CSE 417 Divide & Conquer (pt 3) More Examples

UNIVERSITY of WASHINGTON

Reminders

- > HW2 due Sunday
- > Extra office hours after class (CSE 212)
- > HW3 will be posted tomorrow
 - construct Voronoi diagrams on paper using the algorithm we discuss today
 - (should be quick)



Divide & Conquer Review

> Apply the steps:

- 1. Divide the input data into 2+ parts
- 2. Recursively solve the problem on each part
- 3. Combine the sub-problem solutions into a problem solution

> Key questions:

- 1. Can you solve the problem by combining solutions from sub-problems?
- 2. Is that easier than solving it directly?

> Use master theorem to calculate the running time



Famous Algorithm Review

> Integer Multiplication: Karatsuba

- <u>key point</u>: only 3 recursive calls, so $T(n) = 3 T(n/2) + O(n) \sim O(n^{\lg 3}) = O(n^{1.585})$
- sub-problems are multiplications on numbers half as large
- Matrix Multiplication: Strassen
 - > 7 T(n/2) + O(n²) ~> O(n^{$\log 7$}) = O(n^{2.808})

> **FFT**: Cooley & Tukey

- <u>key point</u>: divides data into odd and even indexes
- 2 T(n/2) + O(n) ~> O(n log n)
- Integer Multiplication: Schönhage & Strassen
 - > use FFTs to reduce to O(n) multiplication problem O(n log n log log n)

Outline for Today

- > Counting inversions
- > Voronoi diagrams
- > Closest pair of points



Counting Inversions

- > Problem: Given an array A of length n, count the number of index pairs (i, j) such that i < j but A[i] > A[j]
- > Example: if A is sorted, then there are 0 inversions
- > Example: if A is in decreasing order, there are n(n-1)/2 inversions
 - there are n(n-1)/2 pairs (i, j) satisfying $0 \le i < j < n$
 - every pair is an inversion



Counting Inversions: Brute Force

> Brute-force solution:

```
int count = 0;
for (int i = 0; i < n; i++)
  for (int j = i + 1; j < n; j++)
      if (A[i] > A[j])
           count += 1;
return count;
```

> Runs in $\Theta(n^2)$ time



Counting Inversions: Application

- Measure the difference between two lists of rankings of n things
 music, candidates, web sites, etc.
- > Replace each element in one list with the ranking (a number) of that item in the second list
- > Example: ranking Beetles band members
 - Your List: John, Paul, George, Ringo
 - My List: Paul, George, John, Ringo
 - Result is [3, 1, 2, 4]
 - > has 2 inversions (3,1) and (3,2)

Counting Inversions: Application

- Measure the difference between two lists of rankings of n things
 music, candidates, web sites, etc.
- > Replace each element in one list with the ranking (a number) of that item in the second list
- > If rankings are the same, result is sorted, so no inversions
 - use number of inversions as a measure of how close they are
- > See the textbook for more applications



- > Apply divide & conquer...
 - 1. Divide A[0..n-1] into halves, A[0..n/2-1] and A[n/2..n-1]
 - > same as merge sort
 - 2. Recursively count inversions in each half
 - 3. Combine...



- > Combine step...
- Consider any pair of indices (i, j)
 Four possibilities
 - **i** in first half, **j** in first half
 - **i** in first half, **j** in second half
 - **i** in second half, **j** in first half
 - i in second half, j in second half

- from recursive call on A[0..n/2-1]
- need to count these...
- 🖿 doesn't satisfy i < j
- from recursive call on A[n/2..n-1]



- > Combine step...
 - count pairs (i, j) with i in first half, j in second half, and A[i] > A[j]
 - answer is that count plus answers from two recursive calls
- > Brute force solution:

> Runs in $\Theta((n/2)(n/2)) = \Theta(n^2)$ time



> Need a <u>faster</u> way to answer this question:

How many elements in A[n/2..n-1] are smaller than A[i]?

- > What technique have we learned that can answer this sort of question?
- > Can apply binary search if A[n/2..n-1] is **sorted**
 - so let's sort it
 - one non-obvious trick: I'll do this recursively



- > Apply divide & conquer...
 - 1. Divide A[0..n-1] into halves, A[0..n/2-1] and A[n/2..n-1]
 - 2. Recursively **sort & count** inversions in each half
 - 3. Combine:
 - > for i = 0 .. n/2, binary search for A[i] in A[n/2..n-1]
 - index gives number of j's with A[i] > A[j]
 - add to count of inversions from recursive calls
 - > apply "two finger" merge to make A sorted

> Apply divide & conquer...

