CSE 417
Binary Search (pt 1)

Reminders

> **HW1 is due next Wednesday**
  – **fixed a typo & added some clarification**

> **Lecture videos available on Canvas**
  – **student questions cannot be heard**
  – **back of heads can be seen**

> **Overloading sign up:**
  https://goo.gl/forms/clZu6Wpy3xro69s13

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Outline for Today

> **Binary search on arrays** ⬅
> **Implementing binary search**

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Review: Binary Search on Arrays

Input: sorted array A and a value x
- array can store any ordered set: ints, floats, strings, etc.

Output: index i in [0, A.length] s.t. A[i-1] <= x < A[i]
- > (partly vacuously true if i = 0 or i = A.length)
- returns where x would be inserted to maintain ordering
- if x appears multiple times, this returns the *last* one
- > move "<=" to the right to get the *first* one

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Review: Binary Search on Arrays

Maintain a region of the array that is unexplored

<= x   x <
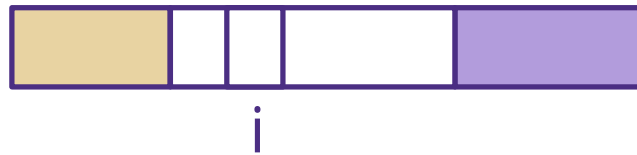
> Start with all white region
> Each iteration reduces size of the white region
> Finish with no white region

Review: Binary Search on Arrays

> Can reduce the size by looking at any element i:

i

> If A[i] <= x, then

> Else x < A[i]

Why?

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Review: Binary Search on Arrays

> Can reduce the size by looking at any element i:

i

> If A[i] <= x, then

> Else x < A[i]
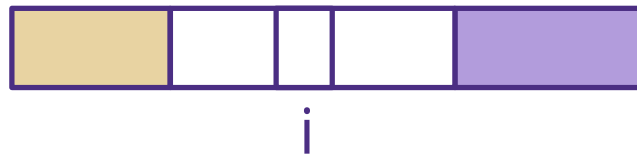
only because
A is **sorted**

Review: Binary Search on Arrays

> **Binary Search**: look at the *middle* element of the white region

i

> This ensures size is *cut in half* each time
> Size of white region approximately $n / 2^k$ after k iterations
> Done after $k = \lg n$ iterations
  – O(1) per iteration, so O(log n) time

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Review: Binary Search on Arrays

Linear search algorithm takes O(n) time
- start at i = 0
- increase i by 1 each time
- stop when A[i] <= x < A[i+1]

Binary search is an **exponential speedup**
- ... since exp(log n) = n ...
- hard to overstate the importance of this

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Simple application

> Suppose we want to find the index i such that

  u A[i] + v = x

> Q: How do we solve this?
  - cannot compute B[i] = u * A[i] + v
  - that would be exponentially slower!

> A: Binary search for (x-v) / u since

  u A[i] + v = x => A[i] = (x – v) / u

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Simple application 2

> Suppose we want to find the index i such that
   tanh(A[i]) = x
   – (or sigmoid or any other monotonic function)

> Q: How do we solve this?

> A: Search for A[i] = $\tanh^{-1}(x)$

> Q: What if the function is not easily invertible?
   – come back to this later...

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Interview question 1

> **Problem**: find the N-th largest number of the form $2^a 3^b 5^c$
> for any a, b, c >= 0
  – i.e., numbers not divisible by anything other than 2, 3, or 5

> **Idea**: generate the numbers *in order*, stopping at N

> **Sub-problem**: find the (m+1)-st number of this form *given* first m
  – we can use the first m numbers to find the next one

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Interview question 1

> **Sub-problem 1**: find the (m+1)-st number of this form given first m

> If (m+1)-st number is $2^a 3^b 5^c$,
> then $2^{a-1} 3^b 5^c$ is smaller and also of this form (assuming a > 0),
> so $2^{a-1} 3^b 5^c$ is **one of the first m** numbers
>   – likewise for b and c
>   – next number is 2, 3, or 5 times an earlier number

> In particular, if (m+1)-st is 2 x an earlier number,
> then it must be the **smallest** 2 x earlier not in the list

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Interview question 1

> **Sub-problem 2**: given a list A[0..m-1] of the first m numbers, in increasing order, find the smallest i such that 2 A[i] > A[m-1]
>
> – equivalently, 2 A[i] >= A[m-1] + 1

> Q: how do we do that?
> A: binary search for (A[m-1]+1) / 2

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Interview question 1

> Start with A = [1]
> **Algorithm:** for m = 1 to N-1
  – binary search to find smallest i s.t. 2 * A[i] > A[m-1]
  – ... likewise for 3 and 5
  – add the smallest of these three numbers to the list

> Q: total running time?
> A: O(N log N)

Interview question 1

> Can we improve this further?

