## CSE 421 Algorithms

#### Richard Anderson Lecture 21 Shortest Paths and Network Flow

## Shortest Paths with Dynamic Programming

## Shortest Path Problem

- Dijkstra's Single Source Shortest Paths Algorithm
  - O(mlog n) time, positive cost edges
- Bellman-Ford Algorithm
  - O(mn) time for graphs with negative cost edges

#### Lemma

• If a graph has no negative cost cycles, then the shortest paths are simple paths

• Shortest paths have at most n-1 edges

# Shortest paths with a fixed number of edges

 Find the shortest path from v to w with exactly k edges

#### Express as a recurrence

- $Opt_k(w) = min_x [Opt_{k-1}(x) + c_{xw}]$
- Opt<sub>0</sub>(w) = 0 if v=w and infinity otherwise

## Algorithm, Version 1

foreach w M[0, w] = infinity; M[0, v] = 0;for i = 1 to n-1 foreach w  $M[i, w] = min_x(M[i-1,x] + cost[x,w]);$ 

## Algorithm, Version 2

foreach w

M[0, w] = infinity;

M[0, v] = 0;

for i = 1 to n-1

foreach w

 $M[i, w] = min(M[i-1, w], min_x(M[i-1,x] + cost[x,w]))$ 

## Algorithm, Version 3

foreach w
 M[w] = infinity;
M[v] = 0;
for i = 1 to n-1
 foreach w
 M[w] = min(M[w], min<sub>x</sub>(M[x] + cost[x,w]))

#### **Correctness Proof for Algorithm 3**

 Key lemma – at the end of iteration i, for all w, M[w] <= M[i, w];</li>

- Reconstructing the path:
  - Set P[w] = x, whenever M[w] is updated from vertex x

## If the pointer graph has a cycle, then the graph has a negative cost cycle

- If P[w] = x then M[w] >= M[x] + cost(x,w)
  - Equal when w is updated
  - M[x] could be reduced after update
- Let  $v_1, v_2, \dots v_k$  be a cycle in the pointer graph with  $(v_k, v_1)$  the last edge added
  - Just before the update
    - $M[v_j] \ge M[v_{j+1}] + cost(v_{j+1}, v_j)$  for j < k
    - $M[v_k] > M[v_1] + cost(v_1, v_k)$
  - Adding everything up
    - $0 > cost(v_1, v_2) + cost(v_2, v_3) + ... + cost(v_k, v_1)$



# **Negative Cycles**

- If the pointer graph has a cycle, then the graph has a negative cycle
- Therefore: if the graph has no negative cycles, then the pointer graph has no negative cycles

## Finding negative cost cycles

• What if you want to find negative cost cycles?





CAD

1.6

EUR

#### **Network Flow**









# Outline

- Network flow definitions
- Flow examples
- Augmenting Paths
- Residual Graph
- Ford Fulkerson Algorithm
- Cuts
- Maxflow-MinCut Theorem

## **Network Flow Definitions**

- Capacity
- Source, Sink
- Capacity Condition
- Conservation Condition
- Value of a flow

#### Flow Example



# Flow assignment and the residual graph





## **Network Flow Definitions**

- Flowgraph: Directed graph with distinguished vertices s (source) and t (sink)
- Capacities on the edges,  $c(e) \ge 0$
- Problem, assign flows f(e) to the edges such that:
  - $0 \le f(e) \le c(e)$
  - Flow is conserved at vertices other than s and t
    - Flow conservation: flow going into a vertex equals the flow going out
  - The flow leaving the source is a large as possible

#### Flow Example



## Find a maximum flow

Value of flow:



Construct a maximum flow and indicate the flow value

#### Find a maximum flow



# Augmenting Path Algorithm

- Augmenting path
  - Vertices  $v_1, v_2, \dots, v_k$

• 
$$v_1 = s$$
,  $v_k = t$ 

 Possible to add b units of flow between v<sub>j</sub> and v<sub>j+1</sub> for j = 1 ... k-1



## Find two augmenting paths



## **Residual Graph**

- Flow graph showing the remaining capacity
- Flow graph G, Residual Graph G<sub>R</sub>
  - G: edge e from u to v with capacity c and flow f
  - $-G_R$ : edge e' from u to v with capacity c -f
  - $-G_R$ : edge e'' from v to u with capacity f

### **Residual Graph**





## Build the residual graph



Residual graph:



## Augmenting Path Lemma

- Let  $P = v_1, v_2, ..., v_k$  be a path from s to t with minimum capacity b in the residual graph.
- b units of flow can be added along the path P in the flow graph.



## Proof

- Add b units of flow along the path P
- What do we need to verify to show we have a valid flow after we do this?

#### Ford-Fulkerson Algorithm (1956)

while not done

Construct residual graph  $G_R$ Find an s-t path P in  $G_R$  with capacity b > 0 Add b units along in G

If the sum of the capacities of edges leaving S is at most C, then the algorithm takes at most C iterations