> Divide + combine is O(n log n) because of n/2 binary searches

- $C = \log_2 2 = 1$, so compare to $n^c = n$
- master theorem does not give a specific answer
 - > must be $\Omega(n \log n)$ since divide + combine is $\Omega(n)$
 - > must be $O(n^{1+\epsilon})$ for any $\epsilon > 0$ since divide + combine is $O(n^{1+\epsilon})$
 - > could be O(n (log n)²) or something like that (can't tell from this analysis)
- > We can improve it exactly as in earlier examples...
 - binary searches are doing a lot of wasted work

- > Apply divide & conquer...
- > Divide + combine is O(n log n) because of n/2 binary searches
- > We can improve it exactly as in earlier examples...
 - − since $A[0] \le A[1] \le ...$ (it's sorted now), indexes returned by each binary search can only increase as we go
 - rather than binary search, just use linear search
 > total number of steps to the right is n/2 so total time is O(n)
- > This is another "two finger" algorithm

- > Apply divide & conquer...
- > Divide + combine is O(n log n) because of n/2 binary searches
- > We can improve it exactly as in earlier examples...
 - sequence of linear searches takes O(n) time
- > This is another "two finger" algorithm
 - in fact, the fingers make the same steps as in merging
 - in fact, we could count and merge simultaneously (exercise!)

- > Apply divide & conquer...
 - 1. Divide A[0..n-1] into halves, A[0..n/2-1] and A[n/2..n-1]
 - 2. Recursively sort & count inversions in each half
 - 3. Combine with "two finger" merge & count inversions
- > Divide + combine in O(n) time, so O(n log n)
 - only slightly faster than binary search approach
 - BUT we look much smarter after covering our tracks

Outline for Today

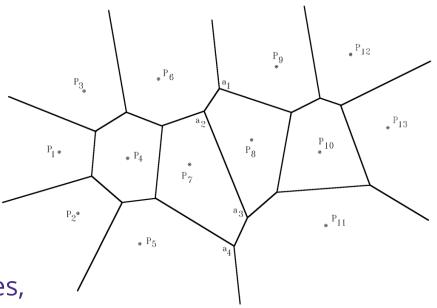
- > Counting inversions> Voronoi diagrams
- > Closest pair of points



Voronoi Diagrams

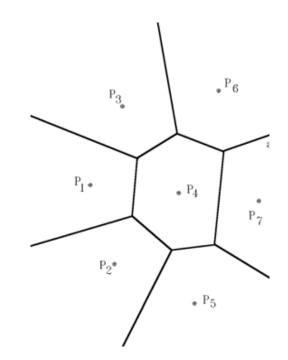
- > Given a set of sites p₁, ..., p_n, separate the plane into the regions *closest* to each site
- > Example on the right has 14 sites, so 14 regions as well
- > (Coding details are complicated, so we'll stay high-level.)

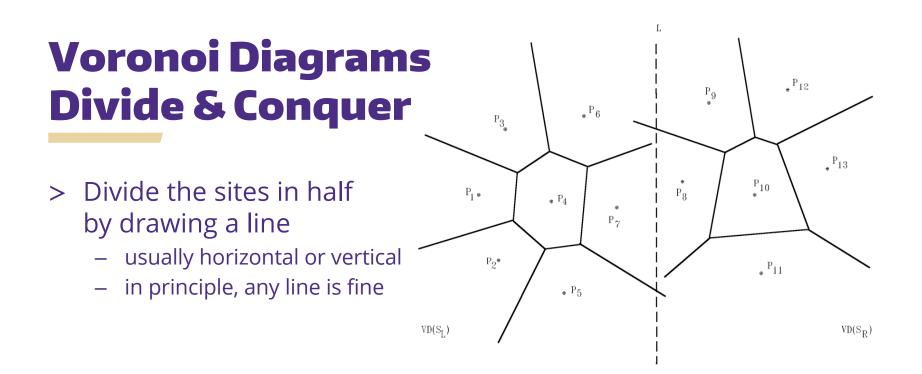
Picture from par.cse.nsysu.edu.tw/~cbyang/course/algo/algonote/algo4.ppt



Voronoi Diagrams

- > Brute force solution:
 - for each site, find its Voronoi region
- > Finding the Voronoi region for a site:
 - for every other site, find the separating line
 - > line that is equal distance from each site
 - > perpendicular bisector of line segment drawn between them
 - somehow fit the closest ones together into the region boundary (complicated)
- > $\Omega(n)$ per region, so $\Omega(n^2)$ all together

