CSE 421: Introduction to Algorithms

Dealing with NP-completeness

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What to do if the problem you want to solve is NP-hard

- You might have phrased your problem too generally
  - e.g., in practice, the graphs that actually arise are far from arbitrary
    - maybe they have some special characteristic that allows you to solve the problem in your special case
      - for example the Independent-Set problem is easy on "interval graphs"
        - Exactly the case for interval scheduling!
    - search the literature to see if special cases already solved

What to do if the problem you want to solve is NP-hard

- Try to find an approximation algorithm
  - Maybe you can't get the size of the best Vertex Cover but you can find one within a factor of **2** of the best
    - Given graph **G**=(**V**,E), start with an empty cover
    - **While** there are still edges in E left
      - **Choose** an edge **e**={**u**,**v**} in **E** and add both **u** and **v** to the cover
      - Remove all edges from **E** that touch either **u** or **v**.
    - Edges chosen don't share any vertices so optimal cover size must be at least # of edges chosen

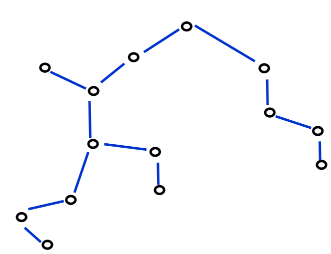
What to do if the problem you want to solve is NP-hard

- Polynomial-time approximation algorithms for **NP**-hard problems can sometimes be ruled out unless **P=NP**
  - E.g. **Coloring Problem:** Given a graph **G**=(**V**,**E**) find the smallest **k** such that **G** has a **k**-coloring.
    - No approximation ratio better than **4/3** is possible unless **P=NP**
      - Otherwise you would have to be able to figure out if a **3**-colorable graph can be colored in **< 4** colors. i.e. if it can be **3**-colored

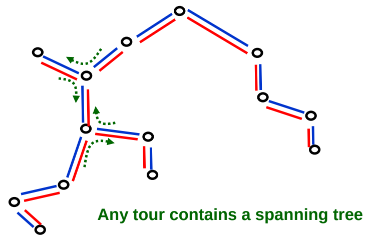
Travelling Sales Problem

- TSP
  - Given a weighted graph **G** find of a smallest weight tour that visits all vertices in **G**
- **NP**-hard
- Notoriously easy to obtain close to optimal solutions

Minimum Spanning Tree Approximation



Minimum Spanning Tree Approximation: Factor of 2

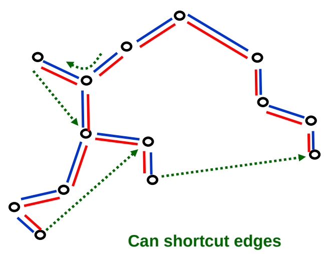


$MST(G) \leq TOUR_{OPT}(G) \leq 2\ MST(G) \leq 2\ TOUR_{OPT}(G)$

Why did this work?

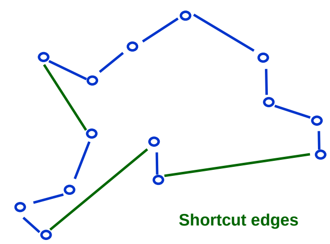
- We found an Euler tour on a graph that used the edges of the original graph (possibly repeated).
- The weight of the tour was the total weight of the new graph.
- Suppose now
  - All edges possible
  - Weights satisfy triangle inequality
    - $c(u,w) \leq c(u,v)+c(v,w)$

Minimum Spanning Tree Approximation: Triangle Inequality



Can shortcut edges
- Go to next new vertex on the Euler tour

Minimum Spanning Tree Approximation: Factor of 2

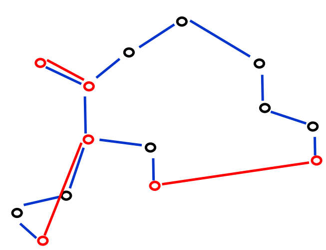


$TOUR_{OPT}(G) \leq 2\ MST(G) \leq 2\ TOUR_{OPT}(G)$

Christofides Algorithm: A factor 3/2 approximation

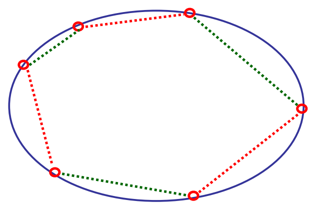
- Any Eulerian subgraph of the weighted complete graph will do
  - Eulerian graphs require that all vertices have even degree so
- Christofides Algorithm
  - Compute an MST **T**
  - Find the set **O** of odd-degree vertices in **T**
  - Add a minimum-weight perfect matching **M** on the vertices in **O** to **T** to make every vertex have even degree
    - There are an even number of odd-degree vertices!
  - Use an Euler Tour **E** in **T∪M** and then shortcut as before
- **Claim:** $TOUR_{OPT} \leq 1.5\ \mathrm{Cost}(E)$

Christofides Approximation



Christofides Approximation

Any tour costs at least the cost of two matchings on O



Claim: 2 Cost(M) ≤ TOUR_{OPT}

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Knapsack Problem

- For any $\varepsilon > 0$ can get an algorithm that gets a solution within $(1+\varepsilon)$ factor of optimal with running time $O(n^2(1/\varepsilon)^2)$
  - "Polynomial-Time Approximation Scheme" or PTAS
  - Based on maintaining just the high order bits in the dynamic programming solution.

