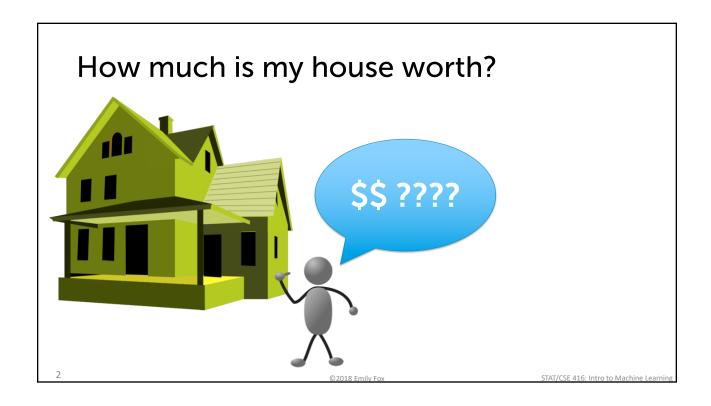
# Regression: Fredicting House Prices

STAT/CSE 416: Intro to Machine Learning Emily Fox University of Washington March 29, 2018

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## Data input output



$$(x_1 = \text{sq.ft.}, y_1 = \$)$$



$$(x_2 = \text{sq.ft.}, y_2 = \$)$$



$$(x_3 = sq.ft., y_3 = \$)$$



$$(x_4 = sq.ft., y_4 = \$)$$



$$(x_5 = \text{sq.ft.}, y_5 = \$)$$

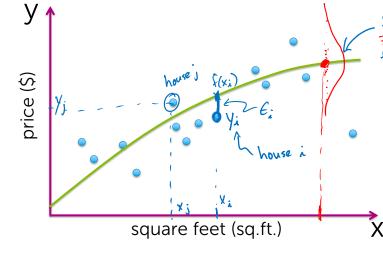
#### Input vs. Output:

- **y** is the quantity of interest
- assume  $\mathbf{y}$  can be predicted from  $\mathbf{x}$

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#### Model – How we assume the world works



F(x)

Expected relationship
between x and y

Regression model:

$$y_i = F(x_i) + e_i$$

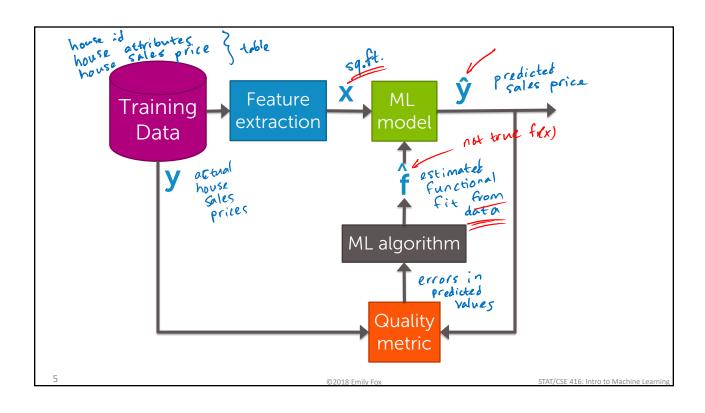
E[E:]= 0 \*

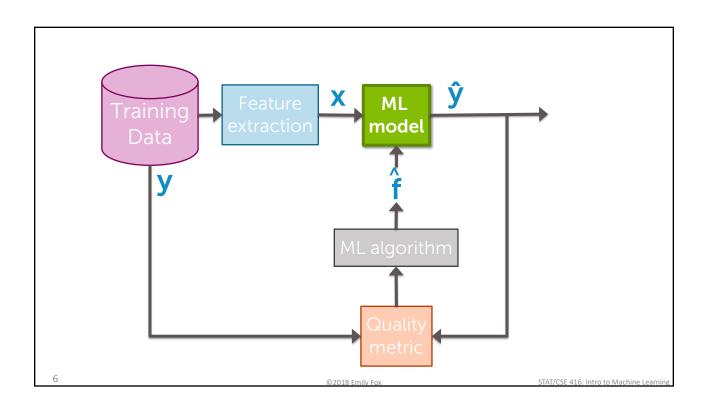
1 expected value

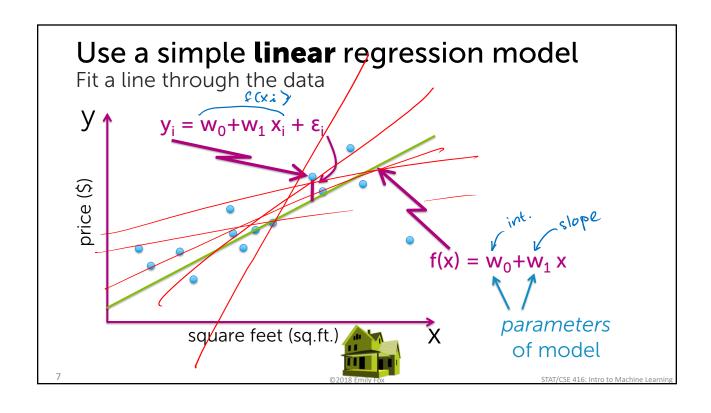
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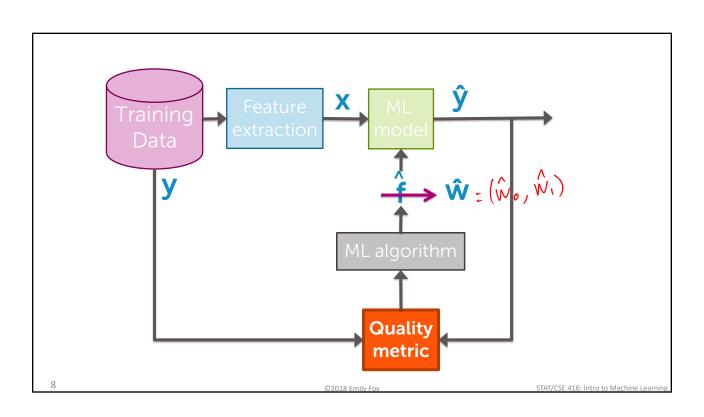
4

