

Divide and Conquer

Paul Beame

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Algorithm Design Techniques

- Divide & Conquer
 - Reduce problem to one or more sub-problems of the same type
 - Typically, each sub-problem is at most a constant fraction of the size of the original problem
 - e.g. Mergesort, Binary Search, Strassen's Algorithm, Quicksort (kind of)

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Fast exponentiation

- Power(a,n)
 - Input: integer n and number a
 - Output: aⁿ
- Obvious algorithm
 - n-1 multiplications
- Observation:
 - if n is even, n=2m, then aⁿ=a^m•a^m

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Divide & Conquer Algorithm

Power(a,n)

if n=0 then return(1)
else if n=1 then return(a)
else

 $\mathbf{x} \leftarrow \text{Power}(\mathbf{a}, \lfloor \mathbf{n}/2 \rfloor)$ if \mathbf{n} is even then return $(\mathbf{x} \cdot \mathbf{x})$

else return(a•x•x)

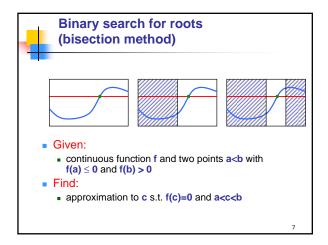


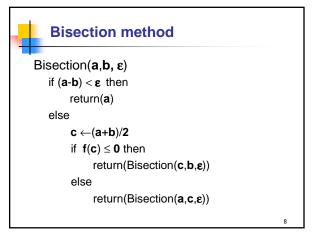
Analysis

- Worst-case recurrence
 - **T**(n)=T(\(\(\nu\n'\2\))+2 for n≥1
 - T(1)=0
- Time
 - $T(n)=T(\lfloor n/2 \rfloor)+2 \le T(\lfloor n/4 \rfloor)+2+2 \le \dots$ $\le T(1)+2+\dots+2 = 2\log_2 n$
- More precise analysis:
 - **T**(**n**)= \[\log_2 \[\nabla \] + # of **1**'s in **n**'s binary representation

A Practical Application- RSA

- Instead of an want an mod N
 - $\mathbf{a}^{i+j} \mod \mathbf{N} = ((\mathbf{a}^i \mod \mathbf{N}) \cdot (\mathbf{a}^j \mod \mathbf{N})) \mod \mathbf{N}$
 - same algorithm applies with each x•y replaced by
 ((x mod N)•(y mod N)) mod N
- In RSA cryptosystem (widely used for security)
 - need aⁿ mod N where a, n, N each typically have 1024 bits
 - Power: at most 2048 multiplies of 1024 bit numbers
 - relatively easy for modern machines
 - Naive algorithm: 2¹⁰²⁴ multiplies







Time Analysis

- At each step we halved the size of the interval
- It started at size b-a
- It ended at size €
- # of calls to f is log₂((b-a)/ε)

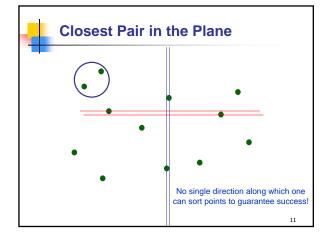
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Euclidean Closest Pair

- Given a set P of n points p₁,...,p_n with realvalued coordinates
- Find the pair of points p_i,p_j∈P such that the Euclidean distance d(p_i,p_j) is minimized
- Θ(n²) possible pairs
- In one dimension there is an easy O(n log n) algorithm
 - Sort the points
 - Compare consecutive elements in the sorted list
- What about points in the plane?

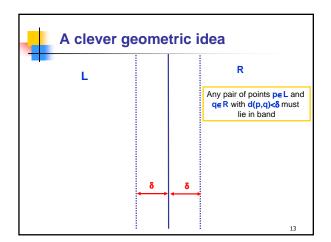
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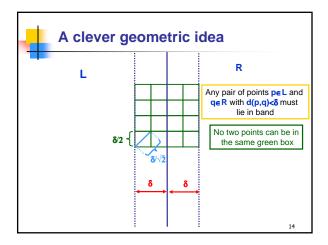


