

# Minimum Spanning Trees and Greedy Algorithms

CSE 417 Winter 21  
Lecture 28

# Greedy Algorithms

What's a greedy algorithm?

An algorithm that builds a solution by:

Considering objects one at a time, in some **order**.

Using a **simple rule** to decide on each object.

Never goes back and changes its mind.

# Greedy Algorithms

## PROS

Simple

## CONS

Rarely correct

Often multiple equally intuitive options

Hard to prove correct

Usually need a fancy “structural result”

Or complicated proof by contradiction

Need to focus  
on proofs!

# Your Takeaways

Greedy algorithms are great *when they work*.

But it's hard to tell when they work – the proofs are subtle.

And you can often invent 2-3 different greedy algorithms; it's rare that 1 works, extremely rare that all would work.

So you have to be EXTREMELY careful.

This will be a crash course in greedy algorithms.

If you have a lot of experience with proofs, I'll be highlighting the general patterns in the proofs.

If you don't, just appreciate the proofs are hard, and promise not to write a greedy algorithm unless someone has proven it correct.

# Three Proof Techniques

“Structural result” – the best solution **must** look like this, and the algorithm produces something that looks like this.

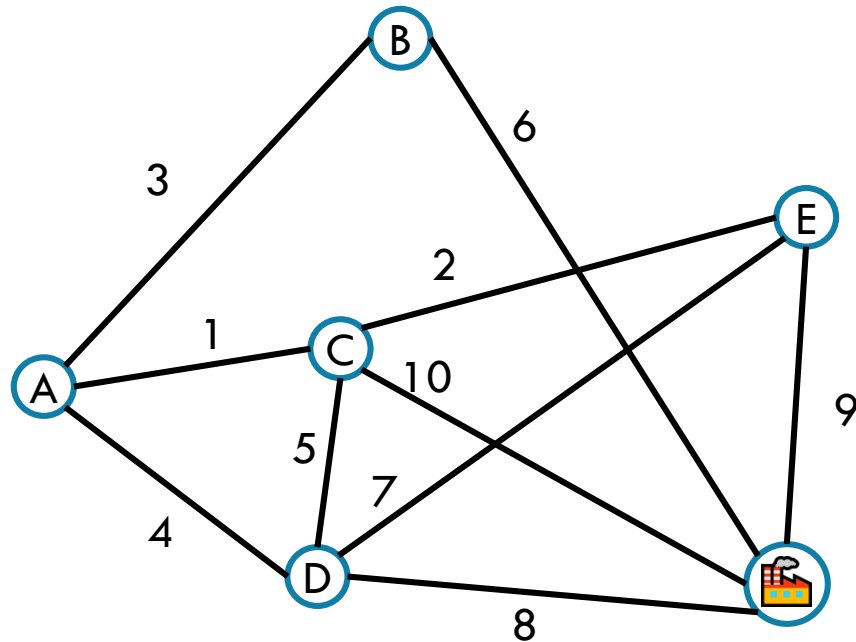
Greedy stays ahead – at every step of the algorithm, the greedy algorithm is at least as good as anything else could be.

Exchange – Contradiction proof, suppose we swapped in an element from the (hypothetical) “better” solution.

Where to start? With some greedy algorithms you’ve already seen.  
Minimum Spanning Trees!

# Minimum Spanning Trees

It's the 1920's. Your friend at the electric company needs to choose where to build wires to connect all these cities to the plant.



She knows how much it would cost to lay electric wires between any pair of cities, and wants the cheapest way to make sure electricity from the plant to every city.

# Minimum Spanning Trees

What do we need? A set of edges such that:

Every vertex touches at least one of the edges. (the edges **span** the graph)

The graph on just those edges is **connected**.

The minimum weight set of edges that meet those conditions.

## Minimum Spanning Tree Problem

**Given:** an undirected, weighted graph  $G$

**Find:** A minimum-weight set of edges such that you can get from any vertex of  $G$  to any other on only those edges.

# Greedy MST algorithms

You've seen two algorithms for MSTs

## Kruskal's Algorithm:

**Order:** Sort the edges in increasing weight order

**Rule:** If connect new vertices (doesn't form a cycle), add the edge.

## Prim's Algorithm:

**Order:** lightest weight edge that adds a new vertex to our current component

**Rule:** Just add it!

# Kruskal's Algorithm

```
KruskalMST(Graph G)
```

```
    initialize each vertex to be its own component
```

```
    sort the edges by weight
```

```
    foreach(edge (u, v) in sorted order) {
```

```
        if(u and v are in different components) {
```

```
            add (u,v) to the MST
```

```
            Update u and v to be in the same component
```

```
        }
```

```
    }
```

# Try It Out

KruskalMST(Graph G)

```
initialize each vertex to be its own component
```

```
sort the edges by weight
```

```
foreach(edge (u, v) in sorted order){
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    if(u and v are in different components){
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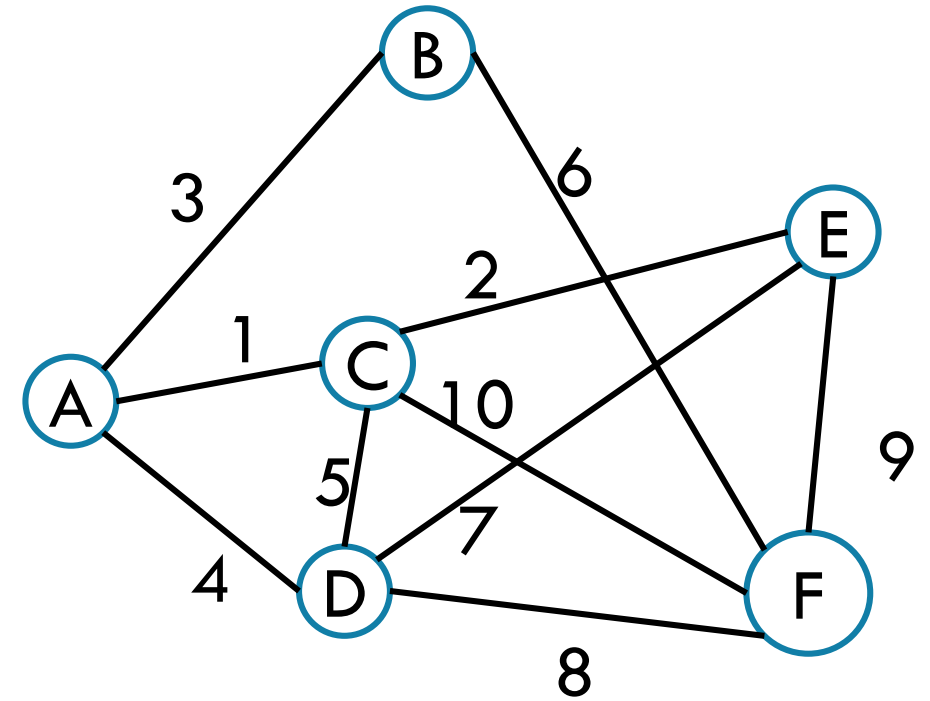
```
        add (u,v) to the MST
```

