

#### **Dynamic Programming**

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## Weighted Interval Scheduling

## **Interval Scheduling**

- Job *j* starts at s(j) and finishes at f(j) and has weight  $w_j$
- Two jobs compatible if they don't overlap.
- Goal: find maximum weight subset of mutually compatible jobs.



## **Unweighted Interval Scheduling: Review**

Recall: Greedy algorithm works if all weights are 1:

- Consider jobs in ascending order of finishing time
- Add job to a subset if it is compatible with prev added jobs.
   Observation: Greedy ALG fails spectacularly if arbitrary weights are allowed:



# Weighted Job Scheduling by Induction

Suppose 1, ..., *n* are all jobs. Let us use induction:

IH: Suppose we can compute the optimum job scheduling for < n jobs.

IS: Goal: For any *n* jobs we can compute OPT. Case 1: Job *n* is not in OPT. -- Then, just return OPT of 1, ..., n - 1. Case 2: Job *n* is in OPT.

-- Then, delete all jobs not compatible with n and recurse.

Q: Are we done? A: No, How many subproblems are there? Potentially  $2^n$  all possible subsets of jobs.



## Sorting to Reduce Subproblems

Why we can't order by start time?

Sorting Idea: Label jobs by finishing time  $f(1) \le \dots \le f(n)$ IS: For jobs 1, ..., *n* we want to compute OPT

Case 1: Suppose OPT has job n.

- So, all jobs *i* that are not compatible with *n* are not OPT
- Let p(n) =largest index i < n such that job i is compatible with n.
- Then, we just need to find OPT of 1, ..., p(n)



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- Let p(n) =largest index i < n such that job i is compatible with n.
- Then, we just need to find OPT of 1, ..., p(n)

Case 2: OPT does not select job n.

• Then, OPT is just the OPT of 1, ..., n-2

Take best of the two

Q: Have we made any progress (still reducing to two subproblems)? A: Yes! This time every subproblem is of the form 1, ..., i for some *i* So, at most *n* possible subproblems.

# Weighted Job Scheduling by Induction

Sorting Idea: Label jobs by finishing time  $f(1) \le \dots \le f(n)$ Def OPT(j) denote the weight of OPT solution of  $1, \dots, j$ 

To solve OPT(j): Case 1: OPT(j) has job *j*.

- So, all jobs *i* that are not compatible with *j* are not OPT(j).
- Let p(j) =largest index i < j such that job i is compatible with j.
- So  $OPT(j) = OPT(p(j)) + w_j$ .

Case 2: OPT(j) does not select job j.

• Then, OPT(j) = OPT(j-1).

$$OPT(j) = \begin{cases} 0 & \text{if } j = 0\\ \max\left(w_j + OPT(p(j)), OPT(j-1)\right) & \text{o. w.} \end{cases}$$

## Algorithm

```
Input: n, s(1), \ldots, s(n) and f(1), \ldots, f(n) and w_1, \ldots, w_n.
Sort jobs by finish times so that f(1) \leq f(2) \leq \cdots f(n).
Compute p(1), p(2), \ldots, p(n)
OPT(j) {
    if ( j = 0 )
        return 0
    else
        return max (w_j + OPT(p(j)), OPT(j-1)).
}
```

## **Recursive Algorithm Fails**

Even though we have only n subproblems, if we do not store the solution to the subproblems

 $\succ$  we may re-solve the same problem many many times.

Ex. Number of recursive calls for family of "layered" instances grows like Fibonacci sequence



## Algorithm with Memoization

Memorization. Compute and Store the solution of each sub-problem in a cache the first time that you face it. lookup as needed.

```
Input: n, s(1), ..., s(n) and f(1), ..., f(n) and w_1, ..., w_n.
Sort jobs by finish times so that f(1) \leq f(2) \leq \cdots f(n).
Compute p(1), p(2), ..., p(n)
for j = 1 to n
   M[j] = empty
M[0] = 0
OPT(i) {
   if (M[j] is empty)
       M[j] = max(w_i + OPT(p(j)), OPT(j-1)).
   return M[j]
}
```

In practice, you may get rightarrow stackoverflow if  $n \gg 10^6$  (depends on the language). 11

# Bottom up Dynamic Programming

You can also avoid recursion

recursion may be easier conceptually when you use induction

```
Input: n, s(1), ..., s(n) and f(1), ..., f(n) and w_1, ..., w_n.
Sort jobs by finish times so that f(1) \leq f(2) \leq \cdots f(n).
Compute p(1), p(2), ..., p(n)
OPT(j) \{
M[0] = 0
for j = 1 to n
M[j] = max (w_j + M[p(j)], M[j-1]).
}
Output M[n]
```

Claim: M[j] is value of OPT(j)Timing: Easy. Main loop is O(n); sorting is  $O(n \log n)$ .





















# **Dynamic Programming**

 Give a solution of a problem using smaller (overlapping) sub-problems where the parameters of all sub-problems are determined in-advance

 Useful when the same subproblems show up again and again in the solution.

