

# CSE 421: Introduction to Algorithms

## Network Flow

Paul Beame

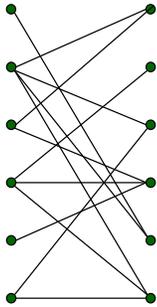
1

## Bipartite Matching

- Given: A bipartite graph  $G=(V,E)$ 
  - $M \subseteq E$  is a matching in  $G$  iff no two edges in  $M$  share a vertex
- Goal: Find a matching  $M$  in  $G$  of maximum possible size

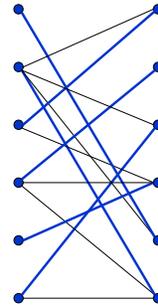
2

## Bipartite Matching



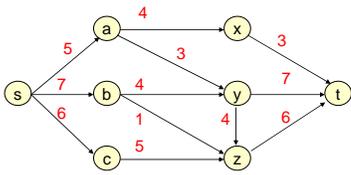
3

## Bipartite Matching



4

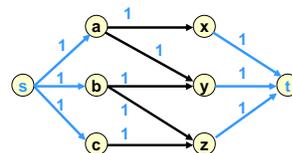
## The Network Flow Problem



- How much stuff can flow from  $s$  to  $t$ ?

5

## Bipartite matching as a special case of flow



6

## Net Flow: Formal Definition

**Given:**

- A digraph  $G = (V, E)$
- Two vertices  $s, t$  in  $V$  (source & sink)
- A **capacity**  $c(u, v) \geq 0$  for each  $(u, v) \in E$  (and  $c(u, v) = 0$  for all non-edges  $(u, v)$ )

**Find:**

- A **flow function**  $f: E \rightarrow \mathbb{R}$  s.t., for all  $u, v$ :
  - $0 \leq f(u, v) \leq c(u, v)$  [Capacity Constraint]
  - if  $u \neq s, t$ , i.e.  $f^{out}(u) = f^{in}(u)$  [Flow Conservation]
- Maximizing total flow  $v(f) = f^{out}(s)$

**Notation:**

$$f^{in}(v) = \sum_{e=(u,v) \in E} f(u, v) \quad f^{out}(v) = \sum_{e=(v,w) \in E} f(v, w)$$

## Example: A Flow Function

$f^{in}(u) = f(s, u) = 2 = f(u, t) = f^{out}(u)$

## Example: A Flow Function

- Not shown:  $f(u, v) = 0$
- Note: **max flow**  $\geq 4$  since  $f$  is a flow function, with  $v(f) = 4$

## Max Flow via a Greedy Alg?

While there is an  $s \rightarrow t$  path in  $G$

- Pick such a path,  $p$
- Find  $c$ , the min capacity of any edge in  $p$
- Subtract  $c$  from all capacities on  $p$
- Delete edges of capacity 0

This does **NOT** always find a max flow:

If pick  $s \rightarrow b \rightarrow a \rightarrow t$  first, flow stuck at 2. But flow 3 possible.

## A Brief History of Flow

#	year	discoverer(s)	bound
1	1951	Dantzig	$O(n^2 m U)$
2	1955	Ford & Fulkerson	$O(nmU)$
3	1950	Dinitz	$O(nm^2)$
4	1970	Edmonds & Karp	$O(n^2 m)$
5	1972	Dinitz	$O(n^2 \log U)$
6	1973	Dinitz	$O(nm \log U)$
7	1974	Gabow	$O(n^3)$
8	1974	Cherkassky	$O(n^2 \sqrt{m})$
9	1980	Gall & Naamad	$O(nm \log^2 n)$
10	1983	Sincor & Tajan	$O(nm \log n)$
11	1986	Goldberg & Rajan	$O(nm \log^2(m))$
12	1987	Ahuja & Orlin	$O(nm + n^2 \log U)$
13	1987	Ahuja et al.	$O(nm \log(n \log U / (m+2)))$
14	1989	Cheriyani & Hagerup	$O(nm + n^2 \log^2 n)$
15	1990	Cheriyani et al.	$O(n^2 \log n)$
16	1990	Ailon	$O(nm + n^{3/2} \log n)$
17	1992	King et al.	$O(nm + n^{1.5})$
18	1993	Phillips & Westbrook	$O(nm \log_{1.5}(n \log n))$
19	1994	King et al.	$O(nm \log_{1.5}(n \log n))$
20	1997	Goldberg & Rao	$O(n^{3/2} \log(n^2/m) \log U)$
			$O(n^{3/2} m \log(n^2/m) \log U)$