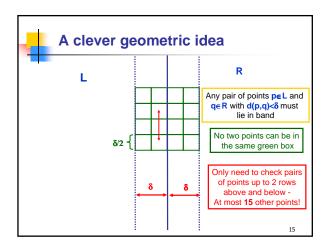


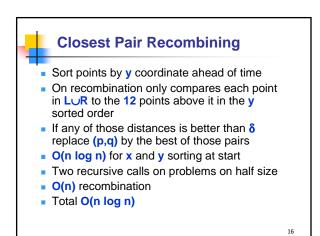
Closest Pair In the Plane: Divide and Conquer

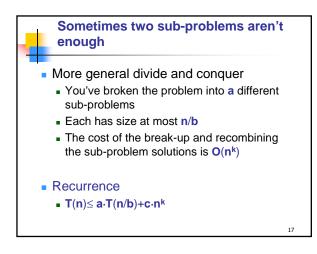
- Sort the points by their x coordinates
- Split the points into two sets of n/2 points L and R by x coordinate
- Recursively compute
 - closest pair of points in L, (p_L,q_L)
 - closest pair of points in R, (p_R,q_R)
- Let δ =min{d(p_L,q_L),d(p_R,q_R)} and let (p,q) be the pair of points that has distance δ
- This may not be enough!
 - Closest pair of points may involve one point from L and the other from R!

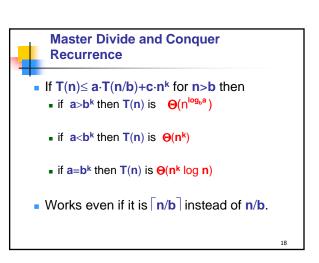


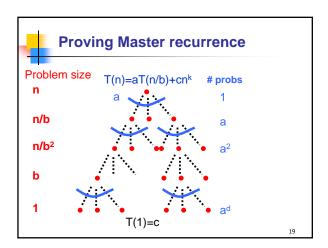


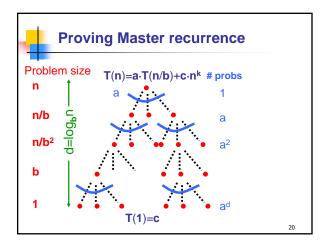


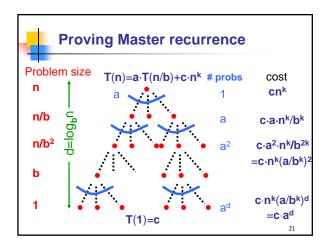


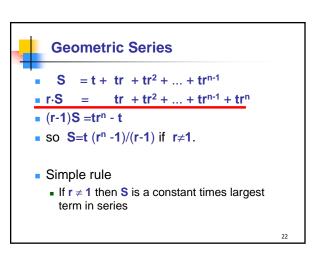


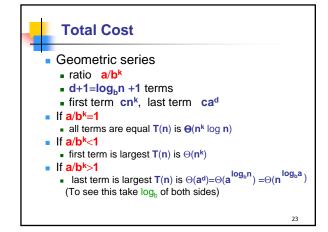


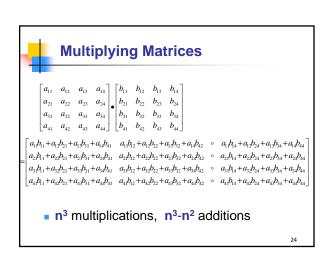






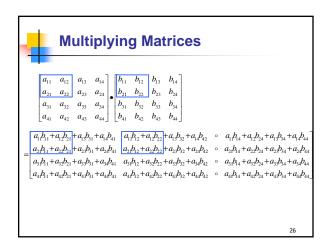


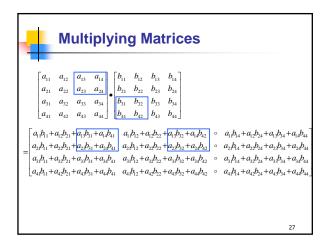


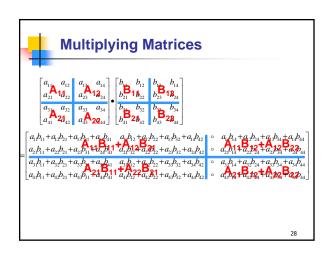


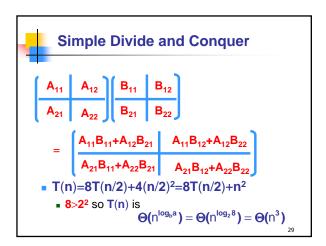
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Multiplying Matrices

