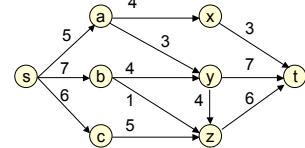


CSE 421 Introduction to Algorithms Summer 2007

The Network Flow Problem

2

The Network Flow Problem



How much stuff can flow from s to t?

3

Net Flow: Formal Definition

Given:
A digraph $G = (V, E)$
Two vertices s, t in V (source & sink)
A capacity $c(u, v) \geq 0$ for each $(u, v) \in E$ (and $c(u, v) = 0$ for all non-edges (u, v))

Find:
A flow function $f: V \times V \rightarrow \mathbb{R}$ s.t., for all u, v :

- $f(u, v) \leq c(u, v)$ [Capacity Constraint]
- $f(u, v) = -f(v, u)$ [Skew Symmetry]
- if $u \neq s, t$, $f(u, v) = 0$ [Flow Conservation]

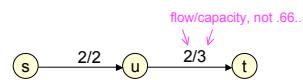
Maximizing total flow $|f| = f(s, V)$

Notation:

$$f(X, Y) = \sum_{x \in X} \sum_{y \in Y} f(x, y)$$

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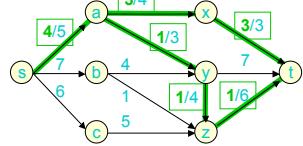
Example: A Flow Function



$$\begin{aligned}
 f(s, u) &= f(u, t) = 2 \\
 f(u, s) &= f(t, u) = -2 \quad (\text{Why?}) \\
 f(s, t) &= -f(t, s) = 0 \quad (\text{In every flow function for this } G. \text{ Why?}) \\
 f(u, V) &= \sum_{v \in V} f(u, v) = f(u, s) + f(u, t) = -2 + 2 = 0
 \end{aligned}$$

5

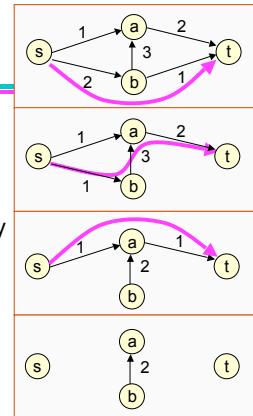
Example: A Flow Function



- Not shown: $f(u,v)$ if $u \rightarrow v$
- Note: max flow ≥ 4 since f is a flow function, with $|f| = 4$

Max Flow via a Greedy Alg?

While there is an $s \rightarrow t$ path in G
 Pick such a path, p
 Find c_p , the min capacity of any edge in p
 Subtract c_p from all capacities on p
 Delete edges of capacity 0

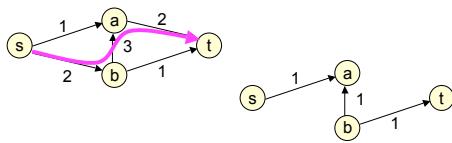


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Max Flow via a Greedy Alg?

This does NOT always find a max flow:
 If you pick $s \rightarrow b \rightarrow a \rightarrow t$ first,



Flow stuck at 2. But flow 3 possible.

A Brief History of Flow

#	year	discoverer(s)	bound
1	1951	Dantzig	$O(n^2 m U)$
2	1955	Ford & Fulkerson	$O(n m d^2)$
3	1970	Dinitz	$O(n m d^2)$
		Edmonds & Karp	
4	1970	Dinitz	$O(n^2 m)$
5	1972	Edmonds & Karp	$O(m^2 n \log U)$
		Dinitz	
6	1973	Dinitz	$O(n m \log U)$
		Gabori	
7	1974	Karzanov	$O(r^2)$
8	1975	Galil & Rosenberg	$O(n^2 / m)$
9	1980	Galil & Naamad	$O(m n \log^2 n)$
10	1983	Sheator & Tarjan	$O(n m \log n)$
11	1986	Goldberg & Tarjan	$O(n m \log(n/m))$
12	1987	Ahuja & Orlin	$O(n m + n^2 \log U)$
13	1987	Ahuja et al.	$O(n m \log(n \sqrt{\log U})/(m+2))$
14	1989	Goldberg & Werneck	$O(n^2 \log(n/\log n))$
15	1990	Closivyan et al.	$O(n^2 \log n)$
16	1990	Alon	$O(n m + n^{3/2} \log n)$
17	1992	King et al.	$O(n m + n^{2/3} t)$
18	1993	Phillips & Westbrook	$O(n m (\log_{m/n} n + \log^{1+\epsilon} n))$
19	1994	King et al.	$O(n m \log_{m/n} n)$
20	1997	Goldberg & Rao	$O(n^{1/3} \log(n/m) \log U)$
			$O(n^{1/3} m \log(n/m) \log U)$