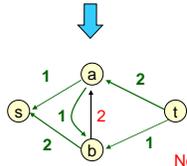
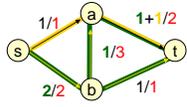
$n = \#$  of vertices  
 $m = \#$  of edges  
 $U =$  Max capacity

Source: Goldberg & Rao, FOCS '97

## Greedy Revisited: Residual Graph & Augmenting Path

Residual Graph

## Greedy Revisited: An Augmenting Path

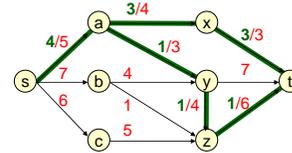


New Residual Graph

13

## Residual Capacity

- The *residual capacity* (w.r.t.  $f$ ) of  $(u,v)$  is  $c_f(u,v) = c(u,v) - f(u,v)$  if  $f(u,v) \leq c(u,v)$  and  $c_f(u,v) = f(v,u)$  if  $f(v,u) > 0$



- e.g.  $c_f(s,b)=7$ ;  $c_f(a,x) = 1$ ;  $c_f(x,a) = 3$

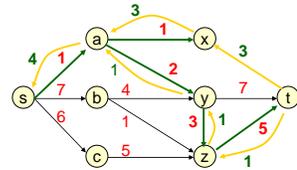
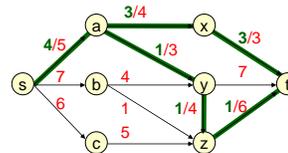
14

## Residual Graph & Augmenting Paths

- The *residual graph* (w.r.t.  $f$ ) is the graph  $G_f = (V, E_f)$ , where  $E_f = \{ (u,v) \mid c_f(u,v) > 0 \}$ 
  - Two kinds of edges
    - Forward edges
      - $f(u,v) < c(u,v)$  so  $c_f(u,v) = c(u,v) - f(u,v) > 0$
    - Backward edges
      - $f(u,v) > 0$  so  $c_f(v,u) = -f(v,u) = f(u,v) > 0$
  - An *augmenting path* (w.r.t.  $f$ ) is a simple  $s \rightarrow t$  path in  $G_f$ .

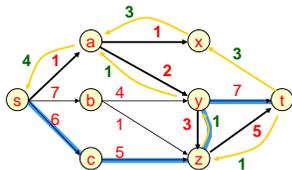
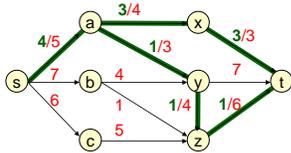
15

## A Residual Network



16

## An Augmenting Path



17

## Augmenting A Flow

augment( $f, P$ )

$c_p \leftarrow \min_{(u,v) \in P} c_f(u,v)$  "bottleneck( $P$ )"

for each  $e \in P$

if  $e$  is a forward edge then

increase  $f(e)$  by  $c_p$

else ( $e$  is a backward edge)

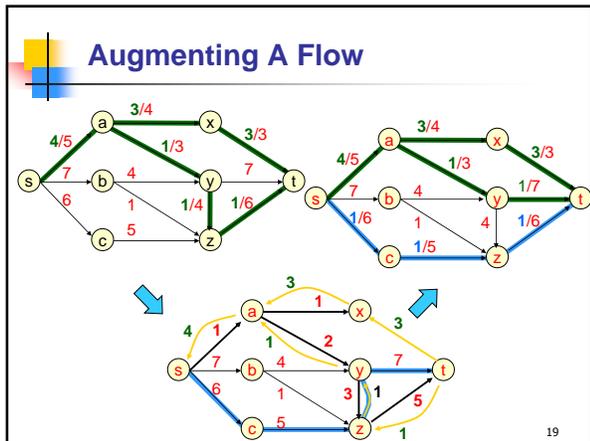
decrease  $f(e)$  by  $c_p$

endif

endfor

return( $f$ )

18



19

### Claim 7.1

If  $G_f$  has an augmenting path  $P$ , then the function  $f' = \text{augment}(f, P)$  is a legal flow.

