

## Lecture05

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# CSE 417 Algorithms

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Lecture 5

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# Announcements

- **HW 1 Due tonight on Gradescope, turn in open until Sunday, 11:59 pm**
  - If you do not have access to Gradescope, let me know.
- **HW 2 Available**

# Worst Case Runtime Function

- Problem  $P$ : Given instance  $I$  compute a solution  $S$
- $A$  is an algorithm to solve  $P$
- $T(I)$  is the number of steps executed by  $A$  on instance  $I$
- $T(n)$  is the maximum of  $T(I)$  for all instances of size  $n$

# Ignore constant factors

- **Constant factors are arbitrary**
  - Depend on the implementation
  - Depend on the details of the model
- **Determining the constant factors is tedious and provides little insight**
- **Express run time as  $T(n) = O(f(n))$**

# Formalizing growth rates

- $T(n)$  is  $O(f(n))$   $[\Gamma : \mathbb{Z}^+ \rightarrow \mathbb{R}^+]$ 
  - If  $n$  is sufficiently large,  $T(n)$  is bounded by a constant multiple of  $f(n)$
  - Exist  $c, n_0$ , such that for  $n > n_0$ ,  $T(n) < c f(n)$
- $T(n)$  is  $\Omega(f(n))$ 
  - $T(n)$  is at least a constant multiple of  $f(n)$
  - There exists an  $n_0$ , and  $\varepsilon > 0$  such that  $T(n) > \varepsilon f(n)$  for all  $n > n_0$
- $T(n)$  is  $\Theta(f(n))$  if  $T(n)$  is  $O(f(n))$  and  $T(n)$  is  $\Omega(f(n))$

# Efficient Algorithms

- Polynomial Time (P): Class of all problems that can be solved with algorithms that have polynomial runtime functions
- Polynomial Time has been a very successful tool for theoretical computer science
- Problems in Polynomial Time often have practical solutions

# Graph Theory

$$|V| = n$$

$$|E| = m$$

- $G = (V, E)$ 
  - $V$  – vertices
  - $E$  – edges
- Undirected graphs
  - Edges sets of two vertices  $\{u, v\}$
- Directed graphs
  - Edges ordered pairs  $(u, v)$
- Many other flavors
  - Edge / vertices weights
  - Parallel edges
  - Self loops



$$\{\{a, b\}, \{b, c\}\}$$

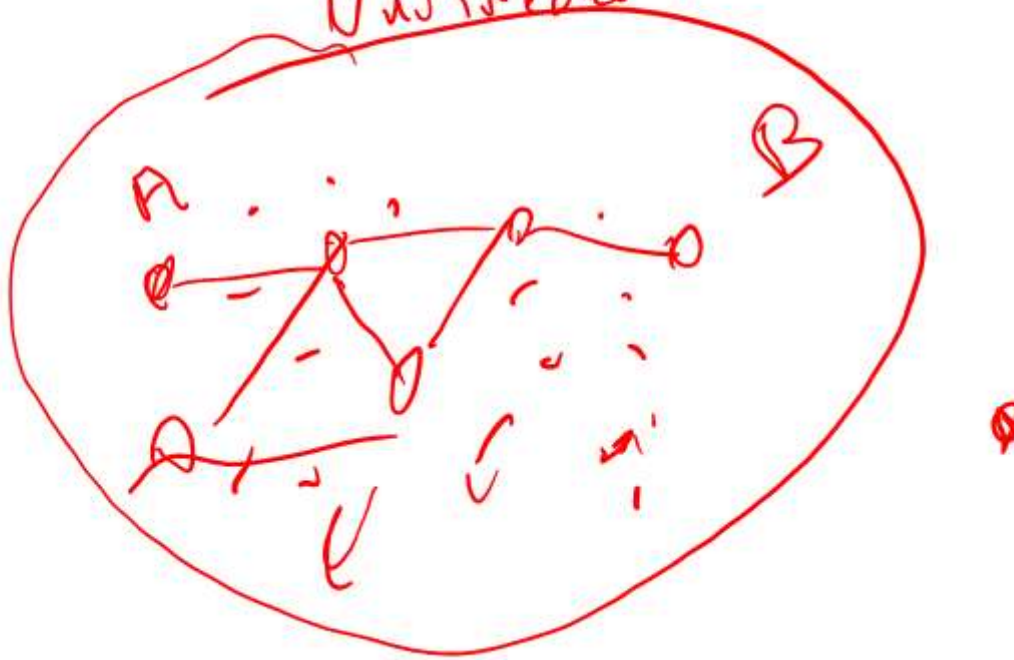
$$\{(a, b), (b, c), (c, b)\}$$



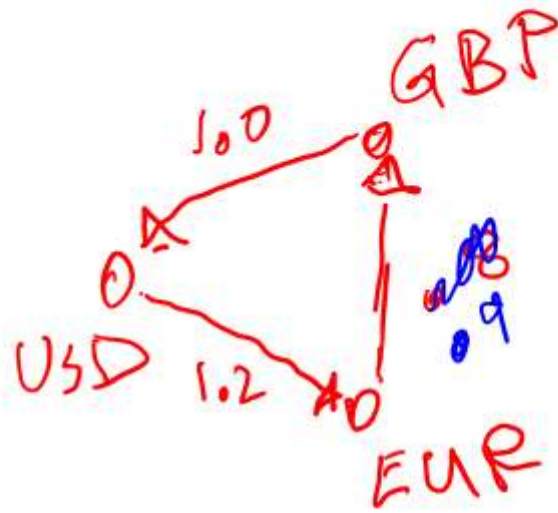
# Facebook Graph

$U =$  accounts  $\sim$  2 Billion

Undirected.





