CSE 417: Algorithms with Complexity

Lecture 23 – Autumn 2024 Shortest Paths Problem and Dynamic Programming

Announcements

- Lecture plans
 - Today: Shortest Paths
 - Friday-Wednesday: Network Flow
 - After Thanksgiving: NP Completeness
- HW 8 Available

Shortest Path Problem

- Dijkstra's Single Source Shortest Paths Algorithm
 - O(mlog n) time, positive cost edges
- Bellman-Ford Algorithm
 - O(mn) time for graphs which can have negative cost edges

Dynamic Programming

Express problem as an optimization

 Order subproblems so that results are computed in proper order

Shortest Paths as DP

- $\text{Dist}_{s}[s] = 0$
- $Dist_s[v] = min_w [Dist_s[w] + c_{wv}]$
- How do we order the computation

- Directed Acyclic graph: Topological Sort
- Dijkstra's algorithm determines an order

Lemma

 If a graph has no negative cost cycles, then the shortest paths are simple paths

• Shortest paths have at most n-1 edges

Shortest paths with a given number of edges

 Find the shortest path from s to w with exactly k edges

Express as a recurrence

Compute distance from starting vertex s

- $Opt_k(w) = min_x [Opt_{k-1}(x) + c_{xw}]$
- Opt₀(w) = 0 if w = s and infinity otherwise

for each w M[0, w] = infinity; M[0, s] = 0; for i = 1 to n-1 for each w M[i, w] = min (M[i, 1 x] + coef[x w

 $M[i, w] = min_x(M[i-1,x] + cost[x,w]);$

for each w M[0, w] = infinity; M[0, s] = 0; for i = 1 to n-1 for each w

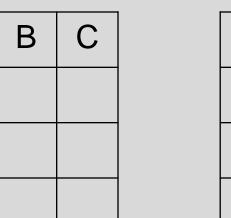
 $M[i, w] = min(M[i-1, w], min_x(M[i-1,x] + cost[x,w]));$

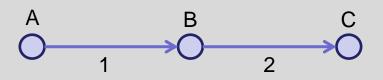
for each w M[w] = infinity; M[s] = 0; for i = 1 to n-1 for each w M[w] = min(M[w], min (M[x] + cost[x w]

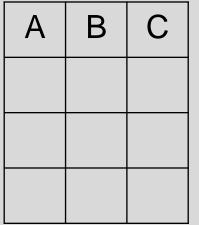
 $M[w] = \min(M[w], \min_{x}(M[x] + cost[x,w]));$

Example:

Α







Α	В	С

Α	В	С

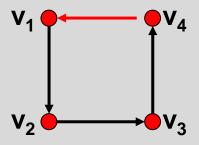
Correctness Proof for Algorithm 3

- Key lemmas, for all w:
 - There exists a path of length M[w] from s to w
 - At the end of iteration i, $M[w] \le M[i, w]$;

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for each w
   M[w] = infinity;
M[s] = 0;
for i = 1 to n-1
  for each w
     for each x
        if (M[w] > M[x] + cost[x,w])
           P[w] = x;
           M[w] = M[x] + cost[x,w];
```

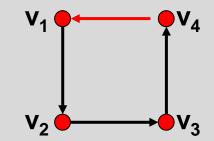
Theorem

If the pointer graph has a cycle, then the graph has a negative cost cycle



If the pointer graph has a cycle, then the graph has a negative cost cycle

- If P[w] = x then $M[w] \ge M[x] + cost(x,w)$
 - Equal when w is updated
 - M[x] could be reduced after update
- Let $v_1, v_2, \dots v_k$ be a cycle in the pointer graph with (v_k, v_1) the last edge added
 - Just before the update
 - $M[v_j] \ge M[v_{j+1}] + cost(v_{j+1}, v_j)$ for j < k
 - $M[v_k] > M[v_1] + cost(v_1, v_k)$
 - Adding everything up
 - $0 > cost(v_1, v_2) + cost(v_2, v_3) + ... + cost(v_k, v_1)$

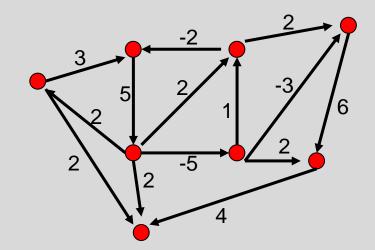


Negative Cycles

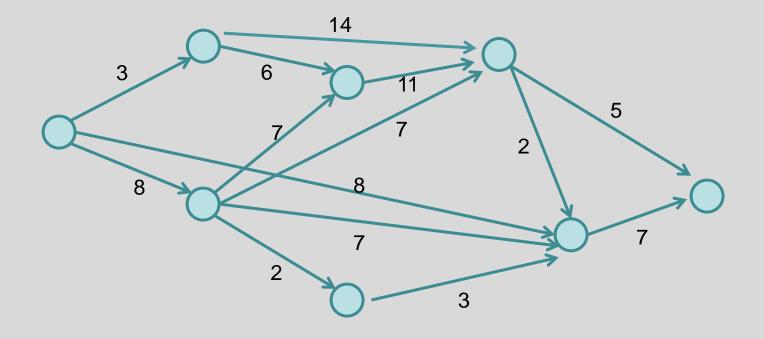
- If the pointer graph has a cycle, then the graph has a negative cycle
- Therefore: if the graph has no negative cycles, then the pointer graph has no negative cycles

Finding negative cost cycles

• What if you want to find negative cost cycles?

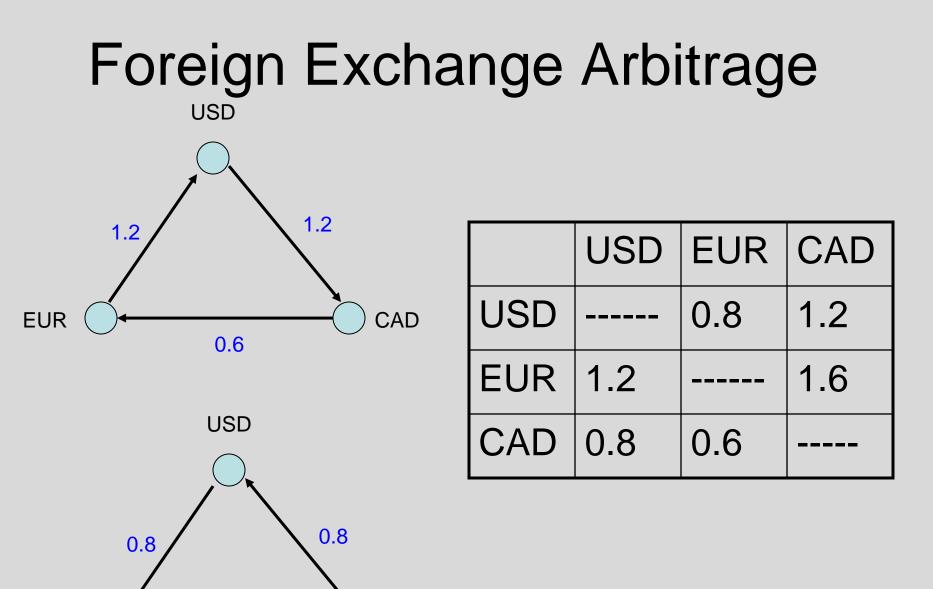


Finding the longest Path in a DAG



What about finding Longest Paths in a directed graph

• Can we just change Min to Max?



CAD

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