Database Systems CSE 414

Lectures 23: Parallel Databases

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Announcement

- · WQ7 due tonight
 - (was due yesterday)
- · HW7 due on Wednesday
- · HW8 (last!) on Spark
 - will be posted later this week

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Why compute in parallel?

- · Multi-cores:
 - Most processors have multiple cores
 - This trend will increase in the future
- · Big data: too large to fit in main memory
 - Distributed query processing on 100-1000 servers
 - Widely available now using cloud services

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Big Data

- Companies, organizations, scientists have data that is too big (and sometimes too complex) to be managed without changing tools and processes
- · Complex data processing:
 - Decision support queries (SQL w/ aggregates)
 - Machine learning (adds linear algebra and iteration)

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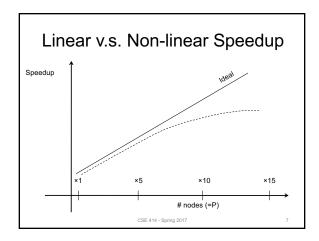
Two Kinds to Parallel Data Processing

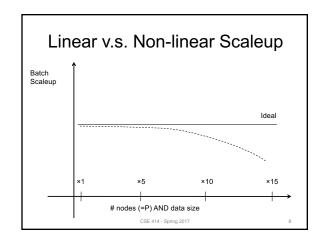
- Parallel databases, developed starting with the 80s (this lecture)
 - OLTP (Online Transaction Processing)
 - OLAP (Online Analytic Processing, or Decision Support)
- General purpose distributed processing: MapReduce, Spark
 - Mostly for Decision Support Queries

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Performance Metrics for Parallel DBMSs

- P = the number of nodes (processors, computers)
- · Speedup:
 - More nodes, same data → higher speed
- · Scaleup:
 - More nodes, more data → same speed
- OLTP: "Speed" = transactions per second (TPS)
- Decision Support: "Speed" = query time





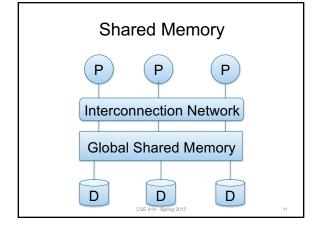
Challenges to Linear Speedup and Scaleup

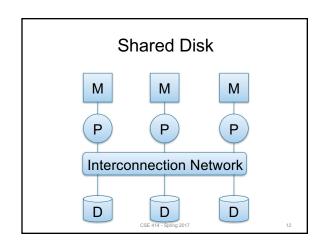
- · Startup cost
 - Cost of starting an operation on many nodes
- Interference
 - Contention for resources between nodes
- Stragglers
 - Slowest node becomes the bottleneck

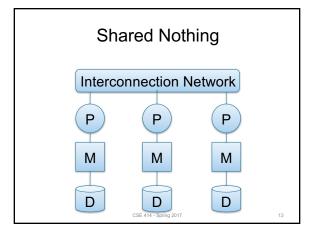
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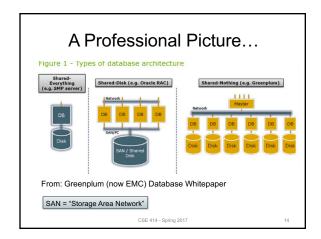
Architectures for Parallel Databases

- · Shared memory
- · Shared disk
- · Shared nothing









Shared Memory

- · Nodes share both RAM and disk
- · Dozens to hundreds of processors

Example: SQL Server runs on a single machine and can leverage many threads to get a query to run faster (see query plans)

- · Easier to program and easy to use
- But very expensive to scale: last remaining cash cows in the hardware industry

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Shared Disk

- · All nodes access the same disks
- Found in the largest "single-box" (noncluster) multiprocessors

Oracle dominates this class of systems.

Characteristics:

 Also hard to scale past a certain point: existing deployments typically have fewer than 10 machines

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Shared Nothing

- · Cluster of machines on high-speed network
- Each machine has its own memory and disk:
 - lowest contention

NOTE: Because all machines today have many cores and many disks, then shared-nothing systems typically run many "nodes" on a single physical machine.

Characteristics:

- · Today, this is the most scalable architecture.
- · Most difficult to administer and tune.

We discuss only Shared Nothing in class

Approaches to Parallel Query Evaluation Inter-query parallelism - Transaction per node - OLTP Inter-operator parallelism - Operator per node - Both OLTP and Decision Support Intra-operator parallelism - Operator on multiple nodes - Decision Support We study only intra-operator parallelism: most scalable

Single Node Query Processing (Review)

Given relations R(A,B) and S(B, C), no indexes:

- Group-by: Y_{A,sum(B)}(R)
 Scan file R, insert into a hash table using attr. A as key
 - When a new key is equal to an existing one, add B to the value
- Join: R™S
 - Scan file S, insert into a hash table using attr. B as key
 Scan file R, probe the hash table using attr. B

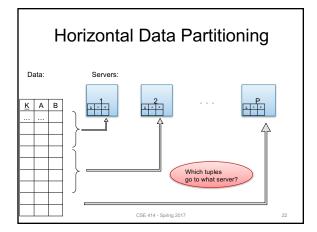
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Distributed Query Processing

- · Data is horizontally partitioned across many servers
- · Operators may require data reshuffling
 - not all the needed data is in one place

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Horizontal Data Partitioning Data: Servers K A B CSE 414 - Spring 2017



Horizontal Data Partitioning

- · Block Partition:
 - Partition tuples arbitrarily s.t. size(R₁)≈ ... ≈ size(Rp)
- Hash partitioned on attribute A:
 - Tuple t goes to chunk i, where i = h(t.A) mod P + 1
- Range partitioned on attribute A:
 - Partition the range of A into $-\infty = v_0 < v_1 < ... < v_P = ∞$
 - Tuple t goes to chunk i, if $v_{i-1} < t.A < v_i$

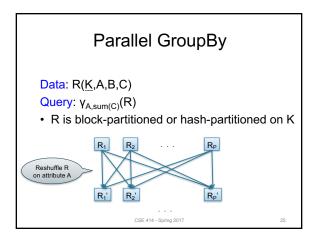
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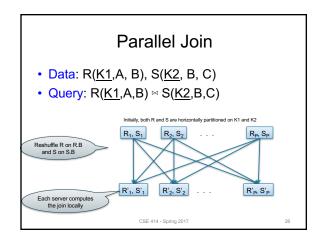
Parallel GroupBy

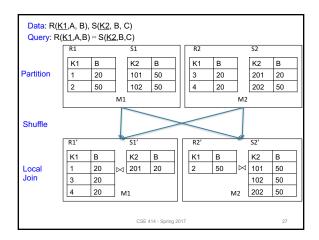
Data: R(K,A,B,C) Query: $\gamma_{A,sum(C)}(R)$

How can we compute in each case?

- R is hash-partitioned on A
- · R is block-partitioned
- R is hash-partitioned on K







Speedup and Scaleup Consider: - Query: YA,sum(C)(R) - Runtime: dominated by reading chunks from disk If we double the number of nodes P, what is the new running time? - Half (each server holds ½ as many chunks) If we double both P and the size of R, what is the new running time? - Same (each server holds the same # of chunks)

Uniform Data v.s. Skewed Data • Let R(K,A,B,C); which of the following partition methods may result in skewed partitions? • Block partition • Hash-partition - On the key K - On the attribute A May be skewed GEE when all records and up in the same value of the attribute, then all records end up in the same partition are partition.

