# CSE 417 Algorithms with Complexity

Richard Anderson - Lecture 23
Shortest Paths Problem and
Dynamic Programming

#### Announcements

- HW 7, 8, 9
- Reading: Wednesday + Next Week
  - Network flow
    - 7.1, 7.2: Ford-Fulkerson Algorithm
  - Applications of Network flow
    - 7.5-7.12: Bipartite Matching, Image segmentation, Baseball elimination, etc.

#### Shortest Path Problem

- Dijkstra's Single Source Shortest Paths Algorithm
  - O(mlog n) time, positive cost edges
- Bellman-Ford Algorithm
  - O(mn) time for graphs which can have negative cost edges

### Dynamic Programming

Express problem as an optimization

 Order subproblems so that results are computed in proper order

#### Shortest Paths as DP

- Dist<sub>s</sub>[s] = 0
- $Dist_s[v] = min_w [Dist_s[w] + c_{wv}]$

How do we order the computation

- Directed Acyclic graph: Topological Sort
- Dijkstra's algorithm determines an order

#### Lemma

 If a graph has no negative cost cycles, then the shortest paths are simple paths

Shortest paths have at most n-1 edges

## Shortest paths with a given number of edges

 Find the shortest path from s to w with exactly k edges

#### Express as a recurrence

Compute distance from starting vertex s

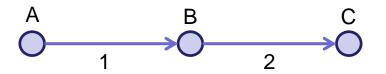
- $Opt_k(w) = min_x [Opt_{k-1}(x) + c_{xw}]$
- $Opt_0(w) = 0$  if w = s and infinity otherwise

```
for each w M[0, w] = infinity; M[0, s] = 0; for i = 1 to n-1 for each w M[i, w] = min_x(M[i-1,x] + cost[x,w]);
```

```
for each w M[0, w] = infinity; M[0, s] = 0; for i = 1 to n-1 for each w M[i, w] = min(M[i-1, w], min_x(M[i-1,x] + cost[x,w]));
```

```
for each w M[w] = infinity; M[s] = 0; for i = 1 to n-1 for each w M[w] = min(M[w], min_x(M[x] + cost[x,w]));
```

## Example:



Α	В	С

Α	В	С

Α	В	С

Α	В	C

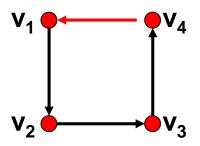
#### Correctness Proof for Algorithm 3

- Key lemmas, for all w:
  - There exists a path of length M[w] from s to w
  - At the end of iteration i,  $M[w] \le M[i, w]$ ;

```
for each w
  M[w] = infinity;
M[s] = 0;
for i = 1 to n-1
  for each w
     for each x
        if (M[w] > M[x] + cost[x,w])
           P[w] = x;
           M[w] = M[x] + cost[x,w];
```

#### **Theorem**

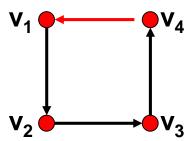
If the pointer graph has a cycle, then the graph has a negative cost cycle



Proof: See text.

## If the pointer graph has a cycle, then the graph has a negative cost cycle

- If P[w] = x then M[w] >= M[x] + cost(x,w)
  - Equal when w is updated
  - M[x] could be reduced after update
- Let v<sub>1</sub>, v<sub>2</sub>,...v<sub>k</sub> be a cycle in the pointer graph with (v<sub>k</sub>,v<sub>1</sub>) the last edge added
  - Just before the update
    - $M[v_i] >= M[v_{i+1}] + cost(v_{i+1}, v_i)$  for j < k
    - $M[v_k] > M[v_1] + cost(v_1, v_k)$
  - Adding everything up
    - $0 > cost(v_1, v_2) + cost(v_2, v_3) + ... + cost(v_k, v_1)$

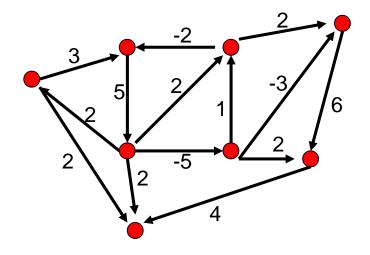


#### **Negative Cycles**

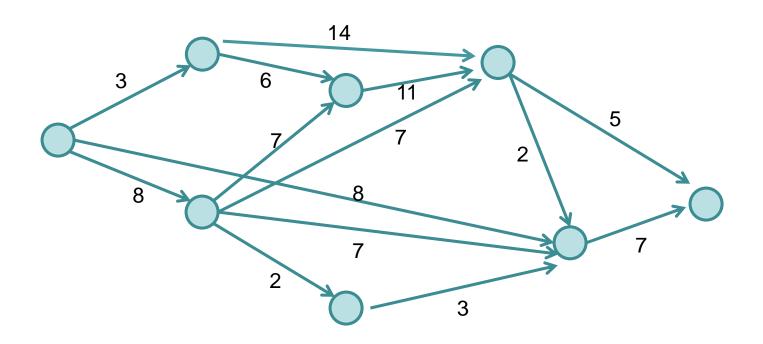
- If the pointer graph has a cycle, then the graph has a negative cycle
- Therefore: if the graph has no negative cycles, then the pointer graph has no negative cycles

## Finding negative cost cycles

What if you want to find negative cost cycles?



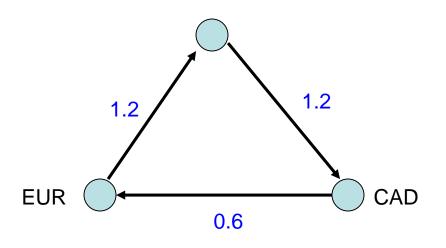
## Finding the longest Path in a DAG



## What about finding Longest Paths in a directed graph

Can we just change Min to Max?

## Foreign Exchange Arbitrage



		USD		
	0.8		8.0	
EUR				CAD
EUR		1.6		CAD

	USD	EUR	CAD
USD		8.0	1.2
EUR	1.2		1.6
CAD	0.8	0.6	