**Proof:**

- $f'$  and  $f$  differ only on the edges of  $P$  so only need to consider such edges  $(u, v)$

20

### Proof of Claim 7.1

- If  $(u, v)$  is a forward edge then
 
$$f'(u, v) = f(u, v) + c_p \leq f(u, v) + c_f(u, v) = f(u, v) + c(u, v) - f(u, v) = c(u, v)$$
- If  $(u, v)$  is a backward edge then  $f$  and  $f'$  differ on flow along  $(v, u)$  instead of  $(u, v)$ 

$$f'(v, u) = f(v, u) - c_p \geq f(v, u) - c_f(u, v) = f(v, u) - f(v, u) = 0$$
- Other conditions like flow conservation still met

21

### Ford-Fulkerson Method

Start with  $f=0$  for every edge

While  $G_f$  has an augmenting path, augment

- Questions:**
  - Does it halt?
  - Does it find a maximum flow?
  - How fast?

22

### Observations about Ford-Fulkerson Algorithm

- At every stage the capacities and flow values are always integers (if they start that way)
- The flow value  $v(f') = v(f) + c_p > v(f)$  for  $f' = \text{augment}(f, P)$ 
  - Since edges of residual capacity 0 do not appear in the residual graph
- Let  $C = \sum_{(s, u) \in E} c(s, u)$ 
  - $v(f) \leq C$
  - F-F** does at most  $C$  rounds of augmentation since flows are integers and increase by at least 1 per step

23

### Running Time of Ford-Fulkerson

- For  $f=0$ ,  $G_f = G$
- Finding an augmenting path in  $G_f$  is graph search  $O(n+m) = O(m)$  time
- Augmenting and updating  $G_f$  is  $O(n)$  time
- Total  $O(mC)$  time
- Does it find a maximum flow?**
  - Need to show that for every flow  $f$  that isn't maximum  $G_f$  contains an  $s$ - $t$ -path

24

### Cuts

- A partition  $(A,B)$  of  $V$  is an  $s$ - $t$ -cut if
  - $s \in A, t \in B$
- Capacity of cut  $(A,B)$  is  $c(A,B) = \sum_{\substack{u \in A \\ v \in B}} c(u,v)$

25

### Convenient Definition

- $f^{out}(A) = \sum_{v \in A, w \notin A} f(v,w)$
- $f^{in}(A) = \sum_{v \in A, u \notin A} f(u,v)$

26

### Claims 7.6 and 7.8

- For any flow  $f$  and any cut  $(A,B)$ ,
  - the net flow across the cut equals the total flow, i.e.,  $v(f) = f^{out}(A) - f^{in}(A)$ , and
  - the net flow across the cut cannot exceed the capacity of the cut, i.e.  $f^{out}(A) - f^{in}(A) \leq c(A,B)$
- Corollary :**  
Max flow  $\leq$  Min cut

27

### Proof of Claim 7.6

- Consider a set  $A$  with  $s \in A, t \notin A$
- $f^{out}(A) - f^{in}(A) = \sum_{v \in A, w \notin A} f(v,w) - \sum_{v \in A, u \notin A} f(u,v)$
- We can add flow values for edges with both endpoints in  $A$  to **both** sums and they would cancel out so
- $f^{out}(A) - f^{in}(A) = \sum_{v \in A, w \in V} f(v,w) - \sum_{v \in A, u \in V} f(u,v)$   
 $= \sum_{v \in A} (\sum_{w \in V} f(v,w) - \sum_{u \in V} f(u,v))$   
 $= \sum_{v \in A} f^{out}(v) - f^{in}(v)$   
 $= f^{out}(s) - f^{in}(s)$
- since all other vertices have  $f^{out}(v) = f^{in}(v)$
- $v(f) = f^{out}(s)$  and  $f^{in}(s) = 0$