```
        Update u and v to be in the same
```

```
component
```

```
    }
```

```
}
```



Edge	Include?	Reason
(A,C)		
(C,E)		
(A,B)		
(A,D)		
(C,D)		

Edge (cont.)	Inc?	Reason
(B,F)		
(D,E)		
(D,F)		
(E,F)		
(C,F)		

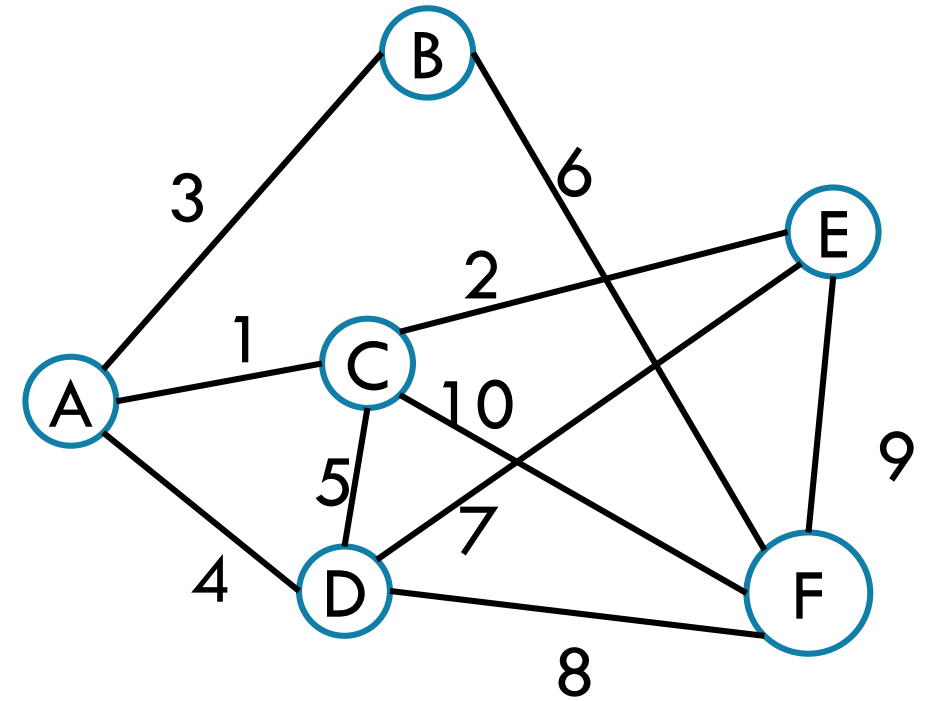
# Try It Out

KruskalMST(Graph G)

```

initialize each vertex to be its own component
sort the edges by weight
foreach(edge (u, v) in sorted order){
    if(u and v are in different components){
        add (u,v) to the MST
        Update u and v to be in the same
component
    }
}

```



Edge	Include?	Reason
(A,C)	Yes	
(C,E)	Yes	
(A,B)	Yes	
(A,D)	Yes	
(C,D)	No	Cycle A,C,D,A

Edge (cont.)	Inc?	Reason
(B,F)	Yes	
(D,E)	No	Cycle A,C,E,D,A
(D,F)	No	Cycle A,D,F,B,A
(E,F)	No	Cycle A,C,E,F,D,A
(C,F)	No	Cycle C,A,B,F,C

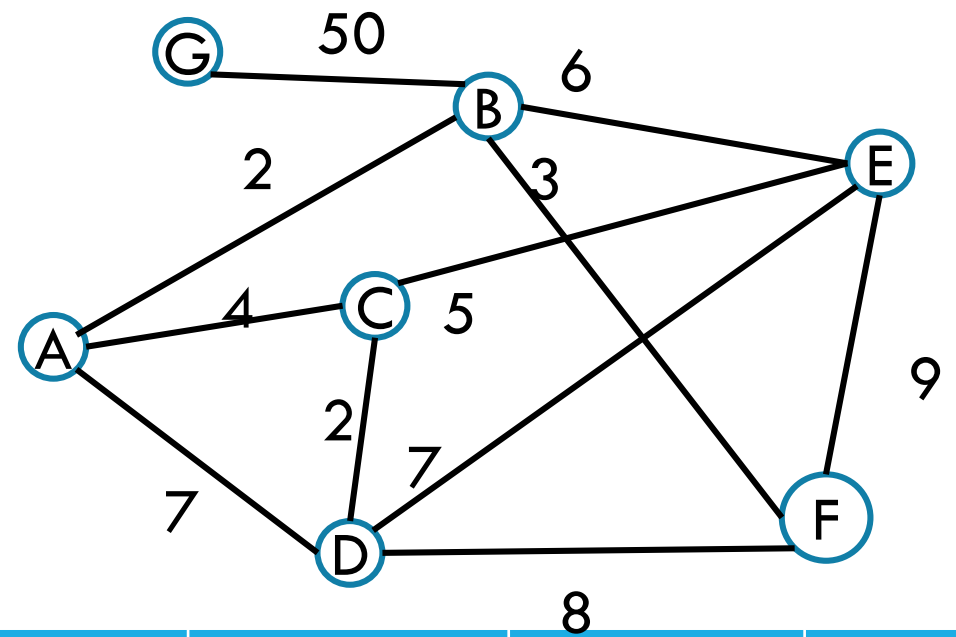
# Code

PrimMST(Graph G)

