



# CSE/STAT 416

## Assessing Performance

Tanmay Shah  
University of Washington  
June 24, 2024

? Questions? Raise hand or [sli.do #cs416](#)

💬 **Before Class:** Did you get to do anything fun during the (short) spring break?

🎵 Listening to: [gretperez](#)



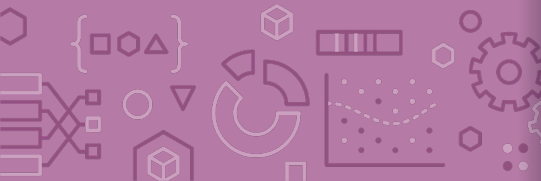
# Logistics

Check EdStem for announcements and clarifications

Module 0 assignments due!

- Learning Reflection 0 due tonight
- HW0 due Wednesday night

We will rush a bit in the next few lectures



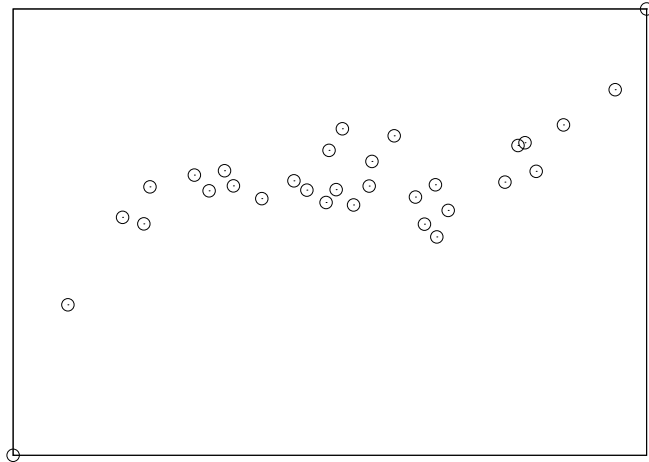
Pre-Class  
Video 1,

Lecture 0  
recap

*Feature Extraction*

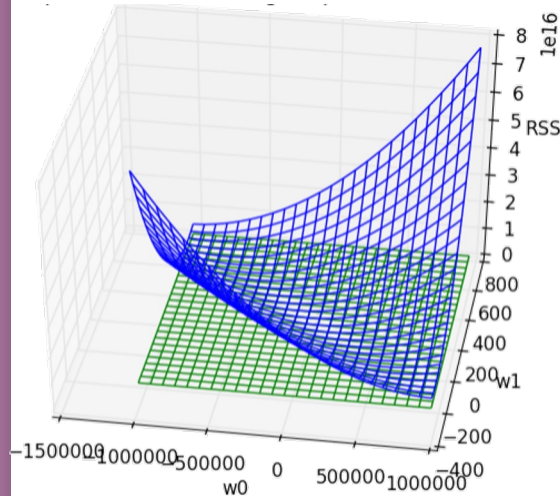
# Mean Squared Error (MSE)

How to define error? **Mean squared error (MSE)**



# Minimizing Cost

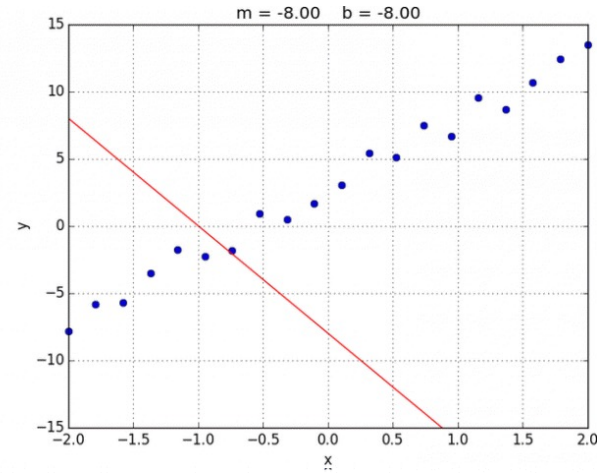
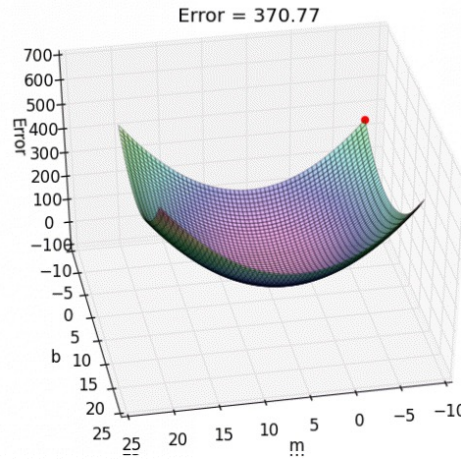
MSE is a function with inputs  $w_0, w_1$ , different settings have different MSE for a dataset



$$\begin{aligned}\hat{w}_0, \hat{w}_1 &= \underset{w_0, w_1}{\operatorname{argmin}} \operatorname{MSE}(w_0, w_1) \\ &= \underset{w_0, w_1}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n (y_i - (w_0 + w_1 x_i))^2\end{aligned}$$

Unfortunately, we can't try it out on all possible settings ☹️

# Gradient Descent



Instead of computing all possible points to find the minimum, just start at one point and “roll” down the hill. Use the gradient (slope) to determine which direction is down.

Start at some (random) weights  $w$

While we haven't converged:

$$w^{(t+1)} = w^{(t)} - \alpha \nabla L(w)$$

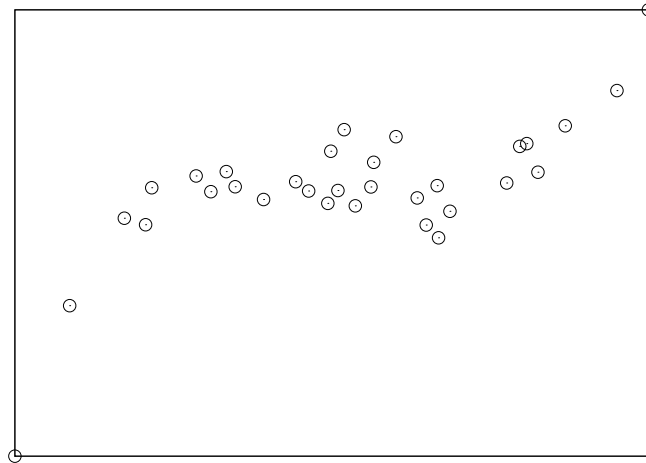
- $\alpha$ : learning rate
- $\nabla L(w)$ : the gradients of loss function  $L$  on a set of weights  $w$

# Higher Order Features

This data doesn't look exactly linear, why are we fitting a line instead of some higher-degree polynomial?

We can! We just have to use a slightly different model!

$$y_i = w_0 + w_1x_i + w_2x_i^2 + w_3x_i^3 + \epsilon_i$$



# Polynomial Regression

## Model

$$y_i = w_0 + w_1x_i + w_2x_i^2 + \dots + w_px_i^p + \epsilon_i$$

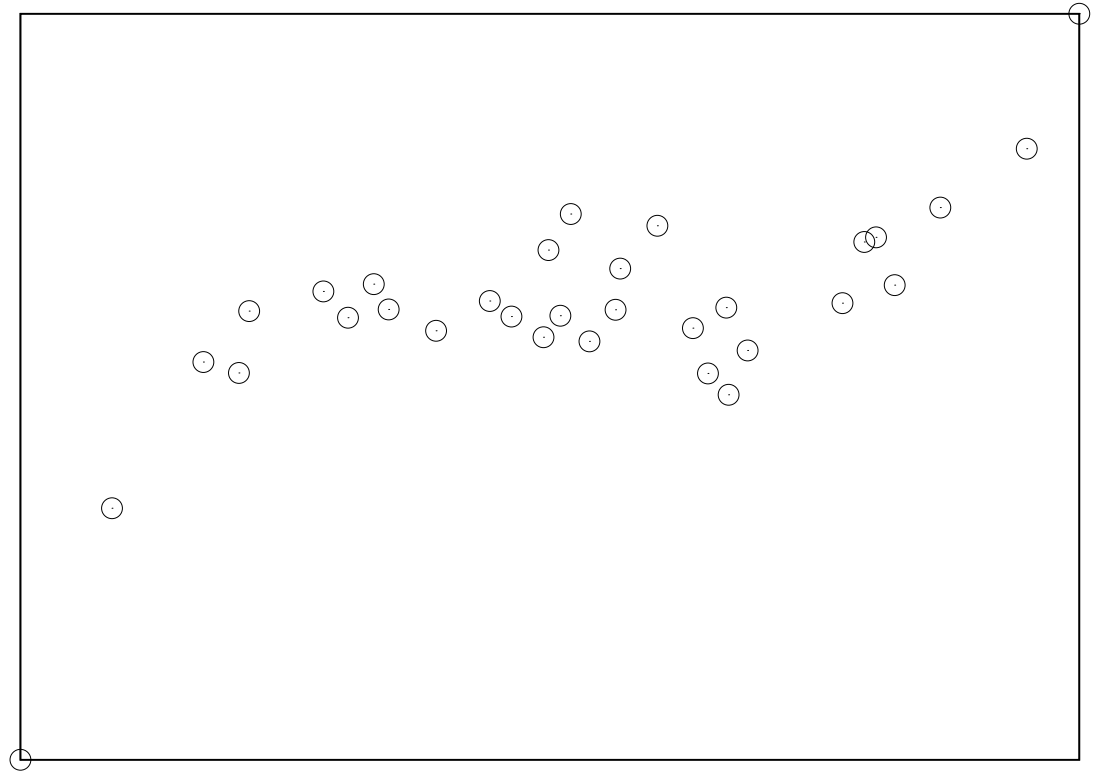
Just like linear regression, but uses more features!

Feature	Value	Parameter
0	1 (constant)	$w_0$
1	$x$	$w_1$
2	$x^2$	$w_2$
...	...	...
p	$x^p$	$w_p$

How do you train it? Gradient descent (with more parameters)



# Polynomial Regression



How to decide what the right degree? Come back later!

