Bellman-Ford CSE 417 Winter 21 Lecture 15



Dynamic Programming on Graphs

We're building up to "Bellman-Ford" and "Floyd-Warshall" Two very clever algorithms – we won't ask you to be as clever.

But they're standard library functions, so it's good to know. And deriving them together is good for practicing DP skills.

Shortest Paths

Shortest Path Problem

Given: A directed graph and a vertex sFind: The length of the shortest path from s to t.

The length of a path is the sum of the edge weights.

Baseline: Dijkstra's Algorithm

Dijkstra's Algorithm

```
Dijkstra (Graph G, Vertex source)
     initialize distances to \infty
                                                         In 373, we said the
      mark source as distance 0
                                                         running time was
      mark all vertices unprocessed
                                                         O(m \log n + n \log n)
      while(there are unprocessed vertices) {
            let u be the closest unprocessed vertex
                                                         Can be sped up to
            foreach(edge (u, v) leaving u) {
                                                         O(m + n \log n) by
                  if(u.dist+weight(u,v) < v.dist){</pre>
                                                         inserting a
                        v.dist = u.dist+weight(u,v)
                                                         different heap
                        v.predecessor = u
                                                         implementation.
      mark u as processed
```

Suppose you have a directed acyclic graph *G*. How could you find distances from *s*?

What's one step in this problem?

Suppose you have a directed acyclic graph *G*. How could you find distances from *s*?

What's one step in this problem? Choosing the predecessor, i.e. "the last edge" on a path.

 $dist(v) = \begin{cases} 0 & \text{if } v \text{ is the source} \\ \min_{u:(u,v)\in E} \{dist(u) + weight(u,v)\} \text{ otherwise} \end{cases}$

Our memoization structure can be the graph itself.

What's an evaluation order? (Remember we're in a DAG!)

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Our memoization structure can be the graph itself.

What's an evaluation order? (Remember we're in a DAG!) A topological sort! – we need to have distances for all incoming edges calculated.

What about cycles?

 $dist(v) = \begin{cases} 0 & \text{if } v \text{ is the source} \\ \min_{u:(u,v)\in E} \{dist(u) + weight(u,v)\} \text{ otherwise} \end{cases}$





We need some way to "order" the paths.

I.e. we need to be sure we always have **something** to look up. It doesn't have to be the perfect distance necessarily... As long as we'll realize it and update later

And as long as we can fix it to the true distance eventually.

Ordering

Instead of dist(v), (the true distance) right from the start, we'll let

dist(v, i) to be the length of the shortest path from the source to v that uses at most i edges.

That breaks ties – counting the number of edges required!

dist(v,i) =

Distances



dist(v,3) = 14

dist(v, 4) = 12

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dist(v,i) =

Ordering

Instead of dist(v), we want the

dist(v, i) to be the length of the shortest path from the source to u that uses at most i edges.

$$dist(v,i) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v \text{ is the source} \\ \infty & \text{if } i = 0 \text{ and } v \text{ is not the source} \\ \min\left\{\min_{u:(u,v)\in E} \{dist(u,i-1)\} + w(u,v), dist(v,i-1)\right\} \text{ o/w} \end{cases}$$

Sample calculation



Vertex∖ <i>i</i>	0	1	2	3	4	5
S	0	0	0	0	0	0
A	∞	3	3	3	3	3
В	∞	8	8	8	8	8
С	∞	∞	9	9	9	9
D	∞	∞	∞	11	11	11
V	∞	∞	∞	14	12	12

```
Initialize source.dist[0]=0, u.dist[0]=\infty for others
for (i from 1 to ??)
     for (every vertex v) //what order?
          v.dist[i] = v.dist[i-1]
           for (each incoming edge (u,v)) / / hmmm
                if(u.dist[i-1]+weight(u,v)<v.dist[i])</pre>
                    v.dist[i]=u.dist[i-1]+weight(u,v)
               endIf
          endFor
                      dist(v,i) = \begin{cases} 0 & \text{if } i = 0 \text{ and } v \text{ is the source} \\ \infty & \text{if } i = 0 \text{ and } v \text{ is not the source} \\ \min \left\{ \min_{u:(u,v) \in E} \{dist(u,i-1)\} + w(u,v), dist(v,i-1) \right\} \end{cases}
     endFor
endFor
```