```
    initialize costToAdd to  $\infty$ 
    mark source as costToAdd 0
    mark all vertices unprocessed, mark source as processed
    foreach(edge (source, v) ) {
        v.costToAdd = weight(source,v)
        v.bestEdge = (source,v)
    }
    while(there are unprocessed vertices){
        let u be the cheapest to add unprocessed vertex
        add u.bestEdge to spanning tree
        foreach(edge (u,v) leaving u){
            if(weight(u,v) < v.costToAdd AND v not processed) {
                v.costToAdd = weight(u,v)
                v.bestEdge = (u,v)
            }
        }
        mark u as processed
    }
```

# Try it Out

```
PrimMST(Graph G)
  initialize costToAdd to  $\infty$ 
  mark source as costToAdd 0
  mark all vertices unprocessed
  mark source as processed
  foreach(edge (source, v) ) {
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      AND v not processed){
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        v.bestEdge = (u,v)
      }
    }
    mark u as processed
  }
}
```

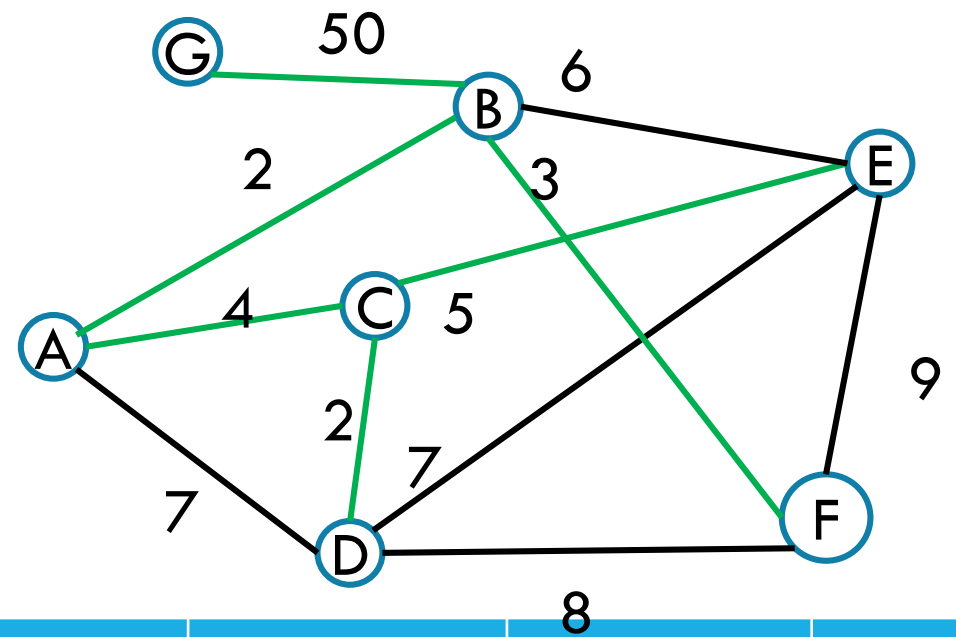


Vertex	costToAdd	Best Edge	Processed
A			
B			
C			
D			
E			
F			
G			

# Try it Out