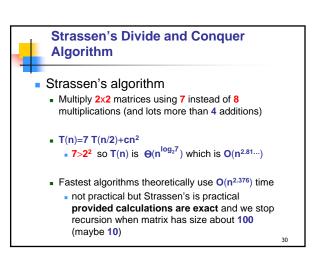
for i=1 to n
for j=1 to n
C[i,j]←0
for k=1 to n
C[i,j]=C[i,j]+A[i,k]·B[k,j]
endfor
endfor
endfor
```













The algorithm

$$\begin{aligned} & P_1 \leftarrow A_{12}(B_{11} + B_{21}); & P_2 \leftarrow A_{21}(B_{12} + B_{22}) \\ & P_3 \leftarrow (A_{11} - A_{12})B_{11}; & P_4 \leftarrow (A_{22} - A_{21})B_{22} \end{aligned}$$

$$P_5 \leftarrow (A_{22} - A_{12})(B_{21} - B_{22})$$

$$P_6 \leftarrow (A_{11} - A_{21})(B_{12} - B_{11})$$

$$P_7 \leftarrow (A_{21} - A_{12})(B_{11} + B_{22})$$

$$C_{11} \leftarrow P_1 + P_3$$
; $C_{12} \leftarrow P_2 + P_3 + P_6 - P_7$

$$C_{21} \leftarrow P_1 + P_4 + P_5 + P_7$$
; $C_{22} \leftarrow P_2 + P_4$

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Another Divide &Conquer Example: Multiplying Faster

- If you analyze our usual grade school algorithm for multiplying numbers
 - Θ(n²) time
 - On real machines each "digit" is, e.g., 32 bits long but still get ⊖(n²) running time with this algorithm when run on n-bit multiplication
- We can do better!
 - We'll describe the basic ideas by multiplying polynomials rather than integers
 - Advantage is we don't get confused by worrying about carries at first

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Notes on Polynomials

- These are just formal sequences of coefficients
 - when we show something multiplied by xk it just means shifted k places to the left – basically no work

Usual polynomial multiplication

$$4x^{2} + 2x + 2$$

$$x^{2} - 3x + 1$$

$$4x^{2} + 2x + 2$$

$$-12x^{3} - 6x^{2} - 6x$$

$$4x^{4} + 2x^{3} + 2x^{2}$$

$$4x^{4} - 10x^{3} + 0x^{2} - 4x + 2$$

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Polynomial Multiplication

- Given:
 - Degree n-1 polynomials P and Q

$$P = a_0 + a_1 x + a_2 x^2 + ... + a_{n-2} x^{n-2} + a_{n-1} x^{n-1}$$

$$Q = b_0 + b_1 x + b_2 x^2 + ... + b_{n-2} x^{n-2} + b_{n-1} x^{n-1}$$

- Compute:
 - Degree 2n-2 Polynomial PQ
 - $\begin{array}{l} \bullet \quad P \; Q = a_0 b_0 + (a_0 b_1 + a_1 b_0) \; X + (a_0 b_2 + a_1 b_1 + a_2 b_0) \; X^2 \\ & \quad + ... + (a_{n-2} b_{n-1} + a_{n-1} b_{n-2}) \; X^{2n-3} + a_{n-1} b_{n-1} \; X^{2n-2} \end{array}$
- Obvious Algorithm:
 - Compute all aibi and collect terms
 - **(n²)** time



Naive Divide and Conquer

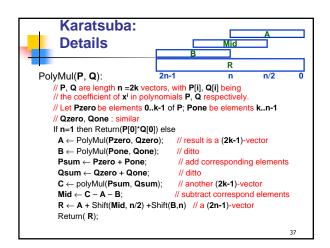