28

### Proof of Claim 7.8

- $v(f) = f^{out}(A) - f^{in}(A)$   
 $\leq f^{out}(A)$   
 $= \sum_{v \in A, w \notin A} f(v,w)$   
 $\leq \sum_{v \in A, w \notin A} c(v,w)$   
 $\leq \sum_{v \in A, w \in B} c(v,w)$   
 $= c(A,B)$

29

### Max Flow / Min Cut Theorem

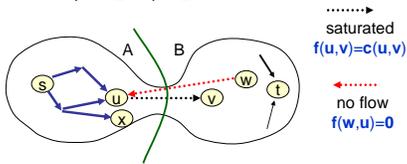
**Claim 7.9** For any flow  $f$ , if  $G_f$  has no augmenting path then there is some  $s$ - $t$ -cut  $(A,B)$  such that  $v(f) = c(A,B)$  (proof on next slide)

- We know by Claims 7.6 & 7.8 that any flow  $f'$  satisfies  $v(f') \leq c(A,B)$  and we know that F-F runs for finite time until it finds a flow  $f$  satisfying conditions of Claim 7.9
  - Therefore by 7.9 for any flow  $f', v(f') \leq v(f)$
- Corollary (1)** F-F computes a maximum flow in  $G$
- (2)** For any graph  $G$ , the value  $v(f)$  of a maximum flow = minimum capacity  $c(A,B)$  of any  $s$ - $t$ -cut in  $G$

30

### Claim 7.9

Let  $A = \{ u \mid \exists \text{ an path in } G_f \text{ from } s \text{ to } u \}$   
 $B = V - A$ ;  $s \in A$ ,  $t \in B$

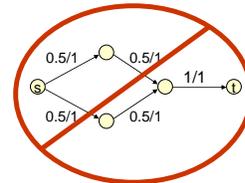


This is true for **every** edge crossing the cut, i.e.  
 $f^{out}(A) = \sum_{u \in A} f(u,v) = \sum_{u \in A} c(u,v) = c(A,B)$  and  $f^{in}(A)=0$  so  
 $v(f) = f^{out}(A) - f^{in}(A) = c(A,B)$

### Flow Integrality Theorem

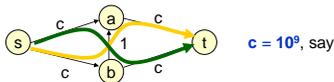
If all capacities are integers

- The max flow has an integer value
- Ford-Fulkerson method finds a max flow in which  $f(u,v)$  is an integer for all edges  $(u,v)$

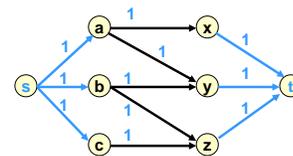


### Corollaries & Facts

- If Ford-Fulkerson terminates, then it's found a max flow.
- It will terminate if  $c(e)$  integer or rational (but may not if they're irrational).
- However, may take exponential time, even with integer capacities:



### Bipartite matching as a special case of flow



Integer flows implies each flow is just a subset of the edges

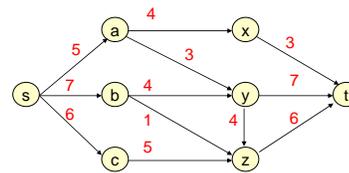
Therefore flow corresponds to a matching