```

PrimMST(Graph G)
  initialize costToAdd to  $\infty$ 
  mark source as costToAdd 0
  mark all vertices unprocessed
  mark source as processed
  foreach(edge (source, v) ) {
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    foreach(edge (u,v) leaving u){
      if(weight(u,v) < v.costToAdd
        AND v not processed){
        v.costToAdd = weight(u,v)
        v.bestEdge = (u,v)
      }
    }
    mark u as processed
  }
  }
  
```



Vertex	costToAdd	Best Edge	Processed
A	--	--	Yes
B	2	(A,B)	Yes
C	4	(A,C)	Yes
D	<del>7</del> 2	<del>(A,D)</del> (C,D)	Yes
E	<del>6</del> 5	<del>(B,E)</del> (C,E)	Yes
F	3	(B,F)	Yes
G	50	(B,G)	Yes

# Correctness

You're already familiar with the algorithms.

We'll use this problem to practice the proof techniques.

We'll do both **structural** and **exchange**

# Structural Proof

For simplicity – assume all edge weights are distinct and that there is only one minimum spanning tree.

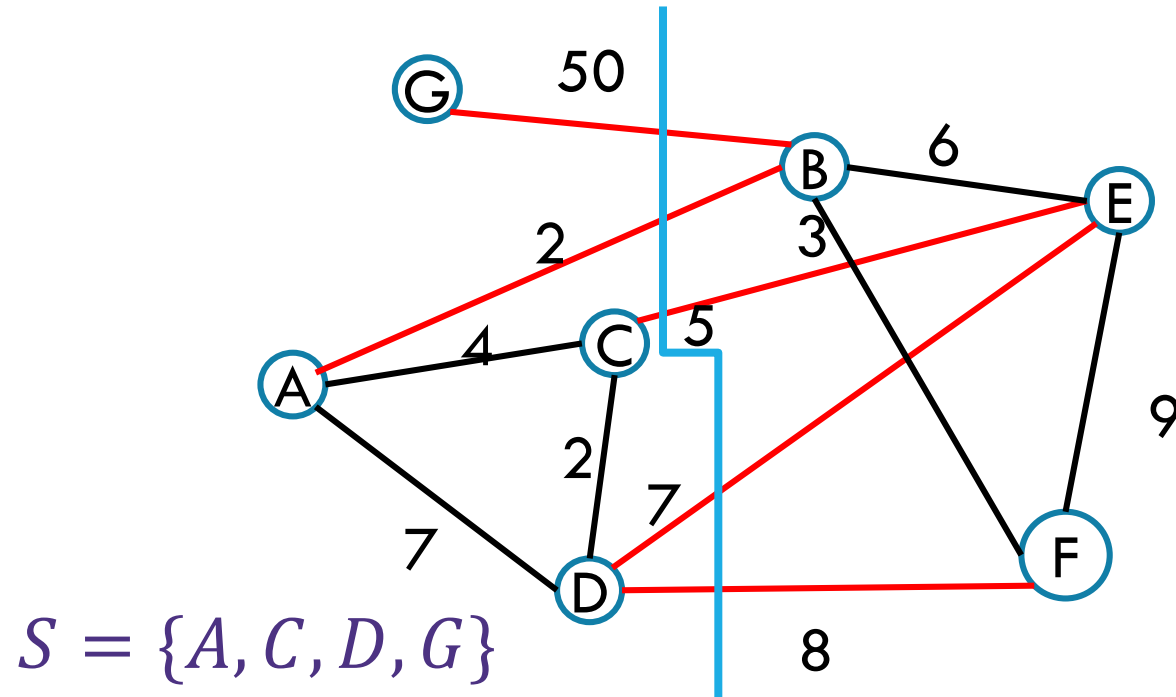
“Structural result” – the best solution **must** look like this, and the algorithm produces something that looks like this.

Example: every spanning tree has  $n - 1$  edges.  
So we better have our algorithm produce  $n - 1$  edges.

Is that enough? No! Lots of different trees (including non minimum ones) have  $n - 1$  edges. Need to say which edges are in the tree.

# Safe Edge

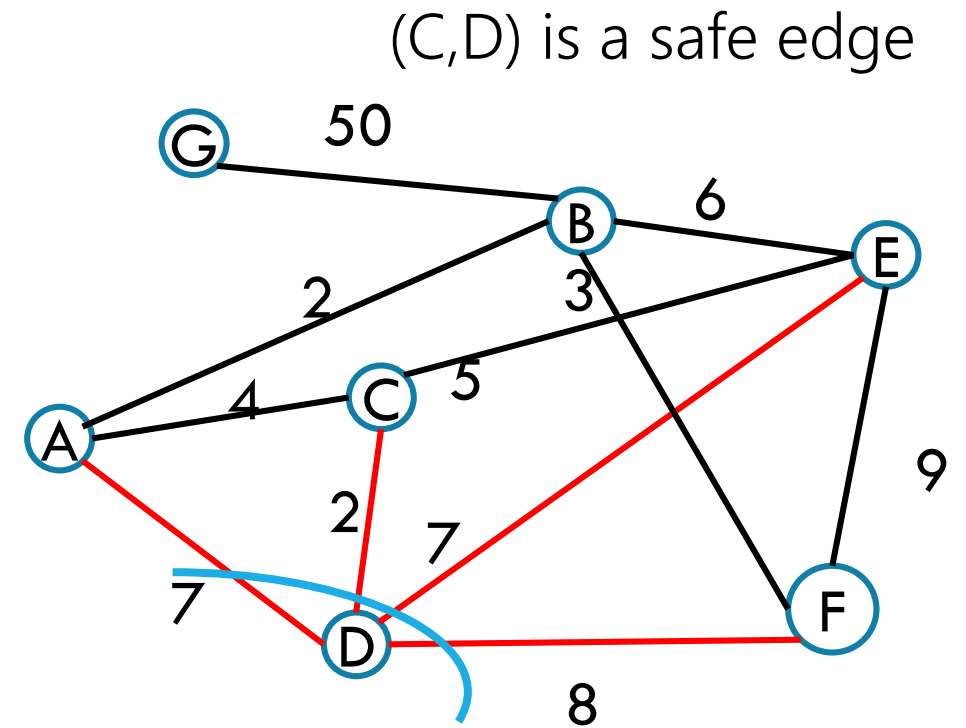
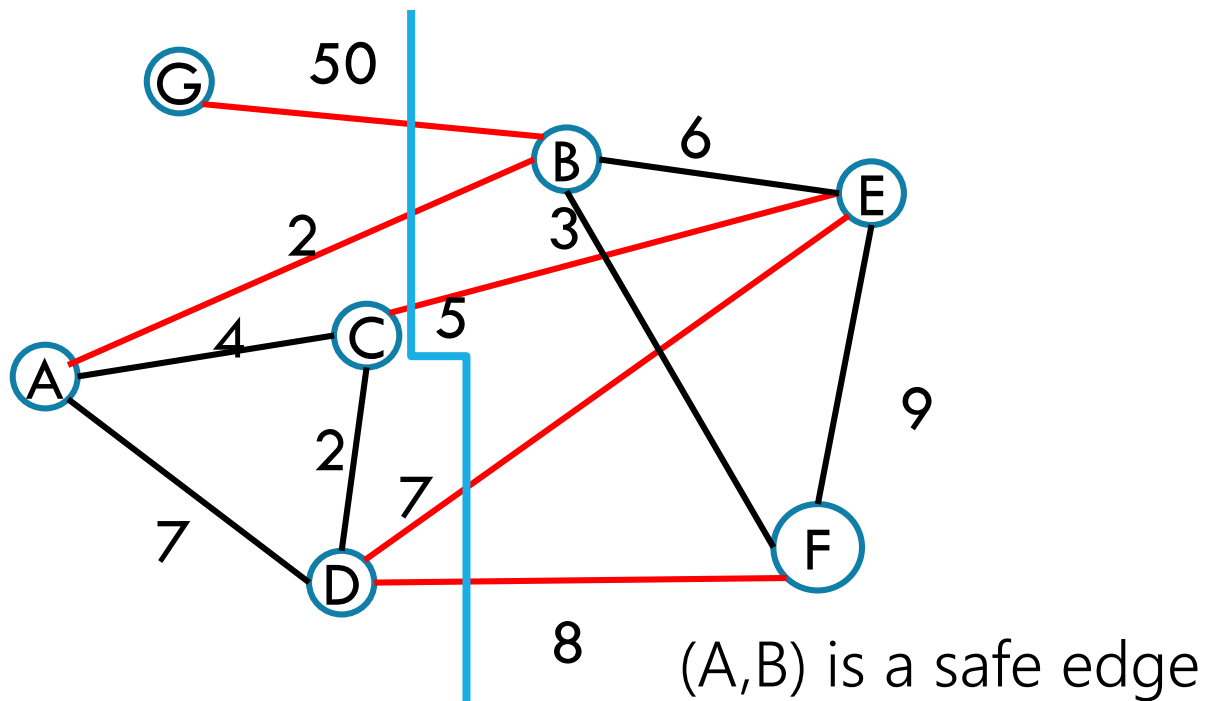
A "cut"  $(S, V \setminus S)$  is a split of the vertices into a subset  $S$  and the remaining vertices  $V \setminus S$ .



Edges in red "span" or "cross" the cut (go from  $S$  to  $V \setminus S$ ).

# Safe Edge

Call an edge,  $e$ , a "safe edge" if there is some cut  $(S, V \setminus S)$  where  $e$  is the minimum edge spanning that cut

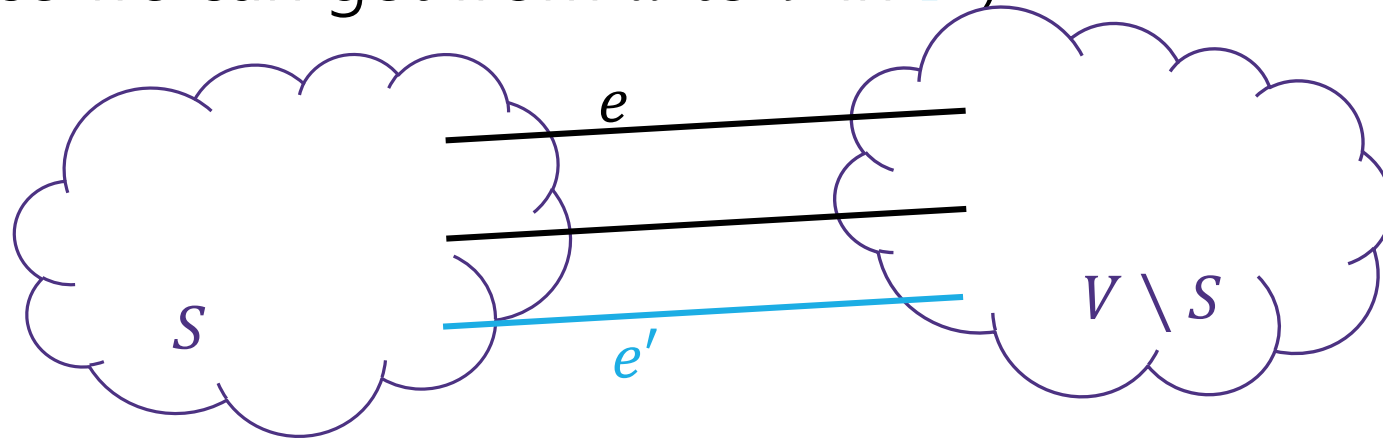


# MSTs and Safe Edges

Every safe edge is in the MST.

**Proof:** Suppose, for the sake of contradiction, that  $e = (u, v)$  is a safe edge, but not in the MST.

Let  $(S, V \setminus S)$  be a cut where  $e$  is the minimum edge spanning  $(S, V \setminus S)$ . Let  $T'$  be the MST. The MST has (at least one) an edge  $e'$  that crosses the cut (since we can get from  $u$  to  $v$  in  $T'$ )

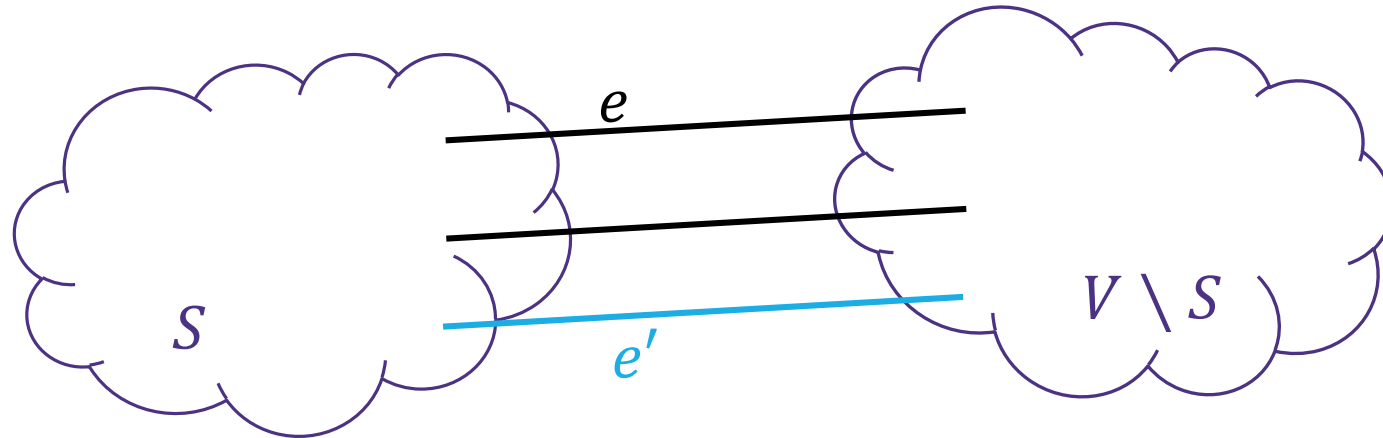


# MSTs and Safe Edges

Add  $e=(u, v)$  to  $T'$ .

The new graph has a cycle including both  $e$  and  $e'$ , The cycle exists because  $u$  and  $v$  were connected to each other in  $T'$  (since it was a spanning tree).

Consider  $T''$ , which is  $T'$  with  $e$  added and  $e'$  removed.



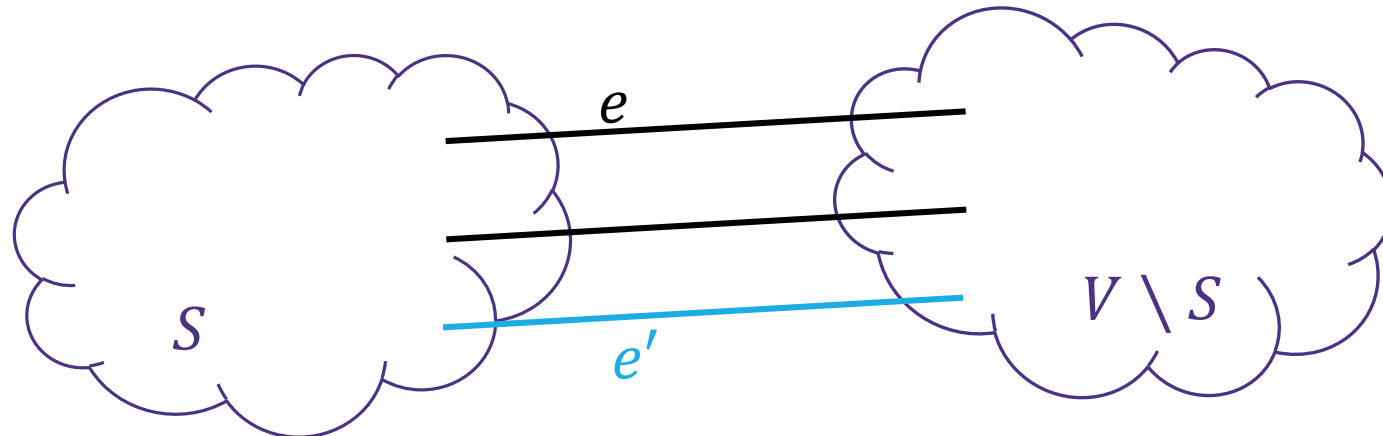
# MSTs and Safe Edges

Consider  $T''$ , which is  $T'$  with  $e$  added and  $e'$  removed.

$T''$  crosses: if the path from  $x$  to  $y$  in  $T'$  didn't use  $e'$  it still exists. If it did use  $e'$ , follow along the path to  $e'$ , along the cycle through  $e$  to the other side.

And it's a tree (it has  $n - 1$  edges).

What's its weight? Less than  $T'$  --  $e$  was the lightest edge spanning  $(S, V \setminus S)$ . That's a contradiction!  $T'$  was the minimum spanning tree.