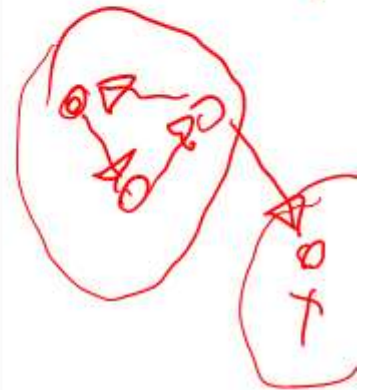
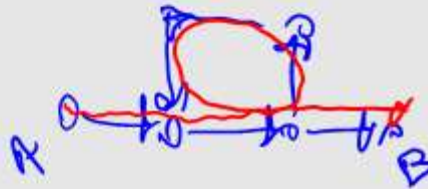
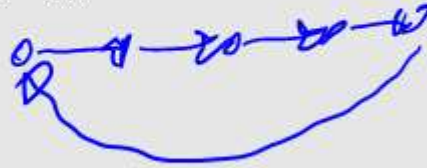


$$1.2 \times 0.8 = 1$$
$$1.2 \times 0.9 = 1.08$$

# Definitions

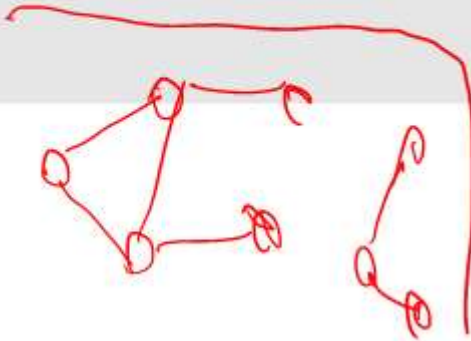
- **Path:**  $v_1, v_2, \dots, v_k$ , with  $(v_i, v_{i+1})$  in  $E$ 
  - Simple Path
  - Cycle
  - Simple Cycle
- **Neighborhood**
  - $N(v)$
- **Distance**
- **Connectivity**
  - Undirected
  - Directed (strong connectivity)
- **Trees**
  - Rooted
  - Unrooted

$$N(v) = \{w \mid (v, w) \in E\}$$

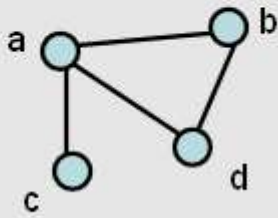


$$N^+(v) = \{w \mid \langle v, w \rangle \in E\}$$

$$N^-(v) = \{w \mid \langle w, v \rangle \in E\}$$



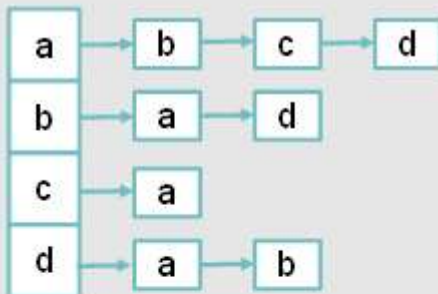
# Sparse, Dense Graph Representation



$$V = \{a, b, c, d\}$$

$$E = \{\{a, b\}, \{a, c\}, \{a, d\}, \{b, d\}\}$$

$$0 \leq m \leq n^2$$



Adjacency List

	1	1	1
1		0	1
1	0		0
1	1	0	

Incidence Matrix

# Implementation Issues

- Graph with  $n$  vertices,  $m$  edges
- Operations
  - Lookup edge
  - Add edge
  - Enumeration edges
  - Initialize graph
- Space requirements