> Compare smallest i s.t. 2 * A[i] > **A[m-1]** and
>   smallest j s.t. 2 * A[j] > **A[m]**
>   – binary search for (A[m-1]+1) / 2 and (A[m]+1) / 2
>   – these two indices should be close

> Seems like we're doing too much work by
>   – could restrict to A[i..m-1] with i from last search
>   – but we can do better…

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Interview question 1

> Compare smallest i s.t. 2 * A[i] > **A[m-1]** and
>   smallest j s.t. 2 * A[j] > **A[m]**

> **Observation**: they must be equal or differ by 1

> Since A[m] is smallest of 2x, 3x, 5x... either A[m] = 2 * A[i] or A[m] < 2 * A[i]
  - if A[m] < 2 * A[i], then j = i since i is still big enough
  - if A[m] = 2 * A[i], then A[m] < 2 * A[i+1] and j = i+1

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Interview question 1

> **Algorithm 2:** maintain indexes of smallest i, j, k s.t.
>   2 A[i], 3 A[j], 5 A[k] > A[m-1]
>   for m = 1 to N-1
>   – add the smallest of 2 A[i], 3 A[j], 5 A[k] to the list
>   – increment i, j, and/or k appropriately

> Q: total running time?
> A: O(N)

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Interview question 1

> An example of how the fastest algorithm can be produced by starting with a basic technique + a lot of elbow grease

> Binary search disappears in the final answer even though we used to get there
  – we will see other examples of this
  – presentations of the best algorithm will often just describe the optimal solution directly without any binary search
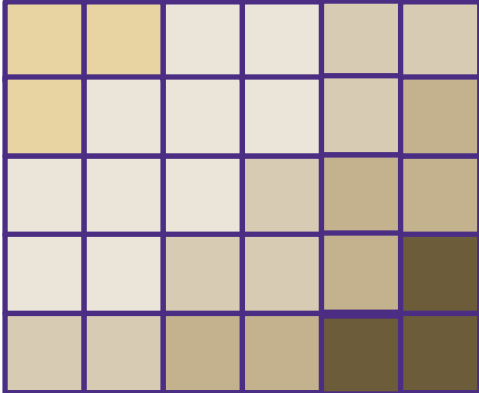   > makes you sound smarter if you do it that way

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Interview question 2

> Find x in a sorted n x n table
  - every row and every column is sorted

> **Algorithm 1**: binary search every row
  - $O(n \log n)$ time

Interview question 2

> Find x in a sorted n x n table
  – every row and every column is sorted

> Once again, the binary searches are doing too much work
  – usually the next answer is about the same as the previous one

> Not the case that the indexes only increase by 0 or 1 each time!

> BUT the total increase over n searches is at most n:
  – we only move left each time
  – so we can take at most n steps all together

Interview question 2

> Find x in a sorted n x n table
  – every row and every column is sorted

> **Algorithm 1**: linear every row starting from answer on previous
  – O(n) time

> Again, binary search disappears

Interview question 2

> Find x in a sorted n x n table
  - every row and every column is sorted

> **Algorithm 1**: linear every row starting from answer on previous
  - O(n) time

> Worth noting: O(n log n) is not much slower than O(n)
  - remember that log n is exponentially smaller than n
> Worth pointing out O(n log n) algorithm in an interview

Practical example: web search

> For each word, make record of all the web pages with that word
  - many terabytes of data
  - too much data for one machine...

> Partition web pages randomly across machines
> Each machine records where word appears in its own pages
  - have enough machines that each gets, say, 100 GB of data

> To look up all pages where word occurs:
  - send request to all machines
  - concatenate the lists they return

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Practical example: web search

> Q: How does each machine get the pages for a word?

> A: sorting and binary search
   – each machine sorts its records on disk
   – look up a word by using binary search

> Algorithm works fine if A is on disk
   – only need the ability to look up A[i] for any i
   – can do this in Java using FileChannel instead of FileInputStream

> Cost is time for lg n disk seeks

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Practical example: web search

> **Key lesson**: not always necessary to use dynamic data structures
- don't always need hash tables and AVL trees (or B+ trees on disk)
- they are more complex, slower, and user more memory (by constant factors)

> Only need them to support intermixed updates and searches
- sorting and binary search are fine if all the updates come first

> Sorting also works fine if the data only changes occasionally
- at one point, web indexes were only changed *nightly*
  > this is not uncommon in practice
- can add new data and re-sort at night when not in use

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Outline for Today

> **Binary search on arrays**
> **Implementing binary search** ⬅

Implementing Algorithms

Key Idea: invariants — facts that are always true
- – critical to correct implementation (and often run time analysis also)
- – often most of the hard work is getting these right

> **Rep invariant**: claim about data structures
- – always true (except briefly when mutating the data structures)
- – ex: in AVL trees, heights of two subtrees at any node differ by at most 1

> **Loop invariant**: claim about method state
- – always true at the *top* of the loop

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Implementing Algorithms

> **Loop invariant**: claim about method state
  – always true at the *top* of the loop

> To prove that a loop is correctly implemented, check:
  – invariant is true initially
  – invariant remains true each time the loop body executes

> Then know the invariant is true after the loop
  – choose the invariant so that, when the loop exits,
    you have enough information to return a correct answer