# Prim's only adds safe edges

When we add an edge, we add the minimum weight one among those that span from the already connected vertices to the not-yet-connected ones.

That's a cut! And that cut shows the edge we added is safe!

So we only add safe edges...

...and we added all the edges we need (every MST has  $n - 1$  edges)

# What about Kruskal's?

Exchange argument:

General outline:

Suppose, you didn't find the best one.

Suppose there's a better MST

Then there's something in the algorithm's solution that doesn't match OPT. (an edge that isn't a safe edge/that's heavier than it needs to be)

Swap (**exchange**) them, and finish the proof (arrive at a contradiction or show that your solution is equal in quality)!

# Kruskal's Proof

Suppose, for the sake of contradiction,  $T_K$ , the tree found by Kruskal's algorithm isn't a minimum spanning tree. Let  $T'$  be the true minimum spanning tree.

Let  $e = (u, v)$  be the lightest edge in  $T_K$  but not in  $T'$ . Add  $e$  to  $T'$ , and we will create a cycle (because there is a way to get from  $u$  to  $v$  in  $T_{OPT}$  by it being a spanning tree).

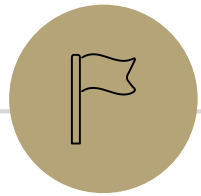
$e$  is not the heaviest edge on the cycle. Anything lighter than  $e$  is already in  $T_K$ , and we put  $e$  in  $T_K$  so it didn't create a cycle there (since we check for cycles before adding it). That means there is an edge on the cycle heavier than  $e$ . Delete that edge, and call the resulting graph  $T''$ . Observe that  $T''$  is a spanning tree (it has  $n - 1$  edges, and spans all the same vertices  $T'$  did since we deleted an edge from a cycle). But it has less weight than  $T'$  which was supposed to be the MST. That's a contradiction!

# Hey...Wait a minute

Those arguments were pretty similar. They both used an “exchange” idea.

The boundaries between the proof principles are a little blurry...

They’re meant to be useful for you for thinking about “where to start” with a proof, not be a beautiful taxonomy of exactly what technique is which.



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## More Greedy Problems

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# Trip Planning

Your goal is to follow a pre-set route from New York to Los Angeles.

You can drive 500 miles in a day, but you need to make sure you can stop at a hotel every night (all possibilities premarked on your map)

You'd like to stop for the fewest number of nights possible – what should you plan?

Greedy: Go as far as you can every night.

Is greedy optimal?

Or is there some reason to “stop short” that might let you go further the next night?

# Trip Planning

Greedy works!

Because “greedy stays ahead”

Let  $g_i$  be the hotel you stop at on night  $i$  in the greedy algorithm.

Let  $OPT_i$  be the hotel you stop at in the optimal plan (the fewest nights plan).

Claim:  $g_i$  is always at least as far along as  $OPT_i$ .

**Intuition:** they start at the same point before day 1, and greedy goes as far as possible, so is “ahead” after day 1.

And if greedy is “ahead” at the start of the day, it will continue to be ahead at the end of the day (since it goes as far as possible, and the distance you can go doesn’t depend on where you start).

