

CSE 417 Algorithms and Complexity Autumn 2024 Lecture 29 NP-Completeness and Beyond

Announcements

- Exam practice problems on course homepage
- Final Exam: Monday, December 9, 8:30 AM

Mon, Dec 2	NP-Completeness
Wed, Dec 4	NP-Completeness
Fri, Dec 6	NP-Completeness and Beyond
Mon, Dec 9	Final Exam

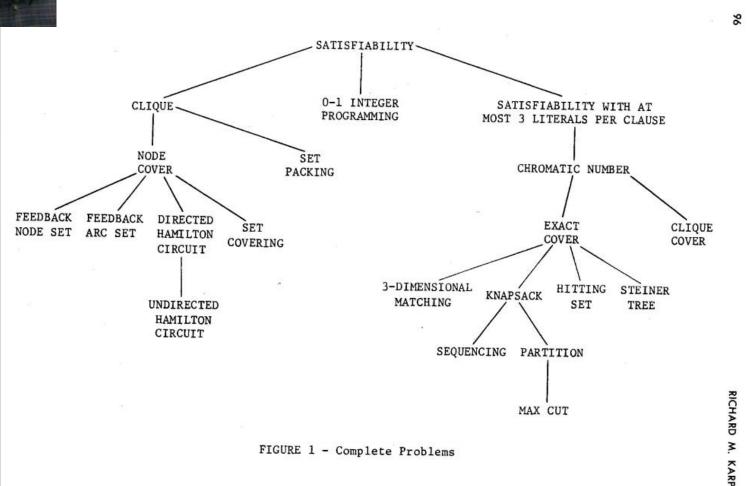
• This is my last lecture

NP-Completeness Proofs

- Prove that problem X is NP-Complete
 - Show that X is in NP (usually easy)
 - Pick a known NP complete problem Y
 - Show $Y <_P X$

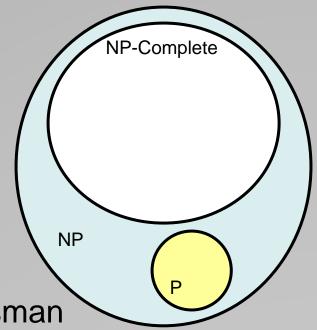


Reducibility Among Combinatorial Problems



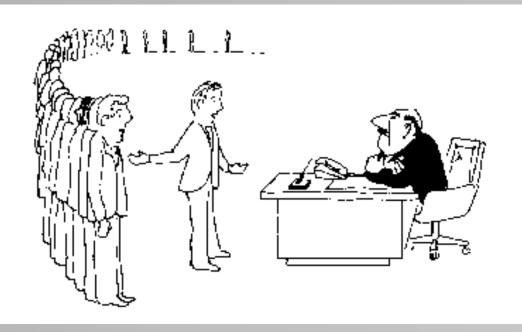
Populating the NP-Completeness Universe

- Circuit Sat <_P 3-SAT
- 3-SAT <_P Independent Set
- 3-SAT <_P Vertex Cover
- Independent Set <_P Clique
- 3-SAT <_P Hamiltonian Circuit
- Hamiltonian Circuit <_P Traveling Salesman
- 3-SAT <_P Integer Linear Programming
- 3-SAT <_P Graph Coloring
- 3-SAT <_P Subset Sum
- Subset Sum <_P Scheduling with Release times and deadlines



Coping with NP-Completeness

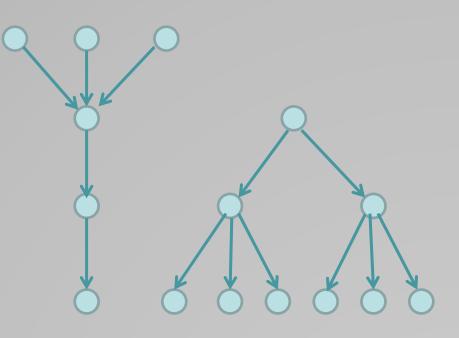
- Approximation Algorithms
- Exact solution via Branch and Bound
- Local Search



I can't find an efficient algorithm, but neither can all these famous people.