- Assume n=2k
 - P = (a₀ + a₁ x + a₂ x² + ... + a_{k-2} x^{k-2} + a_{k-1} x^{k-1}) + (a_k + a_{k+1} x + ... + a_{n-2} x^{k-2} + a_{n-1} x^{k-1}) x^k
 = P₀ + P₁ x^k where P₀ and P₁ are degree k-1 polynomials
 - Similarly $\mathbf{Q} = \mathbf{Q_0} + \mathbf{Q_1} \mathbf{x^k}$
- $P Q = (P_0 + P_1 x^k)(Q_0 + Q_1 x^k)$ $= P_0 Q_0 + (P_1 Q_0 + P_0 Q_1)x^k + P_1 Q_1 x^{2k}$
- 4 sub-problems of size k=n/2 plus linear combining
 - $T(n)=4\cdot T(n/2)+cn$ Solution $T(n)=\Theta(n^2)$

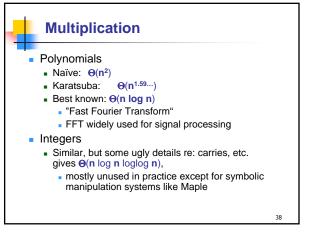
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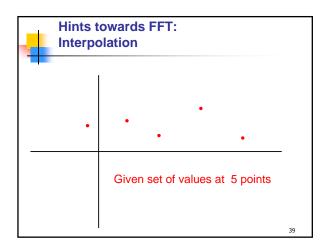


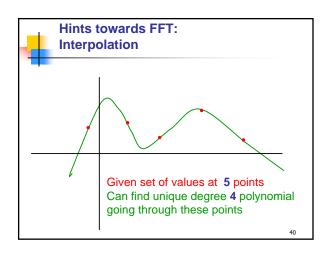
Karatsuba's Algorithm

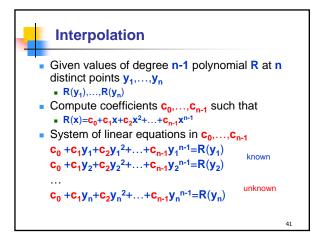
- A better way to compute the terms
 - Compute
 - $A \leftarrow P_0Q_0$
 - $B \leftarrow P_1Q_1$
 - $\mathbf{C} \leftarrow (\mathbf{P}_0 + \mathbf{P}_1)(\mathbf{Q}_0 + \mathbf{Q}_1) = \mathbf{P}_0 \mathbf{Q}_0 + \mathbf{P}_1 \mathbf{Q}_0 + \mathbf{P}_0 \mathbf{Q}_1 + \mathbf{P}_1 \mathbf{Q}_1$
 - Then
 - $P_0Q_1+P_1Q_0=C-A-B$
 - So PQ=A+(C-A-B)xk+Bx2k
 - 3 sub-problems of size n/2 plus O(n) work
 - T(n) = 3 T(n/2) + cn
 - $_{\bullet}$ T(n) = O(n^{\alpha}) where $\alpha = \text{log}_2 3 = 1.59...$

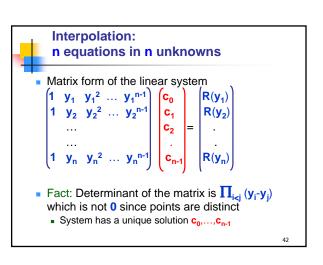


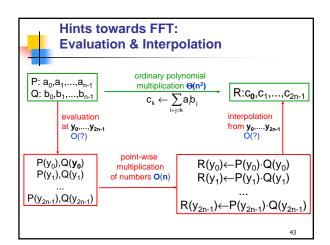


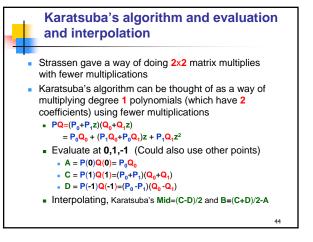






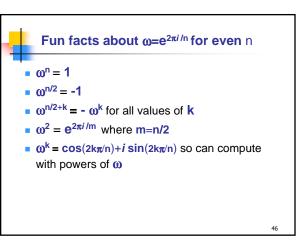


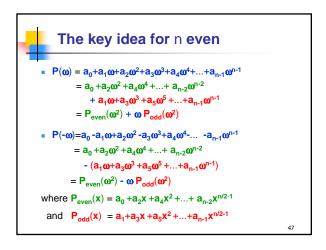


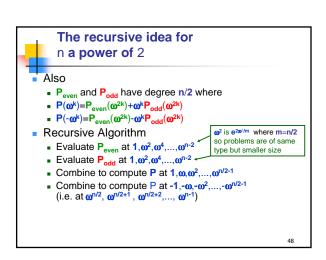




- Evaluation of polynomial at 1 point takes O(n)
 - So 2n points (naively) takes O(n²)—no savings
- Key trick:
 - use carefully chosen points where there's some sharing of work for several points, namely various powers of $\omega = e^{2\pi i/n}$, $i = \sqrt{-1}$
- Plus more Divide & Conquer.
- Result:
 - both evaluation and interpolation in O(n log n) time









Analysis and more

- Run-time
 - $T(n)=2\cdot T(n/2)+cn$ so $T(n)=O(n \log n)$
- So much for evaluation ... what about interpolation?
 - Given
 - $\ \ \, \boldsymbol{r}_0 \!\!=\!\! R(1), \, \boldsymbol{r}_1 \!\!=\!\! R(\omega), \, \boldsymbol{r}_2 \!\!=\!\! R(\omega^2), \! ..., \, \boldsymbol{r}_{n\!-\!1} \!\!=\!\! R(\omega^{n\!-\!1})$
 - Compute
 - $\mathbf{c}_0, \mathbf{c}_1, \dots, \mathbf{c}_{n-1} \text{ s.t. } \mathbf{R}(\mathbf{x}) = \mathbf{c}_0 + \mathbf{c}_1 \mathbf{x} + \dots + \mathbf{c}_{n-1} \mathbf{x}^{n-1}$