Therefore it’s always ahead. And so it uses at most the same number of days as all other solutions.

# Induction

A formal version of the intuition on the last slide is a proof by induction.

The next two slides contain the formal version if you're curious

# Trip Planning

Greedy works!

Because “greedy stays ahead”

Let  $g_i$  be the hotel you stop at on night  $i$  in the greedy algorithm.

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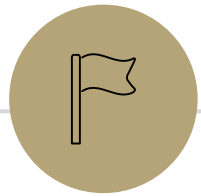
Base Case:  $i = 1$ , OPT and the algorithm choose between the same set of hotels (all at most 500 miles from the start),  $g_i$  is the farthest of those by the algorithm definition, so  $g_i$  is at least as far as  $OPT_i$ .

# Trip Planning

Inductive Hypothesis: Suppose through the first  $k$  hotels,  $g_k$  is farther along than  $OPT_k$ .

Inductive Step:

When we select  $g_{k+1}$ , we can choose any hotel within 500 miles of  $g_k$ , since  $g_k$  is at least as far along as  $OPT_k$  everything less than 500 miles after  $OPT_k$  is also less than 500 miles after  $g_k$ . Since we take the farthest along hotel,  $g_{k+1}$  is at least as far along as  $OPT_{k+1}$ .



**More Greedy**

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# Change-Making

Suppose you need to “make change” with the fewest number of coins possible.

Greedy algorithm:

Take the biggest coin less than the change remaining.

Is the greedy algorithm optimal if you have  
1 cent coins, 10 cent coins, and 15 cent coins?

# Change-Making

The greedy algorithm doesn't always work!

We made you explain this on the homework problem during the DP section.

But there are times where it does

For "standard" US coinage, the greedy algorithm works

And it also always works if your coins always exactly double in value.

Another reason to be very careful with greedy algorithms!

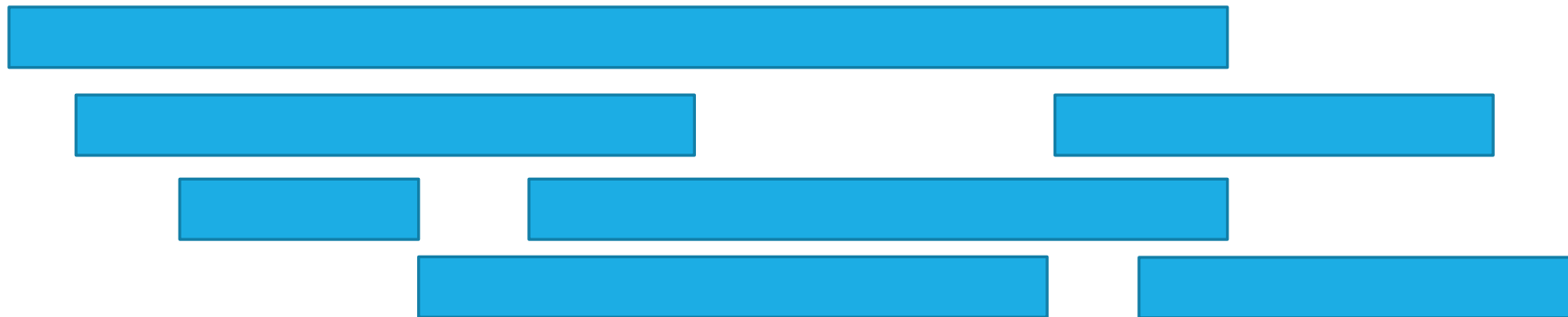
Also a good example of how you can sometimes avoid greedy if you can't figure out a proof – maybe there's a way to write a DP instead!

# Interval Scheduling

You have a single processor, and a set of jobs with fixed start and end times.

Your goal is to maximize the number of jobs you can process.

I.e. choose the maximum number of non-overlapping intervals.

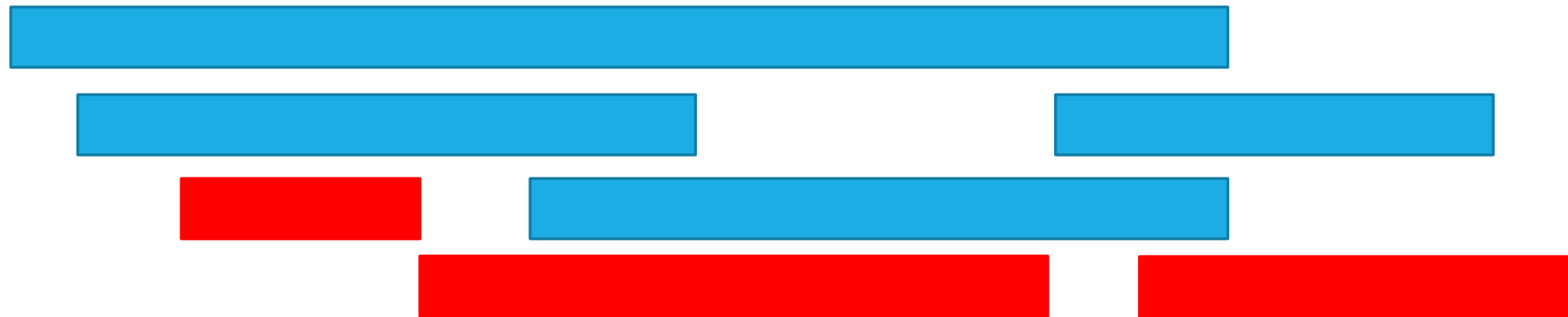


# Interval Scheduling

You have a single processor, and a set of jobs with fixed start and end times.

Your goal is to maximize the number of jobs you can process.

I.e. choose the maximum number of non-overlapping intervals.



3 non-overlapping  
intervals

# Interval Scheduling

You have a single processor, and a set of jobs with fixed start and end times.

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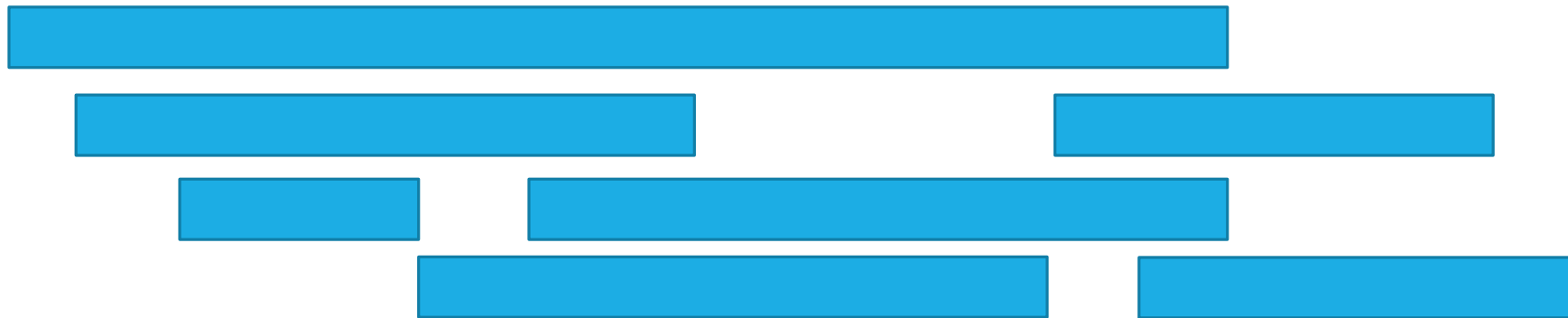
3 other non-overlapping intervals

# Interval Scheduling

You have a single processor, and a set of jobs with fixed start and end times.

Your goal is to maximize the number of jobs you can process.

I.e. choose the maximum number of non-overlapping intervals.



OPT is 3 – there is no way to have 4 non-overlapping intervals; both the red and purple solutions are equally good.