Multiprocessor Scheduling

- Unit execution tasks
- Precedence graph
- K-Processors
- Polynomial time for k=2
- Open for k = constant
- NP-complete is k is part of the problem

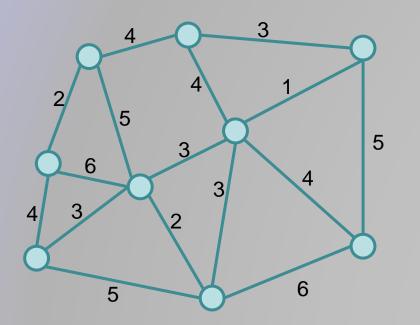


Highest level first is 2-Optimal

Choose k items on the highest level Claim: number of rounds is at least twice the optimal.

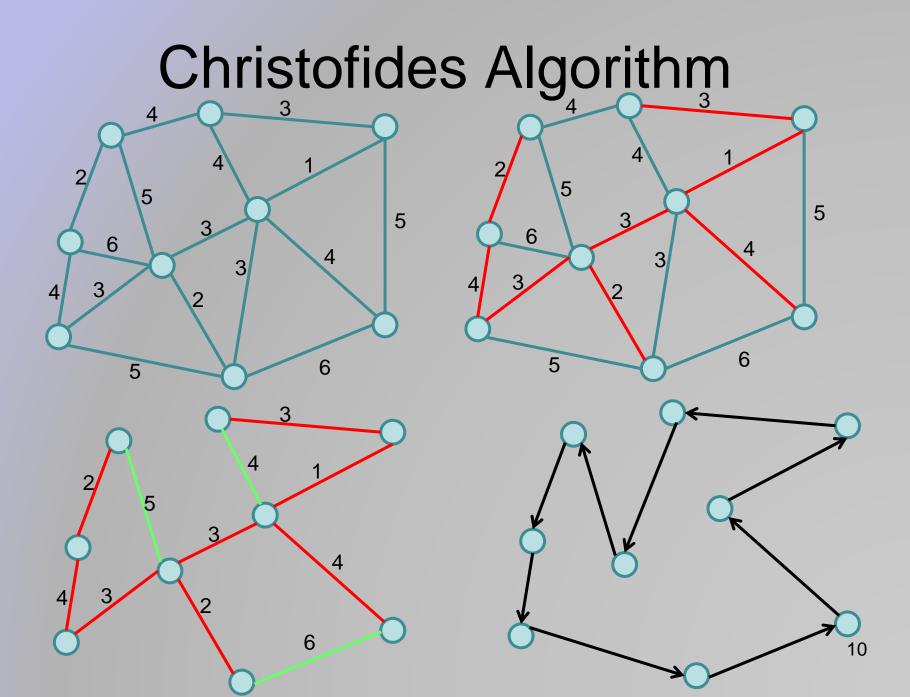
Christofides TSP Algorithm

 Undirected graph satisfying triangle inequality



- 1. Find MST
- 2. Add additional edges so that all vertices have even degree
- 3. Build Eulerian Tour

3/2 Approximation

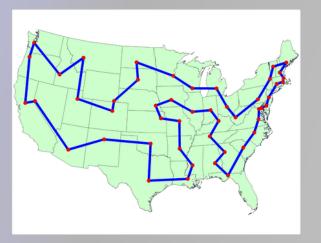


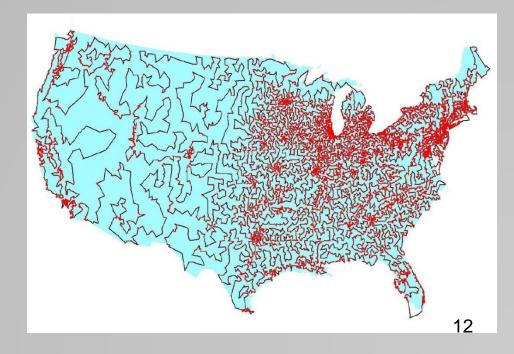
Branch and Bound

- Brute force search tree of all possible solutions
- Branch and bound compute a lower bound on all possible extensions
 - Prune sub-trees that cannot be better than optimal