# Features

**Features** are the values we select or compute from the data inputs to put into our model. **Feature extraction** is the process of turning the data into features.

## Model

$$\begin{aligned}y_i &= w_0 h_0(x_i) + w_1 h_1(x_i) + \dots + w_D h_D(x_i) + \epsilon_i \\ &= \sum_{j=0}^D w_j h_j(x_i) + \epsilon_i\end{aligned}$$

Feature	Value	Parameter
0	$h_0(x)$ often 1 (constant)	$w_0$
1	$h_1(x)$	$w_1$
2	$h_2(x)$	$w_2$
...	...	...
D	$h_D(x)$	$w_D$

# Adding Other Inputs

Generally we are given a data table of values we might look at that include more than one value per house.

Each row is a single house.

Each column (except Value) is a data input.

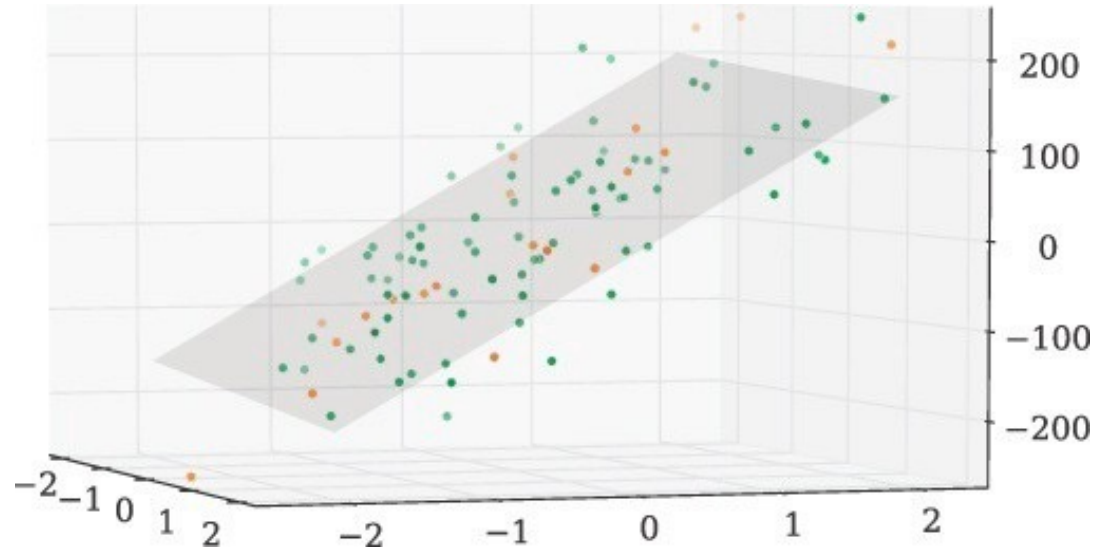
sq. ft.	# bathrooms	owner's age	...	value
1400	3	47	...	70,800
700	3	19	...	65,000
...	...	...	...	...
1250	2	36	...	100,000



## More Inputs - Visually

Adding more features to the model allows for more complex relationships to be learned

$$y_i = w_0 + w_1(sq. ft.) + w_2(\# bathrooms) + \epsilon_i$$



Coefficients tell us the rate of change **if all other features are constant**

# Notation

**Important:** Distinction is the difference between a *data input* and a *feature*.

Data inputs are columns of the raw data

Features are the values (possibly transformed) for the model (done after our feature extraction  $h(x)$ )

Data Input:  $x_i = (x_i[1], x_i[2], \dots, x_i[d])$

Output:  $y_i$

$x_i$  is the  $i^{th}$  row

$x_i[j]$  is the  $i^{th}$  row's  $j^{th}$  data input

$h_j(x_i)$  is the  $j^{th}$  feature of the  $i^{th}$  row

This makes explicit, an often-implicit modeling choice of which features to use and how to transform them.

# Features

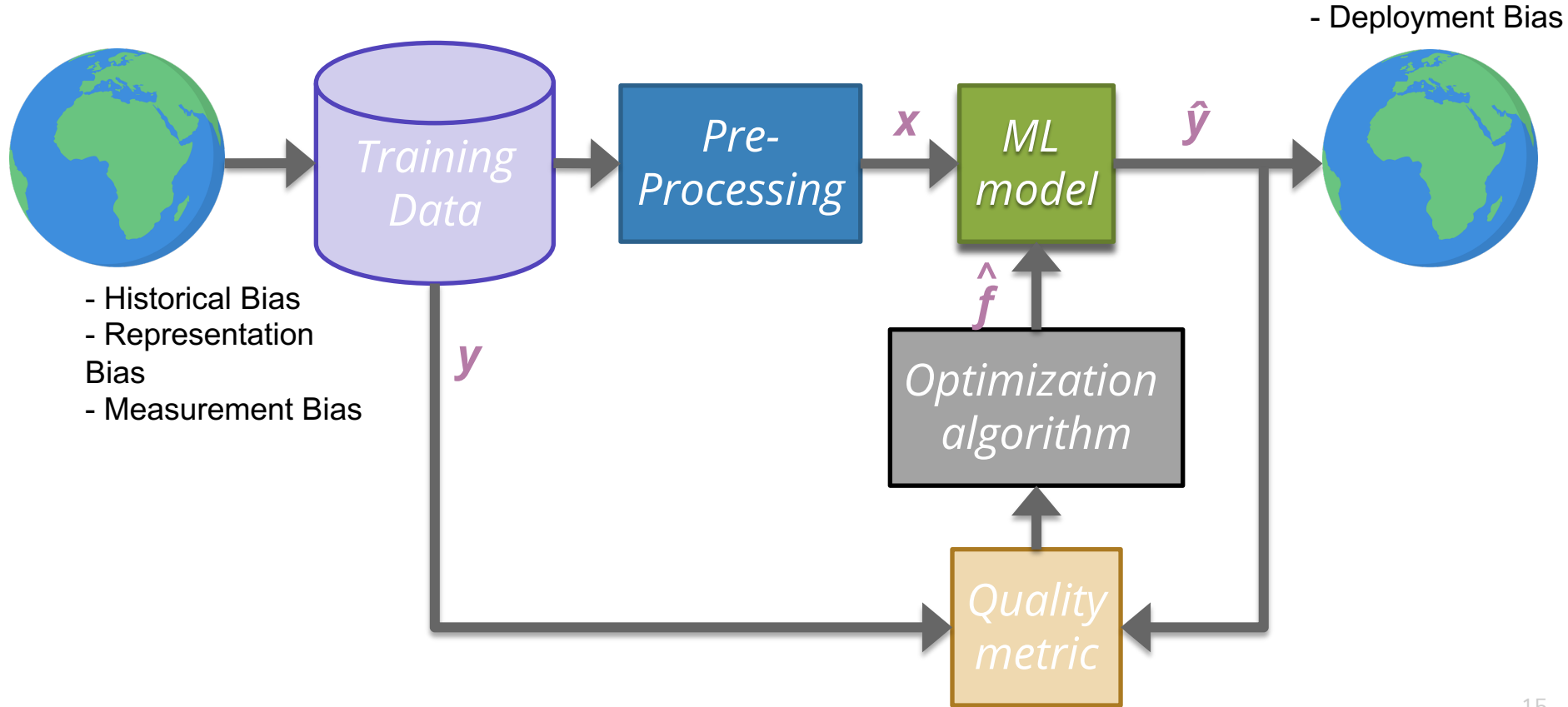
You can use anything you want as features and include as many of them as you want!

Generally, more features means a more complex model. This might not always be a good thing!

Choosing good features is a bit of an art.

Feature	Value	Parameter
0	1 (constant)	$w_0$
1	$h_1(x) \dots x[1] = \text{sq. ft.}$	$w_1$
2	$h_2(x) \dots x[2] = \text{\# bath}$	$w_2$
...	...	...
D	$h_D(x) \dots \text{like } \log(x[7]) * x[2]$	$w_D$

# ML Pipeline



# Linear Regression Recap

## Dataset

$\{(x_i, y_i)\}_{i=1}^n$  where  $x \in \mathbb{R}^d, y \in \mathbb{R}$

## Feature Extraction

$h(x): \mathbb{R}^d \rightarrow \mathbb{R}^D$

$h(x) = (h_0(x), h_1(x), \dots, h_D(x))$

## Regression Model

$y = f(x) + \epsilon$

$$= \sum_{j=0}^D w_j h_j(x) + \epsilon$$

$$= w^T h(x) + \epsilon$$

## Quality Metric

$$MSE(w) = \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2$$

## Predictor

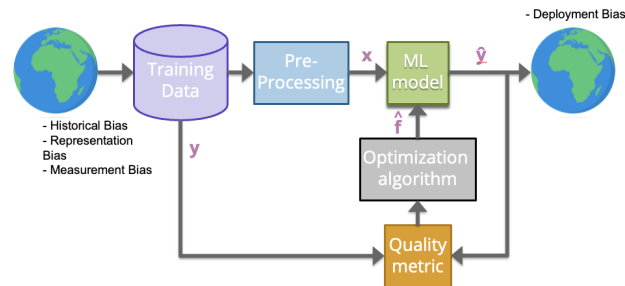
$$\hat{w} = \underset{w}{\operatorname{argmin}} MSE(w)$$