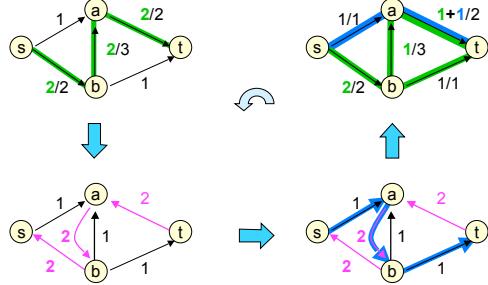
$n = \#$ of vertices
 $m = \#$ of edges
 $U = \text{Max capacity}$

Source: Goldberg & Rao,
 FOCS '97

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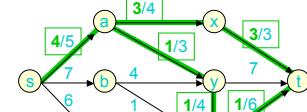
Greed Revisited



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Residual Capacity

- The *residual capacity* (w.r.t. f) of (u,v) is $c_f(u,v) = c(u,v) - f(u,v)$
- E.g.:
 - $c_f(s,b) = 7$;
 - $c_f(a,x) = 1$;
 - $c_f(x,a) = 3$;
 - $c_f(x,t) = 0$ (a **saturated edge**)



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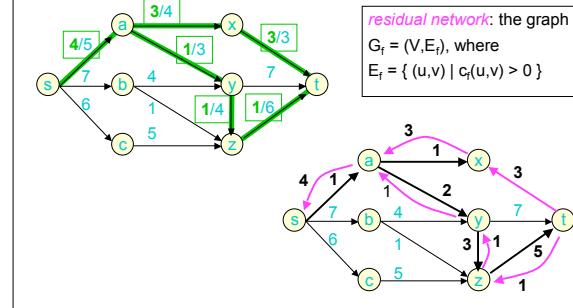
Residual Networks & Augmenting Paths

- The *residual network* (w.r.t. f) is the graph $G_f = (V, E_f)$, where

$$E_f = \{ (u,v) \mid c_f(u,v) > 0 \}$$
- An *augmenting path* (w.r.t. f) is a simple $s \rightarrow t$ path in G_f .

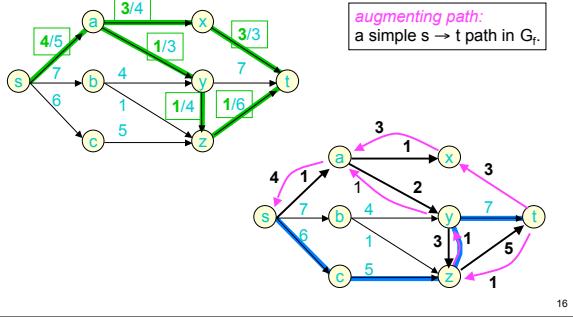
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A Residual Network



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An Augmenting Path



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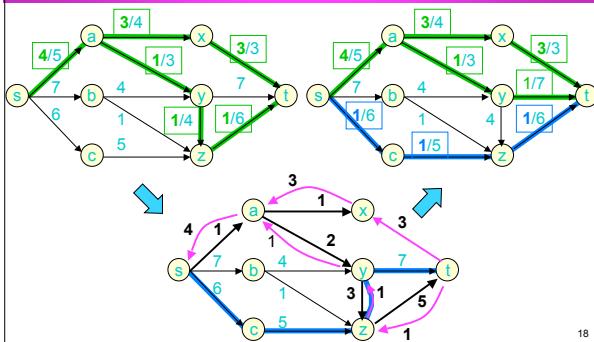
Lemma 1

If f admits an augmenting path p , then f is not maximal.

