CSE 421 Algorithms

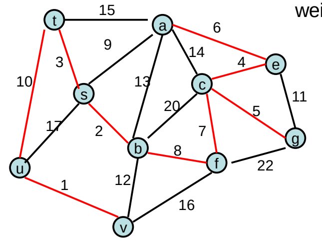
Autumn 2015

Lecture 11

Minimum Spanning Trees (Part II)

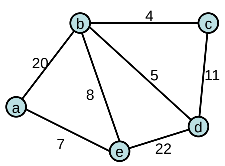
Minimum Spanning Tree

Undirected Graph G=(V,E) with edge weights



Greedy Algorithms for Minimum Spanning Tree

- [Prim] Extend a tree by including the cheapest out going edge
- [Kruskal] Add the cheapest edge that joins disjoint components
- [ReverseDelete] Delete the most expensive edge that does not disconnect the graph

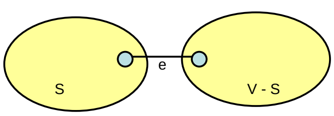


Why do the greedy algorithms work?

- For simplicity, assume all edge costs are distinct

Edge inclusion lemma

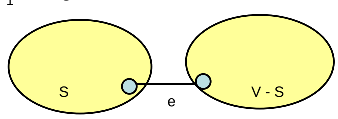
- Let S be a subset of V, and suppose e = (u, v) is the minimum cost edge of E, with u in S and v in V-S
- e is in every minimum spanning tree of G
  - Or equivalently, if e is not in T, then T is not a minimum spanning tree



e is the minimum cost edge between S and V-S

Proof

- Suppose T is a spanning tree that does not contain e
- Add e to T, this creates a cycle
- The cycle must have some edge $e_1 = (u_1, v_1)$ with u_1 in S and v_1 in V-S



- $T_1 = T - \{e_1\} + \{e\}$ is a spanning tree with lower cost
- Hence, T is not a minimum spanning tree

Optimality Proofs

- Prim's Algorithm computes a MST
- Kruskal's Algorithm computes a MST

- Show that when an edge is added to the MST by Prim or Kruskal, the edge is the minimum cost edge between S and V-S for some set S.

Prim's Algorithm

S = { }; T = { };

while S != V

    choose the minimum cost edge
    e = (u,v), with u in S, and v in V-S

    add e to T

    add v to S

Prove Prim's algorithm computes an MST

- Show an edge e is in the MST when it is added to T

Kruskal's Algorithm

Let C = {{v_1}, {v_2}, . . ., {v_n}}; T = { }

while |C| > 1

    Let e = (u, v) with u in C_i and v in C_j be the minimum cost edge joining distinct sets in C

    Replace C_i and C_j by C_i U C_j

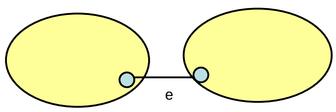
    Add e to T

Prove Kruskal's algorithm computes an MST

- Show an edge e is in the MST when it is added to T

Reverse-Delete Algorithm

- Lemma: The most expensive edge on a cycle is never in a minimum spanning tree



Reverse-Delete Algorithm

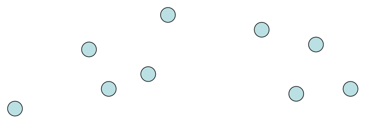
- Let e be the max cost edge whose removal does not disconnect the graph
- Let T be a spanning tree of G=(V, E – {e})

Dealing with the assumption of no equal weight edges

- Force the edge weights to be distinct
  - Add small quantities to the weights
  - Give a tie breaking rule for equal weight edges

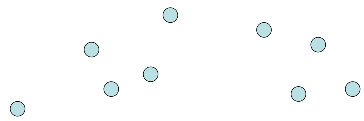
Application: Clustering

- Given a collection of points in an r-dimensional space, and an integer K, divide the points into K sets that are closest together