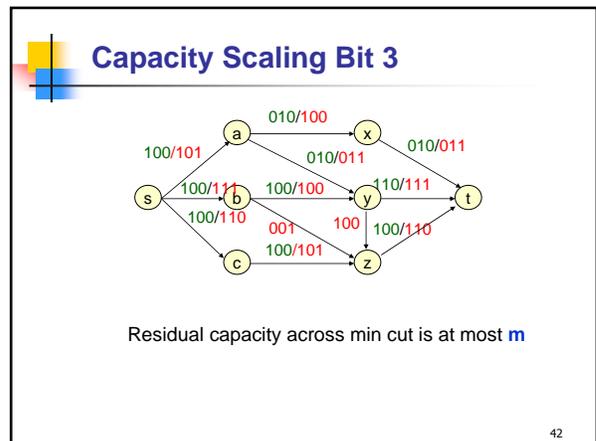
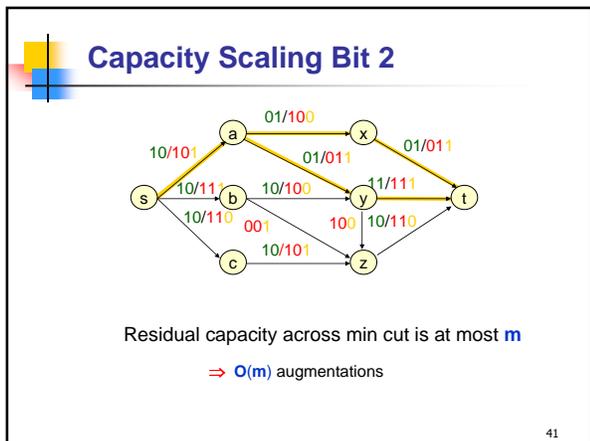
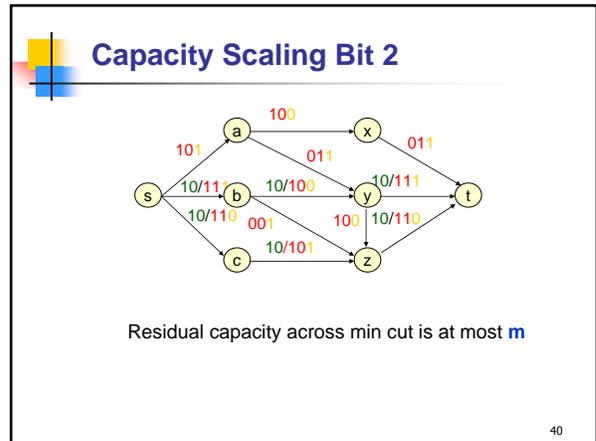
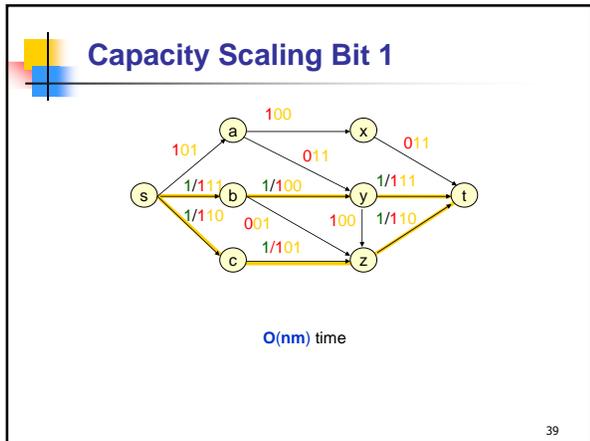
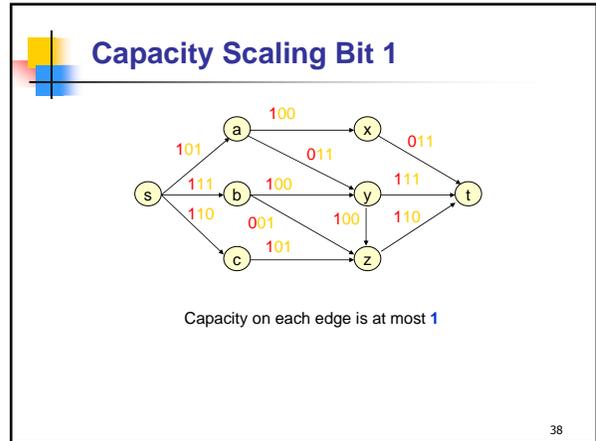
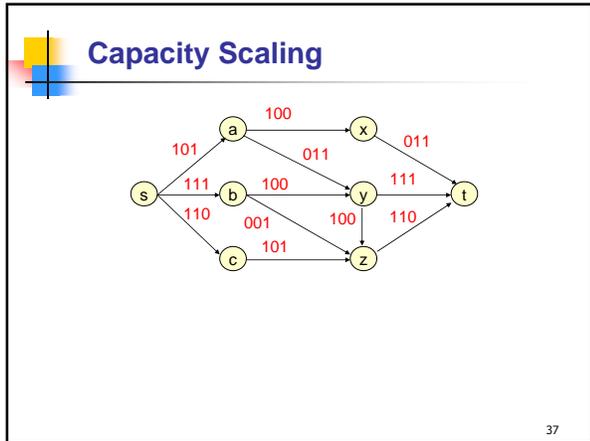
$O(mC) = O(nm)$  running time