## ML Algorithm

Optimized using Gradient Descent

## Prediction

$$\hat{y} = \hat{w}^T h(x)$$







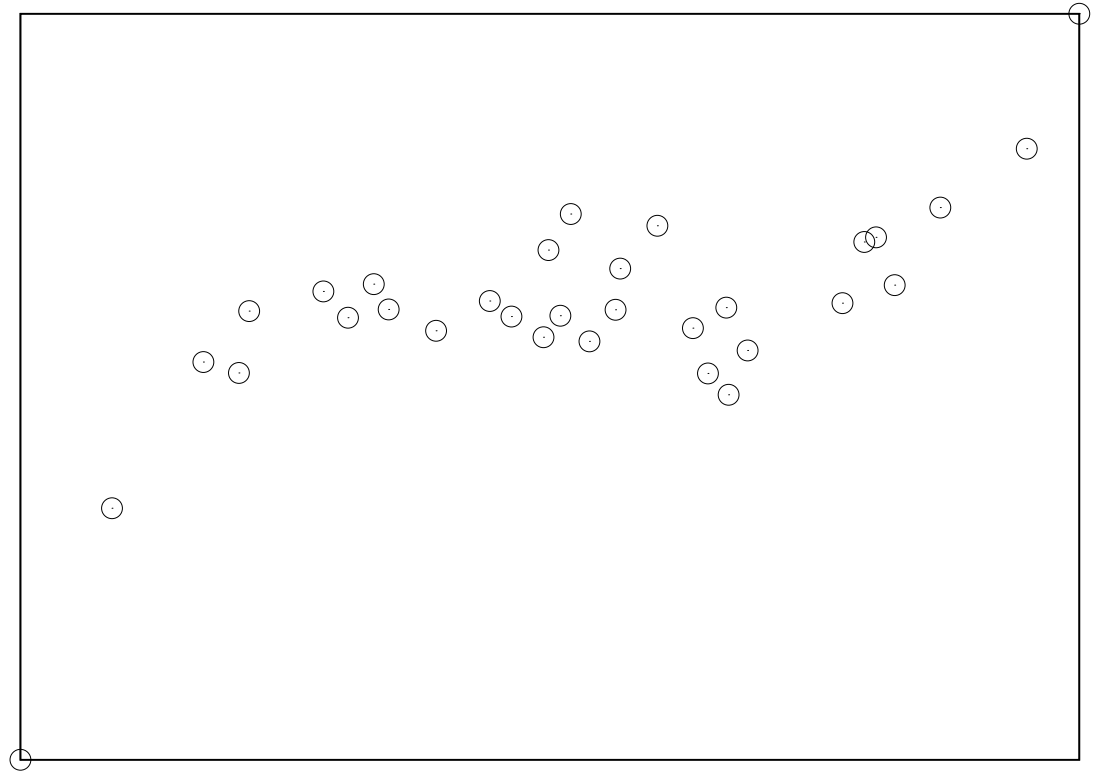
## *Brain Break*



# Pre-Class Video 2

*Assessing Performance*

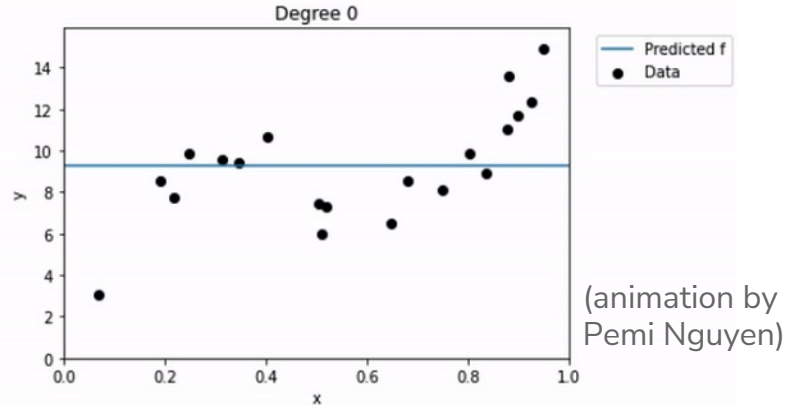
# Polynomial Regression



How do we decide what the right choice of  $p$  is?

# Polynomial Regression

Consider using different degree polynomials on the same training set.



From estimating with your eyes, which one seems to have the lowest MSE on this dataset?

It seems like minimizing the MSE on the training set is not the whole story here ...

# Performance

Why do we train ML models?

We generally want them to do well on **unseen** data.

If we choose the model that minimizes MSE on the data it learned from, we are just choosing the model that can **memorize**, not the one that **generalizes** well.

**Analogy:** Just because you can get 100% on a practice exam you've studied for hours, it doesn't mean you will also get 100% on the real test that you haven't seen before.

Key Idea: Assessing yourself based on something you learned from generally overestimates how well you will do in the future!

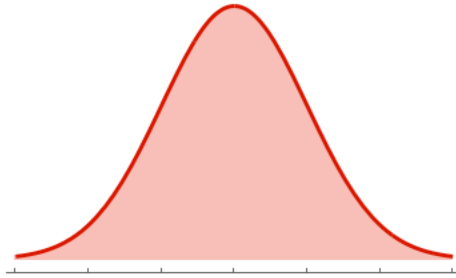


# Future Performance

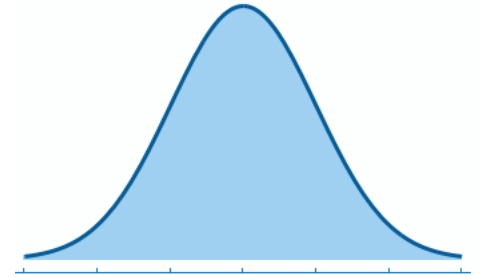
What we care about is how well the model will do on unseen data.

How do we measure this? **True error**

To do this, we need to understand uncertainty in the world



Sq. Ft.



Price | Sq. Ft.

**True Error**



# Model Assessment

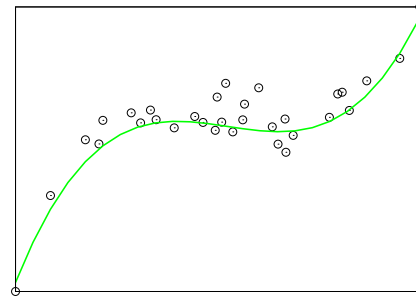
How can we figure out how well a model will do on future data if we don't have any future data?

Estimate it! We can hide data from the model to test it later as an estimate how it will do on future data

We will randomly split our dataset into a **train set** and a **test set**

The train set is to train the model

The test set is to estimate the performance in the future



# Test Error

What we really care about is the **true error**, or how well a model perform on unseen data in the wild, but we can't know that without having an infinite amount of data!

We will use the **test set** to estimate the true error.

**Note:** The train and test set need to be **randomly split** in order for the test set to be truly reflective of data in the real world.

Call the error on the test set the **test error** for a model  $\hat{f}$ :

$$MSE_{test} = \frac{1}{n} \sum_{i \in Test} \left( y^{(i)} - \hat{f}(x^{(i)}) \right)^2$$

If the test set is large enough, this can approximate the true error.



# Train/Test Split

If we use the test set to estimate future, how big should it be?

This comes at a cost of reducing the size of the training set though (in the absence of being able to just get more data)

In practice people generally do train:test as either

80:20

90:10

**Important:** Never train your model on data in the test set!



# Regression Recap

# Linear Regression Model

Assume we have a simple model with **one feature**, where we establish a linear relationship between **the area of a house  $i$**  and **its price**:

$$y_i = w_0 + w_1 x_i + \epsilon_i$$

$w_0, w_1$  are the **parameters** of our model that need to be learned

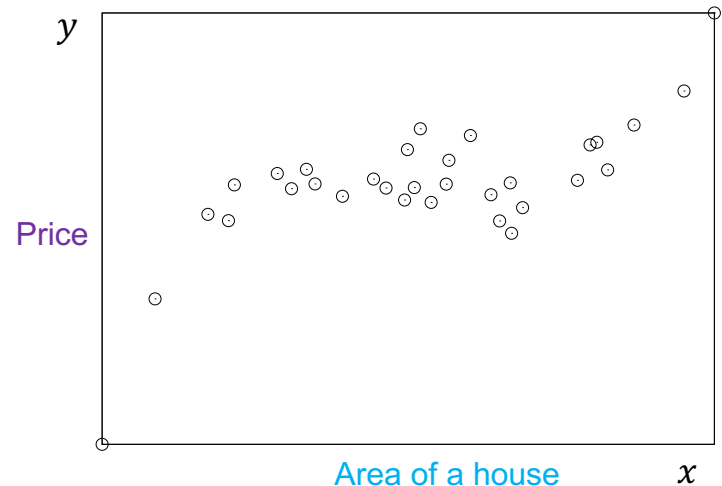
$w_0$  is the intercept / **bias**, representing the starting price of a house

$w_1$  is the slope / **weight** associated with **feature** "area of a house"