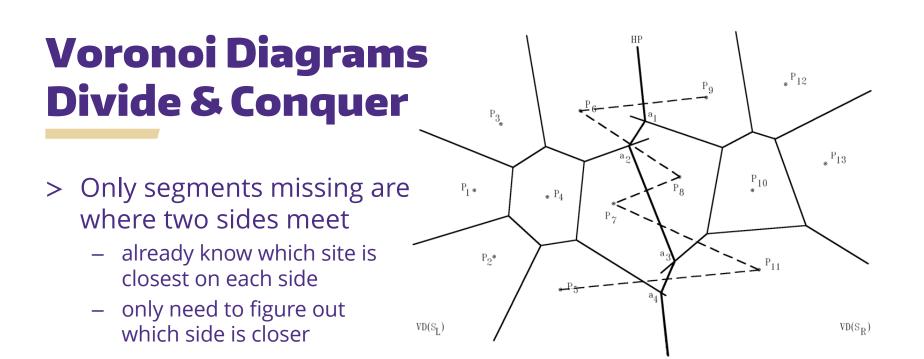




- > Recursively find the Voronoi diagrams for each half
 - use brute force when there are 1–3 sites (easy cases)

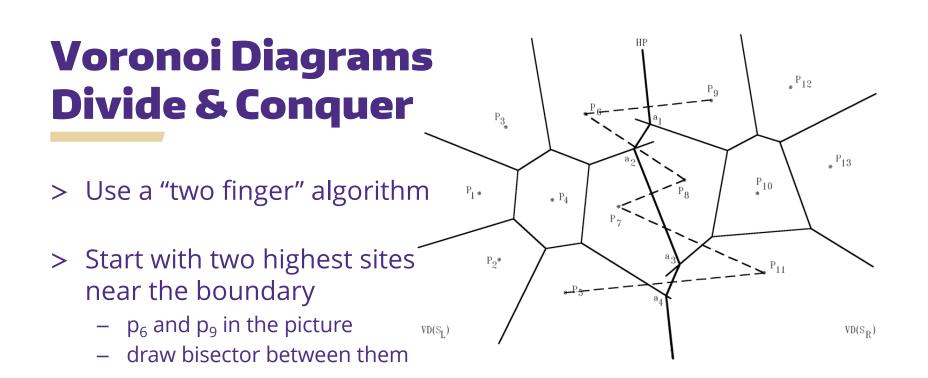
Picture from par.cse.nsysu.edu.tw/~cbyang/course/algo/algonote/algo4.ppt





- > Find piecewise-linear, separating path on boundary
 - equal distance between a site on each side

Picture from par.cse.nsysu.edu.tw/~cbyang/course/algo/algonote/algo4.ppt



- > Extend the bisector until it hits edge of a Voronoi region
 - one of those sites is no longer closest on that side

Voronoi Diagrams Divide & Conquer

- > "Two finger" algorithm
 - finger on site from each side
 - drawing bisector between them
- > Extend bisector to edge of $_{vD(S_L)}$ a Voronoi region
 - one of those sites is no longer closest on that side

 P_3

P₇

P₁ *

P₂*

- move finger to new closest site
- start drawing the new bisector (must connect!)



VD(S_R)

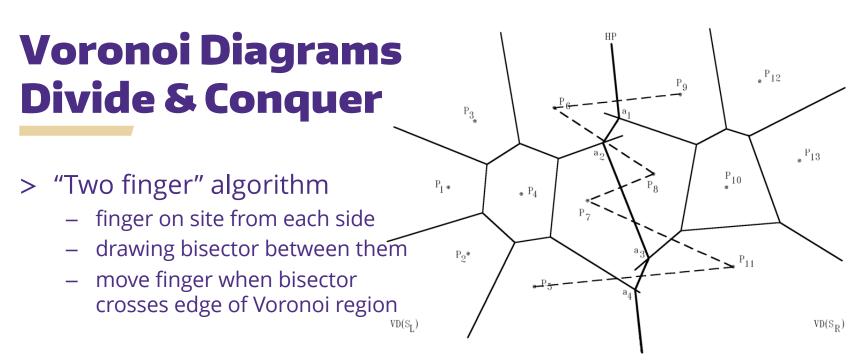
•^P12

P₁₀

~ P₁₁

^P13

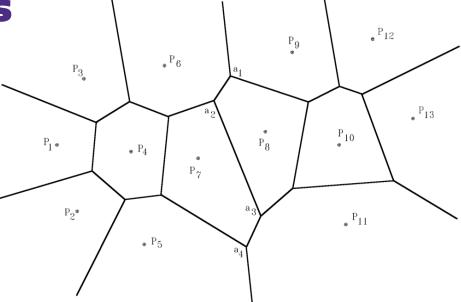
Pg



- > Done when current bisector goes off to infinity
- > Bisectors are equal distance between **closest** two p_i's

