#### Introduction to Database Systems CSE 414

#### Lecture 27: More Operator Costs

# Announcements

- HW8 and WQ7 both due tonight!
- Please fill out course evals online!
- Last lecture on Friday

# **Final Exam**

- Thursday 6/7, 2:30-4:20pm
- Location: here
- Can bring 2 letter-size sheets of notes

   Handwritten or printed
- More info on course website
- Review session:

- Sunday 6/3, 2:30-5pm, SMI 102

# **Big Picture**

- How to choose the "best" query plan to run? (aka query optimization)
- To answer this question we need to understand:
  - Data organization on the disk
  - Index structures and how they are used in queries
  - A way to model query "costs"
  - Compute cost for each query operator
  - Compute cost for each physical plan

Last topics this quarter!

# **Big Picture**

# Why do we care about all these internal details?

# **Cost Parameters**

- Cost = I/O + CPU + Network BW
  - We will focus on I/O in this class
- Parameters (a.k.a. statistics):
  - B(R) = # of blocks (i.e., pages) for relation R
  - T(R) = # of tuples in relation R
  - V(R, a) = # of distinct values of attribute a

```
When a is a key, V(R,a) = T(R)
When a is not a key, V(R,a) can be anything <= T(R)
```

 DBMS collects statistics about base tables must infer them for intermediate results

# Join Algorithms

- Nested loop join (short review)
- Hash join
- Sort-merge join



# Nested Loop Joins (review)

R

а

1

. . .

98

b

7

...

3

С

4

. . .

2

3	43	7
9	24	9
S		
С	d	е
3	43	7

S

С

d

е

# **Nested Loop Joins**

- Tuple-based nested loop R ⋈ S
- R is the outer relation, S is the inner relation

 $\begin{array}{l} \label{eq:for_each_tuple_t_1} \mbox{ for each tuple } t_1 \mbox{ in R } \mbox{ do} \\ \mbox{ for each tuple } t_2 \mbox{ in S } \mbox{ do} \\ \mbox{ if } t_1 \mbox{ and } t_2 \mbox{ join } \mbox{ then } \mbox{ output } (t_1,t_2) \end{array}$ 

What is the Cost?

# **Nested Loop Joins**

- Tuple-based nested loop R ⋈ S
- R is the outer relation, S is the inner relation

• Cost: B(R) + T(R) B(S)

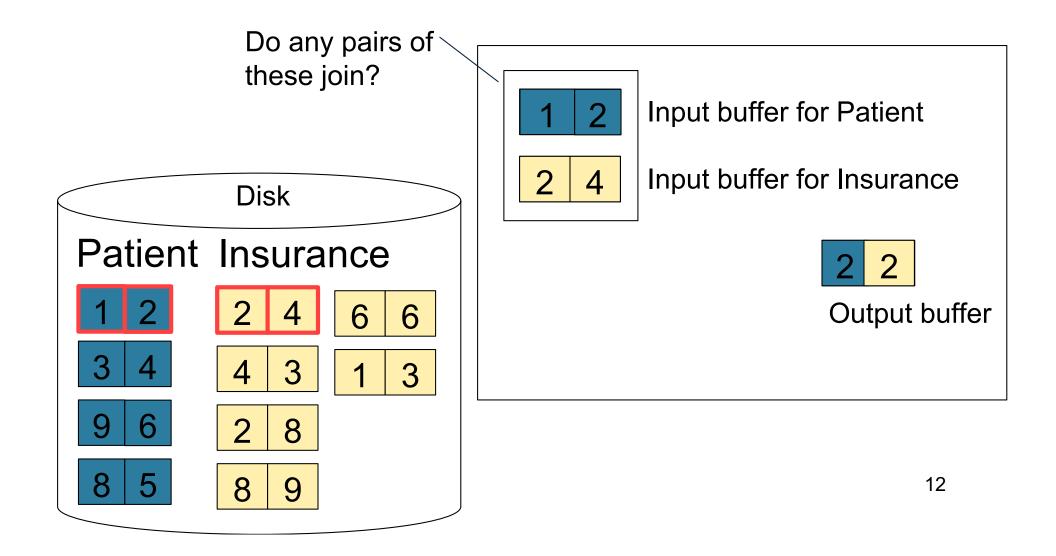
What is the Cost?

