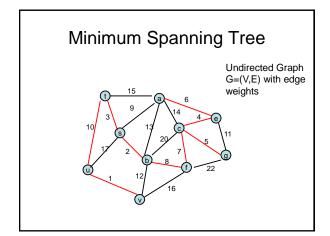
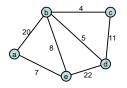
CSE 421 Algorithms

Autumn 2015
Lecture 11
Minimum Spanning Trees (Part II)



Greedy Algorithms for Minimum Spanning Tree

- [Prim] Extend a tree by including the cheapest out going edge
- [Kruskal] Add the cheapest edge that joins disjoint components
- [ReverseDelete] Delete the most expensive edge that does not disconnect the graph



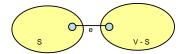
Why do the greedy algorithms work?

For simplicity, assume all edge costs are distinct

Edge inclusion lemma

- Let S be a subset of V, and suppose e =

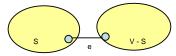
 (u, v) is the minimum cost edge of E, with u in S and v in V-S
- e is in every minimum spanning tree of G
 - Or equivalently, if e is not in T, then T is not a minimum spanning tree



e is the minimum cost edge between S and V-S

Proof

- Suppose T is a spanning tree that does not contain e
- Add e to T, this creates a cycle
- * The cycle must have some edge $e_1 = (u_1, v_1)$ with u_1 in S and v_1 in V-S



- $T_1 = T \{e_1\} + \{e\}$ is a spanning tree with lower cost
- · Hence, T is not a minimum spanning tree

Optimality Proofs

- · Prim's Algorithm computes a MST
- · Kruskal's Algorithm computes a MST
- Show that when an edge is added to the MST by Prim or Kruskal, the edge is the minimum cost edge between S and V-S for some set S.

Prim's Algorithm

Prove Prim's algorithm computes an MST

 Show an edge e is in the MST when it is added to T

Kruskal's Algorithm

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\begin{split} \text{Let } C &= \{\{v_1\}, \{v_2\}, \, \ldots, \{v_n\}\}; \  \, T = \{\,\} \\ \text{while } |C| &> 1 \\ \text{Let } e &= (u, \, v) \text{ with } u \text{ in } C_i \text{ and } v \text{ in } C_j \text{ be the } \\ \text{minimum cost edge joining distinct sets in } C \\ \text{Replace } C_i \text{ and } C_j \text{ by } C_i \text{ U } C_j \\ \text{Add } e \text{ to } T \end{split}
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Prove Kruskal's algorithm computes an MST

• Show an edge e is in the MST when it is added to T

Reverse-Delete Algorithm

• Lemma: The most expensive edge on a cycle is never in a minimum spanning tree

Dealing with the assumption of no equal weight edges

- · Force the edge weights to be distinct
 - Add small quantities to the weights
 - Give a tie breaking rule for equal weight edges

Application: Clustering

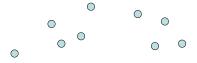
 Given a collection of points in an rdimensional space, and an integer K, divide the points into K sets that are closest together



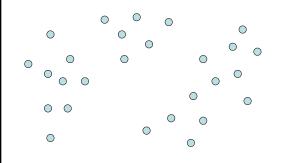
Distance clustering

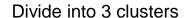
 Divide the data set into K subsets to maximize the distance between any pair of sets

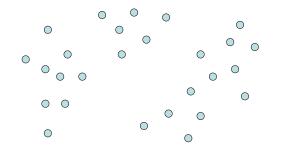
 $- \text{dist} (S_1, S_2) = \min \{ \text{dist}(x, y) \mid x \text{ in } S_1, y \text{ in } S_2 \}$



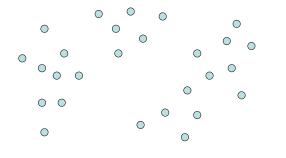
Divide into 2 clusters







Divide into 4 clusters



Distance Clustering Algorithm

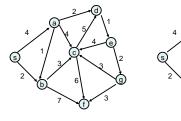
Let
$$C = \{\{v_1\}, \{v_2\}, \ldots, \{v_n\}\}; \ T = \{\ \}$$
 while $|C| > K$

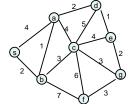
Let e = (u, v) with u in C_i and v in C_j be the minimum cost edge joining distinct sets in C

Replace C_i and C_i by C_i U C_i

K-clustering

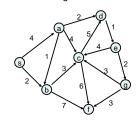
Shortest paths in undirected graphs vs directed graphs

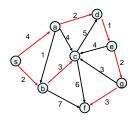




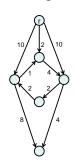
What about the minimum spanning tree of a directed graph?

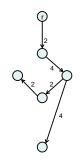
- · Must specify the root r
- · Branching: Out tree with root r





Finding a minimum branching





Finding a minimum branching

- · Remove all edges going into r
- Normalize the edge weights, so the minimum weight edge coming into each vertex has weight zero





This does not change the edges of the minimum branching

Finding a minimum branching

- Consider the graph that consists of the minimum cost edge coming in to each vertex
 - If this graph is a branching, then it is the minimum cost branching
 - Otherwise, the graph contains one or more cycles
 - Collapse the cycles in the original graph to super vertics
 - Reweight the graph and repeat the process