# Greedy Ideas

To specify a greedy algorithm, we need to:

Order the elements (intervals)

Choose a rule for deciding whether to add.

**Rule:** Add interval as long as it doesn't overlap with those we've already selected.

What ordering should we use?

Think of **at least two** orderings you think might work.

# Greedy Algorithm

Some possibilities

Earliest end time (add if no overlap with previous selected)

Latest end time

Earliest start time

Latest start time

Shortest interval

Fewest overlaps (with remaining intervals)

# Greedy

That list slide is the real difficulty with greedy algorithms.  
All of those look at least somewhat plausible at first glance.

With MSTs that was fine – those ideas all worked!  
It's not fine here.

They don't all work.

As a first step – try to find counter-examples to narrow down

# Greedy Algorithm

Earliest end time

Latest end time

Earliest start time

Latest start time

Shortest interval

Fewest overlaps (with remaining intervals)

# Take Earliest Start Time – Counter Example



# Take Earliest Start Time – Counter Example



Algorithm finds  
Optimum

Taking the one with the earliest start time doesn't give us the best answer.

# Shortest Interval



# Shortest Interval



Algorithm finds  
Optimum

Taking the shortest interval first doesn't give us the best answer

# Greedy Algorithm

Earliest end time

Latest end time ✘

Earliest start time ✘

Latest start time

Shortest interval ✘

Fewest overlaps (with remaining intervals)

# Earliest End Time

Intuition: If  $u$  has the earliest end time, and  $u$  overlaps with  $v$  and  $w$  then  $v$  and  $w$  also overlap.

Why?

If  $u$  and  $v$  overlap, then both are “active” at the instant before  $u$  ends (otherwise  $v$  would have an earlier end time).

Otherwise  $v$  would have an earlier end time than  $u$ ! By the same reasoning,  $w$  is also “active” the instant before  $u$  ends. So  $v$  and  $w$  also overlap with each other.

# Earliest End Time

Can you prove it correct?

Do you want to use

Structural Result

Exchange Argument

Greedy Stays Ahead

# Exchange Argument

Let  $A = a_1, a_2, \dots, a_k$  be the set of intervals selected by the greedy algorithm, ordered by endtime

$OPT = o_1, o_2, \dots, o_\ell$  be the maximum set of intervals, ordered by endtime.

Our goal will be to “exchange” to show  $A$  has at least as many elements as  $OPT$ .

Let  $a_i, o_i$  be the first two elements where  $a_i$  and  $o_i$  aren't the same. Since  $a_{i-1}$  and  $o_{i-1}$  are the same, neither  $a_i$  nor  $o_i$  overlaps with any of  $o_1, \dots, o_{i-1}$ . And by the greedy choice,  $a_i$  ends no later than  $o_i$  so  $a_i$  doesn't overlap with  $o_{i+1}$ . So we can exchange  $a_i$  into  $OPT$ , replacing  $o_i$  and still have  $OPT$  be valid.

# Exchange Argument

Repeat this argument until we have changed OPT into  $A$ .

Can OPT have more elements than  $A$ ?

No! After repeating the argument, we could change every element of OPT to  $A$ . If OPT had another element, it wouldn't overlap with anything in OPT, and therefore can't overlap with anything in  $A$  after all the swaps. But then the greedy algorithm would have added it to  $A$ .