Voronoi Diagrams Divide & Conquer

> Combine step takes time proportional to number of sites on the boundary



> Worst case is O(n)

typically only a fraction of n sites are examined

> Master theorem says we get an O(n log n) algorithm

huge improvement over brute force

Picture from par.cse.nsysu.edu.tw/~cbyang/course/algo/algonote/algo4.ppt

HW3: Voronoi diagrams

- > HW3 asks you to compute a Voronoi diagram **on paper**
 - divide by copying half the sites to two separate pieces of paper
 - combine by copying answers back and then adding separating path
- > See the assignment for more details on the algorithm
- > Note: your answer *does not* have to be pixel perfect
 - can just eye-ball the bisectors
 - key is to understand the algorithm:
 - > why is it correct? only boundary is missing & this finds it
 - > why is it efficient? O(n) to compute boundary

Outline for Today

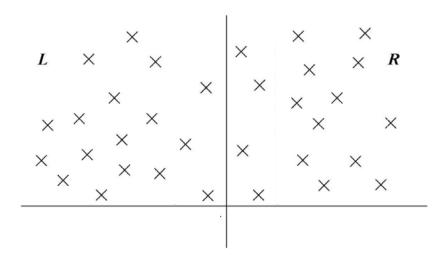
- > Counting inversions
- > Voronoi diagrams
- > Closest pair of points

- > Problem: Given a set of points p₁, ..., p_n in the plane, find the pair of distinct points (p_i, p_j) with minimum distance |p_i – p_j|
- > Brute force solution:
 - compute the distance of every pair; keep track of the closest
 - takes $\Theta(n^2)$ time since there are $n(n-1)/2 = \Theta(n^2)$ pairs



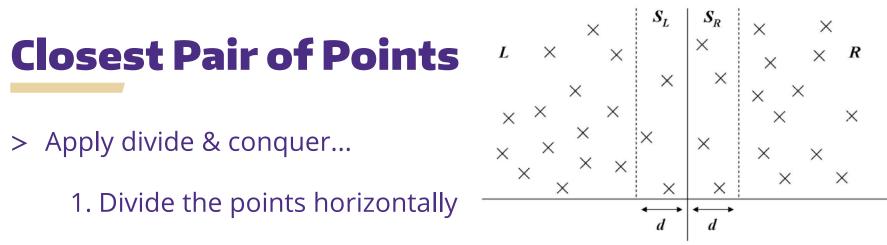
- > Apply divide & conquer...
 - 1. Divide the points horizontally > let L & R be the two halves
 - 2. Recursively finds the closest pair in L and R > let d be the smallest distance of the two
 - 3. Combine: find closest pair p in L, q in R > return closest of the three pairs

Picture from www.inrg.csie.ntu.edu.tw/algorithm2014/course/Divide%20&%20Conquer.pdf

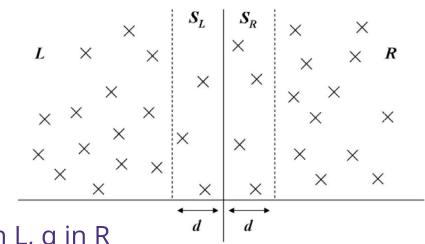


- - 1. Divide the points horizontally
 - 2. Recursively find the closest pairs in L and R
 - > let d be the smallest distance of the two
 - 3. Combine: find closest pair p in L, q in R with |p q| < d
 - > only need to consider p in S_L and q in S_R
 - > where $S_L = L$ within d of line, $S_R = R$ within d of line

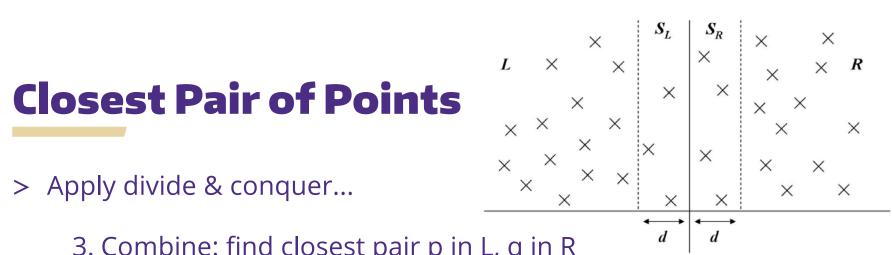
Picture from www.inrg.csie.ntu.edu.tw/algorithm2014/course/Divide%20&%20Conquer.pdf