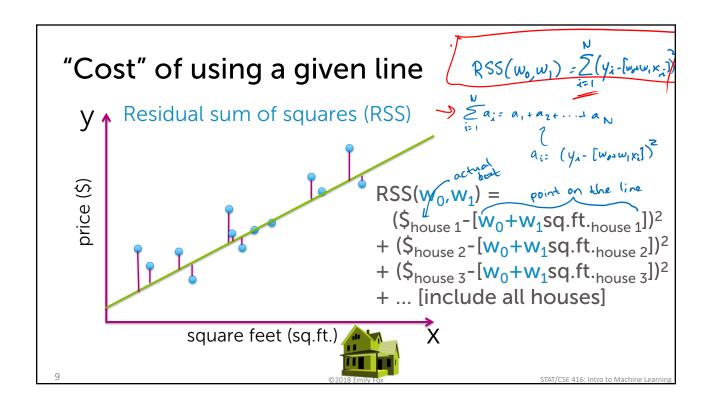
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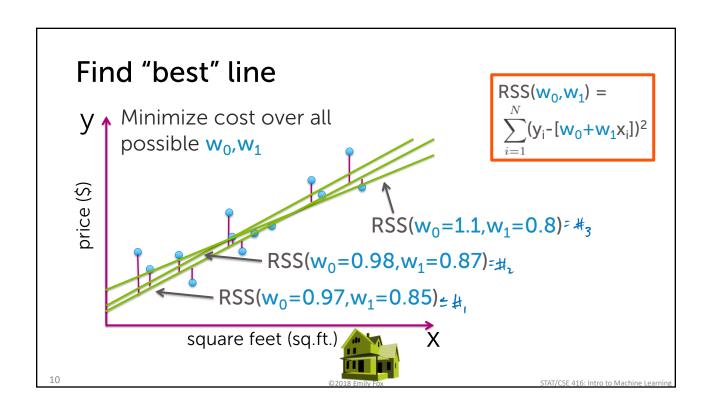