Branch and Bound for TSP

- Enumerate all possible paths
- Lower bound, Current path cost plus MST of remaining points
- Euclidean TSP
 - Points on the plane with Euclidean Distance
 - Sample data set: State Capitals



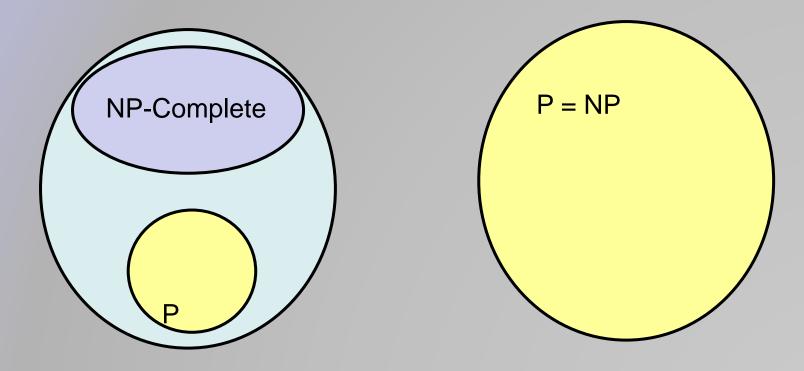


Local Optimization

- Improve an optimization problem by local improvement
 - Neighborhood structure on solutions
 - Travelling Salesman 2-Opt (or K-Opt)
 - Independent Set Local Replacement

What we don't know

• P vs. NP

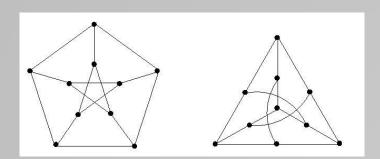


If P ≠ NP, is there anything in between

- Yes, Ladner [1975]
- Problems not known to be in P or NP Complete
 - Factorization
 - Discrete Log

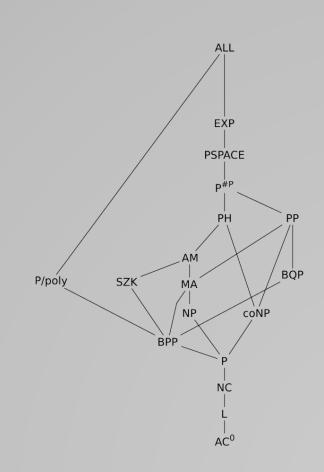
Solve $g^k = b$ over a finite group

Graph Isomorphism



Complexity Theory

- Computational requirements to recognize languages
- Models of Computation
- Resources
- Hierarchies
- //complexityzoo.net



Time complexity

- P: (Deterministic) Polynomial Time
- NP: Non-deterministic Polynomial Time
- EXP: Exponential Time

Space Complexity

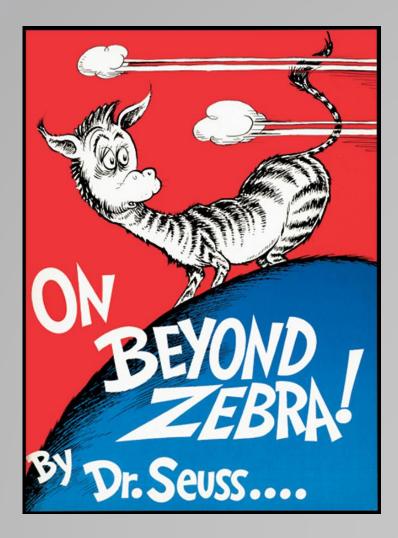
- Amount of Space (Exclusive of Input)
- L: Logspace, problems that can be solved in O(log n) space for input of size n
 - Related to Parallel Complexity

• PSPACE, problems that can be required in a polynomial amount of space

Other types of computation

- Randomization
 - Can you solve problems faster with a random number generator?
- Quantum Computers
 - Can you solve problems faster if you have quantum bits which allow superposition?
 - Probably yes: Shor's Integer Factoring algorithm

So what is beyond NP?