# Graph search

- Find a path from  $s$  to  $t$

$S = \{s\}$

while  $S$  is not empty

$u = \text{Select}(S)$

    visit  $u$

    foreach  $v$  in  $N(u)$

        if  $v$  is unvisited

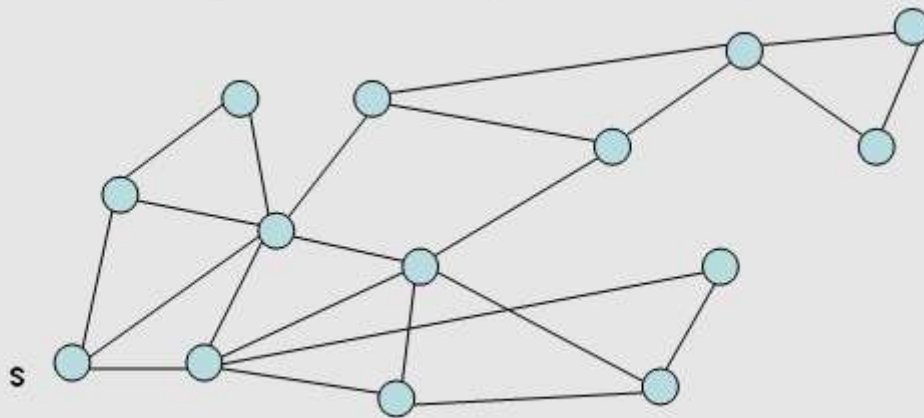
$\text{Add}(S, v)$

$\text{Pred}[v] = u$

        if ( $v = t$ ) then path found

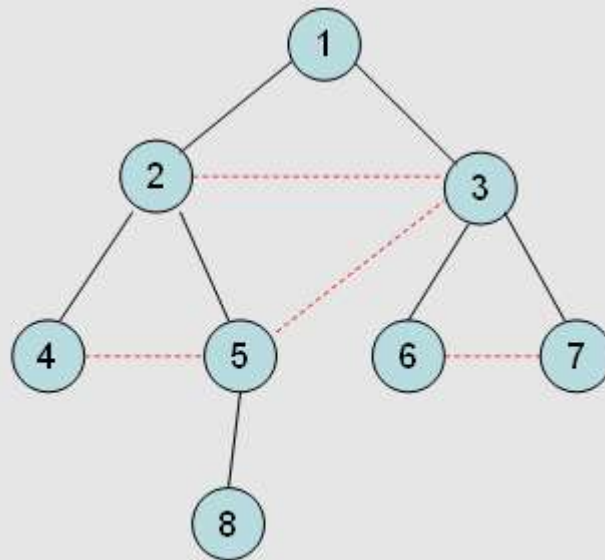
# Breadth first search

- Explore vertices in layers
  - s in layer 1
  - Neighbors of s in layer 2
  - Neighbors of layer 2 in layer 3 . . .



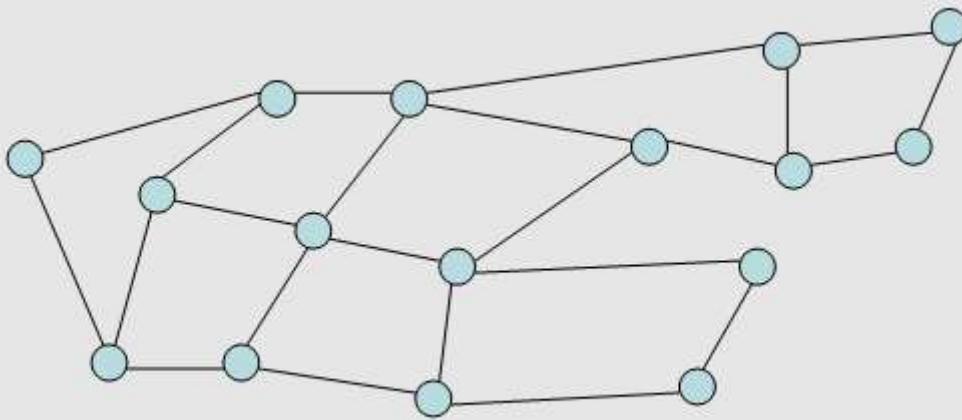
# Key observation

- All edges go between vertices on the same layer or adjacent layers



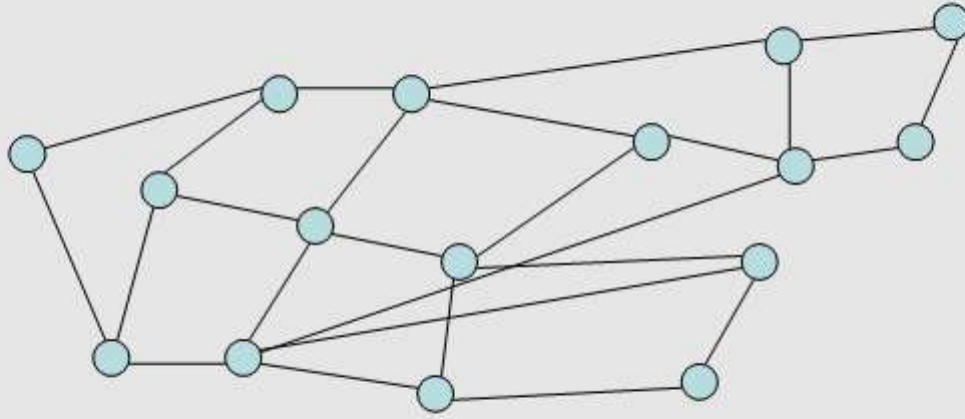
# Bipartite Graphs

- A graph  $V$  is bipartite if  $V$  can be partitioned into  $V_1, V_2$  such that all edges go between  $V_1$  and  $V_2$
- A graph is bipartite if it can be two colored





# Can this graph be two colored?



# Algorithm

- Run BFS
- Color odd layers red, even layers blue
- If no edges between the same layer, the graph is bipartite
- If edge between two vertices of the same layer, then there is an odd cycle, and the graph is not bipartite