Proof: "obvious" -- augment along p by c_p , the min residual capacity of p 's edges.

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Augmenting A Flow



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Lemma 1': Augmented Flows are Flows

If f is a flow & p an augmenting path of capacity c_p , then f' is also a valid flow, where

$$f'(u,v) = \begin{cases} f(u,v) + c_p, & \text{if } (u,v) \text{ in path } p \\ f(u,v) - c_p, & \text{if } (v,u) \text{ in path } p \\ f(u,v), & \text{otherwise} \end{cases}$$

Proof:

- a) Flow conservation -- easy
- b) Skew symmetry -- easy
- c) Capacity constraints -- pretty easy

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Lma 1': Augmented Flows are Flows

$$f'(u,v) = \begin{cases} f(u,v) + c_p, & \text{if } (u,v) \text{ in path } p \\ f(u,v) - c_p, & \text{if } (v,u) \text{ in path } p \\ f(u,v), & \text{otherwise} \end{cases}$$

f a flow & p an aug path of cap c_p , then f' also a valid flow.

Proof (Capacity constraints):

$(u,v), (v,u)$ not on path: no change

(u,v) on path:

$$\begin{aligned} f'(u,v) &= f(u,v) + c_p & f'(v,u) &= f(v,u) - c_p \\ &\leq f(u,v) + c_f(u,v) && < f(v,u) \\ &= f(u,v) + c(u,v) - f(u,v) && \leq c(v,u) \\ &= c(u,v) \end{aligned}$$

Residual Capacity:
 $0 < c_p \leq c_f(u,v) = c(u,v) - f(u,v)$
 Cap Constraints:
 $-c(v,u) \leq f(u,v) \leq c(u,v)$

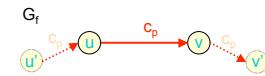
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Lemma 1' Example – Case 1

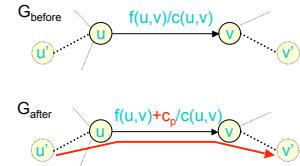
Let (u,v) be any edge in augmenting path. Note

$$c_f(u,v) = c(u,v) - f(u,v) \geq c_p > 0$$

Case 1: $f(u,v) \geq 0$:



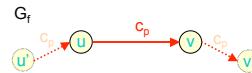
Add forward flow



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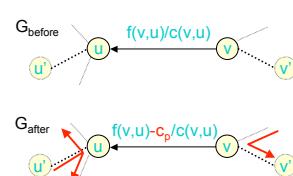
Lemma 1' Example – Case 2

Let (u,v) be any edge in augmenting path. Note
 $c_f(u,v) = c(u,v) - f(u,v) \geq c_p > 0$



Case 2: $f(u,v) \leq -c_p$:
 $f(v,u) = -f(u,v) \geq c_p$

Cancel/redirect reverse flow



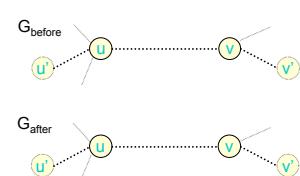
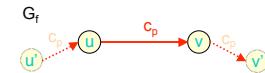
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Lemma 1' Example – Case 3

Let (u,v) be any edge in augmenting path. Note
 $c_f(u,v) = c(u,v) - f(u,v) \geq c_p > 0$

Case 3: $-c_p < f(u,v) < 0$:

???