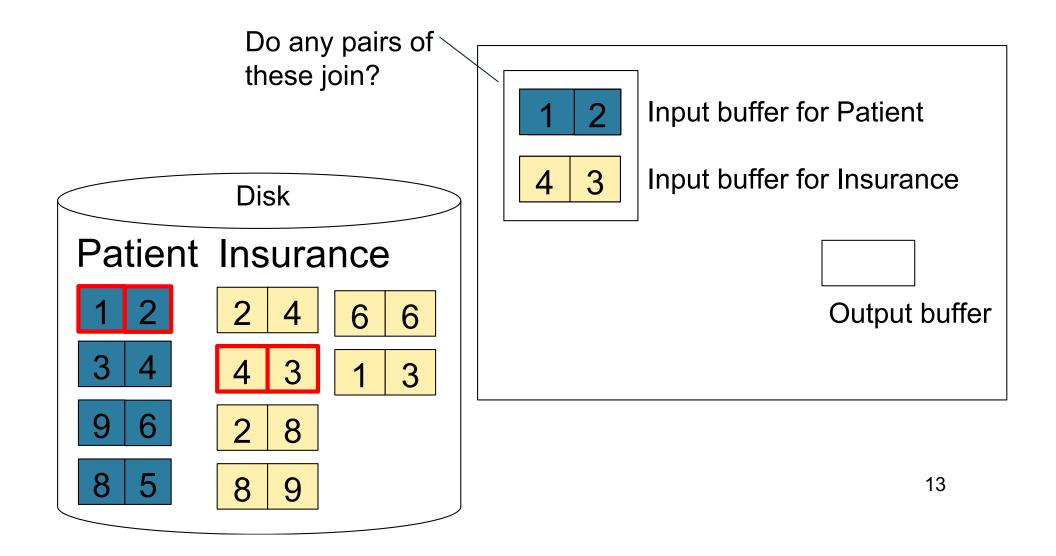
Multiple-pass since S is read many times

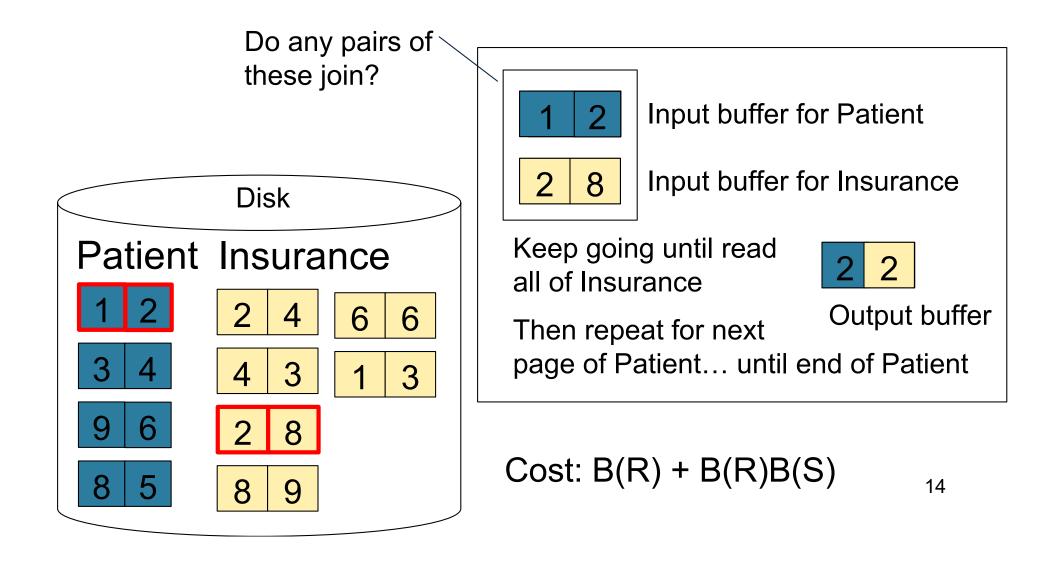
 $\begin{array}{l} \label{eq:for} \mbox{for each page of tuples r in R do} \\ \mbox{for each page of tuples s in S do} \\ \mbox{for all pairs of tuples } t_1 \mbox{ in r, } t_2 \mbox{ in s} \\ \mbox{if } t_1 \mbox{ and } t_2 \mbox{ join } \mbox{then} \mbox{ output } (t_1,t_2) \end{array}$ 

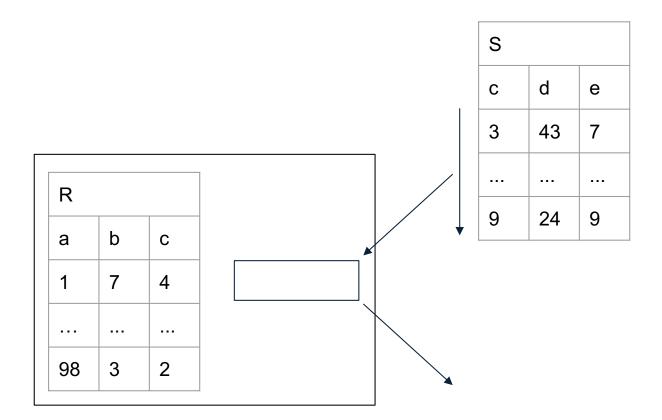
• Cost: B(R) + B(R)B(S)

What is the Cost?







