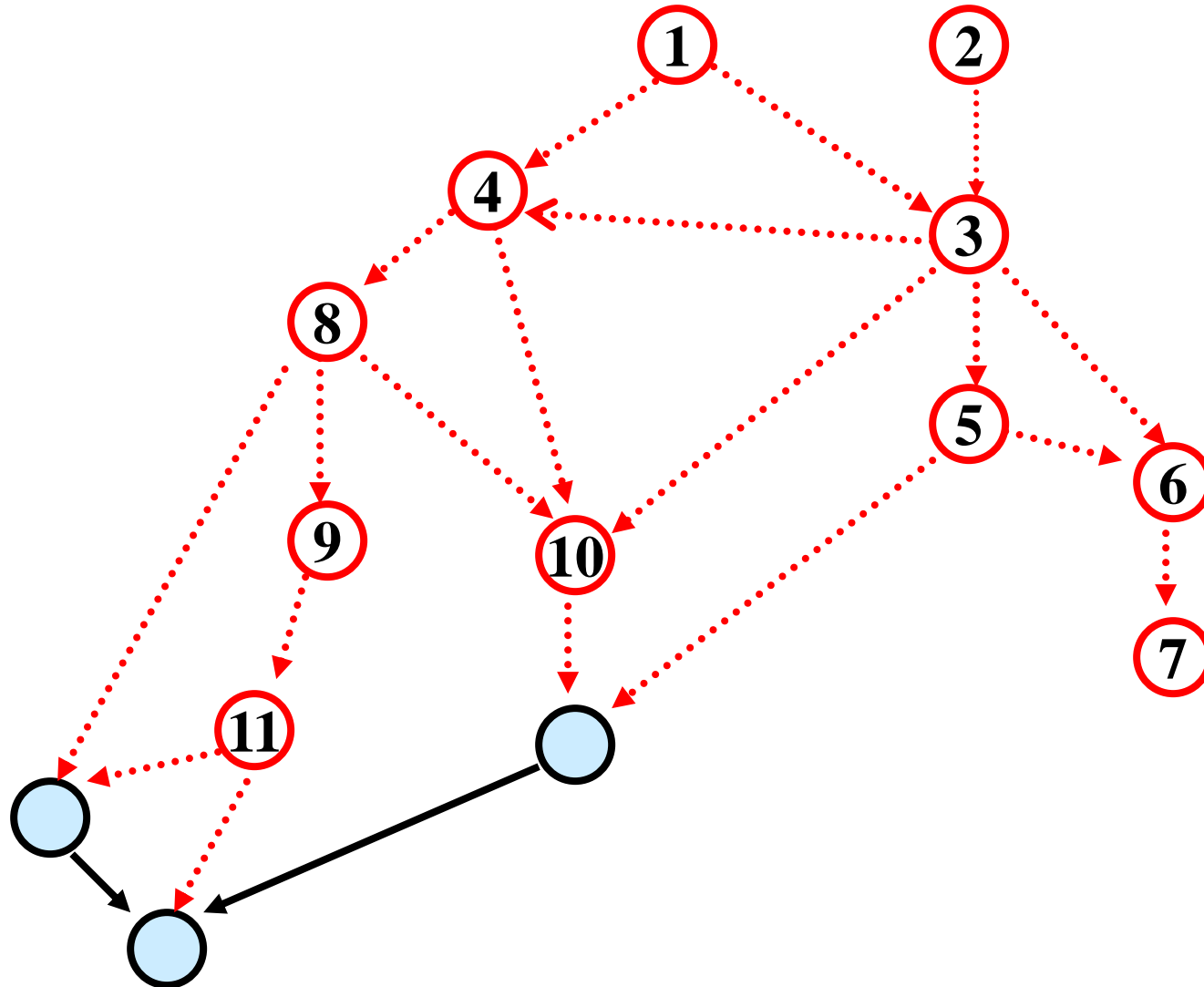
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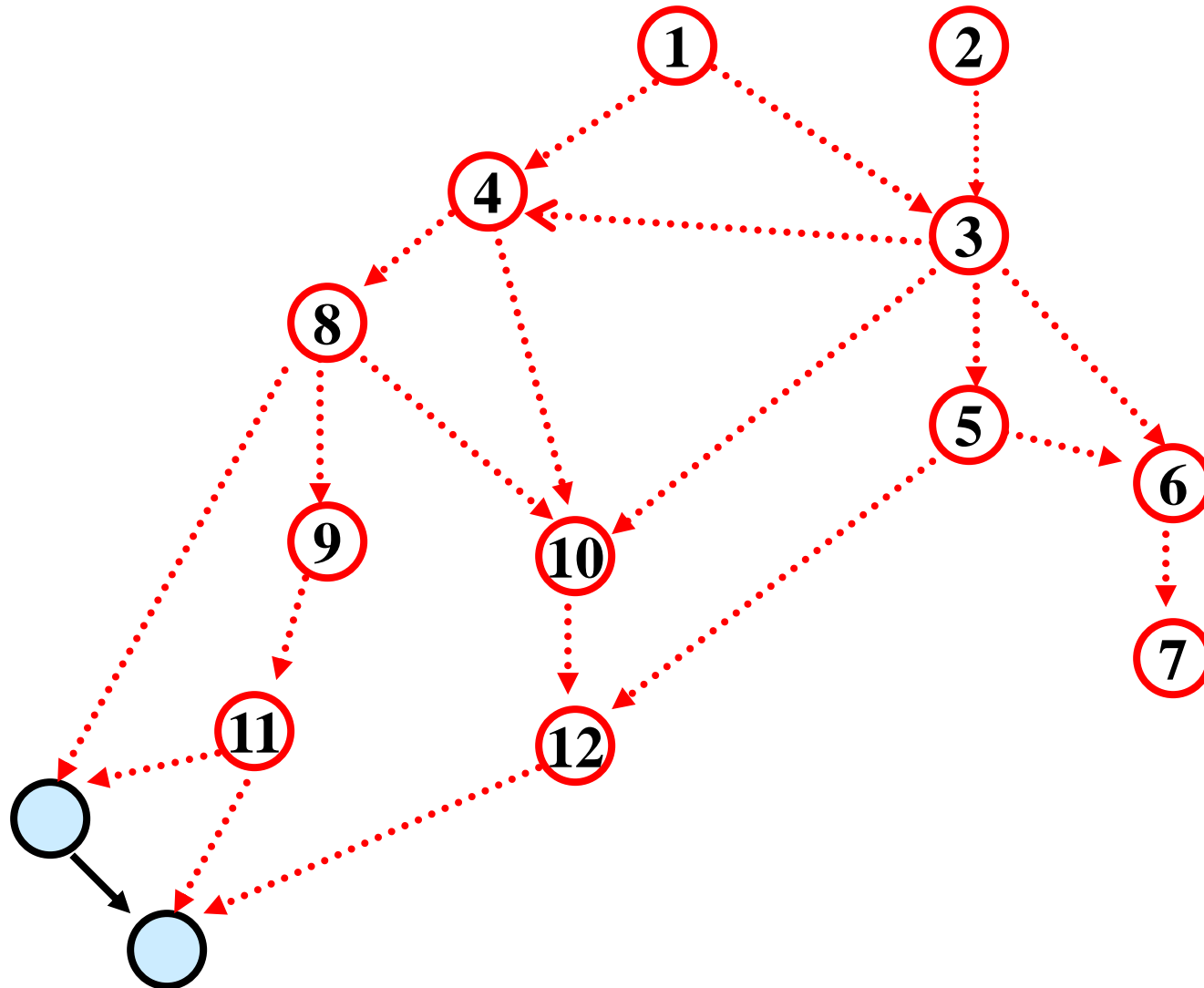
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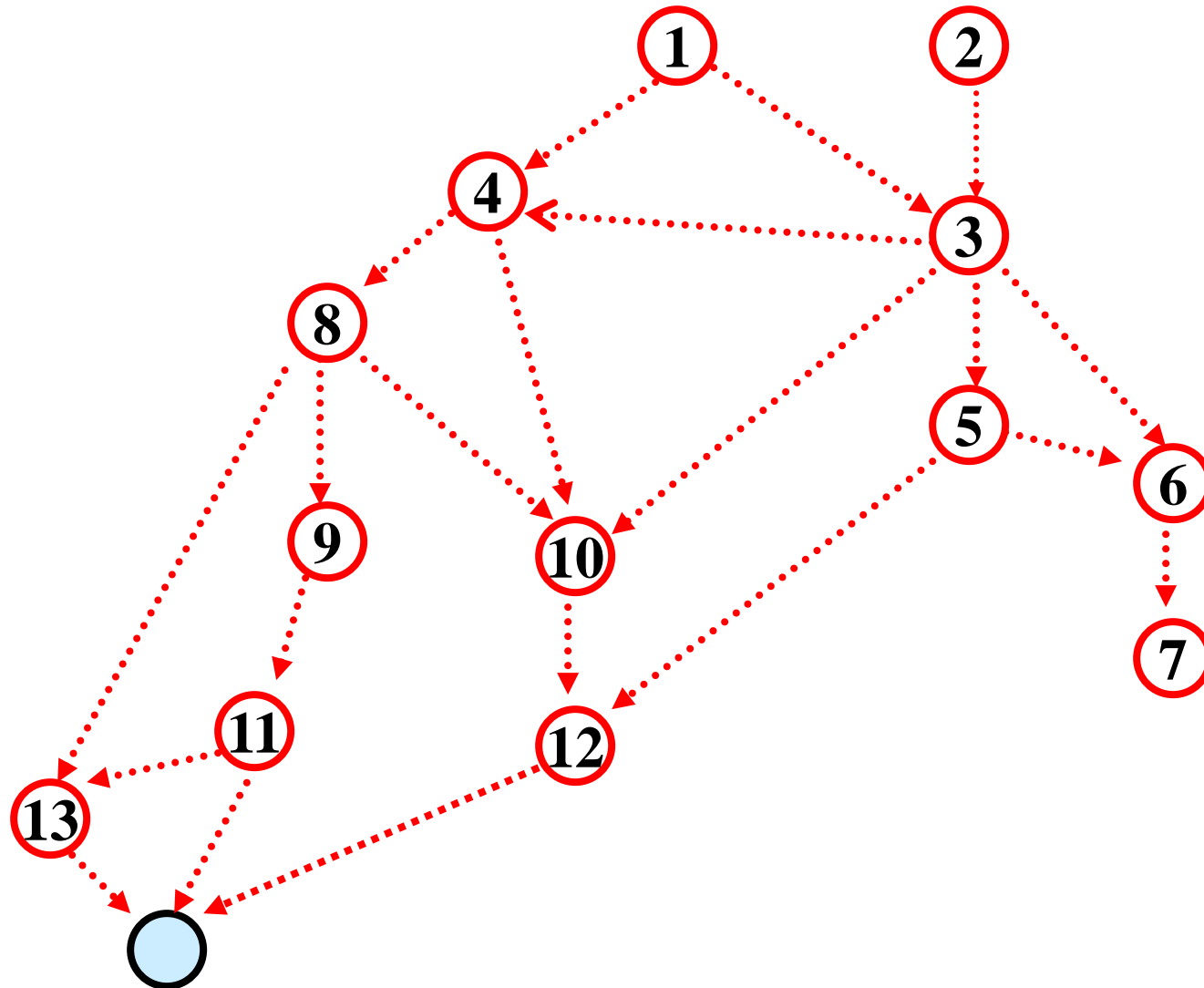
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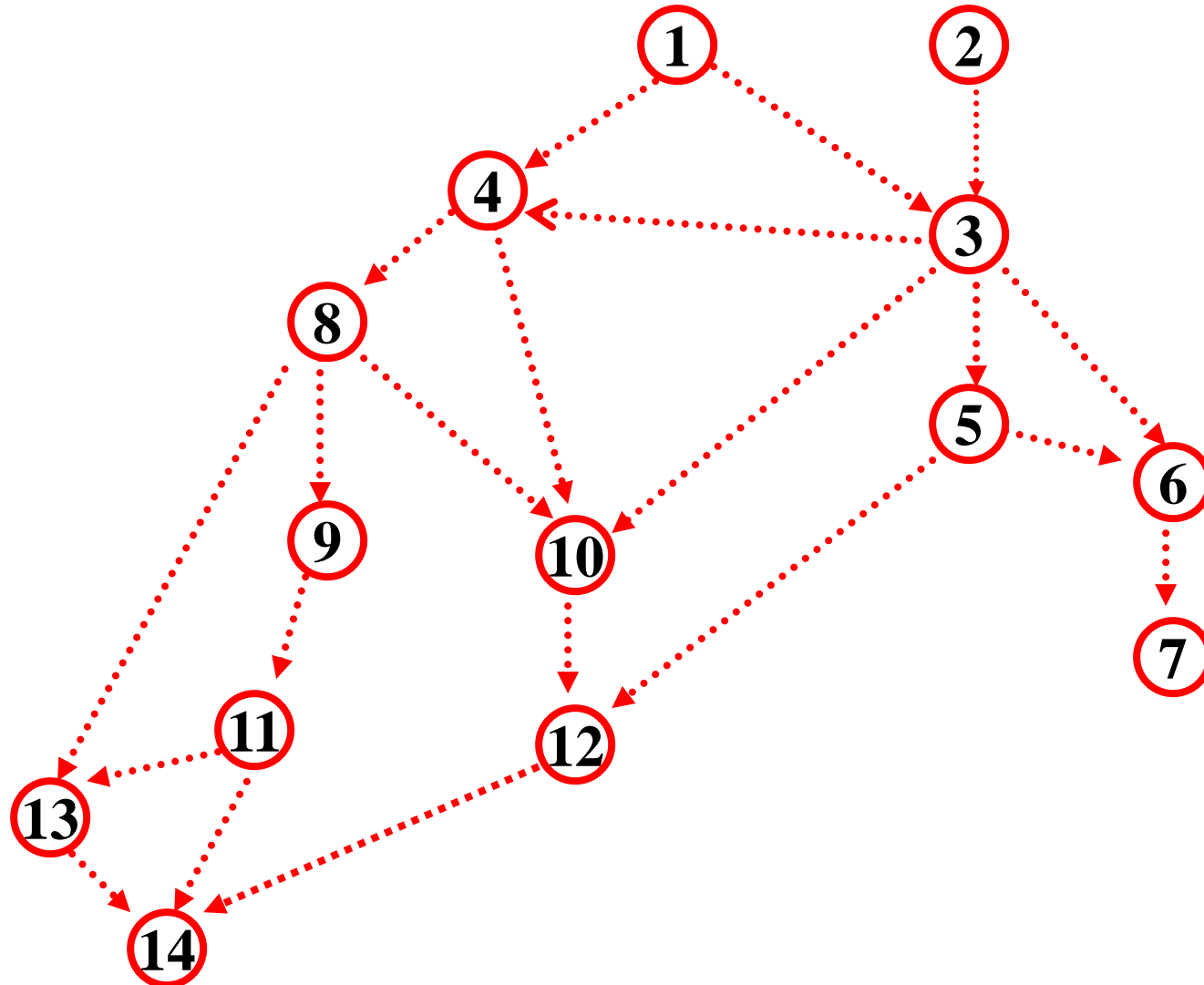
# Topological Sort



# Topological Sort



# Topological Sort







# Implementing Topological Sort

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- Go through all edges, computing array with in-degree for each vertex  $O(m+n)$
- Maintain a queue (or stack) of vertices of in-degree **0**
- Remove any vertex in queue and number it
- When a vertex is removed, decrease in-degree of each of its neighbors by **1** and add them to the queue if their degree drops to **0**

Total cost  $O(m+n)$



# Strongly Connected Components & Topological Sort work well together

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- Shrinking each s.c.c. of directed graph to a vertex yields a DAG
- Can apply topological sort to the resulting DAG to get a good order to deal with the s.c.c.'s of the original graph one at a time