CSE 421: Introduction to Algorithms

Complexity and Representative Problems

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Measuring efficiency: The RAM model

- RAM = Random Access Machine
- Time ≈ # of instructions executed in an ideal assembly language
  - each simple operation (+,*,-,=,if,call) takes one time step
  - each memory access takes one time step

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Complexity analysis

- Problem size N
  - **Worst-case complexity**: **max** # steps algorithm takes on any input of size **N**
  - **Best-case complexity:** **min** # steps algorithm takes on any input of size **N**
  - **Average-case complexity**: **avg** # steps algorithm takes on inputs of size **N**

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Stable Matching

- Problem size
  - $N=2n^2$ words
    - $2n$ people each with a preference list of length n
  - $2n^2 \log n$ bits
    - specifying an ordering for each preference list takes $n\log n$ bits
- Brute force algorithm
  - Try all $n!$ possible matchings
- Gale-Shapley Algorithm
  - n^2 iterations, each costing constant time
    - For each man an array listing the women in preference order
    - For each woman an array listing the preferences indexed by the names of the men
    - An array listing the current partner (if any) for each woman
    - An array listing the preference index of the last woman each man proposed to (if any)

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Complexity

- The complexity of an algorithm associates a number **T(N)**, the best/worst/average-case time the algorithm takes, with each problem size **N**.
- Mathematically,
  - **T** is a function that maps positive integers giving problem size to positive real numbers giving number of steps.

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Efficient = Polynomial Time

- Polynomial time
  - Running time $T(N) \le cN^k+d$ for some $c,d,k>0$
- Why polynomial time?
  - If problem size grows by at most a constant factor then so does the running time
    - E.g. $T(2N) \le c(2N)^k+d \le 2^k(cN^k+d)$
    - Polynomial-time is exactly the set of running times that have this property
  - Typical running times are small degree polynomials, mostly less than N^3, at worst N^6, not N^{100}

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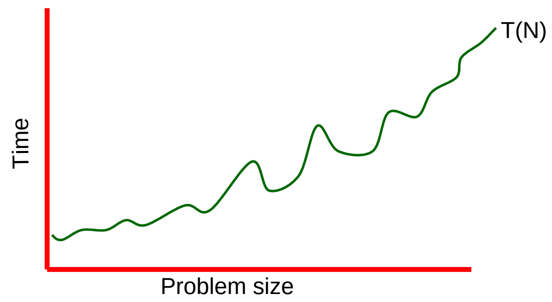
Complexity

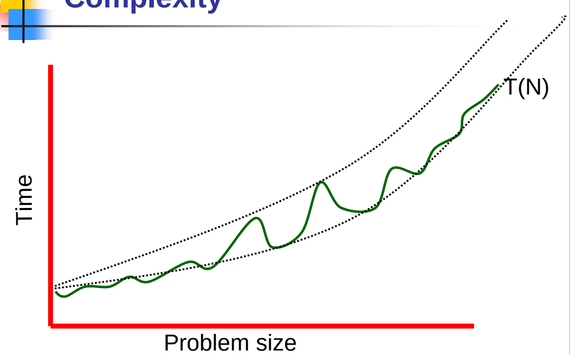


O-notation etc

- Given two positive functions **f** and **g**
  - **f(N)** is **O(g(N))** iff there is a constant **c>0** so that **f(N)** is eventually always **≤ c g(N)**
  - **f(N)** is **o(g(N))** iff the ratio **f(N)/g(N)** goes to **0** as **N** gets large
  - **f(N)** is **Ω(g(N))** iff there is a constant **ε>0** so that **f(N)** is **≥ ε g(N)** for infinitely many values of **N**
  - **f(N)** is **Θ(g(N))** iff **f(N)** is **O(g(N))** and **f(N)** is **Ω(g(N))**

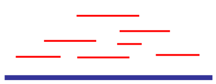
Note: The definition of **Ω** is the same as "f(N) is **not** o(g(N))"

Complexity



5 Representative Problems

- Interval Scheduling
  - Single resource
  - Reservation requests
    - Of form "Can I reserve it from start time **s** to finish time **f**?"
    - **s < f**
  - **Find:** maximum number of requests that can be scheduled so that no two reservations have the resource at the same time



Interval scheduling

- Formally
  - Requests **1,2,…,n**
    - request **i** has start time s_i and finish time $f_i > s_i$
  - Requests **i** and **j** are **compatible** iff either
    - request **i** is for a time entirely before request **j**
      - $f_i \leq s_j$
    - or, request **j** is for a time entirely before request **i**
      - $f_j \leq s_i$
  - Set **A** of requests is **compatible** iff every pair of requests **i,j∈ A, i≠j** is compatible
  - Goal: Find maximum size subset **A** of compatible requests