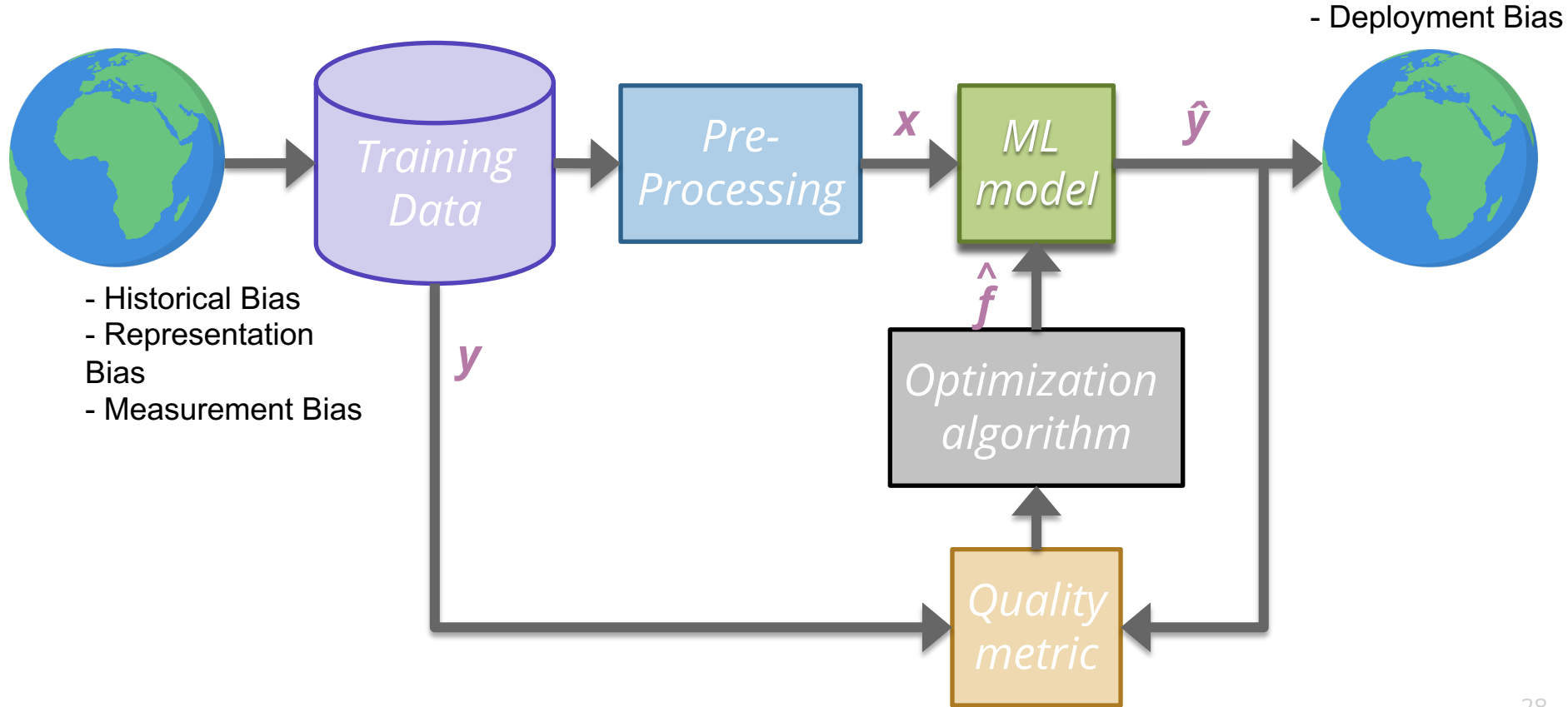
Learn estimates of these parameters  $\hat{w}_1, \hat{w}_0$  and use them to predict new value for any input  $x$ !

$$\hat{y} = \hat{w}_1 x + \hat{w}_0$$

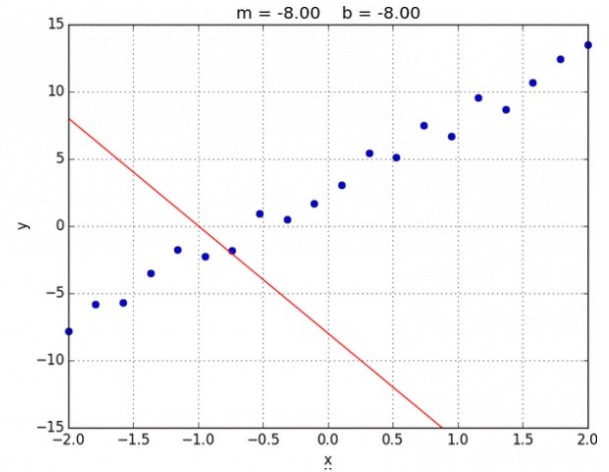
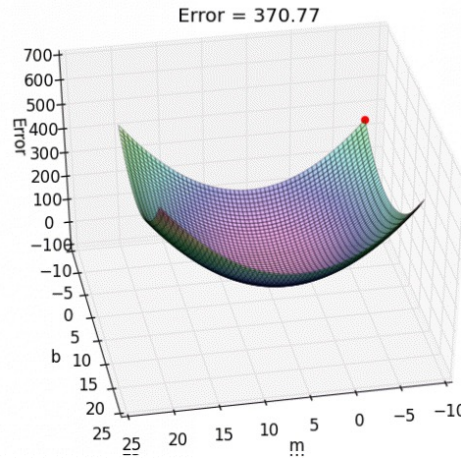
Why don't we add  $\epsilon$ ?



# ML Pipeline



# Gradient Descent



Instead of computing all possible points to find the minimum, just start at one point and “roll” down the hill. Use the gradient (slope) to determine which direction is down.

Start at some (random) weights  $w$

While we haven't converged:

$$w^{(t+1)} = w^{(t)} - \alpha \nabla L(w)$$

- $\alpha$ : learning rate
- $\nabla L(w)$ : the gradients of loss function  $L$  on a set of weights  $w$

# Pre-Class 1

## Recap: Features

You can use anything you want as features and include as many of them as you want!

Generally, more features means a more complex model. This might not always be a good thing!

Choosing good features is a bit of an art.

Feature	Value	Parameter
0	1 (constant)	$w_0$
1	$h_1(x) \dots x[1] = \text{sq. ft.}$	$w_1$
2	$h_2(x) \dots x[2] = \text{\# bath}$	$w_2$
...	...	...
D	$h_D(x) \dots \text{like } \log(x[7]) * x[2]$	$w_D$

# Linear Regression Recap

## Dataset

$\{(x_i, y_i)\}_{i=1}^n$  where  $x \in \mathbb{R}^d, y \in \mathbb{R}$

## Feature Extraction

$h(x): \mathbb{R}^d \rightarrow \mathbb{R}^D$

$h(x) = (h_0(x), h_1(x), \dots, h_D(x))$

## Regression Model

$y = f(x) + \epsilon$

$$= \sum_{j=0}^D w_j h_j(x) + \epsilon$$

$$= w^T h(x) + \epsilon$$

## Quality Metric

$$MSE(w) = \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2$$

## Predictor

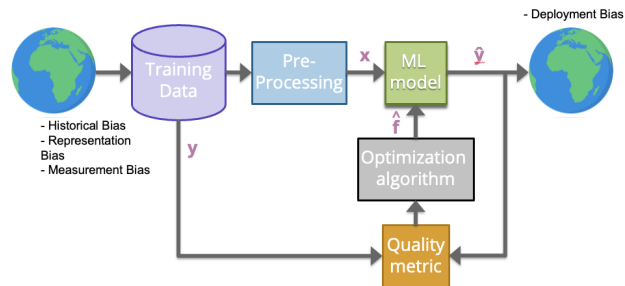
$$\hat{w} = \underset{w}{\operatorname{argmin}} MSE(w)$$

## ML Algorithm

Optimized using Gradient Descent

## Prediction

$$\hat{y} = \hat{w}^T h(x)$$



# Term recap

**Supervised learning:** The machine learning task of learning a function that maps an input to an output based on example input-output pairs.

**Regression:** A supervised learning task where the outputs are continuous values.

**Feature:**

- An attribute that we're selecting for our model
- Can come from the original dataset, or through some transformations (**feature extraction**)

**Parameter:** The weight or bias associated with a feature. The goal of machine learning is to adjust the weights to optimize the loss functions on training data.

**Loss function:** A function that computes the distance between the predicted output from a machine learning model and the actual output.

**Machine learning model:** An algorithm that combs through an amount of data to find patterns, make predictions, or generate insights

**Optimization algorithm:** An algorithm used to minimize the loss during training. The most common one is **Gradient Descent**.



# Pre-Class 2

## Recap: Model Evaluation

Low training error != a good model

To avoid memorizing, need to test on data we didn't train on

**Training set** to train on and a **test set** for evaluation

- Test set is a stand-in for all future data





**Goal:** Get you actively participating in your learning

### Typical Activity

- Question is posed
- **Think** (1 min): Think about the question on your own
- **Pair** (2 min): Talk with your neighbor to discuss question
  - If you arrive at different conclusions, discuss your logic and figure out why you differ!
  - If you arrived at the same conclusion, discuss why the other answers might be wrong!
- **Share** (1 min): We discuss the conclusions as a class

During each of the **Think** and **Pair** stages, you will respond to the question via a sli.do poll

- Not worth any points, just here to help you learn!

sli.do #cs416

# slido

Think 

1 minute

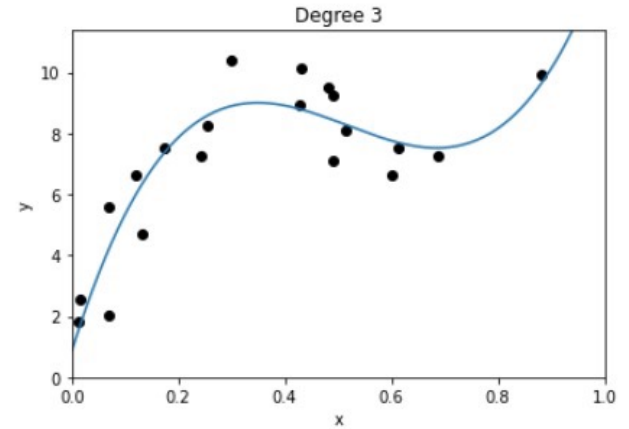
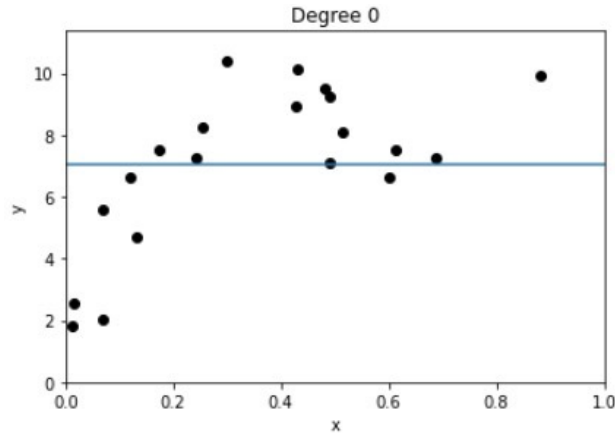
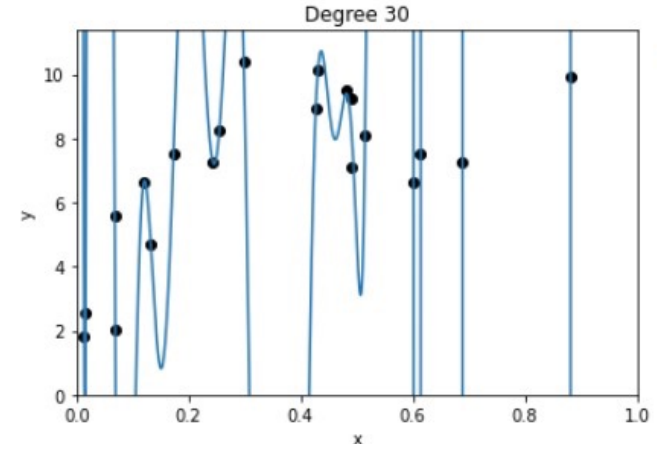
Which of the models do you expect to have the:

Highest Train Error

Highest Test Error

Lowest Train Error

Lowest Test Error



# slido

Group 

2 minute

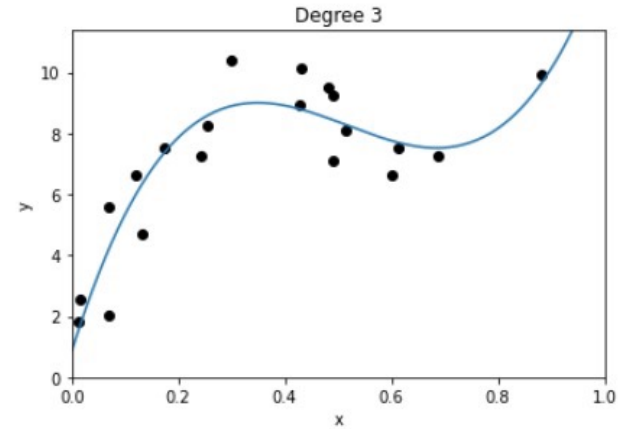
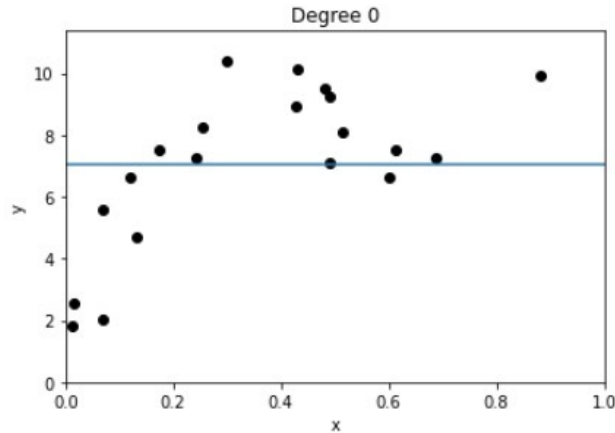
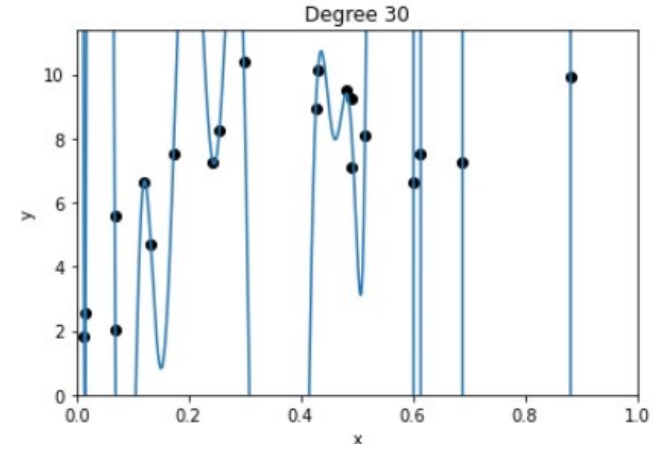
Which of the models do you expect to have the:

Highest Train Error

Highest Test Error

Lowest Train Error

Lowest Test Error



# Model Complexity

# Model Complexity

There is not a well-defined way to measure the complexity of a model. It depends on the nature of the models.

We usually associate it with the number of parameters. A model with more parameters is usually more complex.

Example with polynomial regression:

- Model 1: (2 parameters)

- $y = w_0 + w_1x$

- Model 2: (4 parameters)

- $y = w_0 + w_1x + w_2x^2 + w_3x^3$

We say that model 2 is more complex than model 1.

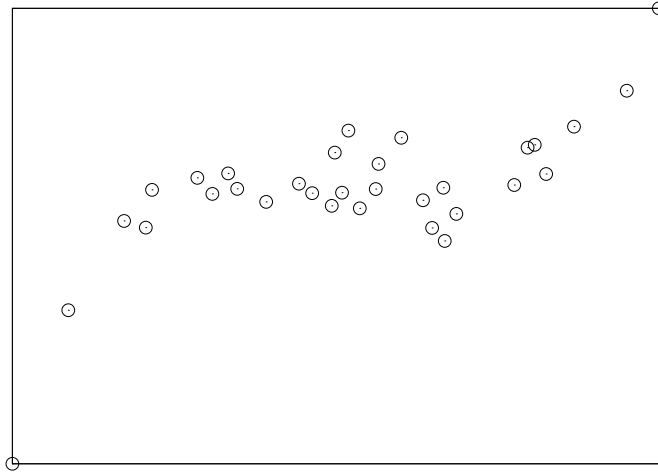


# Training Error

What happens to **training error** as we increase model complexity?

Start with the simplest model (a constant function)

End with a very high degree polynomial

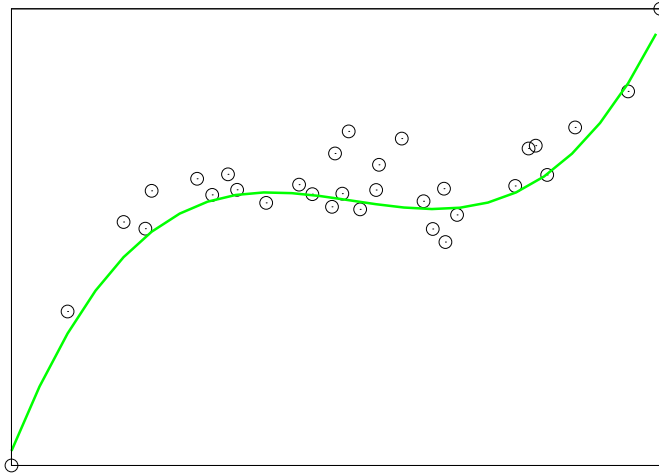


# True Error

What happens to **true error** as we increase model complexity?

Start with the simplest model (a constant function)

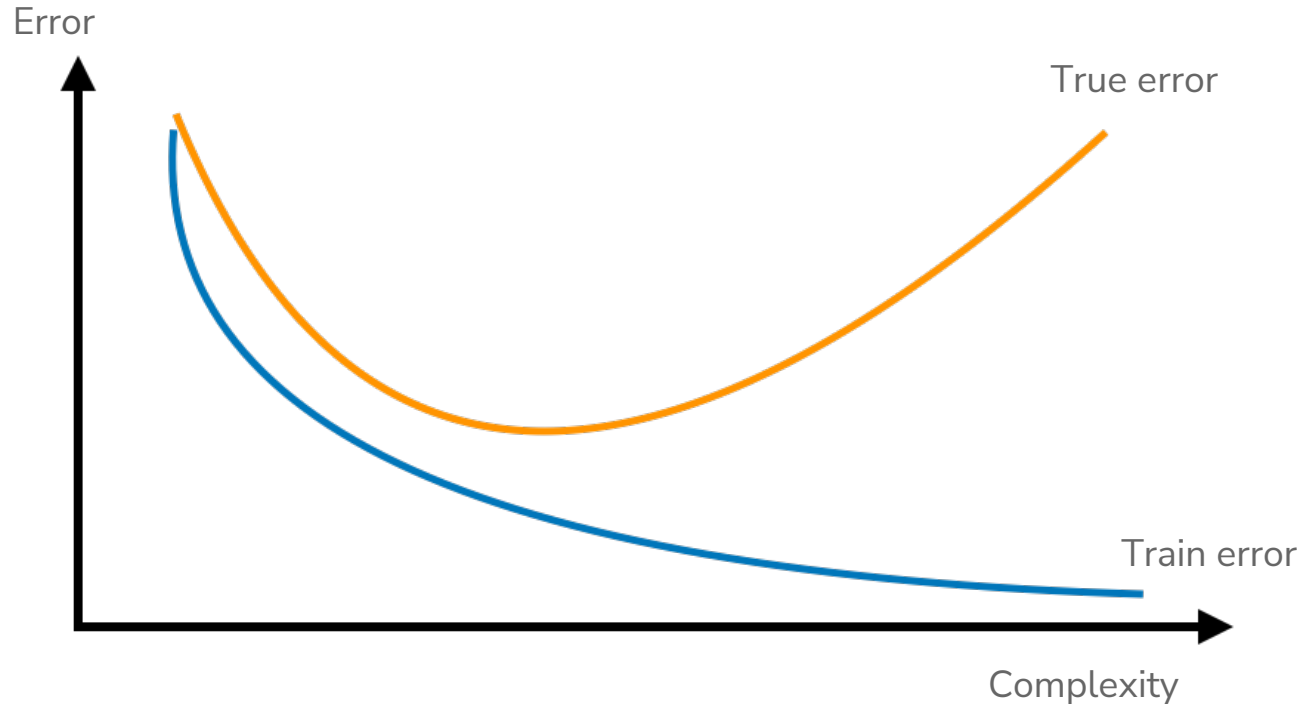
End with a very high degree polynomial





# Train/True Error

Compare what happens to train and true error as a function of model complexity



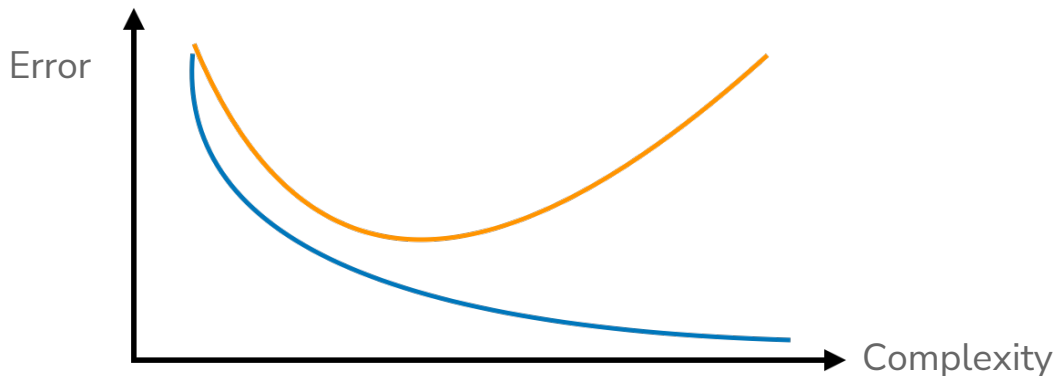
# Overfitting

**Overfitting** happens when we too closely match the training data and fail to generalize.

Overfitting occurs when you train a predictor  $\hat{w}$  but there exists another predictor  $w'$  from the same model class such that:

$$error_{true}(w') < error_{true}(\hat{w})$$

$$error_{train}(w') > error_{train}(\hat{w})$$





Think 

1 min

Consider the learning task of predicting the price of a house based on its features. **Evaluate the statement: “To make the model more accurate, we should include as many features as possible (e.g., square footage, # bathrooms, location, etc.).**