Initialize source.dist[0]=0, u.dist[0]= ∞ for others for (i from 1 to n-1) The shortest path will never need more than n-1 edges for (every vertex (more than that and you've got a cycle) v.dist[i] = v.dist[i-1] for (each incoming edge (u,v)) / / hmmm if(u.dist[i-1]+weight(u,v)<v.dist[i])</pre> v.dist[i]=u.dist[i-1]+weight(u,v) endIf endFor endFor endFor

Initialize sour Only ever need values from the last iteration for (i from 1 to Order doesn't matter!!

for(every vertex v) //what order?
 v.dist[i] = v.dist[i-1]
 for(each incoming edge (u,v))//hmmm
 if(u.dist[i-1]+weight(u,v)<v.dist[i])
 v.dist[i]=u.dist[i-1]+weight(u,v)
 endIf
 endFor
endFor</pre>

endFor

Initialize source.dist[0]=0, u.dist[0]= ∞ for others for (i from 1 to n-1) for(every vertex v) //any order v.dist[i] = v.dist[i-1] for (each incoming edge (u,v)) / / hmmm if(u.dist[i-1]+weight(u,v)<v.dist[i])</pre> v.dist[i]=u.dist[i-1]+weight(u,v) endIf Graphs don't usually have easy access to their incoming endFor edges (just the outgoing ones) endFor endFor

Initialize source.dist[0]=0, u.dist[0]= ∞ for others for (i from 1 to n-1) for (every vertex v) //any order v.dist[i] = v.dist[i-1] for(each incoming edge (u,v))//hmmm if(u.dist[i-1]+weight(u,v)<v.dist[i])</pre> v.dist[i]=u.dist[i-1]+weight(u,v) endIf endFor

endFor endFor endFor But the order doesn't matter – as long as we check every edge, the processing order is irrelevant. So if we only have access to outgoing edges...

Initialize source.dist[0]=0, u.dist[0]= ∞ for others for (i from 1 to n-1) set u.dist[i] to u.dist[i-1] for every u for (every vertex u) //any order for (each outgoing edge (u,v)) / /better! if(u.dist[i-1]+weight(u,v)<v.dist[i])</pre> v.dist[i]=u.dist[i-1]+weight(u,v) endIf endFor endFor endFor

Initialize source.dist[0]=0, u.dist[0]=∞ for others
for(i from 1 to n-1)
 set u.dist[i] to u.dist[i-1] for every u
 for(every vertex u) //any order
 for(each outgoing edge (u,v))//better!
 if(u.dist[i-1]+weight(u,v)<v.dist[i])
 v.dist[i]=u.dist[i-1]+weight(u,v)</pre>

endIf endFor endFor endFor

We don't really need all the different values... Just the most recent value.

Initialize source.dist=0, u.dist=∞ for others
for(i from 1 to n-1)
 set u.dist[i] to u.dist[i-1] for every u
 for(every vertex u) //any order
 for(each outgoing edge (u,v))//better!
 if(u.dist+weight(u,v)<v.dist)
 v.dist=u.dist+weight(u,v)</pre>

endIf endFor endFor endFor

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for(i from 1 to n-1)
 for(every vertex u) //any order
 for(each outgoing edge (u,v))//better!
 if(u.dist+weight(u,v)<v.dist)
 v.dist=u.dist+weight(u,v)
 endIf</pre>

endFor endFor endFor

We don't really need all the different values... Just the most recent value.

A Caution

We did change the code when we got rid of the indexing You might have a mix of dist[i], dist[i+1], dist[i+2],... at the same time.

That's ok!

You'll only "override" a value with a better one. And you'll eventually get to dist(u, n - 1)After iteration *i*, *u* stores dist(u, k) for some $k \ge i$.

Exit early

If you made it through an entire iteration of the outermost loop and don't update any *dist(*)

Then you won't do any more updates in the next iteration either. You can exit early.