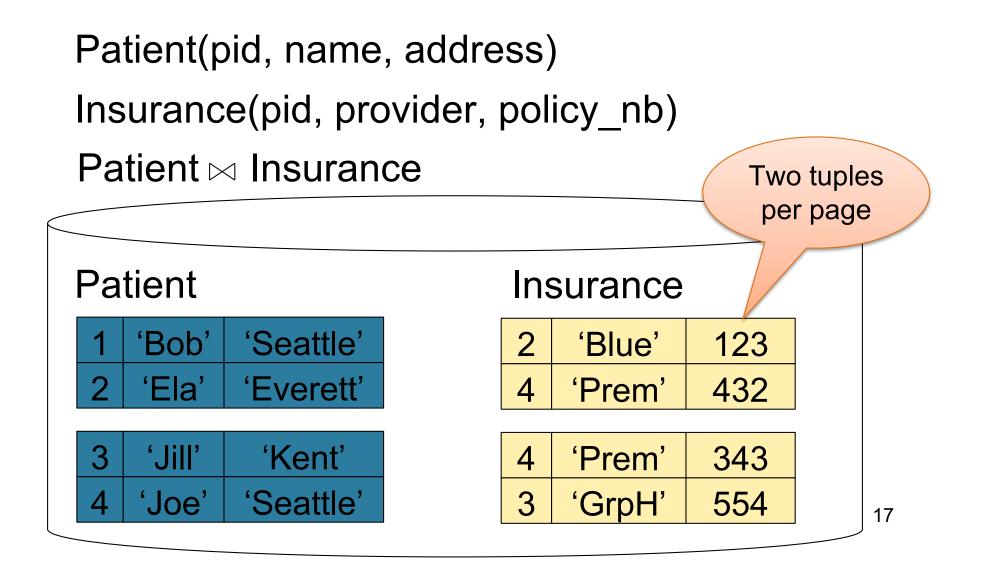


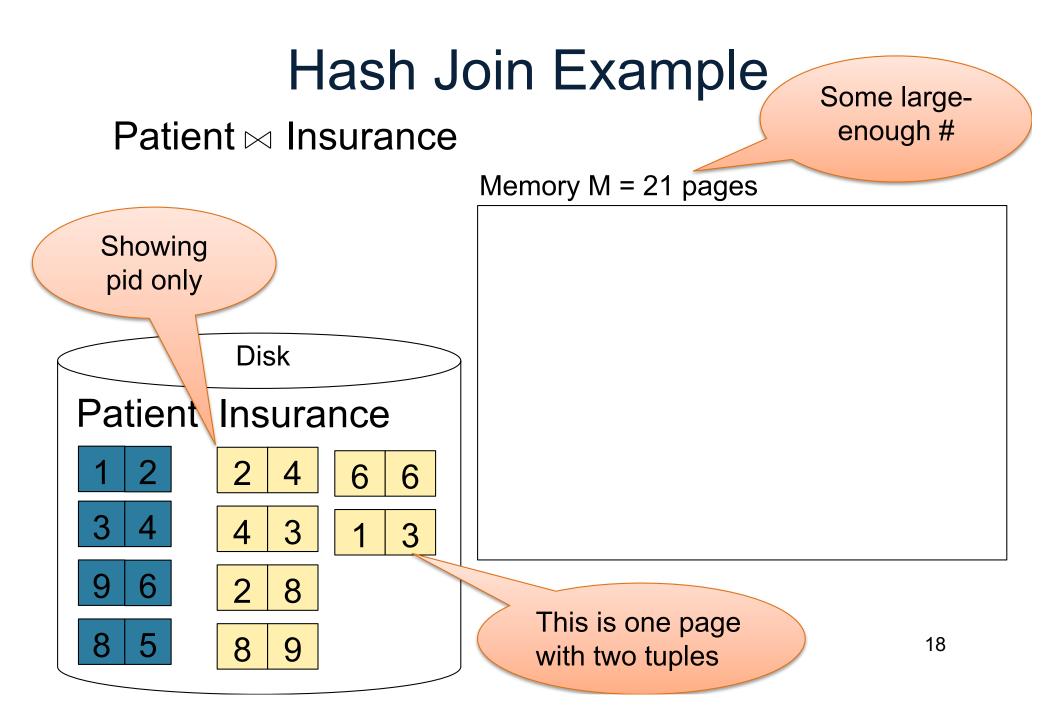
# Hash Join

# Hash Join

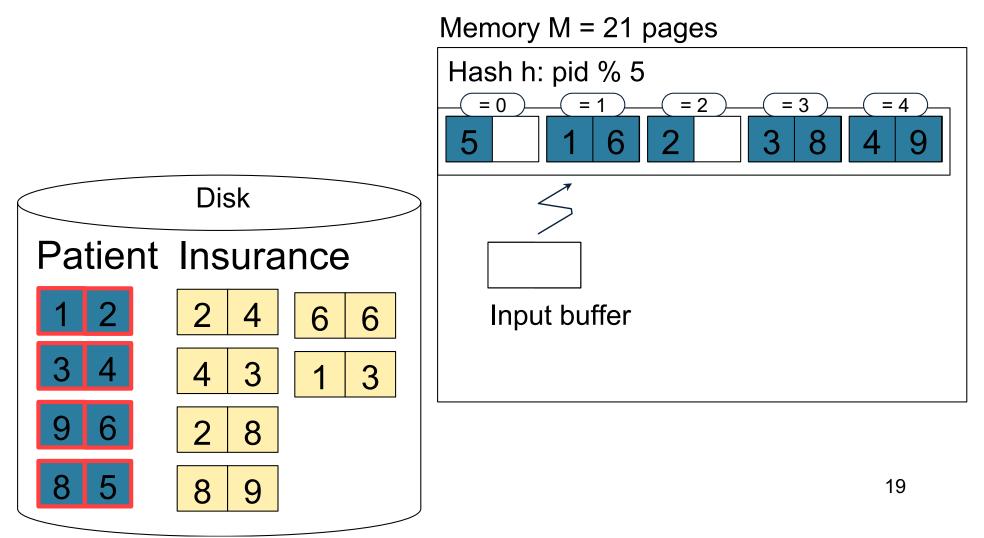
Hash join:  $R \bowtie S$ 

- Scan R, build hash table in main memory
- Then scan S and join
- Cost: B(R) + B(S)
- Which relation to build the hash table on?
- One-pass algorithm when  $B(R) \le M$ 
  - M = number of memory pages available