True

False

Unsure

sli.do #cs416

# slido

Group 

1 min

sli.do #cs416

Consider the learning task of predicting the price of a house based on its features. **Evaluate the statement: “To make the model more accurate, we should include as many features as possible (e.g., square footage, # bathrooms, location, etc.).**

True

False

Unsure



## *Brain Break*



# Bias-Variance Tradeoff

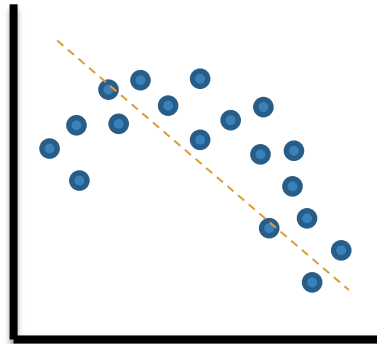
# Underfitting / Overfitting

The ability to overfit/underfit is a knob we can turn based on the model complexity.

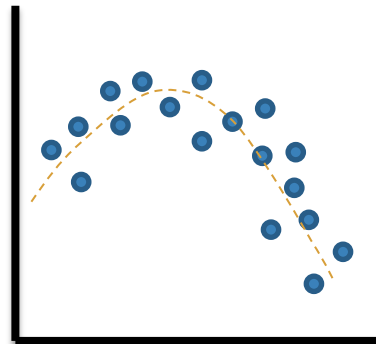
More complex => easier to overfit

Less complex => easier to underfit

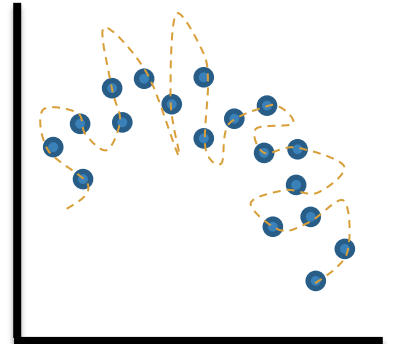
In a bit, we will talk about how to choose the “just right”, but now we want to look at this phenomena of overfitting/underfitting from another perspective.



Underfitting



Optimal



Overfitting

# Signal vs. Noise

Learning from data relies on balancing two aspects of our data

**Signal**

**Noise**

Complex models make it easier to fit too closely to the noise

Simple models have trouble picking up the signal

*the signal and the  
and the noise and  
the noise and the  
noise and the no  
why most noise a  
predictions fail to  
but some don't n  
and the noise and  
the noise and the  
nate silver noise  
noise and the no*





# Source of errors in a model

Total errors for a machine learning model comes from 3 types:

**Bias**

**Variance**

**Irreducible Error**

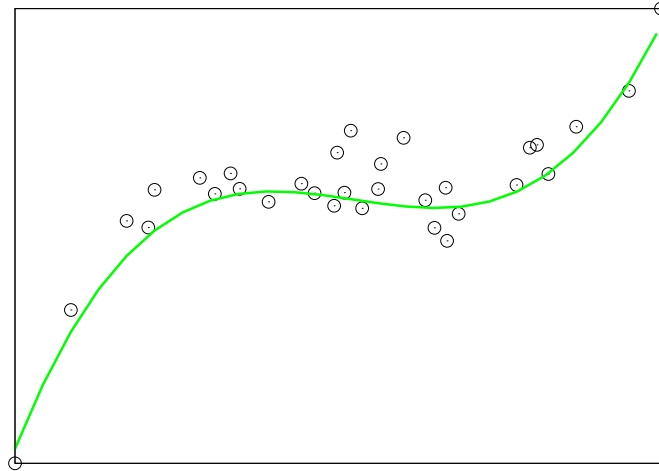
Irreducible error is the one that we can't avoid or possibly eliminate. They are caused by elements outside of our control, such as noise from observations.



# Bias

A model that is too simple fails to fit the signal. In some sense, this signifies a fundamental limitation of the model we are using to fail to fit the signal. We call this type of error **bias**.

**Bias** is the difference between the average prediction of our model **and** the expected value which we are trying to predict.

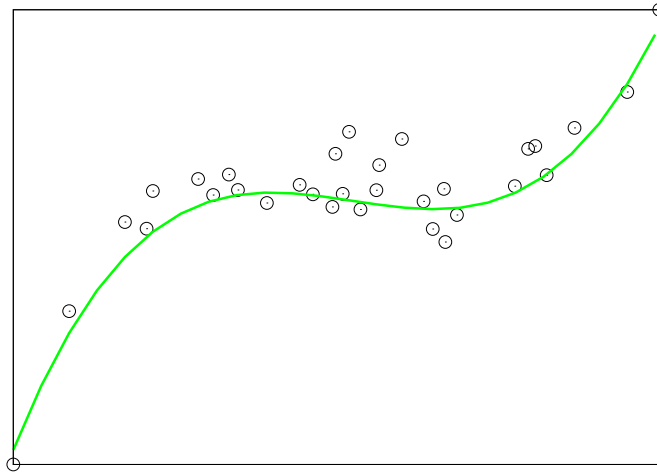


Low complexity (simple) models tend to have high bias.

# Variance

A model that is too complicated for the task overly fits to small fluctuations. The flexibility of the complicated model makes it capable of memorizing answers rather than learning general patterns. This contributes to the error as **variance**.

**Variance** is the variability in the model prediction, meaning how much the predictions will change if a different training dataset is used.



High complexity models tend to have high variance.

# Bias-Variance Tradeoff

Tradeoff between bias and variance:

Simple models: High bias + Low variance

Complex models: Low bias + High variance

Source of errors for a particular model  $\hat{f}$  using MSE loss function:

$$\mathbb{E}[(y - \hat{f}(x))^2] = \text{bias}[\hat{f}(x)]^2 + \text{var}(\hat{f}(x)) + \sigma_\epsilon^2$$

**Error = Biased squared + Variance + Irreducible Error**



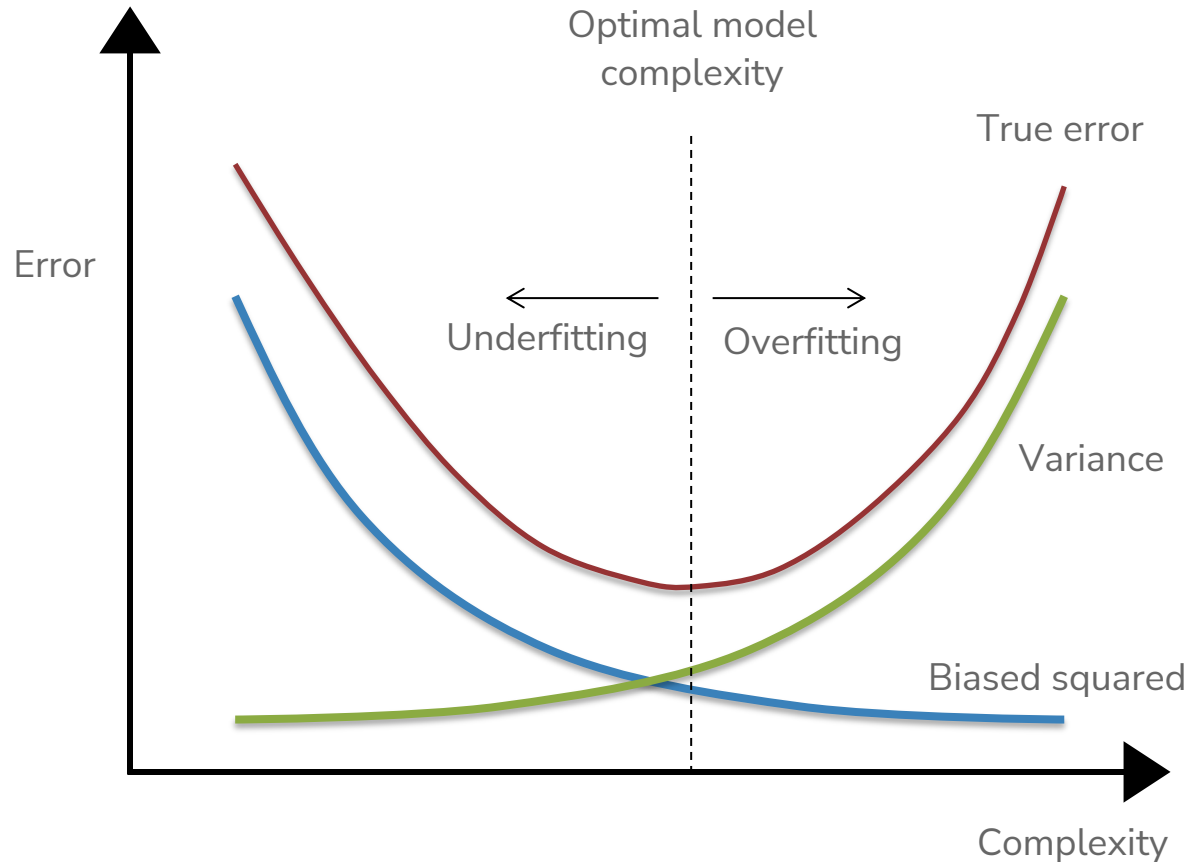
# Bias-Variance Tradeoff

Visually, this looks like the following!