### Capacity-scaling algorithm

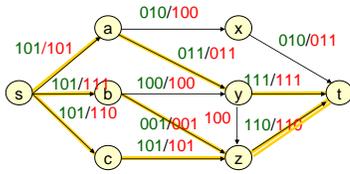
- General idea:
  - Choose augmenting paths  $P$  with 'large' capacity  $c_P$
  - Can augment flows along a path  $P$  by any amount  $b \leq c_P$ 
    - Ford-Fulkerson still works
  - Get a flow that is maximum for the high-order bits first and then add more bits later

### Capacity Scaling





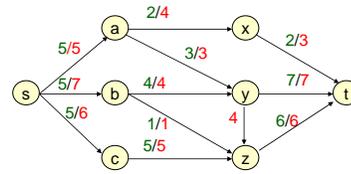
### Capacity Scaling Bit 3



After  $O(m)$  augmentations

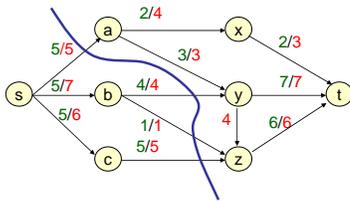
43

### Capacity Scaling Final



44

### Capacity Scaling Min Cut



45

### Total time for capacity scaling

- $\log_2 U$  rounds where  $U$  is largest capacity
- At most  $m$  augmentations per round
  - Let  $c_i$  be the capacities used in the  $i^{\text{th}}$  round and  $f_i$  be the maxflow found in the  $i^{\text{th}}$  round
    - For any edge  $(u,v)$ ,  $c_{i+1}(u,v) \leq 2c_i(u,v)+1$
  - $i+1^{\text{st}}$  round starts with flow  $f = 2 f_i$
  - Let  $(A, B)$  be a min cut from the  $i^{\text{th}}$  round
    - $v(f_i) = c_i(A, B)$  so  $v(f) = 2c_i(A, B)$
    - $v(f_{i+1}) \leq c_{i+1}(A, B) \leq 2c_i(A, B) + m = v(f) + m$
- $O(m)$  time per augmentation
- Total time  $O(m^2 \log U)$

46

### Edmonds-Karp Algorithm

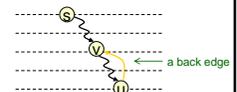
- Use a **shortest** augmenting path (via Breadth First Search in residual graph)
- Time:  $O(n m^2)$

47

### BFS/Shortest Path Lemmas

Distance from  $s$  in  $G_f$  is never reduced by:

- **Deleting** an edge  
Proof: no new (hence no shorter) path created
- **Adding** an edge  $(u,v)$ , provided  $v$  is nearer than  $u$   
Proof: BFS is unchanged, since  $v$  visited before  $(u,v)$  examined



48

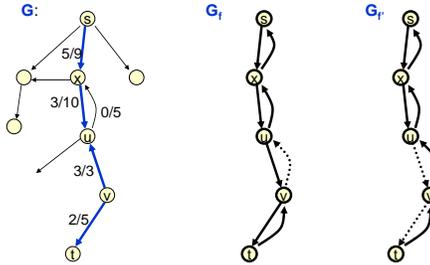
## Key Lemma

Let  $f$  be a flow,  $G_f$  the residual graph, and  $P$  a shortest augmenting path. Then no vertex is closer to  $s$  after augmentation along  $P$ .