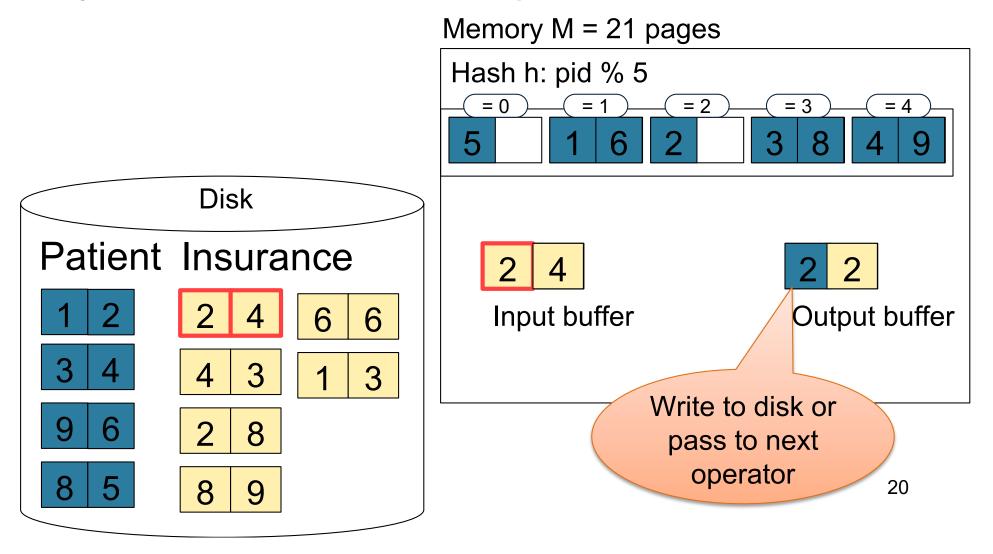




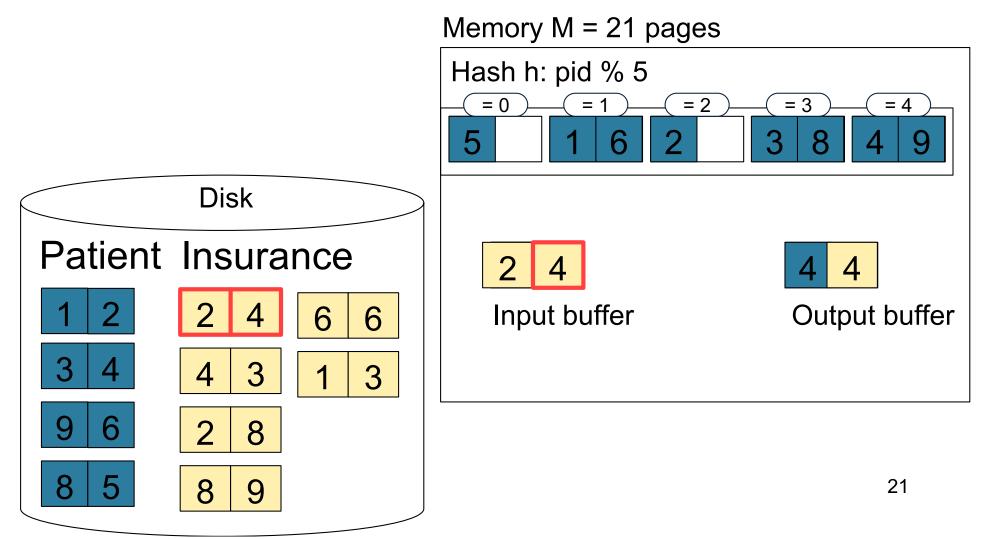
Step 1: Scan Patient and build hash table in memory



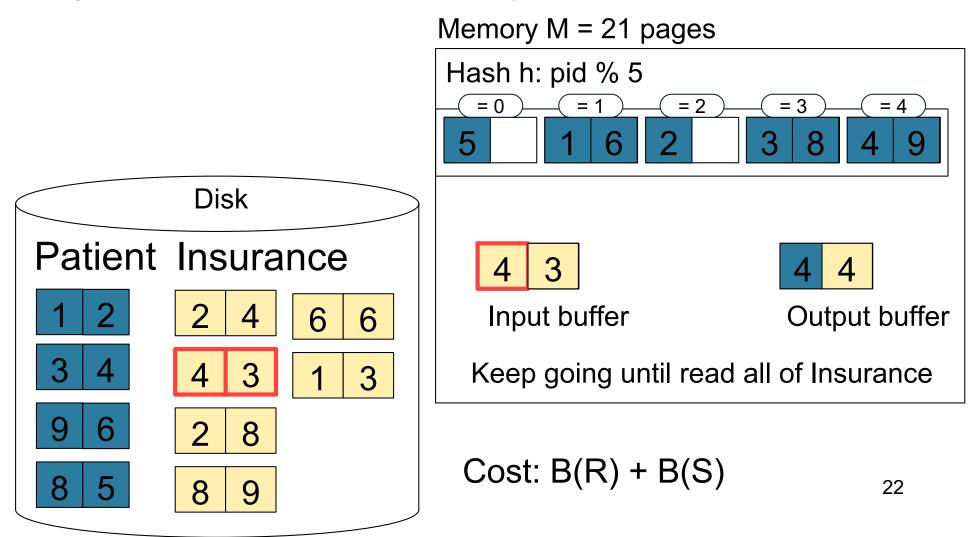
Step 2: Scan Insurance and probe into hash table