$$\text{Error} = \text{Bias}^2 + \text{Variance} + \text{Irreducible Error}$$



# Bias – Variance Tradeoff



# Dataset Size

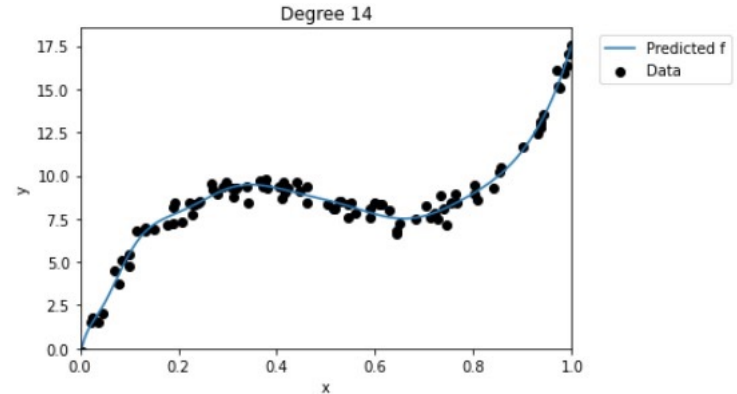
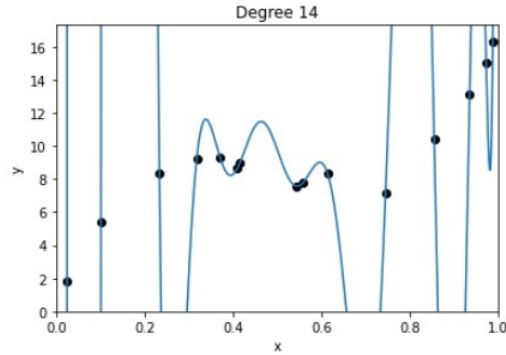
So far our entire discussion of error assumes a fixed amount of data. What happens to our error (true error and training error) as we get more data?



# Dataset Size

Model complexity doesn't depend on the size of the training set

The larger the training set, the lower the variance of the model, thus less overfitting





# Demo

## Bias-Variance Tradeoff

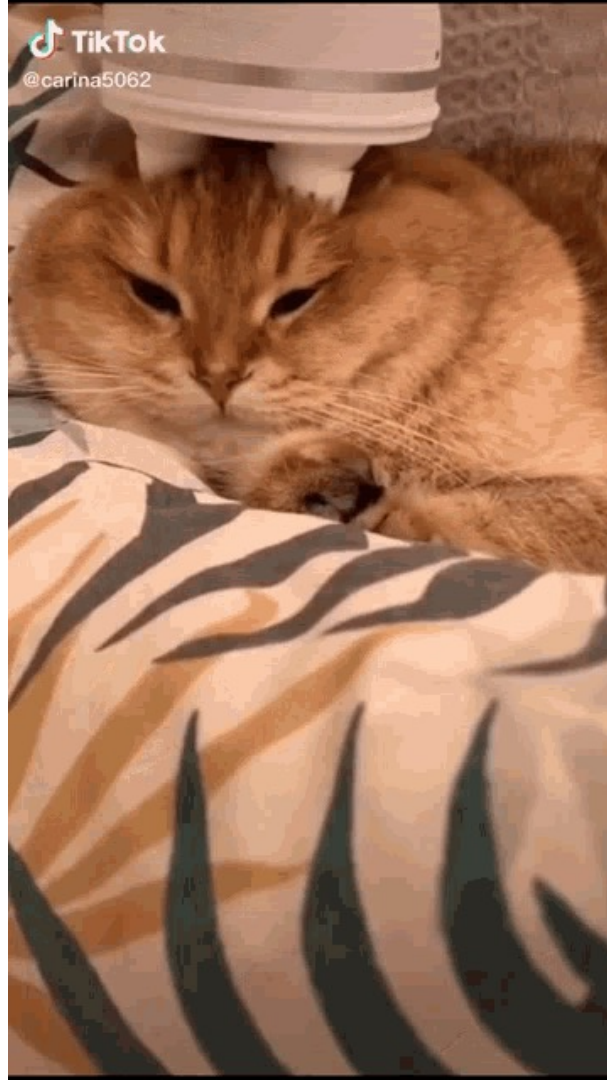
Training a linear regression model in Python

Observing the effect of the bias-variance tradeoff as compared to model complexity





## *Brain Break*



# Choosing Complexity

# Choosing Complexity

So far we have talked about the affect of using different complexities on our error. Now, how do we choose the right one?



# slido

Think 

1 min

slido #cs416

Suppose I wanted to figure out the right degree polynomial for my dataset (we'll try  $p$  from 1 to 20). What procedure should I use to do this? Pick the best option

For each possible degree polynomial  $p$ :

Train a model with degree  $p$  on the training set, pick  $p$  that has the lowest test error

Train a model with degree  $p$  on the training set, pick  $p$  that has the highest test error

Train a model with degree  $p$  on the test set, pick  $p$  that has the lowest test error

Train a model with degree  $p$  on the test set, pick  $p$  that has the highest test error

None of the above

# slido

Group 

2 min

slido #cs416

Suppose I wanted to figure out the right degree polynomial for my dataset (we'll try  $p$  from 1 to 20). What procedure should I use to do this? Pick the best option

For each possible degree polynomial  $p$ :

Train a model with degree  $p$  on the training set, pick  $p$  that has the lowest test error

Train a model with degree  $p$  on the training set, pick  $p$  that has the highest test error

Train a model with degree  $p$  on the test set, pick  $p$  that has the lowest test error

Train a model with degree  $p$  on the test set, pick  $p$  that has the highest test error

None of the above

# Choosing Complexity

We can't just choose the model that has the lowest **train** error because that will favor models that overfit!

It then seems like our only other choice is to choose the model that has the lowest **test** error (since that is our approximation of the true error)

This is almost right. However, the test set has been **tampered**, thus is no longer is an unbiased estimate of the true error.

We didn't technically train the model on the test set (that's good), but we chose **which model** to use based on the performance of the test set.

- It's no longer a stand in for "the unknown" since we probed it many times to figure out which model would be best.

NEVER EVER EVER touch the test set until the end. You only use it ONCE to evaluate the performance of the best model you have selected during training.

# Choosing Complexity

We will talk about two ways to pick the model complexity without ruining our test set.

- Using a validation set

- Doing (k-fold) cross validation



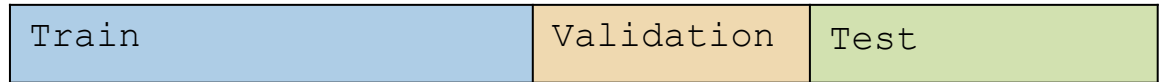


# Validation Set

So far we have divided our dataset into train and test



We can't use Test to choose our model complexity, so instead, break up Train into ANOTHER dataset



We will pick the model that does best on validation. Note that this now makes the validation error of the “best” model a biased estimate of true error. The test error will be an unbiased estimate though since we never looked at it!



## Validation Set

The process generally goes

```
train, validation, test = random_split(dataset)
```

for each model complexity **p**:

```
    model = train_model(model_p, train)
```

```
    val_err = error(model, validation)
```

keep track of **p** and **model** with smallest **val\_err**

```
return best p & error(model, test)
```



# Validation Set

## Pros

Easy to describe and implement

Pretty fast

- Only requires training a model and predicting on the validation set for each complexity of interest

## Cons

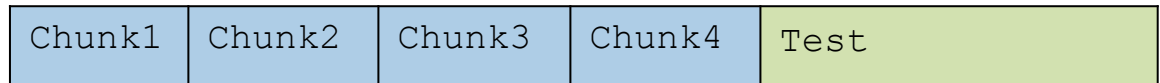
- Have to sacrifice even more training data
- Prone to overfitting\*



# Cross-Validation

Clever idea: Use many small validation sets without losing too much training data.

Still need to break off our test set like before. After doing so, break the training set into  $k$  chunks.



For a given model complexity, train it  $k$  times. Each time use all but one chunk and use that left out chunk to determine the validation error.



# Cross Validation

For a set of hyperparameters, perform Cross Validation on k folds



## Cross-Validation

The process generally goes

```
chunk_1, ..., chunk_k, test = random_split(dataset)  
for each model complexity p:  
    for i in [1, k]:  
        model = train_model(model_p, chunks - i)  
        val_err = error(model, chunk_i)  
    avg_val_err = average val_err over chunks  
    keep track of p with smallest avg_val_err  
return model trained on train (all chunks) with  
best p & error(model, test)
```

# Cross-Validation

## Pros

- Prevent overfitting: By training the model on multiple folds instead of only 1 training set, this learns the model with the best generalization capabilities.
- Don't have to actually get rid of any training data!

## Cons

- Slow. For each model selection, we have to train  $k$  times
- Very computationally expensive



# Cross-Validation

Generally, the more folds you use the better as you aren't relying on the specifics of a single validation fold.

Theoretical best estimator\* is to use  $k = n$

- Called "**Leave One Out Cross Validation**" (LOOCV)

In practice, people use  $k = 5$  to 10 for computational simplicity





# Poll Everywhere

Think 

1 min

[pollev.com/cs416](https://pollev.com/cs416)

Say we are testing  $p$  different polynomial degrees, using the pseudocode for  $k$ -fold cross-validation.

How many models would we train?