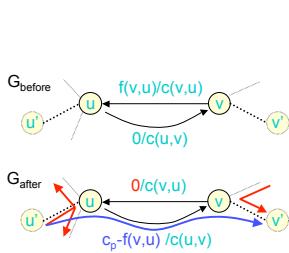
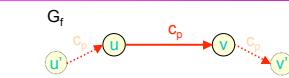
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Lemma 1' Example – Case 3

Let (u,v) be any edge in augmenting path. Note
 $g_f(u,v) = c(u,v) - f(u,v) \geq c_p > 0$

Case 3: $-c_p < f(u,v) < 0$
 $c_p > f(v,u) > 0$:

Both:
cancel/redirect
reverse flow
and
add forward flow



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Ford-Fulkerson Method

While G_f has an augmenting path,
augment

Questions:

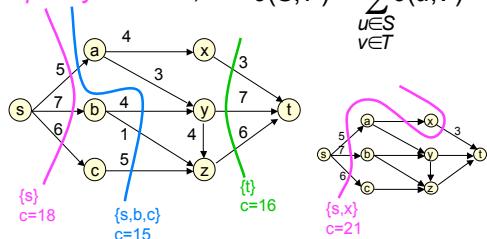
- » Does it halt?
- » Does it find a maximum flow?
- » How fast?

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Cuts

- A partition S, T of V is a **cut** if $s \in S, t \in T$

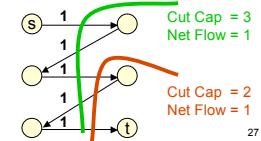
- **Capacity** of cut S, T is $c(S, T) = \sum_{u \in S} \sum_{v \in T} c(u, v)$



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Lemma 2

- For any flow f and any cut S, T ,
 - the net flow across the cut equals the total flow, i.e., $|f| = f(S, T)$, and
 - the net flow across the cut cannot exceed the capacity of the cut, i.e. $f(S, T) \leq c(S, T)$
- Corollary:
 $\text{Max flow} \leq \text{Min cut}$



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Max Flow / Min Cut Theorem

For any flow f , the following are equivalent

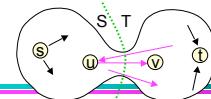
- (1) $|f| = c(S, T)$ for some cut S, T (a min cut)
- (2) f is a maximum flow
- (3) f admits no augmenting path

Proof:

- (1) \Rightarrow (2): corollary to lemma 2
- (2) \Rightarrow (3): contrapositive of lemma 1

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$$(3) \Rightarrow (1)$$



$$S = \{ u \mid \exists \text{ an augmenting path wrt } f \text{ from } s \text{ to } u \}$$

$$T = V - S; s \in S, t \in T$$

For any (u, v) in $S \times T$, \exists an augmenting path from s to u , but **not** to v .

$\therefore (u, v)$ has 0 residual capacity:

$$(u, v) \in E \Rightarrow \text{saturated} \quad f(u, v) = c(u, v)$$

$$(v, u) \in E \Rightarrow \text{no flow} \quad f(u, v) = 0 = -f(v, u)$$

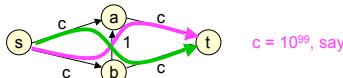
This is true for every edge crossing the cut, i.e.

$$|f| = f(S, T) = \sum_{u \in S} \sum_{v \in T} f(u, v) = \sum_{u \in S, v \in T, (u, v) \in E} f(u, v) = \sum_{u \in S, v \in T, (u, v) \in E} c(u, v) = c(S, T) \quad 29$$

Idea: where's bottleneck

Corollaries & Facts

- If Ford-Fulkerson terminates, then it's found a max flow.
- It will terminate if $c(e)$ integer or rational (but may not if they're irrational).
- However, may take exponential time, even with integer capacities:



$c = 10^{99}$, say

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Edmonds-Karp Algorithm

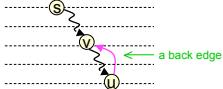
- Use a **shortest** augmenting path (via Breadth First Search in residual graph)
- Time: $O(n m^2)$

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BFS/Shortest Path Lemmas

Distance from s is never reduced by:

- Deleting an edge
proof: no new (hence no shorter) path created
- Adding an edge (u,v) , provided v is nearer than u
proof: BFS is unchanged, since v visited before (u,v) examined



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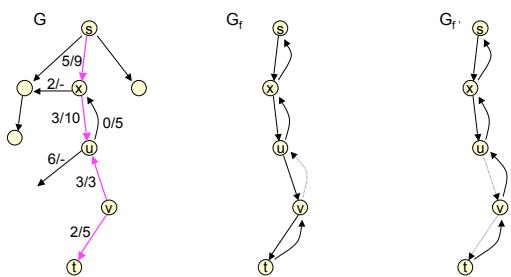
Lemma 3

Let f be a flow, G_f the residual graph, and p a shortest augmenting path. Then no vertex is closer to s after augmentation along p .