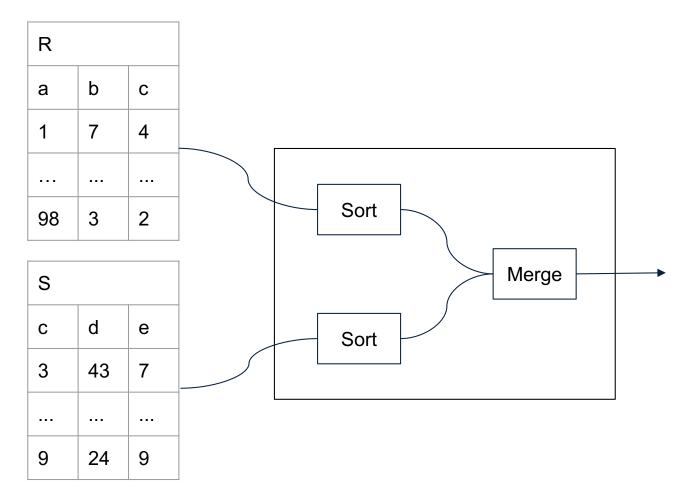


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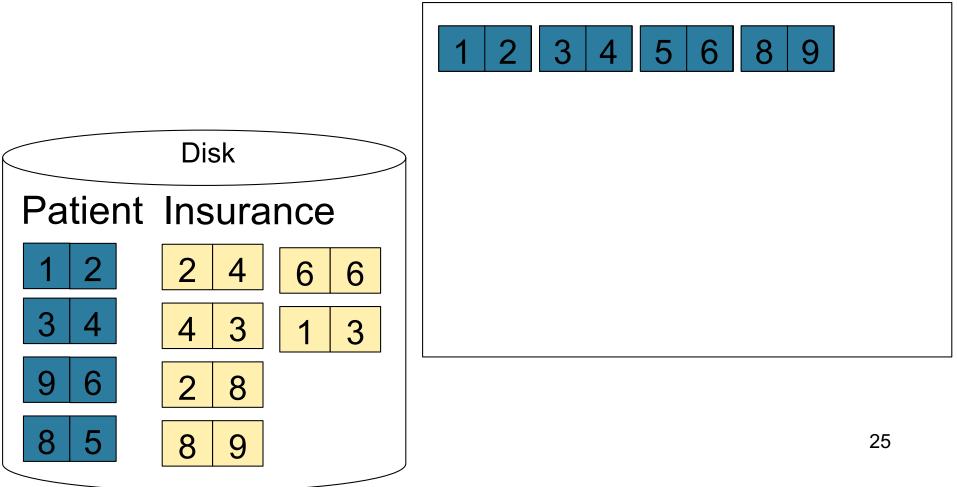
# Sort-Merge Join

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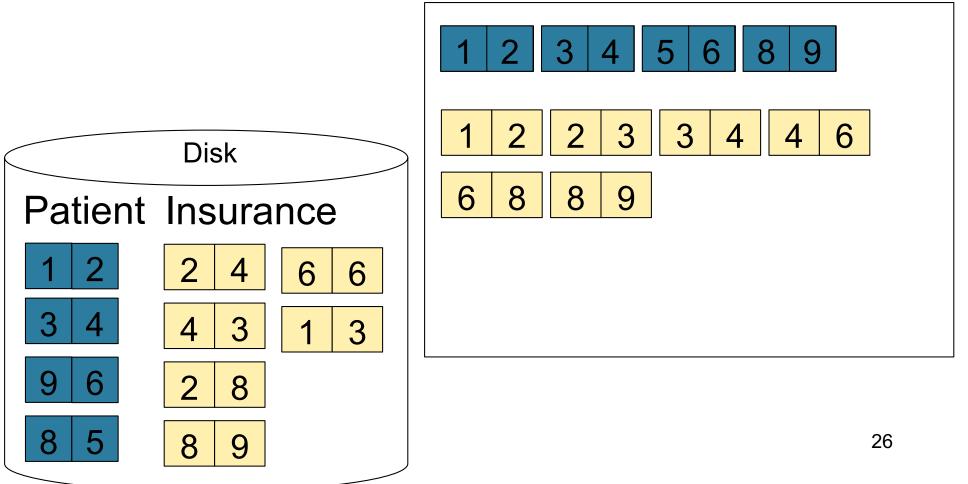
Sort-merge join:  $R \bowtie S$ 