**Proof:** Augmentation along  $P$  only deletes forward edges, or adds back edges that go to previous vertices along  $P$

49

## Augmentation vs BFS



50

## Theorem

The Edmonds-Karp Algorithm performs  $O(mn)$  flow augmentations

Proof:

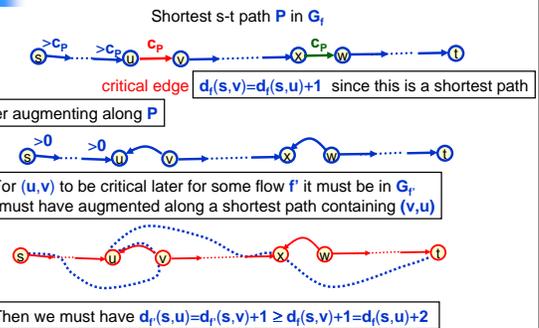
Call  $(u,v)$  **critical** for augmenting path  $P$  if it's closest to  $s$  having min residual capacity  
It will disappear from  $G_f$  after augmenting along  $P$

In order for  $(u,v)$  to be critical again the  $(u,v)$  edge must re-appear in  $G_f$  but that will only happen when the distance to  $u$  has increased by 2 (next slide)

It won't be critical again until farther from  $s$  so each edge critical at most  $n/2$  times

51

## Critical Edges in $G_f$



52

## Corollary

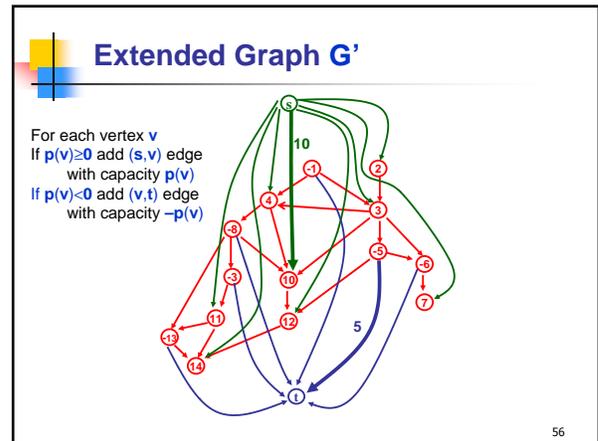
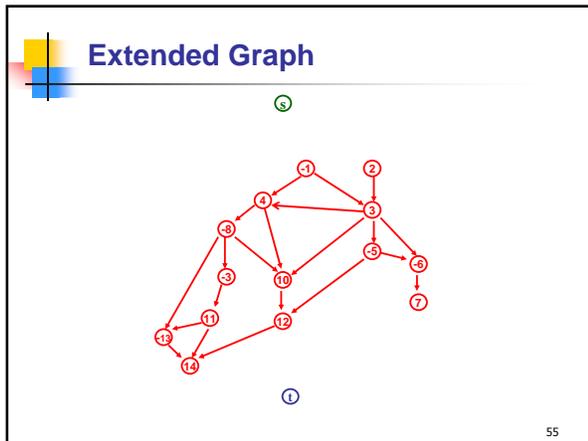
- Edmonds-Karp runs in  $O(nm^2)$  time

