CSE 421
Algorithms

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Lecture 20

Space Efficient LCS

Longest Common Subsequence

- $C=c_1\ldots c_g$ is a subsequence of $A=a_1\ldots a_m$ if C can be obtained by removing elements from A (but retaining order)
- LCS(A, B): A maximum length sequence that is a subsequence of both A and B
- Wednesday's Result:
  - O(mn) time, O(mn) space LCS Algorithm
- Today's Result:
  - O(mn) time, O(m+n) space LCS Algorithm

Digression: String Alignment Problem

- Align sequences with gaps

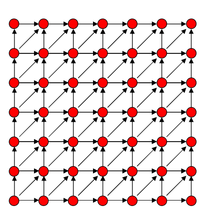
```
CAT TGA  AT

CAGAT AGGA
```

- Charge δ_x if character x is unmatched
- Charge γ_{xy} if character x is matched to character y
- Find alignment to minimize sum of costs

Optimization Recurrence for the String Alignment Problem

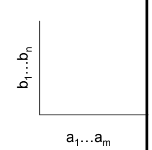
- Charge δ_x if character x is unmatched
- Charge γ_{xy} if character x is matched to character y
- $A = a_1a_2\ldots a_m$; $B = b_1b_2\ldots b_n$
- Opt[j, k] is the value of the minimum cost alignment $a_1a_2\ldots a_j$ and $b_1b_2\ldots b_k$

Dynamic Programming Computation



Storing the path information

```
A[1..m],  B[1..n]
for i := 1 to m     Opt[i, 0] := 0;
for j := 1 to n     Opt[0,j] := 0;
Opt[0,0] := 0;
for i := 1 to m
        for j := 1 to n
                if A[i] = B[j]  {  Opt[i,j] := 1 + Opt[i-1,j-1];  Best[i,j] := Diag; }
                else if Opt[i-1, j] >= Opt[i, j-1]
                        {  Opt[i, j] := Opt[i-1, j], Best[i,j] := Left; }
                else    {  Opt[i, j] := Opt[i, j-1], Best[i,j] := Down; }
```

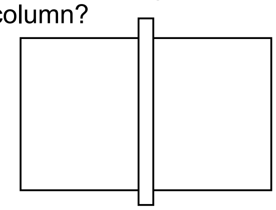


Observations about the Algorithm

- The computation can be done in O(m+n) space if we only need one column of the Opt values or Best Values
- The algorithm can be run from either end of the strings

Divide and Conquer Algorithm

- Where does the best path cross the middle column?



- For a fixed i, and for each j, compute the LCS that has a_i matched with b_j

Constrained LCS

- $LCS_{i,j}(A,B)$: The LCS such that
  - $a_1,\ldots,a_i$ paired with elements of $b_1,\ldots,b_j$
  - $a_{i+1},\ldots a_m$ paired with elements of $b_{j+1},\ldots,b_n$
- $LCS_{4,3}$(abbacbb, cbbaa)

A = RRSSRTTRTS
B=RTSRRSTST

Compute $LCS_{5,0}(A,B)$, $LCS_{5,1}(A,B)$, $LCS_{5,2}(A,B)$,…,$LCS_{5,9}(A,B)$

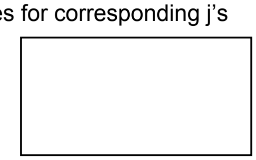
A = RRSSRTTRTS
B=RTSRRSTST

Compute $LCS_{5,0}(A,B)$, $LCS_{5,1}(A,B)$, $LCS_{5,2}(A,B)$,…,$LCS_{5,9}(A,B)$

j	left	right
0	0	3
1	1	3
2	1	3
3	2	3
4	3	3
5	3	2
6	3	2
7	3	1
8	4	1
9	4	0

Computing the middle column

- From the left, compute $LCS(a_1\ldots a_{m/2},b_1\ldots b_j)$
- From the right, compute $LCS(a_{m/2+1}\ldots a_m,b_{j+1}\ldots b_n)$
- Add values for corresponding j's



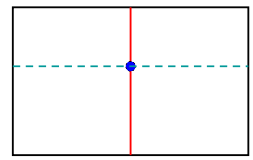
- Note – this is space efficient

Divide and Conquer

- $A = a_1,\ldots,a_m$ $B = b_1,\ldots,b_n$
- Find j such that
  - $LCS(a_1\ldots a_{m/2}, b_1\ldots b_j)$ and
  - $LCS(a_{m/2+1}\ldots a_m, b_{j+1}\ldots b_n)$ yield optimal solution
- Recurse

Algorithm Analysis

- $T(m,n) = T(m/2, j) + T(m/2, n-j) + cnm$



Prove by induction that T(m,n) <= 2cmn

Shortest Path Problem

- Dijkstra's Single Source Shortest Paths Algorithm
  - O(mlog n) time, positive cost edges
- General case – handling negative edges
- If there exists a negative cost cycle, the shortest path is not defined
- Bellman-Ford Algorithm
  - O(mn) time for graphs with negative cost edges

Lemma

- If a graph has no negative cost cycles, then the shortest paths are simple paths
- Shortest paths have at most n-1 edges

Shortest paths with a fixed number of edges

- Find the shortest path from v to w with exactly k edges

Express as a recurrence

- $Opt_k(w) = \min_x [Opt_{k-1}(x) + c_{xw}]$
- $Opt_0(w) = 0$ if v=w and infinity otherwise

Algorithm, Version 1

```
foreach w
        M[0, w] = infinity;
M[0, v] = 0;
for i = 1 to n-1
        foreach w
                M[i, w] = min_x(M[i-1,x] + cost[x,w]);
```

Algorithm, Version 2

```
foreach w
        M[0, w] = infinity;
M[0, v] = 0;
for i = 1 to n-1
        foreach w
                M[i, w] = min(M[i-1, w], min_x(M[i-1,x] + cost[x,w]))
```

Algorithm, Version 3

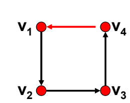
```
foreach w
        M[w] = infinity;
M[v] = 0;
for i = 1 to n-1
        foreach w
                M[w] = min(M[w], min_x(M[x] + cost[x,w]))
```

Correctness Proof for Algorithm 3

- Key lemma – at the end of iteration i, for all w, M[w] <= M[i, w];
- Reconstructing the path:
  - Set P[w] = x, whenever M[w] is updated from vertex x

If the pointer graph has a cycle, then the graph has a negative cost cycle

- If P[w] = x then M[w] >= M[x] + cost(x,w)
  - Equal after update, then M[x] could be reduced
- Let $v_1, v_2, \ldots v_k$ be a cycle in the pointer graph with (v_k, v_1) the last edge added
  - Just before the update
    - $M[v_j] >= M[v_{j+1}] + cost(v_{j+1}, v_j)$ for $j < k$
    - $M[v_k] > M[v_1] + cost(v_1, v_k)$
  - Adding everything up
    - $0 > cost(v_1,v_2) + cost(v_2,v_3) + \ldots + cost(v_k, v_1)$



Negative Cycles

- If the pointer graph has a cycle, then the graph has a negative cycle
- Therefore: if the graph has no negative cycles, then the pointer graph has no negative cycles

Finding negative cost cycles

- What if you want to find negative cost cycles?