- Scan R and sort in main memory
- Scan S and sort in main memory
- Merge R and S
- Cost: B(R) + B(S)
- One pass algorithm when B(S) + B(R) <= M</li>
- Typically, this is NOT a one pass algorithm

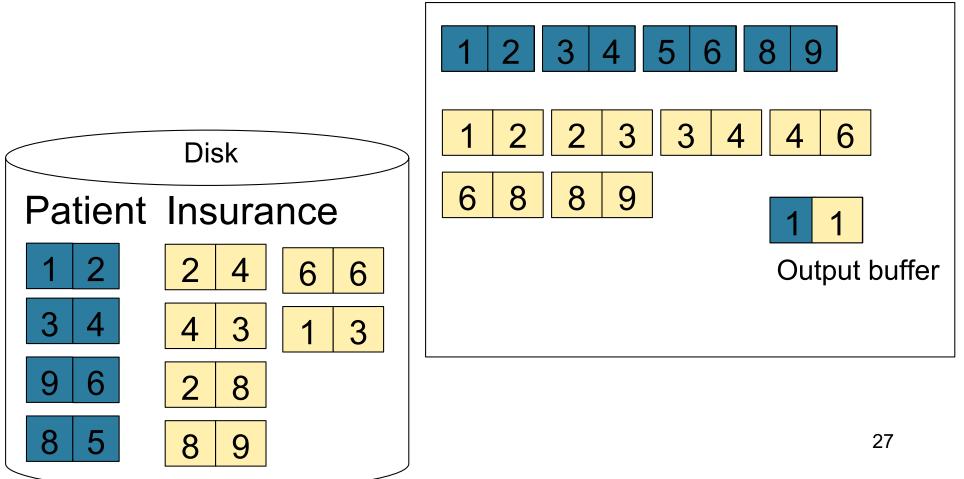
#### Step 1: Scan Patient and sort in memory



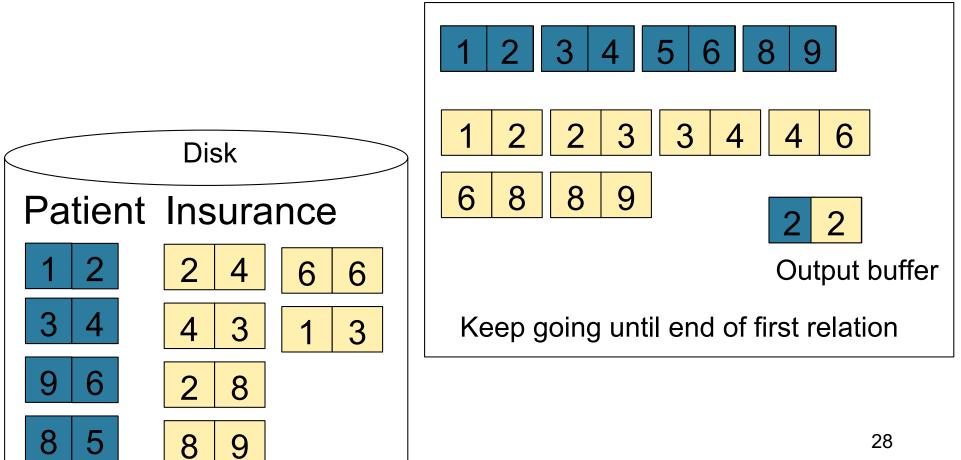
#### Step 2: Scan Insurance and sort in memory

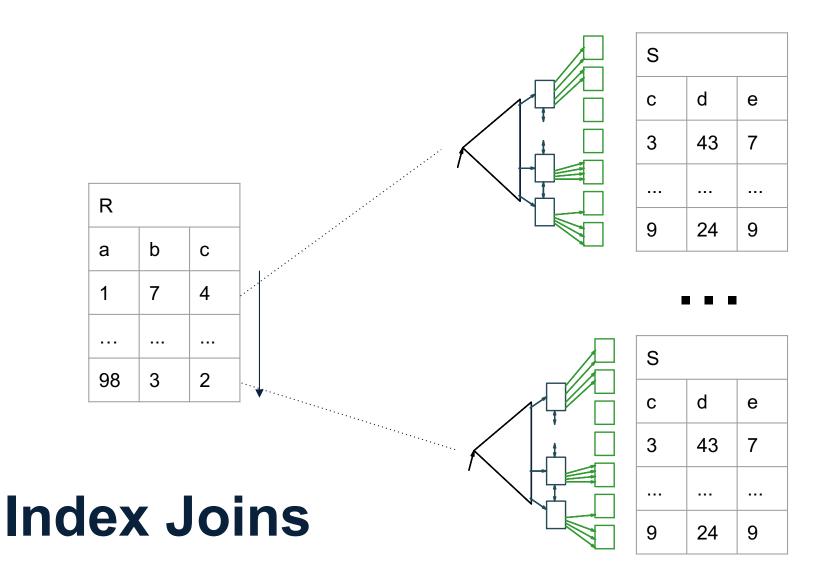


#### Step 3: Merge Patient and Insurance



#### Step 3: Merge Patient and Insurance





# R ⋈ S

- Assume S has an index on the join attribute
- Iterate over R, for each tuple fetch corresponding tuple(s) from S
- Cost:
  - If index on S is clustered:
     B(R) + T(R) \* (B(S) \* 1/V(S,a))
  - If index on S is unclustered:
     B(R) + T(R) \* (T(S) \* 1/V(S,a))



#### Index Nested Loop Join

#### If index on S is clustered: B(R) + T(R) \* (B(S) \* 1/V(S,a))

Still have to scan in R

Why is the multiplier term T(R)?