More ideas to save constant factors on Wikipedia (or the textbook)

Laundry List of shortest pairs (so far)

Algorithm	Running Time	Special Case	Negative edges?
BFS	O(m+n)	ONLY unweighted graphs	Χ
Simple DP	O(m+n)	ONLY for DAGs	Χ
Dijkstra's	$O(m + n \log n)$		X
Bellman-Ford	O(mn)		ŚŚŚ

```
Initialize source.dist=0, u.dist=\infty for others
for (i from 1 to n-1)
   for (every vertex u) //any order
       for (each outgoing edge (u,v)) //better!
          if(u.dist+weight(u,v)<v.dist)</pre>
             v.dist=u.dist+weight(u,v)
         endIf
      endFor
                   What happens if there's a negative cycle?
   endFor
endFor
```

Negative Edges

Negative Cycles



The fastest way from *a* to *e*

(i.e. least-weight walk) isn't defined!

No valid answer $(-\infty)$

Negative edges, but only nonnegative cycles



Dijkstra's might fail

But the shortest path IS defined.

There is an answer



Vertex∖ <i>i</i>	0	1	2	3	4	5	6
S	0	0	0	0	0		
А	∞	3	3	3	3		
В	∞	8	8	8	5		
С	∞	∞	9	9	9		
D	∞	∞	∞	1	1		
V	∞	∞	∞	14	2		

Laundry List of shortest pairs (so far)

Algorithm	Running Time	Special Case only	Negative edges?
BFS	O(m+n)	ONLY unweighted graphs	Χ
Simple DP	O(m+n)	ONLY for DAGs	Χ
Dijkstra's	$O(m + n \log n)$		X
Bellman-Ford	O(mn)		Yes!



All Pairs

For Dijkstra's or Bellman-Ford we got the distances from the source to every vertex.

What if we want the distances from every vertex to every other vertex?

Another Recurrence

 $dist(v) = \begin{cases} 0 & \text{if } v \text{ is the source} \\ \min_{u:(u,v)\in E} \{dist(u) + weight(u,v)\} \text{ otherwise} \end{cases}$

Another clever way to order paths.

Put the vertices in some (arbitrary) order 1,2, ..., n

Let dist(u, v, i) be the distance from u to v where the only intermediate nodes are 1,2, ..., i

Another Recurrence

Put the vertices in some (arbitrary) order 1,2,...,n

Let dist(u, v, i) be the distance from u to v where the only intermediate nodes are 1,2, ..., i

$$dist(u, v, i) = \begin{cases} weight(u, v) & \text{if } i = 0, (u, v) \text{ exists} \\ 0 & \text{if } i = 0, u = v \\ \infty & \text{if } i = 0, \text{ no edge } (u, v) \\ min\{dist(u, i, i - 1) + dist(i, v, i - 1), dist(u, v, i - 1)\} \text{ otherwise} \end{cases}$$

```
dist[][] = new int[n-1][n-1]
for(int i=0; i<n; i++)</pre>
   for(int j=0; j<n; j++)</pre>
      dist[i][j] = edge(i,j) ? weight(i,j) : \infty
for(int i=0; i<n; i++)</pre>
    dist[i][i] = 0
for every vertex r
   for every vertex u
       for every vertex v
          if(dist[u][r] + dist[r][v] < dist[u][v])
               dist[u][v]=dist[u][r] + dist[r][v]
```

"standard" form of the "Floyd-Warshall" algorithm. Similar to Bellman-Ford, you can get rid of the last entry of the recurrence (only need 2D array, not 3D array).

Running Time

 $O(n^3)$

How does that compare to Dijkstra's?

Running Time

If you really want all-pairs...

Could run Dijkstra's n times... $O(mn \log n + n^2 \log n)$ If $m \approx n^2$ then Floyd-Warshall is faster!

Floyd-Warshall also handles negative weight edges. Ask Robbie after how to detect them.

Takeaways

Some clever dynamic programming on graphs.

Which library to use?

Need just one source?

Dijkstra's if no negative edge weights.

Bellman-Ford if negative edges.

Need all sources?

Flord-Warshall if negative edges or $m \approx n^2$

Repeated Dijkstra's otherwise