NP vs. Co-NP

 Given a Boolean formula, is it true for some choice of inputs

 Given a Boolean formula, is it true for all choices of inputs

Problems beyond NP

 Exact TSP, Given a graph with edge lengths and an integer K, does the minimum tour have length K

 Minimum circuit, Given a circuit C, is it true that there is no smaller circuit that computes the same function a C

Polynomial Hierarchy

- Level 1
 - $-\exists X_1 \Phi(X_1), \forall X_1 \Phi(X_1)$
- Level 2

 $- \forall X_1 \exists X_2 \Phi(X_1, X_2), \exists X_1 \forall X_2 \Phi(X_1, X_2)$

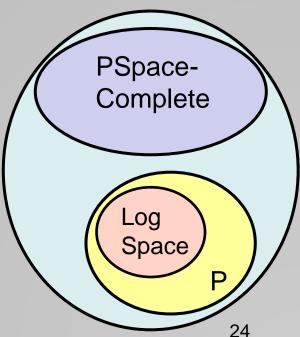
Level 3

 $- \forall X_1 \exists X_2 \forall X_3 \Phi(X_1, X_2, X_3), \exists X_1 \forall X_2 \exists X_3 \Phi(X_1, X_2, X_3)$

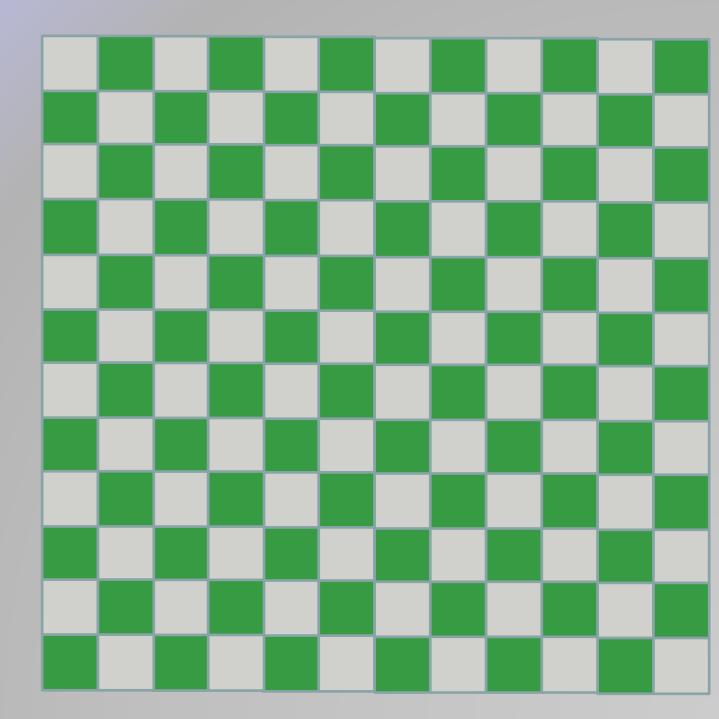
Polynomial Space

- Quantified Boolean Expressions $-\exists X_1 \forall X_2 \exists X_3 ... \exists X_{n-1} \forall X_n \Phi(X_1, X_2, X_3 ... X_{n-1} X_n)$
- Space bounded games
 - Competitive Facility Location Problem
 - N x N Chess
- Counting problems

 The number of Hamiltonian Circuits



N X N Chess



Even Harder Problems

```
public int[] RecolorSwap(int[] coloring) {
           int k = maxColor(coloring);
           for (int v = 0; v < nVertices; v++) {</pre>
               if (coloring[v] == k) {
                   int[] nbdColorCount = ColorCount(v, k, coloring);
                   List<Edge> edges1 = vertices[v].Edges;
                   foreach (Edge e1 in edges1) {
                        int w = e1.Head;
                        if (nbdColorCount[coloring[w]] == 1)
                            if (RecolorSwap(v, w, k, coloring))
                                break;
                    }
               }
           return coloring;
       }
```

Is this code correct?

Halting Problem

 Given a program P that does not take any inputs, does P eventually exit?

Impossibility of solving the Halting Problem

Suppose Halt(P) returns true if P halts, and false otherwise

Consider the program G:

What is Halt(G)?

```
bool G {
    if (Halt(G)){
        while (true) ;
    }
    else {
        return true;
    }
}
```

Undecidable Problems

- The Halting Problem is undecidable
- Impossible problems are hard . . .