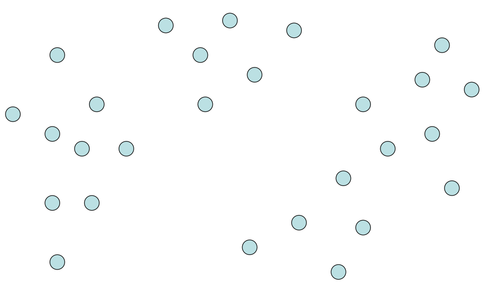


Distance clustering

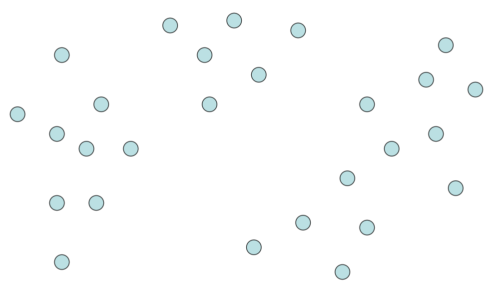
- Divide the data set into K subsets to maximize the distance between any pair of sets
  - dist (S_1, S_2) = min {dist(x, y) | x in S_1, y in S_2}



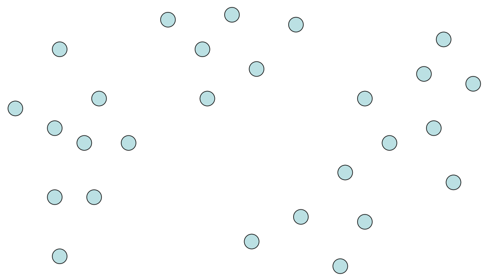
Divide into 2 clusters



Divide into 3 clusters



Divide into 4 clusters



Distance Clustering Algorithm

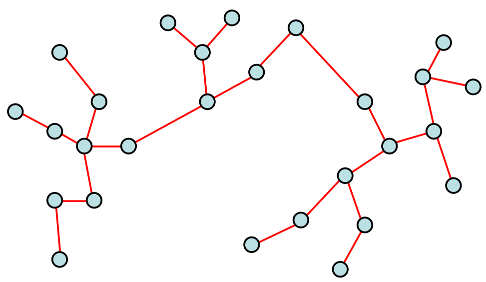
Let C = {{v_1}, {v_2},. . ., {v_n}}; T = { }

while |C| > K

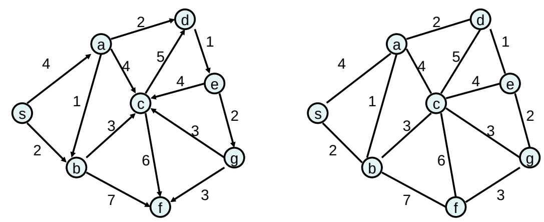
Let e = (u, v) with u in C_i and v in C_j be the minimum cost edge joining distinct sets in C

Replace C_i and C_j by C_i U C_j

K-clustering

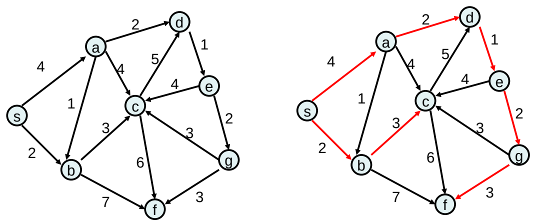


Shortest paths in undirected graphs vs directed graphs

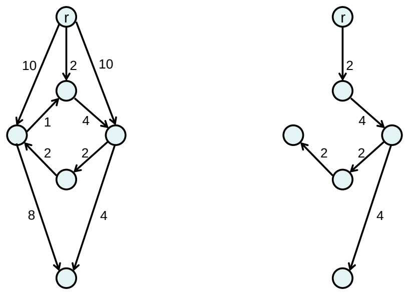


What about the minimum spanning tree of a directed graph?

- Must specify the root r
- Branching: Out tree with root r



Finding a minimum branching



Finding a minimum branching

- Remove all edges going into r
- Normalize the edge weights, so the minimum weight edge coming into each vertex has weight zero

This does not change the edges of the minimum branching

Finding a minimum branching

- Consider the graph that consists of the minimum cost edge coming in to each vertex
  - If this graph is a branching, then it is the minimum cost branching
  - Otherwise, the graph contains one or more cycles
    - Collapse the cycles in the original graph to super vertics
    - Reweight the graph and repeat the process

Finding a minimum branching