

Reference Sheet

BFS(s)

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1: Initialize: All vertices marked "undiscovered"
2: Mark  $s$  discovered
3:  $queue \leftarrow \{s\}$ 
4: while  $queue$  not empty do
5:    $u \leftarrow removeFront(queue)$ 
6:   for all edge  $(u, x)$  do
7:     if  $x$  is "undiscovered" then
8:       Mark  $x$  "discovered"
9:       Append  $x$  on  $queue$ 
10:    end if
11:  end for
12:  Mark  $u$  "fully explored"
13: end while

```

TopologicalOrder(G)

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1:  $count[w] \leftarrow$  (remaining) number of incoming edges to  $w$ 
2:  $S \leftarrow$  set of (remaining) nodes with no incoming edges
3: while  $S$  not empty do
4:   Remove some  $v$  from  $S$ 
5:   make  $v$  next in topological order
6:   for all edges from  $v$  to some  $w$  do
7:     decrement  $count[w]$ 
8:     if  $count[w] = 0$  then
9:       add  $w$  to  $S$ 
10:    end if
11:  end for
12: end while

```

DFS(v):

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1:  $v.dfs\# = dfscounter++$ 
2: for all edge  $(v, x)$  do
3:   if  $x.dfs\# = -1$  then
4:     DFS( $x$ )
5:   else
6:     (code for back edges, etc.)
7:   end if
8:   Mark  $v$  "completed"
9: end for

```

Shortest Weighted Path(G, s, l)

- 1: Let S be the set of explored nodes
- 2: $S = \{s\}$ and $d(s) = 0$
- 3: **while** $S \neq V$ **do**
- 4: Select a node $v \notin S$ with at least one edge from S for which

$$d'(v) = \min_{e=(u,v):u \in S} d(u) + l_e$$

is as small as possible.

- 5: Add v to S and define $d(v) = d'(v)$
 - 6: **end while**
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Min Spanning Tree(G, l) (Prim's Algorithm)

- 1: Arbitrarily choose some starting node x .
 - 2: Let $V_{new} = \{x\}$, $E_{tree} = \{\}$.
 - 3: **while do** $V_{new} \neq V$
 - 4: Choose edge $e = (u, v)$ with minimal weight such that $u \in V_{new}$ and $v \notin V_{new}$
 - 5: Add v to V_{new} and e to E_{tree} .
 - 6: **end while**
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Huffman(C, f)

- 1: Insert node for each letter into priority queue by freq
 - 2: **while** queue length > 1 **do**
 - 3: Remove smallest 2 nodes, call them x, y
 - 4: Make new node z with children x, y .
 - 5: $f(z) = f(x) + f(y)$
 - 6: Insert z into queue
 - 7: **end while**
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O, Ω, Θ

- $f(n)$ is $O(g(n))$ iff there is a constant $c > 0$ so that $f(n)$ is eventually always $\leq c g(n)$
- $f(n)$ is $\Omega(g(n))$ iff there is a constant $c > 0$ so that $f(n)$ is eventually always $\geq c g(n)$
- $f(n)$ is $\Theta(g(n))$ iff there is are constants $c_1, c_2 > 0$ so that eventually always $c_1 g(n) \leq f(n) \leq c_2 g(n)$

Greedy Analysis Strategies

- Greedy algorithm *stays ahead*. Show that after each step of the greedy algorithm, its solution is at least as good as any other algorithm's.
- *Structural*. Discover a simple "structural" bound asserting that every possible solution must have a certain value. Then show that your algorithm always achieves this bound.

- *Exchange argument.* Gradually transform any solution to the one found by the greedy algorithm without hurting its quality.

Master Recurrence

- If $T(n) = aT(n/b) + cn^k$ for $n > b$ then
 - if $a > b^k$ then $T(n)$ is $\Theta(n^{\log_b a})$.
(many subproblems \Rightarrow leaves dominate)
 - if $a < b^k$ then $T(n)$ is $\Theta(n^k)$
(few subproblems \Rightarrow top level dominates)
 - if $a = b^k$ then $T(n)$ is $\Theta(n^k \log n)$
(balanced \Rightarrow all $\log n$ levels contribute)

Minimum Stamp Recurrence

$$Opt(i) = \min \left(\begin{cases} 0 & i = 0 \\ 1 + Opt(i - 5) & i \geq 5 \\ 1 + Opt(i - 4) & i \geq 4 \\ 1 + Opt(i - 1) & i \geq 1 \end{cases} \right)$$

Minimum Stamp: Memoized Code

Initialize M to array of “empty” values

procedure MEMOIZESTAMP(n)

if $M[n] =$ “empty” **then** $M[n] = \min \left(\begin{cases} 0 & i = 0 \\ 1 + MemoizeStamp(i - 5) & i \geq 5 \\ 1 + MemoizeStamp(i - 4) & i \geq 4 \\ 1 + MemoizeStamp(i - 1) & i \geq 1 \end{cases} \right)$

end if

return $M[n]$

end procedure

Minimum Stamp: Iterative Code

for $i = 1$ to n **do**

$M(i) = \min \left(\begin{cases} 0 & i = 0 \\ 1 + M(i - 5) & i \geq 5 \\ 1 + M(i - 4) & i \geq 4 \\ 1 + M(i - 1) & i \geq 1 \end{cases} \right)$

end for

RNA folding recurrence

$$Opt[i, j] = \begin{cases} 0 & \text{if } i \geq j - 4 \\ \max \left\{ \begin{array}{l} Opt[i, j - 1] \\ \max_t (1 + Opt[i, t - 1] + Opt[t + 1, j - 1]) \end{array} \right. \end{cases}$$

NP

A decision problem is in NP if and only if there is a polynomial time procedure $verify()$ and an integer k such that

1. For every YES problem instance x there is a hint h with $|h| \leq |x|^k$ such that $verify(x, h) = YES$
2. For every NO problem instance x there is no hint h with $|h| \leq |x|^k$ such that $verify(x, h) = YES$

NP-hard

A problem B is NP-hard if and only if every problem in NP is polynomial time reducible to B .

NP-complete

A problem B is NP-complete if and only if both:

1. B is in NP
2. B is NP-hard

Polynomial-Time Reductions

Given two decision problems, A, B , we say that A is polynomial-time reducible to B , $A \leq_P B$ if there exists some polynomial-time function f that converts each instance x of problem A into an instance $f(x)$ of problem B such that x is a YES instance of A if and only if $f(x)$ is a YES instance of B .