Synchronization Part 1

CSE 410 - Computer Systems November 26, 2001

Readings and References

Reading

 Chapter 7, Operating System Concepts, Silberschatz, Galvin, and Gagne. Read the following sections: 7.1, 7.2 (not the subsections),
 7.3

Other References

 Chapter 6, Multithreaded Programming with Pthreads, First edition, Bil Lewis and Daniel J. Berg, Sun Microsystems Press

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Too Much Milk

	You	Your Roommate
3:00	Look in fridge; no milk	
3:05	Leave for store	
3:10	Arrive at store	Look in fridge; no milk
3:15	Buy milk	Leave for store
3:20	Arrive home; put milk away	Arrive at store
3:25		Buy milk
3:30		Arrive home; put milk away
		Oh no, Mr. Bill, too much milk!

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Modeling the Problem

- Model you and your roommate as threads
- "Looking in the fridge" and "putting away milk" are reading/writing a variable

Correctness Properties

- Decomposed into safety and liveness
 - > safety
 - the program never does anything bad
 - > liveness
 - the program eventually does something good
- Although easy to state, these properties are not always easy to meet

Mutual Exclusion

shared state variables

Synchronization

> only one thread does a particular thing at a time. One thread doing it excludes all others.

Synchronization Definitions

> coordinated access by more than one thread to

- Critical Section
 - only one thread executes in a critical section at once

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Locks

- A lock provides mutual exclusion
 - > Only one thread can hold the lock at a time
 - A lock is also called a mutex (for mutual exclusion)
- Thread must *acquire the lock* before entering a critical section of code
- Thread releases the lock after it leaves the critical section

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Too Much Milk: A Solution

Lock Implementation Issue

- A context switch can happen at any time
 - > very simple acquire/release functions don't work
 - > in this case, both threads think they set lockInUse

Disable Interrupts

· disable interrupts to prevent a context switch

> simple but imperfect solution

```
Lock::Acquire() {
  disable interrupts;
}
Lock::Release() {
  enable interrupts;
}
```

- · Kernel can't get control when interrupts disabled
- · Critical sections may be long
 - > turning off interrupts for a long time is bad
- turning off interrupts is difficult and costly in multiprocessor systems

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Disable Interrupts with flag

only disable interrupts when updating a lock flag

```
initialize value = FREE;

Lock::Acquire() {
    disable interrupts;
    while(value != FREE) {
        enable interrupts;
        disable interrupts;
        disable interrupts;
    }
}

value = BUSY;
    enable interrupts
}
Lock::Release() {
    disable interrupts;
    value = FREE;
    enable interrupts;
}
```

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Atomic Operations

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- An *atomic operation* is an operation that cannot be interrupted
- On a multiprocessor disabling interrupts doesn't work well
- Modern processors provide atomic readmodify-write instruction or equivalent
- These instructions allow locks to be implemented on a multiprocessor

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Examples of Atomic Instructions

- **Test and set** (many architectures)
 - > sets a memory location to 1 and returns the previous value
 - > if result is 1, lock was already taken, keep trying
 - > if result is 0, you are the one who set it so you've got the lock
- Exchange (x86)
 - > swaps value between register and memory
- Compare & swap (68000)

```
read location value
if location value equals comparison value
store update value, set flag true
else
set flag false
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```

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Quasi-atomic for load/store ISA

• Remember our MIPS pipeline

- > only one memory stage per instruction
- > thus, can't do atomic "read, modify, write" directly

Load linked and store conditional

- > read value in one instruction (LL—load linked) and remember where the value came from
- > do some operation on the value
- when store occurs, check if value has been modified in the meantime (SC—store conditional)
- > if not modified, store new value and return "success"
- > if modified, return "failure"

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Locks with Test and Set

```
Lock::Release() {
  value = 0;
}

Lock::Acquire() {
  while(TestAndSet(value)) {}
}
```

• This works, but take a careful look at the while loop ... when does it exit?

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Busy Waiting

- CPU cycles are consumed while the thread is waiting for value to become 0
- This is very inefficient
- Big problem if the thread that is waiting has a higher priority than the thread that holds the lock

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Locks with Minimal Busy Waiting

- Use a queue for threads waiting on the lock
- A guard variable provides mutual exclusion

```
Lock::Acquire() {
                                   Lock::Release() {
  while(TestAndSet(guard)){}
                                     while(TestAndSet(guard){}
  if( value != FREE ) {
                                     if(anyone on wait queue){
    Put self on wait queue;
                                       move thread from wait
    guard = 0 and switch();
                                         queue to ready queue;
  } else {
                                     } else {
    value = BUSY;
                                       value = FREE;
    guard = 0;
                                     guard = 0;
                                                             17
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```

Synchronization Summary

- · Threads often work independently
- But sometimes threads need to access shared data
- Access to shared data must be mutually exclusive to ensure safety and liveness
- Locks are a good way to provide mutual exclusion
- Next time we'll see other synchronization primitives—semaphores and condition variables

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