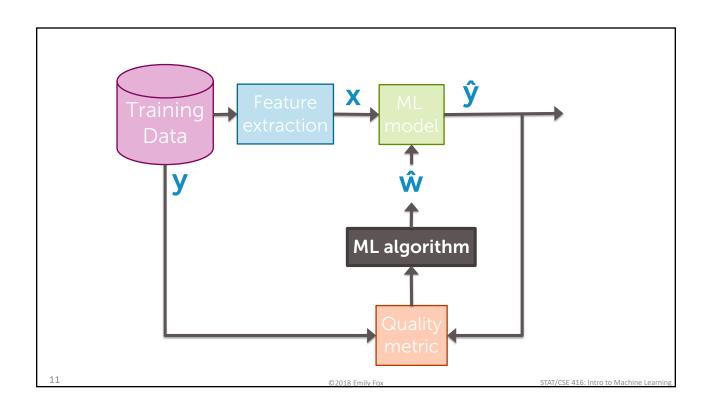


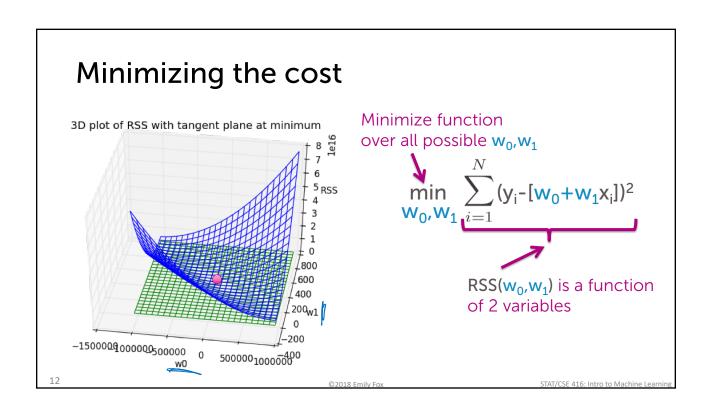


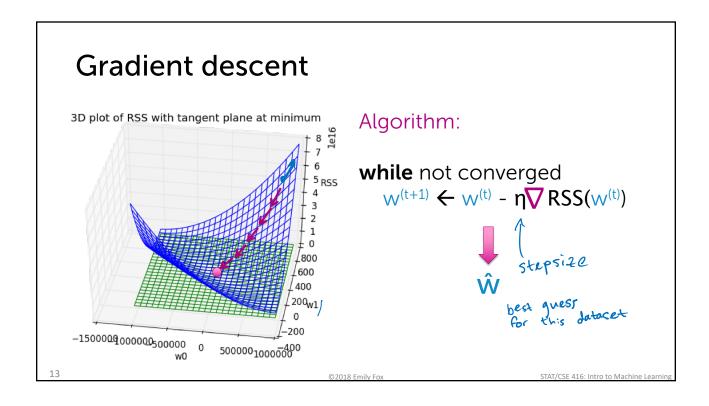




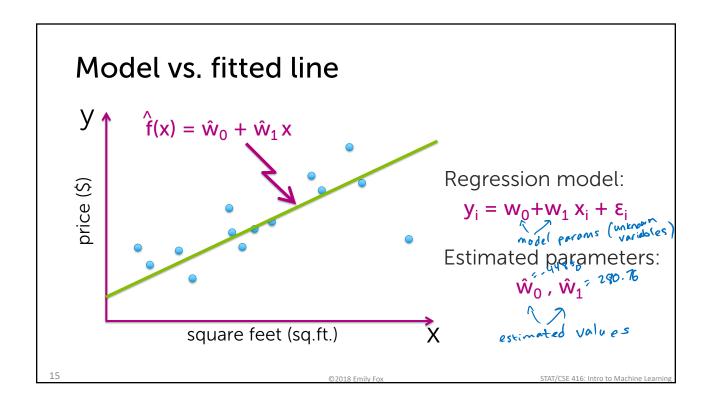


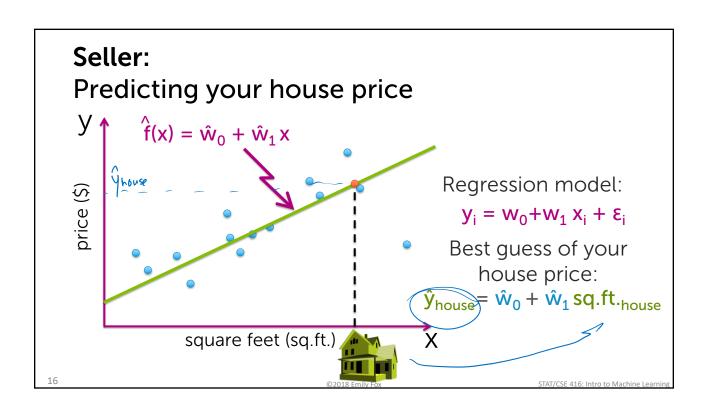


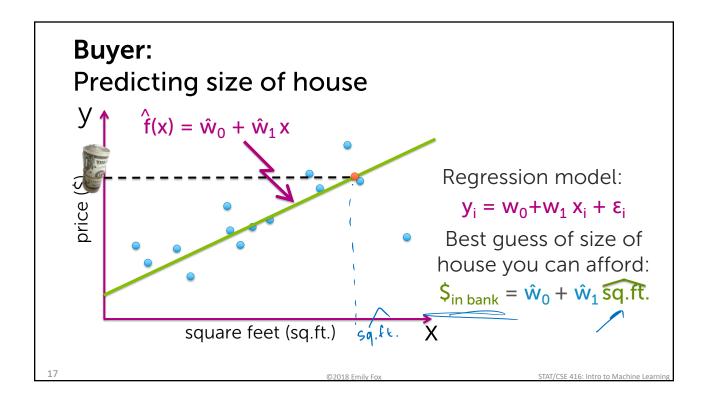


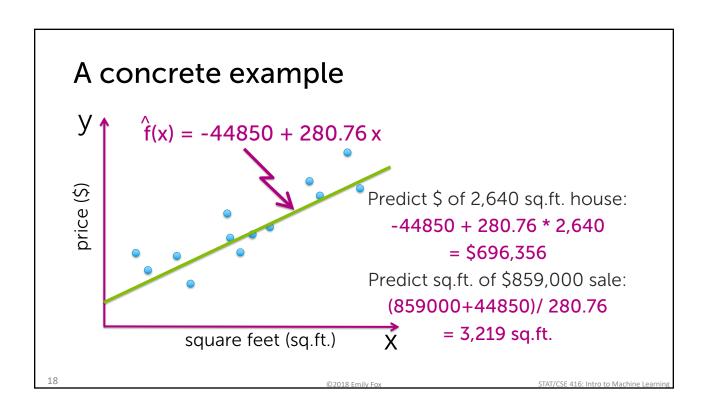