Interval Scheduling

- We shall see that an optimal solution can be found using a "greedy algorithm"
  - Myopic kind of algorithm that seems to have no look-ahead
  - These algorithms only work when the problem has a special kind of structure
  - When they do work they are typically very efficient

Weighted Interval Scheduling

- Same problem as interval scheduling except that each request **i** also has an associated value or weight $\mathbf{w_i}$
  - $\mathbf{w_i}$ might be
    - amount of money we get from renting out the resource for that time period
    - amount of time the resource is being used
- Goal: Find compatible subset **A** of requests with maximum total weight

Weighted Interval Scheduling

- Ordinary interval scheduling is a special case of this problem
  - Take all $\mathbf{w_i = 1}$
- Problem is quite different though
  - E.g. one weight might dwarf all others
- "Greedy algorithms" don't work
- Solution: "Dynamic Programming"
  - builds up optimal solutions from smaller problems using a compact table to store them

Bipartite Matching

- A graph G=(V,E) is bipartite iff
  - **V** consists of two disjoint pieces **X** and **Y** such that every edge **e** in **E** is of the form (**x**,**y**) where $\mathbf{x \in X}$ and $\mathbf{y \in Y}$
  - Similar to stable matching situation but in that case all possible edges were present
- $\mathbf{M \subseteq E}$ is a matching in **G** iff no two edges in **M** share a vertex
  - Goal: Find a matching **M** in **G** of maximum possible size

Bipartite Matching

- Models assignment problems
  - **X** represents jobs, **Y** represents machines
  - **X** represents professors, **Y** represents courses
- If **|X|=|Y|=n**
  - **G** has perfect matching iff maximum matching has size **n**
- **Solution:** polynomial-time algorithm using "augmentation" technique
  - also used for solving more general class of network flow problems

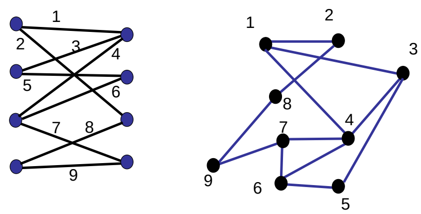
Independent Set

- Given a graph **G**=(**V**,**E**)
  - A set $\mathbf{I \subseteq V}$ is independent iff no two nodes in **I** are joined by an edge
- Goal: Find an independent subset **I** in **G** of maximum possible size
- Models conflicts and mutual exclusion

Independent Set

- Generalizes
  - Interval Scheduling
    - Vertices in the graph are the requests
    - Vertices are joined by an edge if they are **not** compatible
  - Bipartite Matching
    - Given bipartite graph **G**=(**V**,**E**) create new graph **G'**=(**V'**,**E'**) where
      - **V'=E**
      - Two elements of **V'** (which are edges in **G**) are joined if they share an endpoint in **G**

Bipartite Matching vs Independent Set



G=(U∪V,E)

G'=(V',E')

Independent Set

- No polynomial-time algorithm is known
  - But to convince someone that there was a large independent set all you'd need to do is show it to them
    - they can easily convince themselves that the set is large enough and independent
  - Convincing someone that there isn't one seems much harder
- We will show that Independent Set is NP-complete
  - Class of all the hardest problems that have the property above

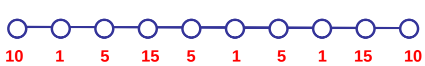
Competitive Facility Location

- Two players competing for market share in a geographic area
  - e.g. McDonald's, Burger King
- Rules:
  - Region is divided into **n** zones, **1**,…,**n**
  - Each zone **i** has a value b_i
    - Revenue derived from opening franchise in that zone
  - No adjacent zones may contain a franchise
    - i.e., zoning regulations limit density
  - Players alternate opening franchises
- Find: Given a target total value **B** is there a strategy for the second player that always achieves ≥ **B**?

Competitive Facility Location

- Model geography by
  - A graph **G**=(**V**,**E**) where
    - **V** is the set {**1**,…,**n**} of zones
    - **E** is the set of pairs (**i**,**j**) such that **i** and **j** are adjacent zones
- Observe:
  - The set of zones with franchises will form an independent set in **G**

Competitive Facility Location



Target **B** = **20** achievable ?

What about **B** = **25** ?

Competitive Facility Location

- Checking that a strategy is good seems hard
  - You'd have to worry about all possible responses at each round!
    - a giant search tree of possibilities
- Problem is PSPACE-complete
  - Likely strictly harder than NP-complete problems
  - PSPACE-complete problems include
    - Game-playing problems such as **n**×**n** chess and checkers
    - Logic problems such as whether quantified boolean expressions are always true
    - Verification problems for finite automata