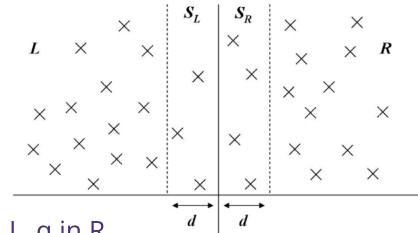
- > Apply divide & conquer...
 - 3. Combine: find closest pair p in L, q in R > only need to consider p in S_L and q in S_R
- > Unfortunately, this is still too many to check by brute force... could be, say, n/6 on each side, giving $\Theta((n/6)(n/6)) = \Theta(n^2)$ time
- > Will reduce the search by considering vertical distance also...



- - 3. Combine: find closest pair p in L, q in R > only need to consider p in S_1 and q in S_R
- Before we start, sort all the points by y-coordinate.
- Now get S_1 and S_R sorted by y-coordinate in O(n) time (by filtering big list)
- > For each p in S_L , just compare to those in S_R whose y-coordinate is within d of p's

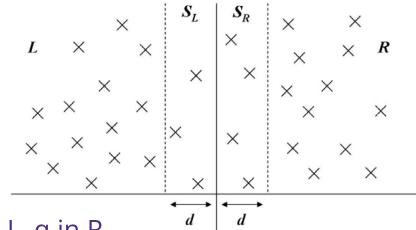


- > Apply divide & conquer...
 - 3. Combine: find closest pair p in L, q in R
 - > only need to consider p in S_L and q in S_R whose y-coordinate is within d of p's
- > Three finger algorithm:
 - one finger on p in S_L
 - one finger on p in S_L
 one finger first q in S_R with q.y ≥ p.y d
 - − one finger last q in S_R with q.y ≤ p.y + d



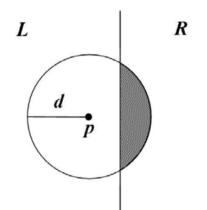
O(n) total finger moves compare p to all q's in this range

- > Apply divide & conquer...
 - 3. Combine: find closest pair p in L, q in R
 - > only need to consider p in S_L and q in S_R whose y-coordinate is within d of p's
- > Three finger algorithm:
 - one finger on p in S_L
 - one finger on p in S_L one finger first q in S_R with q.y \ge p.y d
 - − one finger last q in S_R with q.y ≤ p.y + d

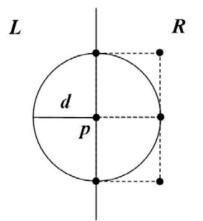


compare p to all q's in this range **Q**: how many are there?

Want to check for points in this shaded region:

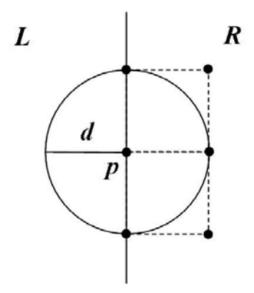


Will check all points in this d x 2d region:



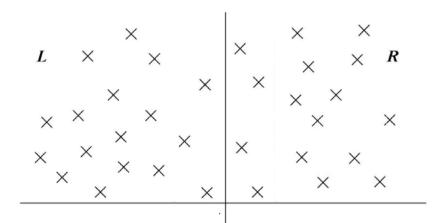
Pictures from www.inrg.csie.ntu.edu.tw/algorithm2014/course/Divide%20&%20Conquer.pdf

- > Q: How many points could be in the d x 2d box?
- > A: no more than 6 (see picture)
 - key point is that *no points in R are closer than d apart*!
 - this limits the number that could be close to p to O(1)
- > Example where a lot of elbow grease and problemspecific analysis is needed to find the best solution
 - used general techniques to get most of the way there





- > Apply divide & conquer...
 - 1. Divide the points into L & R
 - 2. Recursively finds the closest pair in L and R > let d be the smallest distance of the two
 - 3. Combine: find closest pair p in L, q in R with |p q| < d
 - > only need to consider p in $\rm S_L$ and
 - q in S_R whose y-coordinate is within d of p's
 - > only O(1) such points for each p
 - > return smallest of the 3 pairs above



- > Apply divide & conquer...
 - 1. Divide the points into L & R
 - 2. Recursively finds the closest pair in L and R
 - 3. Combine: find closest pair p in L, q in R with |p q| < d > each p is compared to O(1) q's, so O(n) time
- > Divide + combine in O(n) time
- > Running time is O(n log n) by master theorem