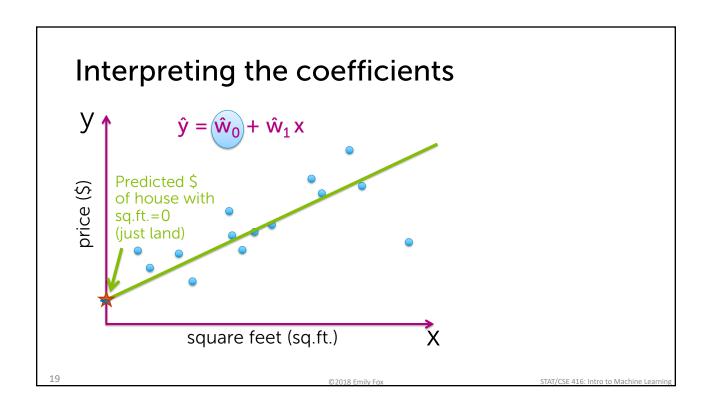
The fitted line: use + interpretation

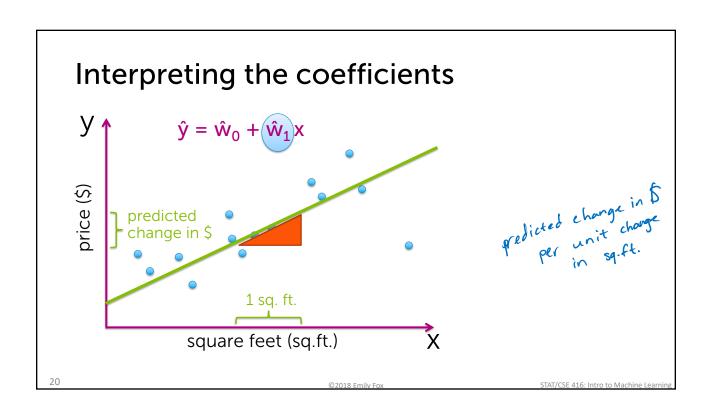


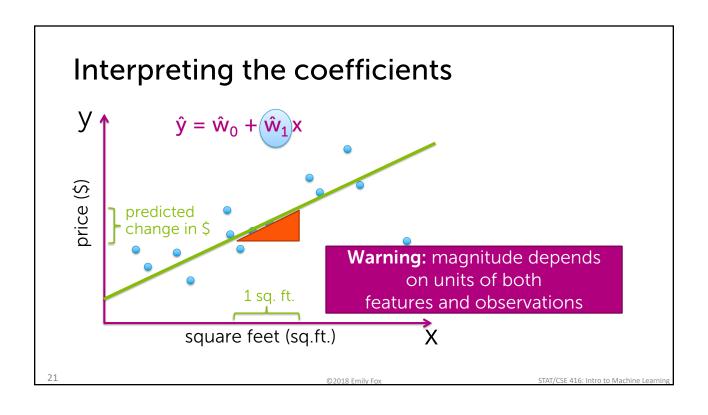


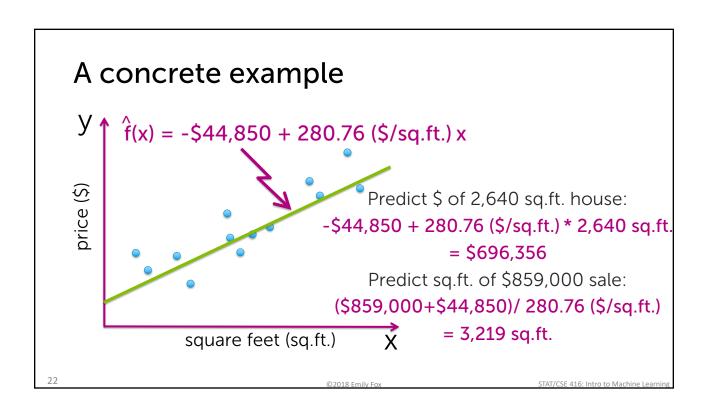


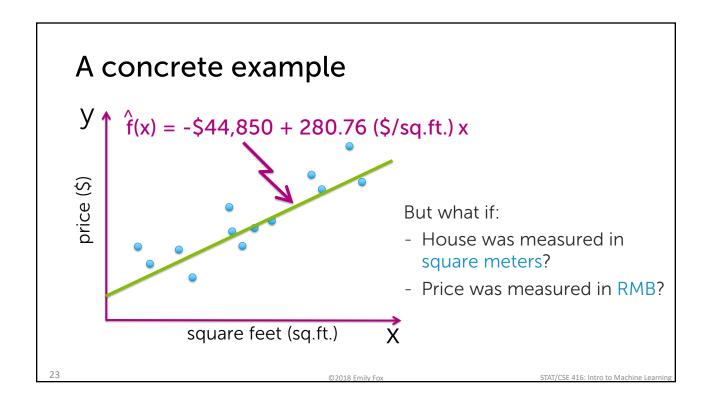




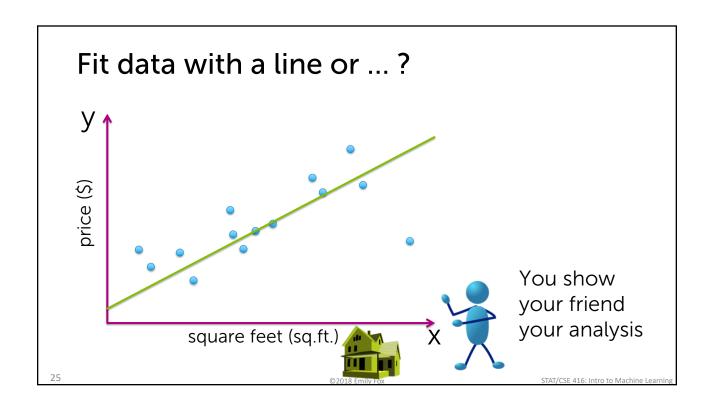


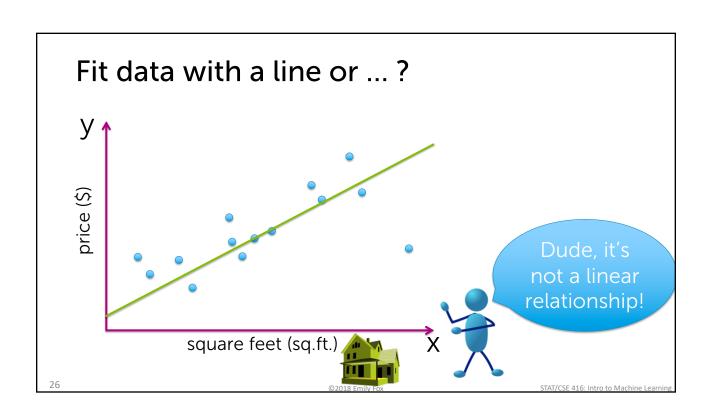