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What to do if the problem you want to solve is NP-hard

- More on approximation algorithms
  - Recent research has classified problems based on what kinds of approximations are possible if **P≠NP**
    - Best: $(1+\varepsilon)$ factor for any $\varepsilon > 0$.
      - packing and some scheduling problems, TSP in plane
    - Some fixed constant factor > 1, e.g. **2, 3/2, 100**
      - Vertex Cover, TSP in space, other scheduling problems
    - $\Theta(\log n)$ factor
      - Set Cover, Graph Partitioning problems
    - Worst: $\Omega(n^{1-\varepsilon})$ factor for any $\varepsilon > 0$
      - Clique, Independent-Set, Coloring

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What to do if the problem you want to solve is NP-hard

- Try an algorithm that is provably fast "on average".
  - To even try this one needs a model of what a typical instance is.
  - Typically, people consider "random graphs"
    - e.g. all graphs with a given # of edges are equally likely
  - Problems:
    - real data doesn't look like the random graphs
    - distributions of real data aren't analyzable

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What to do if the problem you want to solve is NP-hard

- Try to search the space of possible hints/certificates in a more efficient way and hope it is quick enough
  - **Backtracking search**
    - E.g. For SAT there are 2^n possible truth assignments
    - If we set the truth values one-by-one we might be able to figure out whole parts of the space to avoid,
      - e.g. After setting $x_1 \leftarrow 1$, $x_2 \leftarrow 0$ we don't even need to set x_3 or x_4 to know that it won't satisfy $(\neg x_1 \vee x_2) \wedge (\neg x_2 \vee x_3) \wedge (x_4 \vee \neg x_3) \wedge (x_1 \vee \neg x_4)$
    - Related technique: **branch-and-bound**
  - Backtracking search can be very effective even with exponential worst-case time
    - For example, the best SAT algorithms used in practice are all variants on backtracking search and can solve surprisingly large problems – more later

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What to do if the problem you want to solve is NP-hard

- Use heuristic algorithms and hope they give good answers
  - No guarantees of quality
  - Many different types of heuristic algorithms

  - Many different options, especially for optimization problems, such as TSP, where we want the best solution.
    - We'll mention several on following slides

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Heuristic algorithms for NP-hard problems

- **local search** for optimization problems
  - need a notion of two solutions being neighbors
  - Start at an arbitrary solution **S**
  - While there is a neighbor **T** of **S** that is better than **S**
    - **S←T**
- Usually fast but often gets stuck in a local optimum and misses the global optimum
  - With some notions of neighbor can take a long time in the worst case

e.g., Neighboring solutions for TSP

Solution S   Solution T

Two solutions are neighbors iff there is a pair of edges you can swap to transform one to the other

Heuristic algorithms for NP-hard problems

- **randomized local search**
  - start local search several times from random starting points and take the best answer found from each point
    - **more expensive than plain local search but usually much better answers**
- **simulated annealing**
  - like local search but at each step sometimes move to a worse neighbor with some probability
    - probability of going to a worse neighbor is set to decrease with time as, presumably, solution is closer to optimal
    - helps avoid getting stuck in a local optimum but often **slow to converge** (much more expensive than randomized local search)
    - analogy with slow cooling to get to lowest energy state in a crystal (or in forging a metal)

Heuristic algorithms for NP-hard problems

- **genetic algorithms**
  - view each solution as a **string** (analogy with DNA)
  - maintain a **population of good solutions**
  - allow **random mutations** of single characters of individual solutions
  - **combine two solutions** by taking part of one and part of another (analogy with crossover in sexual reproduction)
  - get rid of solutions that have the worst values and make multiple copies of solutions that have the best values (analogy with natural selection -- survival of the fittest).
  - **little evidence that they work well and they are usually very slow**
    - **as much religion as science**

Heuristic algorithms

- **artificial neural networks**
  - based on very elementary model of human neurons
  - **Set up a circuit of artificial neurons**
    - each artificial neuron is an analog circuit gate whose computation depends on a set of **connection strengths**
  - **Train the circuit**
    - Adjust the connection strengths of the neurons by giving many positive & negative training examples and seeing if it behaves correctly
  - **The network is now ready to use**
  - **useful for ill-defined classification problems such as optical character recognition but not typical cut & dried problems**

Other directions

- DNA computing
  - **Each possible hint for an NP problem is represented as a string of DNA**
    - fill a test tube with all possible hints
  - **View verification algorithm as a series of tests**
    - e.g. checking each clause is satisfied in case of Satisfiability
  - **For each test in turn**
    - **use lab operations to filter out all DNA strings that fail the test** (**works in parallel** on all strings; uses PCR)
  - **If any string remains the answer is a YES.**
  - **Relies on fact that Avogadro's # 6×10^{23} is large to get enough strings to fit in a test-tube.**
  - **Error-prone & problem sizes typically very small!**

Other directions

- Quantum computing
  - **Use physical processes at the quantum level to implement "weird" kinds of circuit gates**
    - unitary transformations
  - **Quantum objects can be in a superposition of many pure states at once**
    - can have **n** objects together in a superposition of **2^n** states
  - **Each quantum circuit gate operates on the whole superposition of states at once**
    - inherent **parallelism** but classical randomized algorithms have a similar parallelism: **not enough on its own**
    - **Advantage over classical: parallel copies interfere with each other.**
  - **Need totally new kinds of algorithms to work well. Theoretically able to factor efficiently but huge practical problems: errors, decoherence.**