So  $A$  has the same number of elements as OPT does, and we really found an optimal

# Greedy Stays Ahead

Let  $A = a_1, a_2, \dots, a_k$  be the set of intervals selected by the greedy algorithm, ordered by endtime

$OPT = o_1, o_2, \dots, o_\ell$  be the maximum set of intervals, ordered by endtime.

Our goal will be to show that for every  $i$ ,  $a_i$  ends no later than  $o_i$ .

Proof by induction:

Base case:  $a_1$  has the earliest end time of any interval (since there are no other intervals in the set when we consider  $a_1$  we always include it), thus  $a_1$  ends no later than  $o_1$ .

# Greedy Stays Ahead

Inductive Hypothesis: Suppose for all  $i \leq k$ ,  $a_i$  ends no later than  $o_i$ .

IS: Since (by IH)  $a_k$  ends no later than  $o_k$ , greedy has access to everything that doesn't overlap with  $a_k$ . Since  $a_k$  ends no later than  $o_k$ , that includes  $o_{k+1}$ . Since we take the first one that doesn't overlap,  $a_{k+1}$  will also end before  $o_{k+1}$ .

Therefore  $a_{k+1}$  ends no later than  $o_{k+1}$

Wrapping Up: Since every  $a_i$  ends no later than  $o_i$ , the last interval greedy selects ( $a_n$ ) is no later than  $o_n$ . There cannot be an  $o_{n+1}$ , as if it didn't overlap with  $o_n$  it also wouldn't overlap with  $a_n$  and would have been added by greedy.

# Greedy Algorithm

Earliest end time ✓

Latest end time ✗

Earliest start time ✗

Latest start time

Shortest interval ✗

Fewest overlaps (with remaining intervals)

# Fewest Overlaps counter-example



The top middle item will be selected first, eliminating the chance of getting the 4 intervals in OPT.

# Other Greedy Algorithms

It turns out latest start time and fewest overlaps also work.

Latest start time is actually the same as earliest end time (imagine “reflecting” all the jobs along the time axis – the one with the earliest end time ends up having the last start time).

What about fewest overlaps?

Doesn't work!

# Greedy Algorithm

Earliest end time ✓

Latest end time ✗

Earliest start time ✗

Latest start time ✓

Shortest interval ✗

Fewest overlaps (with remaining intervals) ✗

# Summary

Greedy algorithms

You'll probably have 2 (or 3...or 6) ideas for greedy algorithms. Check some simple examples before you implement!

Greedy algorithms rarely work.

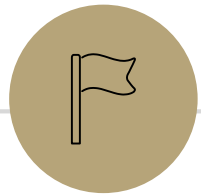
When they work AND you can prove they work, they're great!

Proofs are often tricky

**Structural results** are the hardest to come up with, but the most versatile.

**Greedy stays ahead** usually use induction

**Exchange** start with the **first** difference between greedy and optimal.



# Which Technique

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# Which Technique?

When I see a new problem, how do I know which option to use?

Try modeling first – use the problems we've already solved

Preferences? Try stable matching.

Assignments? Try network flow.

Etc.

# Which Technique?

Modeling Didn't work?

What does this remind you of?

Then try:

recursive thinking (will lead to DP or D&C)

Ask how you would represent the problem visually (might lead to graphs)

Finally: remember your problem might be hard!