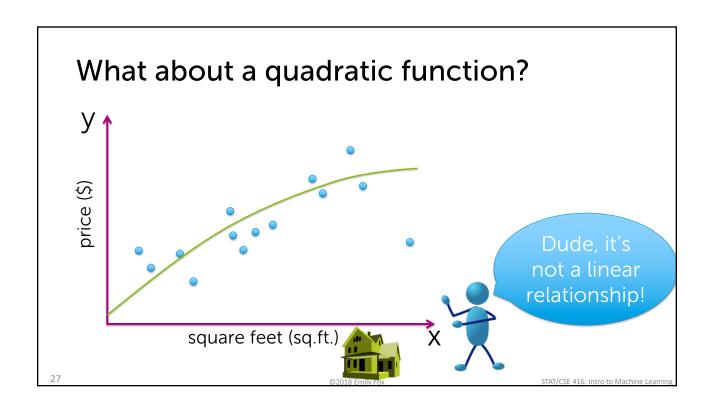


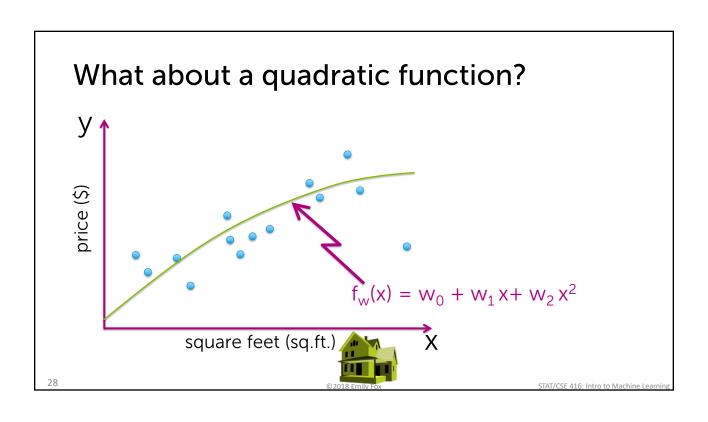


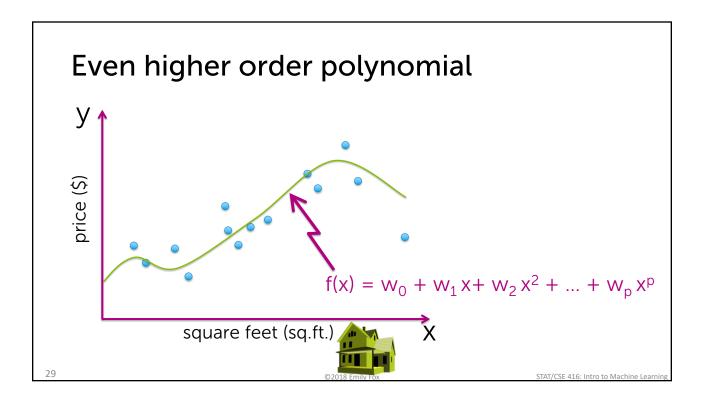
Adding higher order effects











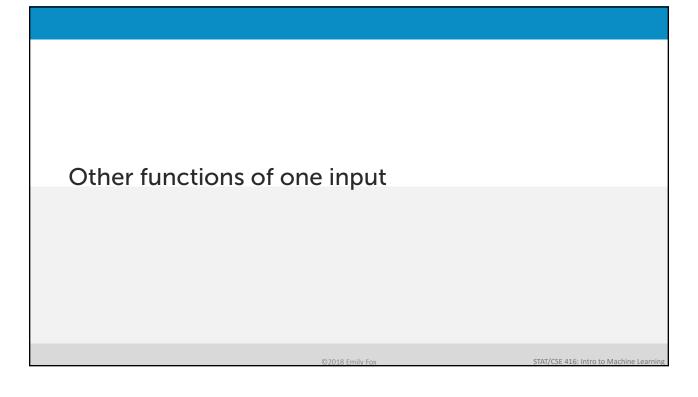
# Polynomial regression Model: $y_i = w_0 + w_1 x_i + w_2 x_i^2 + ... + w_p x_i^p + \epsilon_i$