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Implementing Binary Search on Arrays

> Method state: indexes i and j

> Loop invariant: A[0], ..., A[i-1] <= x and x < A[j], ..., A[n-1]

Notes on notation:
- A[0], ..., A[i-1] <= x means A[0] <= x and ... and A[i-1] <= x
- vacuously true if i <= 0
  > only making claims about indexes >= 0 and <= i-1

Implementing Binary Search on Arrays

```
int i = 0, j = n;
```
true initially

```
// Invariant: A[0], ..., A[i-1] <= x and x < A[j], ..., A[n-1]
while (i < j) {
  int m = (i + j) / 2;
  if (A[m] <= x)
    i = m + 1;
  else
    j = m;
}

return i;
```

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Implementing Binary Search on Arrays

```
int i = 0, j = n;

// Invariant: A[0], …, A[i-1] <= x and x < A[j], …, A[n-1]
while (i < j) {
  int m = (i + j) / 2;
  if (A[m] <= x)
    i = m + 1;          ←———————————    A[i-1] = A[m] <= x
  else
    j = m;
}

return i;
```

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Implementing Binary Search on Arrays

```
int i = 0, j = n;

// Invariant: A[0], ..., A[i-1] <= x and x < A[j], ..., A[n-1]
while (i < j) {
    int m = (i + j) / 2;
    if (A[m] <= x)
        i = m + 1;          ⟵          A[i-1] = A[m] <= x
    else
        j = m;                          Q: What about A[i], ..., A[m-1]?
}

return i;
```

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Implementing Binary Search on Arrays

```
int i = 0, j = n;

// Invariant: A[0], ..., A[i-1] <= x and x < A[j], ..., A[n-1]
while (i < j) {
  int m = (i + j) / 2;
  if (A[m] <= x)
    i = m + 1;        ⟵        A[i-1] = A[m] <= x
  else
    j = m;                     Q: What about A[i], ..., A[m-1]?
}                              A: Also <= x since A is sorted

return i;
```

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Implementing Binary Search on Arrays

```
int i = 0, j = n;

// Invariant: A[0], …, A[i-1] <= x and x < A[j], …, A[n-1]
while (i < j) {
  int m = (i + j) / 2;
  if (A[m] <= x)
    i = m + 1;
  else
    j = m;          ⟵           x < A[m] = A[j]
}

return i;
```

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Implementing Binary Search on Arrays

```
int i = 0, j = n;

// Invariant: A[0], ..., A[i-1] <= x and x < A[j], ..., A[n-1]
while (i < j) {
  int m = (i + j) / 2;
  if (A[m] <= x)
    i = m + 1;
  else
    j = m;
}

return i;
```

x < A[m] = A[j]

x < A[m+1], .., A[j-1]
since A is sorted

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Implementing Binary Search on Arrays

```
// Invariant: A[0], ..., A[i-1] <= x and x < A[j], ..., A[n-1]
while (i < j) { ... }
```

> When we exit the loop, we have
  – i = j and A[0], ..., A[i-1] <= x and x < A[j], ..., A[n-1]
    > (actually, we only obviously have i >= j, but a more careful check shows i = j)
  – in other words, A[0], ..., A[i-1] <= x and x < A[i], ..., A[n-1]
  – thus, the problem specification says i is exactly what we promised to return
    > this is not uncommon...
    > loop invariants are often "weakened" versions of output promise

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Implementing Binary Search on Arrays

> When we exit the loop, we return the right answer

> Q: Do we actually exit the loop?
  – usually you get that from the run time analysis,
  – but we did this somewhat sloppily….

> A: Yes, provided that i increases or j decreases every time.
> Q: Do they?

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Implementing Binary Search on Arrays

> We set m = (i + j) / 2
  – this means that i <= m <= j

> If we set i = m + 1, then $i_{new} >= i_{old} + 1$
  – looks good!

> If we set j = m, then $j_{new} <= j_{old}$
  – we are in trouble if $m = j_{old}$!

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Implementing Binary Search on Arrays

> Can we have m = j when we set m = (i + j) / 2?

> Can see that m will be closer to j when i is closer to j...
so consider i = j – 1 (the worst case)

> Then m = (j – 1 + j) / 2 = (2j – 1) / 2...
> In Java, this integer division will **truncate** to j – 1
  – we got lucky!

> But Math.round((i + j) / 2.0) could loop forever!

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Implementing Binary Search on Arrays

Lessons:

1. invariants are critical to implementing complex algorithms & data structures

2. implementing algorithms correctly requires careful attention to detail
    > easy to make mistakes on this, one of the easiest algorithms we will see!
    > this comes up in interviews too

3. if a library implementation is available, use it!
    > don't waste your time or risk releasing buggy code

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Implementing Binary Search on Arrays

> For the most part, we will stick to pseudocode from here on
  - you'll still need to write code in the HWs

> From a theory perspective, this wasn't a real problem
  - we only run into it when j – i is small
  - we could switch to linear search when j – i < 1000
    asymptotic complexity would be the same

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