- a)  $pk$
- b)  $p(k - 1)$
- c)  $p^k$
- d)  $pk + 1$

```
chunk_1, ..., chunk_k, test = random_split(dataset)
for each model complexity p:
    for i in [1, k]:
        model = train_model(model_p, chunks - i)
        val_err = error(model, chunk_i)
    avg_val_err = average val_err over chunks
    keep track of p with smallest avg_val_err
return model trained on train (all chunks) with
best p & error(model, test)
```

Think 

1 min

[pollev.com/cs416](https://pollev.com/cs416)

Say we are testing  $p$  different polynomial degrees, using the pseudocode for  $k$ -fold cross-validation.

How many models would we train?

- a)  $pk$
- b)  $p(k - 1)$
- c)  $p^k$
- d)  $pk + 1$

```
chunk_1, ..., chunk_k, test = random_split(dataset)
for each model complexity p:
    for i in [1, k]:
        model = train_model(model_p, chunks - i)
        val_err = error(model, chunk_i)
    avg_val_err = average val_err over chunks
    keep track of p with smallest avg_val_err
return model trained on train (all chunks) with
best p & error(model, test)
```

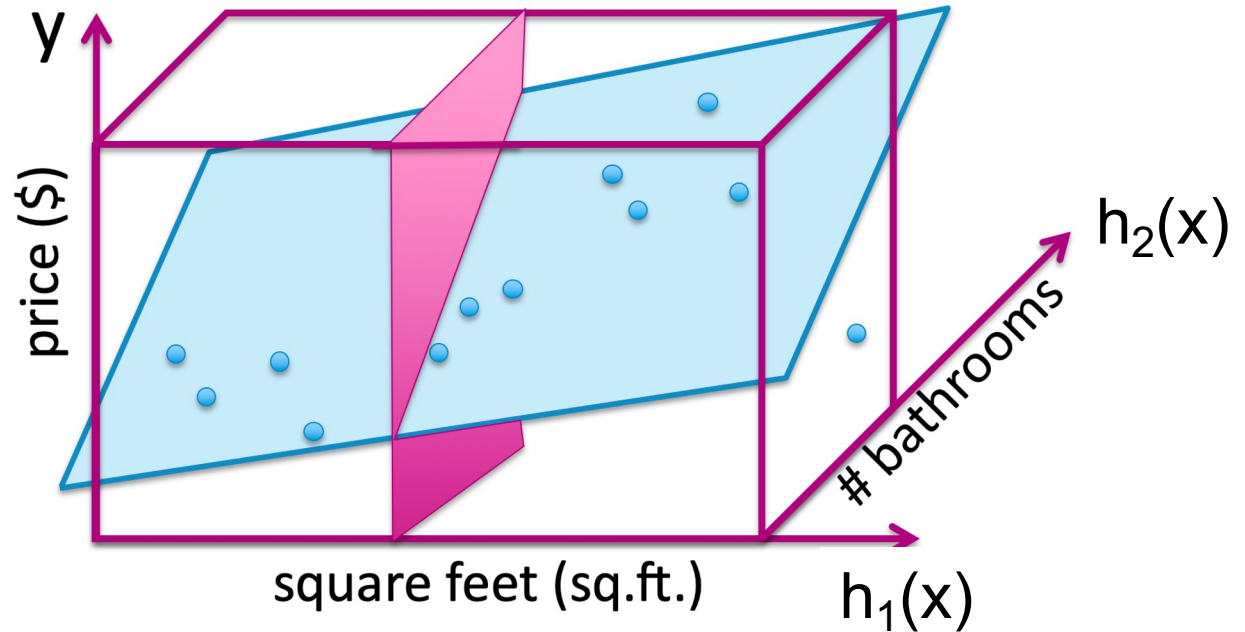
# Coefficients and Overfitting

# Interpreting Coefficients

Interpreting Coefficients – Multiple Linear Regression

$$\hat{y} = \hat{w}_0 + \hat{w}_1 h_1(x) + \hat{w}_2 h_2(x)$$

Fix



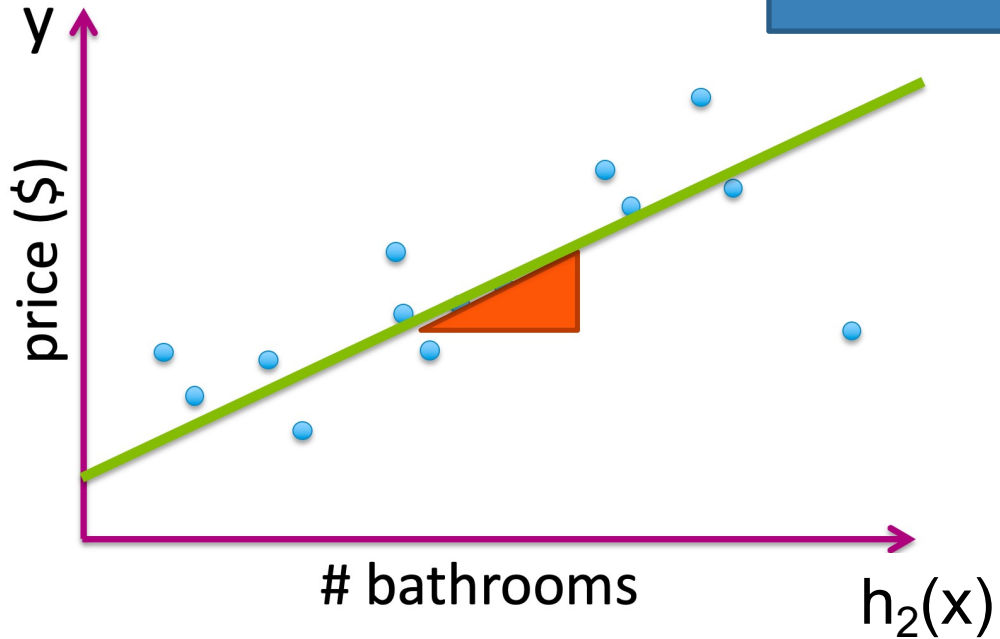
# Interpreting Coefficients

Interpreting Coefficients – Multiple Linear Regression

$$\hat{y} = \hat{w}_0 + \hat{w}_1 h_1(x) + \hat{w}_2 h_2(x)$$

Fix

Holding  $h_1(x)$  fixed!



# Interpreting Coefficients

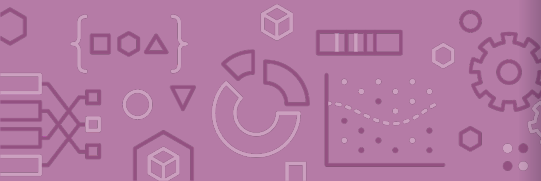
This also extends for multiple regression with many features!

$$\hat{y} = \hat{w}_0 + \sum_{j=1}^D \hat{w}_j h_j(x)$$

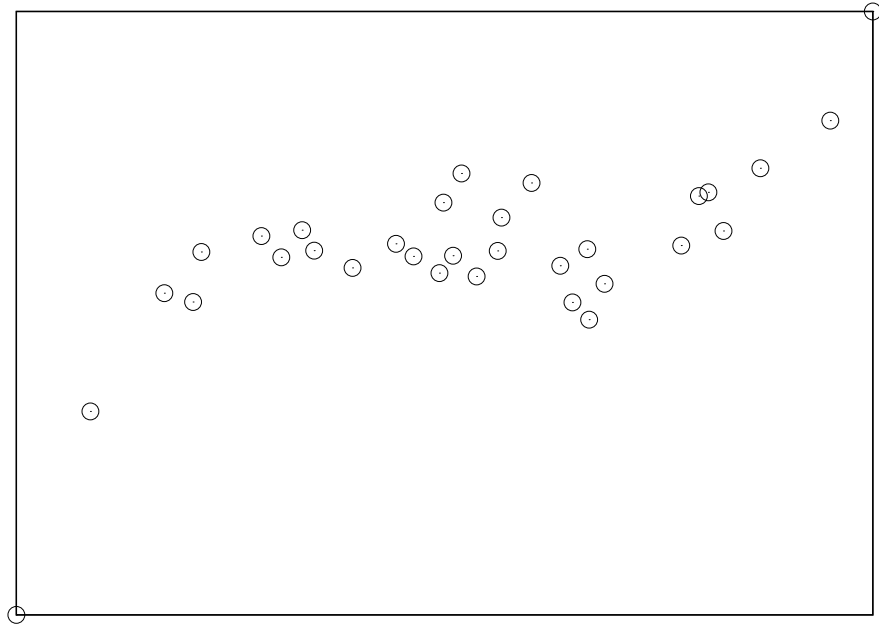
Interpret  $\hat{w}_j$  as the change in  $y$  per unit change in  $h_j(x)$  if all other features are held constant.

This is generally not possible for polynomial regression or if other features use same data input!

Can't “fix” other features if they are derived from same input.



# Overfitting



Often, overfitting is associated with very large estimated parameters  $\hat{w}$ !



# Poll Everywhere

Think 

2 Minutes

What characterizes overfitting?

(Low / High) Train Error, (Low / High) Test Error

(Low / High) Bias, (Low / High) Variance

In which scenario is it more likely for a model to overfit?

(Few / Many) Features

(Few / Many) Parameters

(Small / Large) Polynomial Degree

(Small / Large) Dataset

[pollev.com/cs416](https://pollev.com/cs416)



# Prevent Overfitting

Last time, we **trained multiple models**, using cross validation / validation set, to find one that was less likely to overfit

For selecting polynomial degree, we train  $p$  models.

For selecting which features to include, we'd have to train \_\_\_\_\_ models!

Can we **train one model** that isn't prone to overfitting in the first place?

**Big Idea:** Have the model self-regulate to prevent overfitting by making sure its coefficients don't get "too large"

This idea is called **regularization**.



# Recap

**Theme:** Assess the performance of our models

**Ideas:**

Model complexity

Train vs. Test vs. True error

Overfitting and Underfitting

Bias-Variance Tradeoff

Error as a function of train set size

Choosing best model complexity

- Validation set
- Cross Validation