T(R) must be used because we cannot assume that a whole block of R (B(R)) will have the same attribute to join on, and thus use the same index access on S for. What does 1/V(S,a) represent?

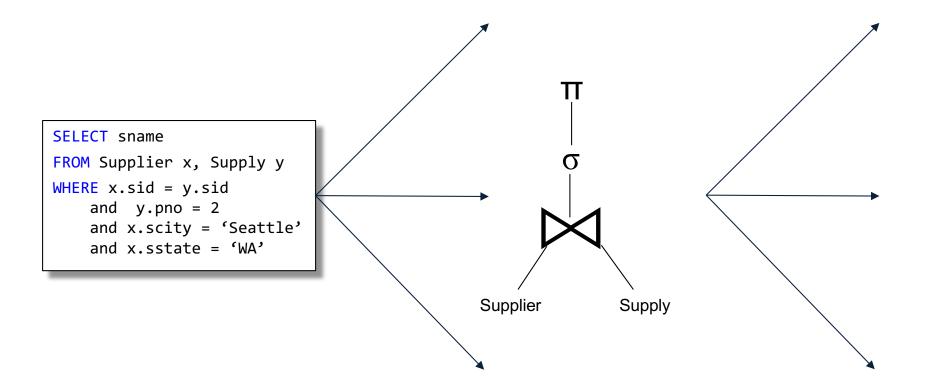
1/V(S,a) represents the nature of the B+ Tree index. We are only scanning as much as we need. Note that the performance of the index join will decrease as V decreases.

#### Index Nested Loop Join

# If index on S is unclustered: B(R) + T(R) \* (T(S) \* 1/V(S,a))

Why did this change from B(R) to T(R)?

Remember that tuples are stored on contiguous blocks. In a clustered index from before we know we can scan a single chunk of the disk to get the entire desired range. In an unclustered index we no longer can assume contiguous access. Thus we estimate that every tuple needs its own I/O operation.



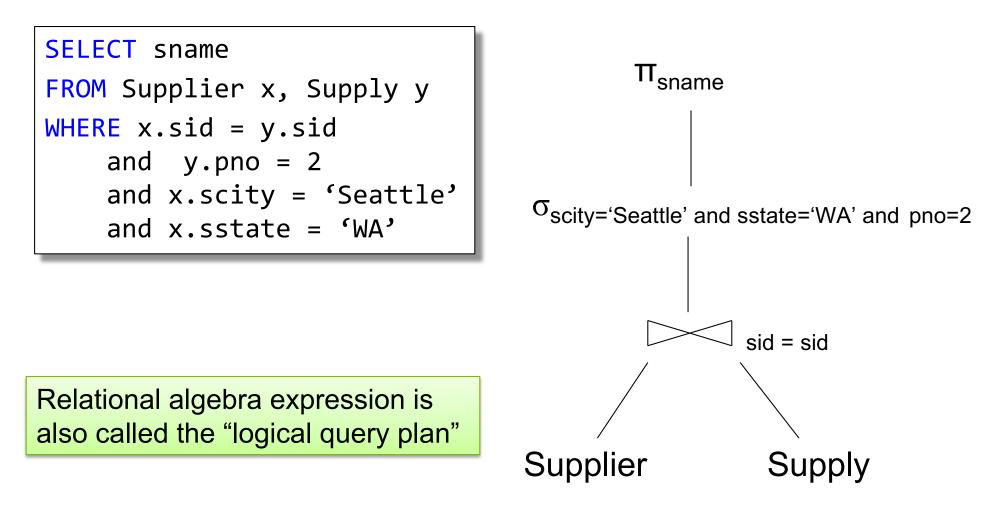
# Generating Query Plans (review)

# Review: Logical vs Physical Plans

- Logical plans:
  - Created by the parser from the input SQL text
  - Expressed as a relational algebra tree
  - Each SQL query has many possible logical plans
- Physical plans:
  - Goal is to choose an efficient implementation for each operator in the RA tree
  - Each logical plan has many possible physical plans