## **Knapsack Problem**

# **Knapsack Problem**

Given *n* objects and a "knapsack."

Item *i* weighs  $w_i > 0$  kilograms and has value  $v_i > 0$ .

Knapsack has capacity of W kilograms.

Goal: fill knapsack so as to maximize total value.

Ex: OPT is { 3, 4 } with value 40.

Greedy: repeatedly add item with maximum ratio  $v_i/w_i$ .

Ex: { 5, 2, 1 } achieves only value =  $35 \implies$  greedy not optimal.



	Item	Value	Weight
	1	1	1
11	2	6	2
	3	18	5
	4	22	6
	5	28	7

# **Dynamic Programming: First Attempt**

Let OPT(i) = Max value of subsets of items 1, ..., *i* of weight  $\leq W$ .

Case 1: *OPT*(*i*) does not select item *i* 

- In this case OPT(i) = OPT(i-1)

Case 2: OPT(i) selects item *i* 

- In this case, item i does not immediately imply we have to reject other items
- The problem does not reduce to OPT(i-1) because we now want to pack as much value into box of weight  $\leq W w_i$

Conclusion: We need more subproblems, we need to strengthen IH.

# Stronger DP (Strengthening Hypothesis)

What is the ordering of item we should pick?

Let OPT(i, w) = Max value of subsets of items 1, ..., *i* of weight  $\leq w$ 

Case 1: *OPT*(*i*, *w*) selects item *i* 

• In this case,  $OPT(i, w) = v_i + OPT(i - 1, w - w_i)$ 

Case 2: OPT(i, w) does not select item i

• In this case, OPT(i, w) = OPT(i - 1, w).

Take best of the two

Therefore,

$$OPT(i,w) = \begin{cases} 0 & \text{If } i = 0\\ OPT(i-1,w) & \text{If } w_i > w\\ \max(OPT(i-1,w), v_i + OPT(i-1,w-w_i)) & \text{O.W.}, \end{cases}$$

```
Comp-OPT(i,w)
if M[i,w] == empty
if (i==0)
    M[i,w]=0
    recursive
else if (w<sub>i</sub> > w)
    M[i,w]= Comp-OPT(i-1,w)
else
    M[i,w]= max {Comp-OPT(i-1,w), v<sub>i</sub> + Comp-OPT(i-1,w-w<sub>i</sub>)}
return M[i, w]
```

```
for w = 0 to W
    M[0, w] = 0
for i = 1 to n
    for w = 1 to W
    if (w<sub>i</sub> > w)
        M[i, w] = M[i-1, w]
    else
        M[i, w] = max {M[i-1, w], v<sub>i</sub> + M[i-1, w-w<sub>i</sub>]}
```

```
return M[n, W]
```

		0	1	2	3	4	5	6	7	8	9	10	11
	φ	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0											
 n + 1	{ 1, 2 }	0											
	{ 1, 2, 3 }	0											
	{ 1, 2, 3, 4 }	0											
↓ ↓	{1,2,3,4,5}	0											

	Item	Value	Weight
W = 11	1	1	1
if $(w_i > w)$	2	6	2
M[i, w] = M[i-1, w]	3	18	5
$M[i, w] = \max \{M[i-1, w], v_i + M[i-1, w-w_i]\}$	4	22	6
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OPT: { 4, 3 } value = 22 + 18 = 40		Item	Value	Weight
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	{1}	0	1	1	1	1	1	1	1	1	1	1	1
 n + 1	{ 1, 2 }	0	1	6	7	7	7	7	7	7	7	7	7
	{ 1, 2, 3 }	0	1	6	7	7	18	19					
	{ 1, 2, 3, 4 }	0	1										
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	ф	0	0	0	0	0	0	0	0	0	0	0	0
	{1}	0	1	1	1	1	1	1	1	1	1	1	1
 n + 1	{ 1, 2 }	0	1	6	7	7	7	7	7	7	7	7	7
	{ 1, 2, 3 }	0	1	6	7	7	18	19	24	25	25	25	25
	{ 1, 2, 3, 4 }	0	1	6	7	7	18	22	24	28	29		
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\_\_\_\_

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	{ 1, 2, 3 }	0	1	6	7	7	18	19	24	25	25	25	25
	{ 1, 2, 3, 4 }	0	1	6	7	7	18	22	24	28	29	29	40
Ļ	{1,2,3,4,5}	0	1	6	7	7	18	22	28	29	34	34	40

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# Knapsack Problem: Running Time

#### Running time: $\Theta(n \cdot W)$

- Not polynomial in input size!
- "Pseudo-polynomial."
- Decision version of Knapsack is NP-complete.

#### Knapsack approximation algorithm:

There exists a polynomial algorithm that produces a feasible solution that has value within 0.01% of optimum in time  $Poly(n, \log W)$ .



**UW Expert** 

## DP Ideas so far

- You may have to define an ordering to decrease #subproblems
- You may have to strengthen DP, equivalently the induction, i.e., you have may have to carry more information to find the Optimum.

 This means that sometimes we may have to use two dimensional or three dimensional induction