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Interpolation ≈ Evaluation: strange but true

- Weird fact:
 - $\begin{array}{l} \blacksquare \ \ \text{If we define a new polynomial} \\ S(x) = r_0 + r_1 x + r_2 x^2 + ... + r_{n-1} x^{n-1} \ \ \text{where} \ r_0, \, r_1, \, ... \ , \, r_{n-1} \\ \text{are the evaluations of } R \ \ \text{at } 1, \, \omega, \, ... \ , \, \omega^{n-1} \end{array}$
 - Then $c_k=S(\omega^{-k})/n$ for k=0,...,n-1
- So...
 - evaluate **S** at **1**,**ω**⁻¹,**ω**⁻²,...,**ω**⁻⁽ⁿ⁻¹⁾ then divide each answer by **n** to get the **c**₀,...,**c**_{n-1}
 - w¹ behaves just like w did so the same O(n log n) evaluation algorithm applies!

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Divide and Conquer Summary

- Powerful technique, when applicable
- Divide large problem into a few smaller problems of the same type
- Choosing sub-problems of roughly equal size is usually critical
- Examples:
 - Merge sort, quicksort (sort of), polynomial multiplication, FFT, Strassen's matrix multiplication algorithm, powering, binary search, root finding by bisection, ...

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Why this is called the discrete Fourier transform

- Real Fourier series
 - Given a real valued function f defined on $[0,2\pi]$ the Fourier series for f is given by $f(x)=a_0+a_1\cos(x)+a_2\cos(2x)+...+a_m\cos(mx)+...$ where

 $a_{m} = \frac{1}{2\pi} \int_{0}^{2\pi} f(x) \cos(mx) dx$

- is the component of f of frequency m
- In signal processing and data compression one ignores all but the components with large a_m and there aren't many since



Why this is called the discrete Fourier transform

- Complex Fourier series
 - Given a function f defined on $[0,2\pi]$ the complex Fourier series for f is given by $f(z)=b_0+b_1 e^{iz}+b_2 e^{2iz}+...+b_m e^{miz}+...$ where $b_m=\frac{1}{2\pi}\int\limits_{-2\pi}^{2\pi}f(z)e^{miz}dz$

is the component of f of frequency m

• If we **discretize** this integral using values at n 2π /n apart equally spaced points between 0 and 2π we get

$$\overline{b}_m = \frac{1}{n} \sum_{k=0}^{n-1} f_k \; e^{\cdot 2kmi\pi/n} = \frac{1}{n} \sum_{k=0}^{n-1} f_k \; \; \omega^{-km} \; \text{where} \; f_k = f(2k\pi/n)$$

just like interpolation!