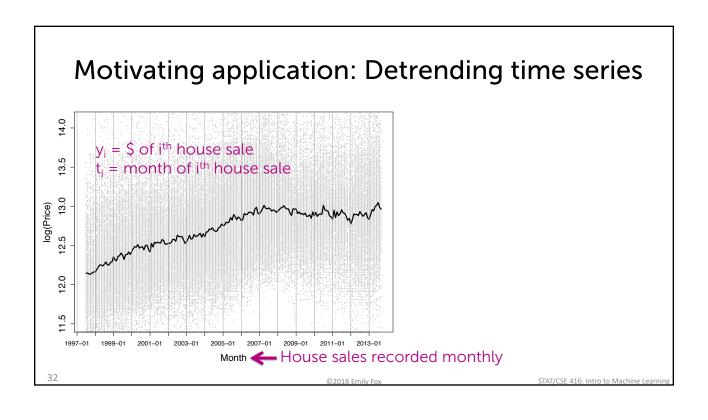
#### treat as different features

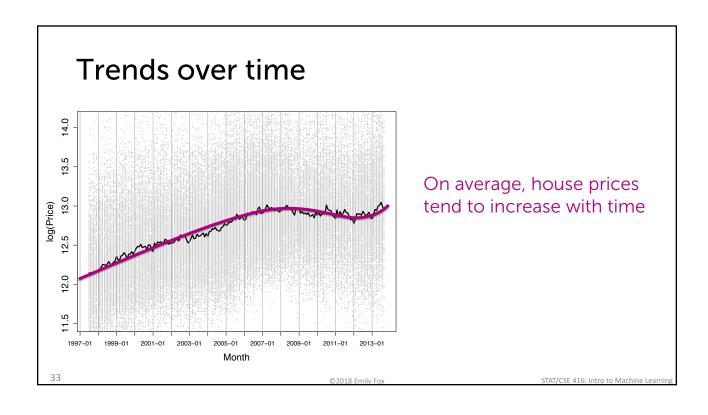
feature 1 = 1 (constant) parameter  $1 = w_0$ feature 2 = x parameter  $2 = w_1$ feature  $3 = x^2$  parameter  $3 = w_2$ ...

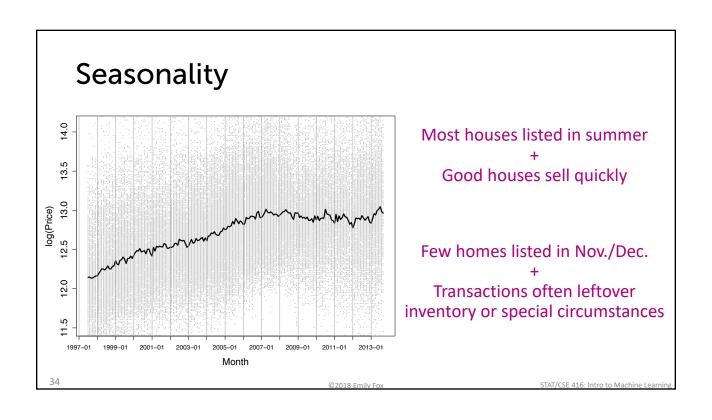
feature  $p+1 = x^p$  parameter  $p+1 = w_p$ 

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#### An example detrending

#### Model:

Trigonometric identity: sin(a-b)=sin(a)cos(b)-cos(a)sin(b) $\rightarrow sin(2\pi t_i / 12 - \Phi) = sin(2\pi t_i / 12)cos(\Phi) - cos(2\pi t_i / 12)sin(\Phi)$ 

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### An example detrending

Equivalently,

$$y_i = w_0 + w_1 t_i + w_2 \sin(2\pi t_i / 12) + w_3 \cos(2\pi t_i / 12) + \varepsilon_i$$

feature 1 = 1 (constant)