53

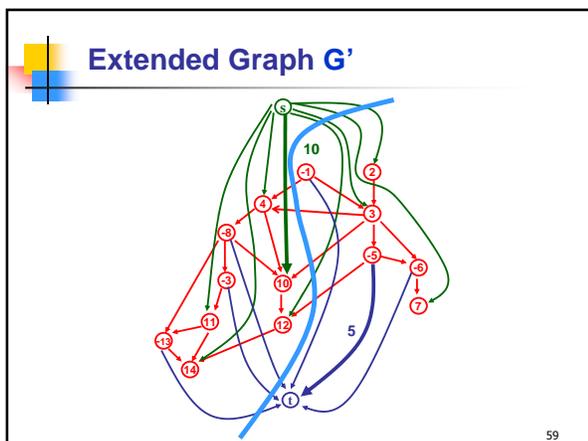
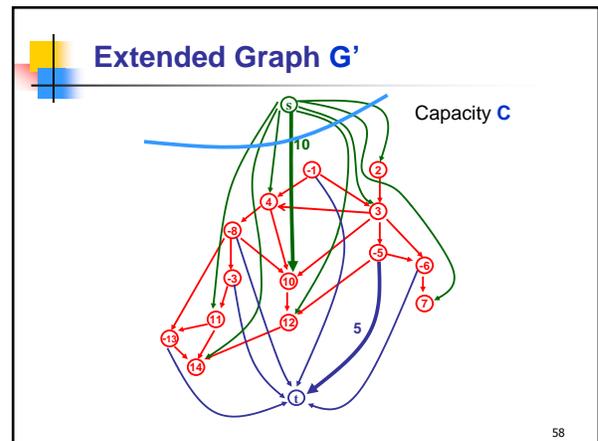
## Project Selection a.k.a. The Strip Mining Problem

- Given**
  - a directed acyclic graph  $G=(V,E)$  representing precedence constraints on tasks (a task points to its predecessors)
  - a profit value  $p(v)$  associated with each task  $v \in V$  (may be positive or negative)
- Find**
  - a set  $A \subseteq V$  of tasks that is closed under predecessors, i.e. if  $(u,v) \in E$  and  $u \in A$  then  $v \in A$ , that maximizes  $\text{Profit}(A) = \sum_{v \in A} p(v)$

54



- ### Extended Graph G'
- Want to arrange capacities on edges of  $G$  so that for minimum  $s$ - $t$ -cut  $(S, T)$  in  $G'$ , the set  $A = S - \{s\}$ 
    - satisfies precedence constraints
    - has maximum possible profit in  $G$
  - Cut capacity with  $S = \{s\}$  is just  $C = \sum_{v: p(v) > 0} p(v)$ 
    - $\text{Profit}(A) \leq C$  for any set  $A$
  - To satisfy precedence constraints don't want any original edges of  $G$  going forward across the minimum cut
    - That would correspond to a task in  $A = S - \{s\}$  that had a predecessor not in  $A = S - \{s\}$
  - Set capacity of each of these edges to  $C + 1$ 
    - The minimum cut has size at most  $C$
- 57



- ### Project Selection
- Claim** Any  $s$ - $t$ -cut  $(S, T)$  in  $G'$  such that  $A = S - \{s\}$  satisfies precedence constraints has capacity
 
$$c(S, T) = C - \sum_{v \in A} p(v) = C - \text{Profit}(A)$$
  - Corollary** A minimum cut  $(S, T)$  in  $G'$  yields an optimal solution  $A = S - \{s\}$  to the profit selection problem
  - Algorithm** Compute maximum flow  $f$  in  $G'$ , find the set  $S$  of nodes reachable from  $s$  in  $G'_f$  and return  $S - \{s\}$
- 60



## Proof of Claim

- $A=S-\{s\}$  satisfies precedence constraints
  - No edge of  $G$  crosses forward out of  $A$  by our choice of capacities
  - Only forward edges cut are of the form  $(v,t)$  for  $v \in A$  or  $(s,v)$  for  $v \notin A$
  - The  $(v,t)$  edges for  $v \in A$  contribute
$$\sum_{v \in A: p(v) < 0} -p(v) = - \sum_{v \in A: p(v) < 0} p(v)$$
  - The  $(s,v)$  edges for  $v \notin A$  contribute
$$\sum_{v \in A: p(v) > 0} p(v) = C - \sum_{v \in A: p(v) > 0} p(v)$$
  - Therefore the total capacity of the cut is
$$c(S,T) = C - \sum_{v \in A} p(v) = C - \text{Profit}(A)$$