Proof: Augmentation only deletes edges, adds back edges

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Augmentation vs BFS



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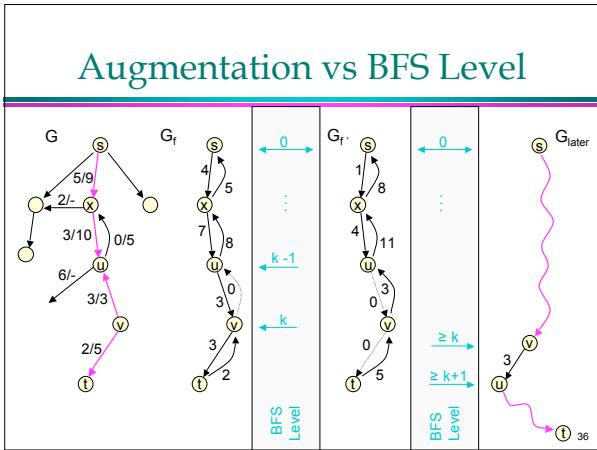
Theorem 2

The Edmonds-Karp Algorithm performs $O(mn)$ flow augmentations

Proof:

$\{u,v\}$ is critical on augmenting path p if it's closest to s having min residual capacity. Won't be critical again until farther from s . So each edge critical at most n times.

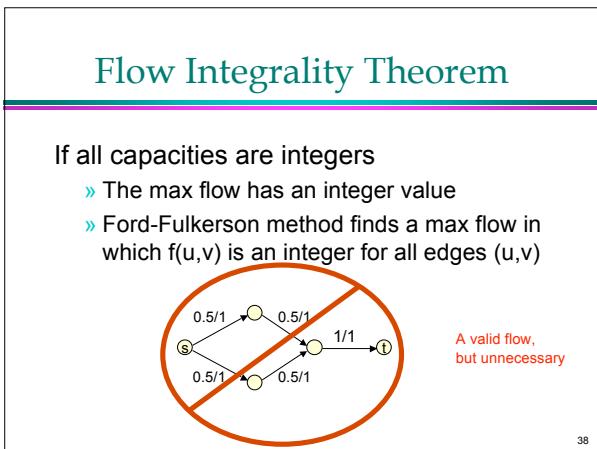
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Corollary

Edmonds-Karp runs in $O(nm^2)$

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Bipartite Maximum Matching

Bipartite Graphs:

- $G = (V, E)$
- $V = L \cup R$ ($L \cap R = \emptyset$)
- $E \subseteq L \times R$

Matching:

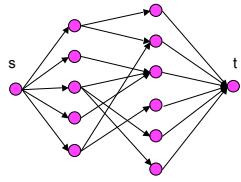
- A set of edges $M \subseteq E$ such that no two edges touch a common vertex

Problem:

- Find a matching M of maximum size

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Reducing Matching to Flow



Given bipartite G , build flow network N as follows:

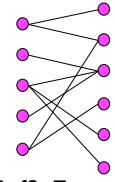
- Add source s , sink t
- Add edges $s \rightarrow L$
- Add edges $R \rightarrow t$
- All edge capacities 1

Theorem:
Max flow iff
max matching

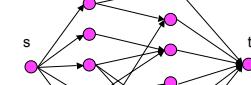
40

Reducing Matching to Flow

Theorem: Max matching size = max flow value



$M \rightarrow f?$ Easy – send flow only through M
 $f \rightarrow M?$ Flow integrality Thm, + cap constraints



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Notes on Matching

- Max Flow Algorithm is probably overly general here
- But most direct matching algorithms use "augmenting path" type ideas similar to that in max flow – See text & homework
- Time $mn^{1/2}$ possible via Edmonds-Karp

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