feature 2 = t

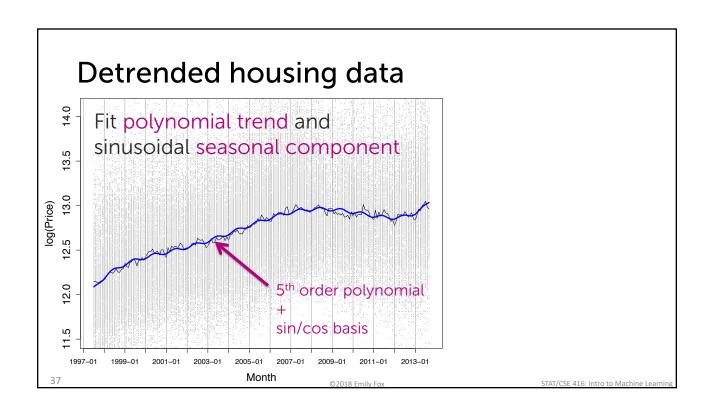
feature  $3 = \sin(2\pi t/12)$ 

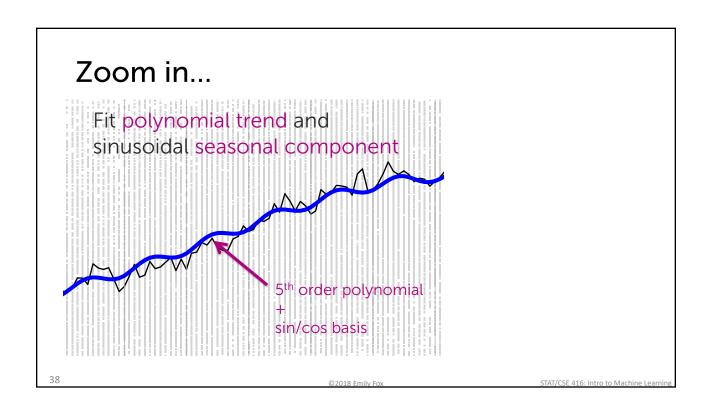
 $feature 4 = cos(2\pi t/12)$ 

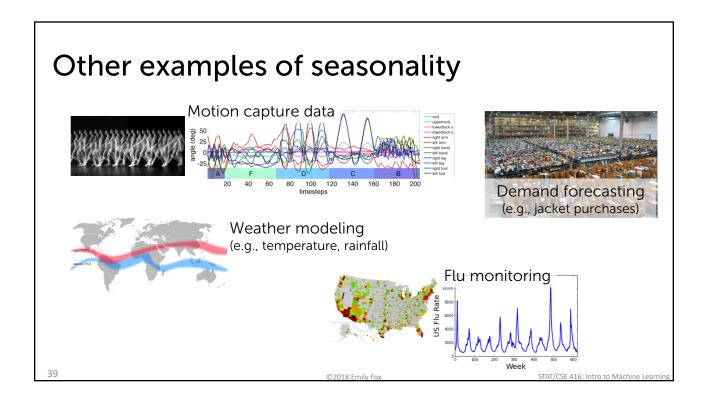
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### Generic basis expansion

Model:

$$y_{i} = w_{0}h_{0}(x_{i}) + w_{1}h_{1}(x_{i}) + ... + w_{D}h_{D}(x_{i}) + \epsilon_{i}$$

$$= \sum_{j=0}^{D} w_{j}h_{j}(x_{i}) + \epsilon_{i}$$

$$j^{th} feature$$

$$j^{th} regression coefficient$$
or weight

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#### Generic basis expansion

```
Model:
```

$$y_{i} = w_{0}h_{0}(x_{i}) + w_{1}h_{1}(x_{i}) + ... + w_{D}h_{D}(x_{i}) + \varepsilon_{i}$$
$$= \sum_{j=0}^{D} w_{j}h_{j}(x_{i}) + \varepsilon_{i}$$

 $feature 1 = h_0(x)...often 1 (constant)$ 

feature 2 =  $h_1(x)$ ... e.g., x

feature  $3 = h_2(x)... e.g., x^2 \text{ or } \sin(2\pi x/12) \text{ or } \log(x)$ 

...

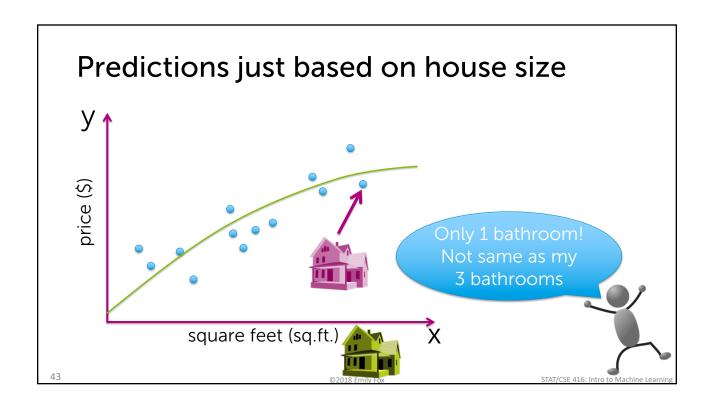
feature  $D+1 = h_D(x)... e.g., x^p$ 

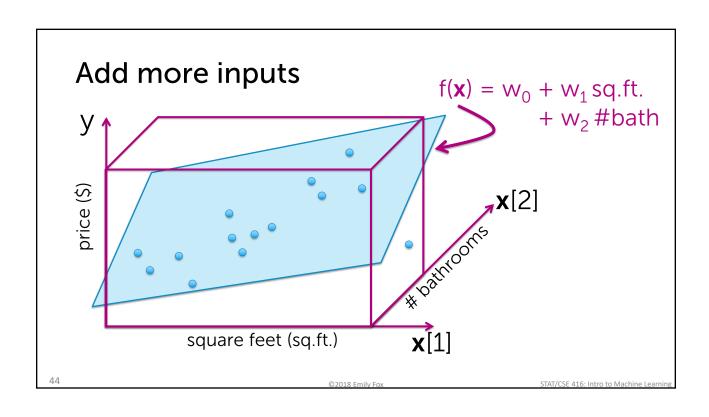
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#### Adding other inputs

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#### Many possible inputs

- Square feet
- # bathrooms
- # bedrooms
- Lot size
- Year built
- ...