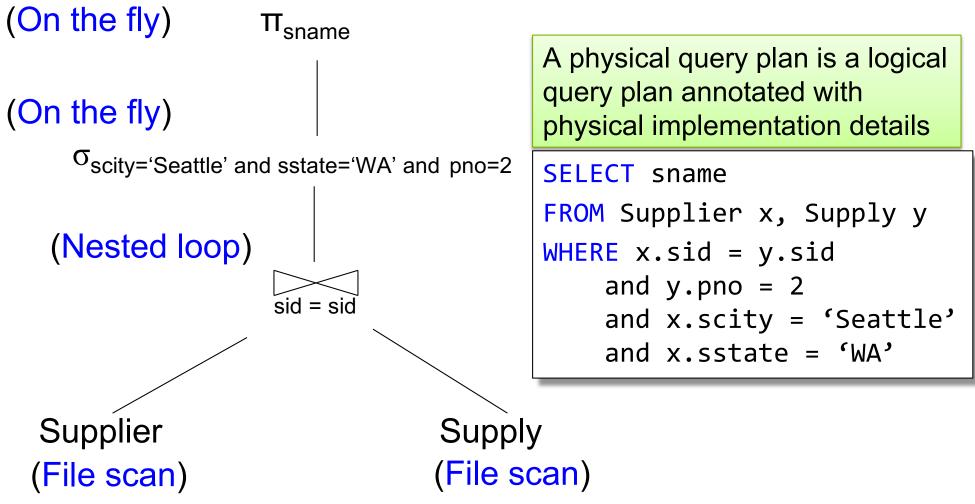
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Supply(sid, pno, quantity)

## **Review: Relational Algebra**



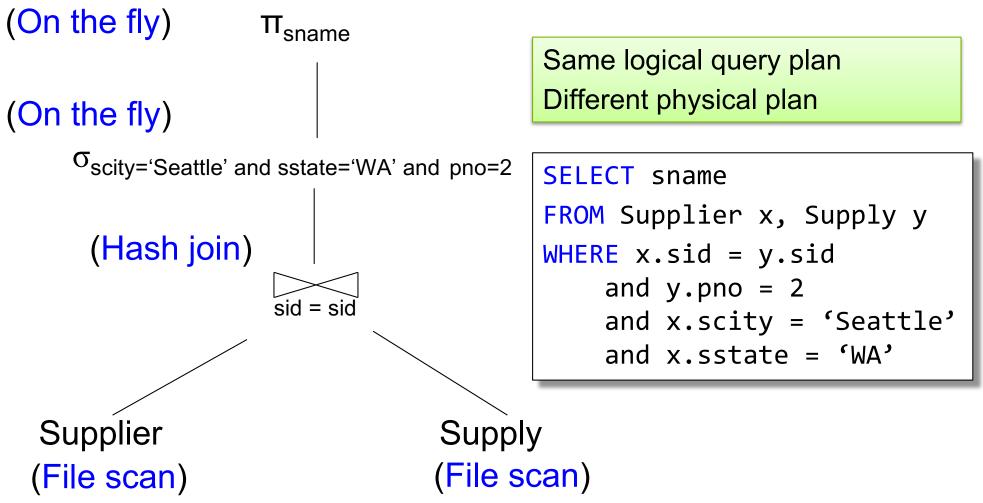
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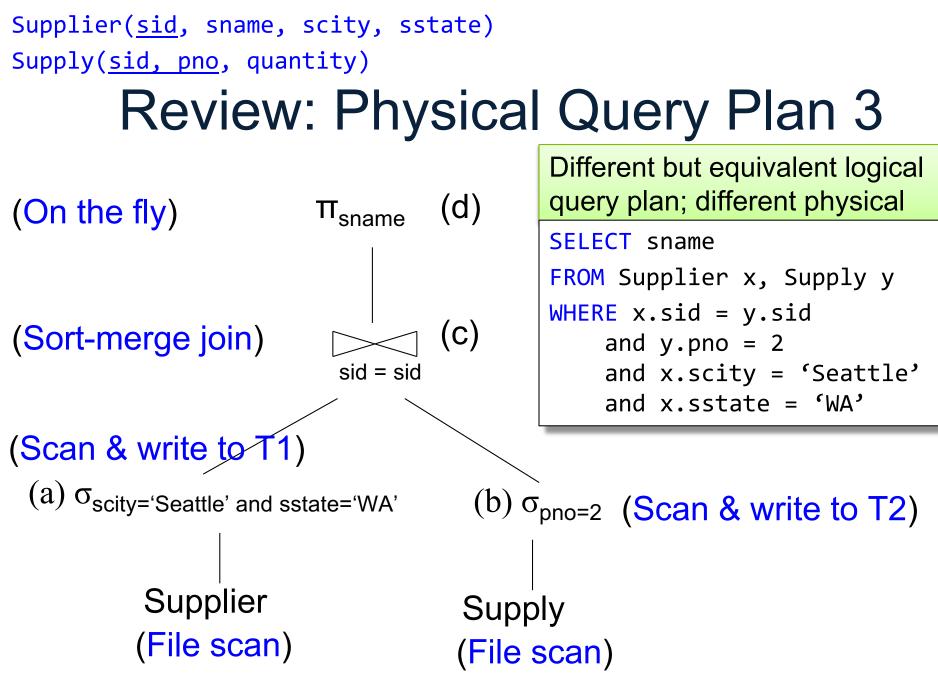
# **Review: Physical Query Plan 1**



Supplier(sid, sname, scity, sstate)
Supply(sid, pno, quantity)

# **Review: Physical Query Plan 2**





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# Query Optimization: Overview

- Compute cost of each operator
  - This depends on:
    - Table statistics (# of tuples etc)
    - Algorithm used
- Cost of a physical plan = sum(each operator cost)
- Cost each plan and choose the one with lowest cost