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#### General notation

Output: y 🛩 scalar

Inputs:  $\mathbf{x} = (\mathbf{x}[1], \mathbf{x}[2], ..., \mathbf{x}[d])$ 

d-dim vector

Notational conventions:

 $\mathbf{x}[j] = j^{th} input (scalar)$ 

 $h_i(\mathbf{x}) = j^{th}$  feature (scalar)

 $\mathbf{x}_{i}$  = input of i<sup>th</sup> data point (vector)

 $\mathbf{x}_{i}[j] = j^{th}$  input of  $i^{th}$  data point (scalar)

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### Generic linear regression model

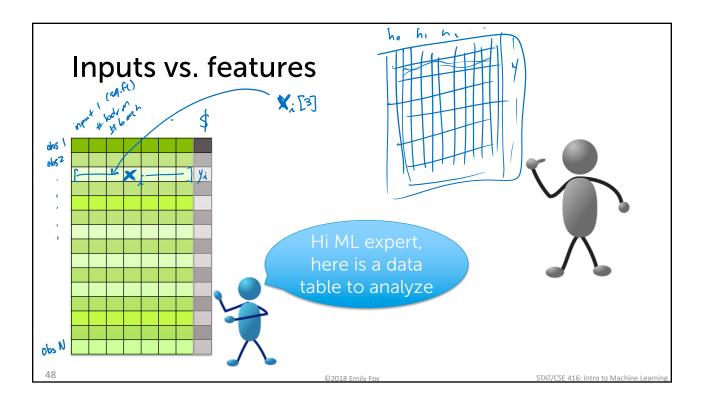
```
Model:

y_{i} = \underset{D}{w_{0}} h_{0}(\mathbf{x}_{i}) + \underset{1}{w_{1}} h_{1}(\mathbf{x}_{i}) + ... + \underset{D}{w_{D}} h_{D}(\mathbf{x}_{i}) + \epsilon_{i}
= \sum_{j=0}^{D} \underset{1}{w_{j}} h_{j}(\mathbf{x}_{i}) + \epsilon_{i}
```

```
feature 1 = h_0(\mathbf{x}) ... e.g., 1
feature 2 = h_1(\mathbf{x}) ... e.g., \mathbf{x}[1] = \text{sq. ft.}
feature 3 = h_2(\mathbf{x}) ... e.g., \mathbf{x}[2] = \text{#bath}
or, \log(\mathbf{x}[7]) \mathbf{x}[2] = \log(\text{#bed}) x #bath
```

feature  $D+1 = h_D(\mathbf{x})$  ... some other function of  $\mathbf{x}[1],...,\mathbf{x}[d]$ 

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#### More on notation

```
# observations (\mathbf{x}_i, y_i): N
```

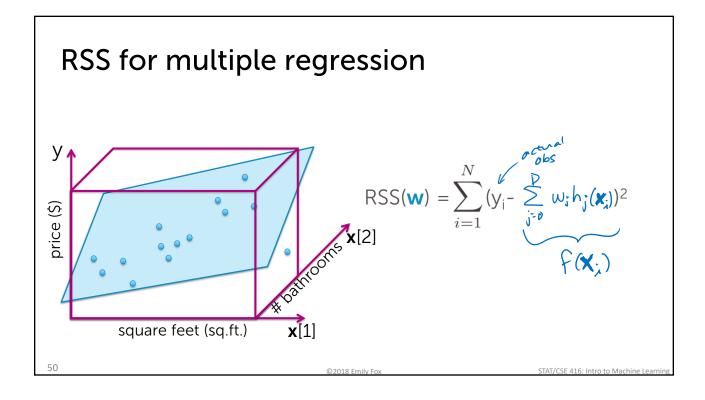
# inputs x[j]: d

# features  $h_i(\mathbf{x}) : D$ 

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## How many features to use?

• More on this soon!

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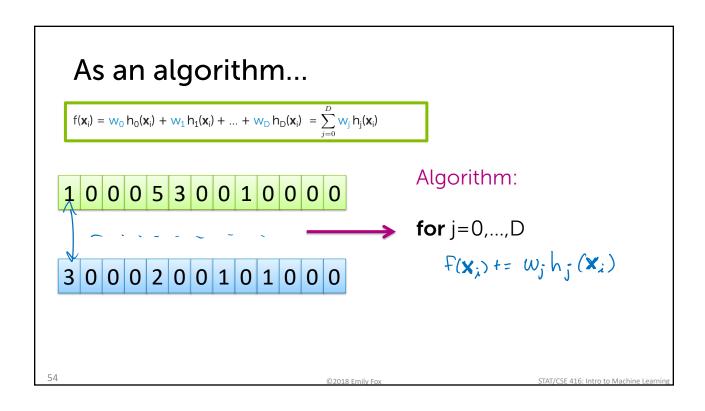
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A compact representation

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## Compact notation

$$f(\mathbf{x}_i) = w_0 h_0(\mathbf{x}_i) + w_1 h_1(\mathbf{x}_i) + ... + w_D h_D(\mathbf{x}_i) = \sum_{j=0}^{D} w_j h_j(\mathbf{x}_i)$$

write this operation as:

wh(x;)

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