# The ZPL Compiler: **Portable Parallel Programming**

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# What is Parallel Programming?

Parallel Programming: Computing using several processors cooperatively ("in parallel")

The promise: "If I run my program on 1,000 processors, it will run 1,000 times faster!" (perfect speedup)

The reality: This is very difficult to achieve

# Why is Perfect Speedup Difficult to Achieve?

Imagine trying to get 1,000 people to solve a problem cooperatively:

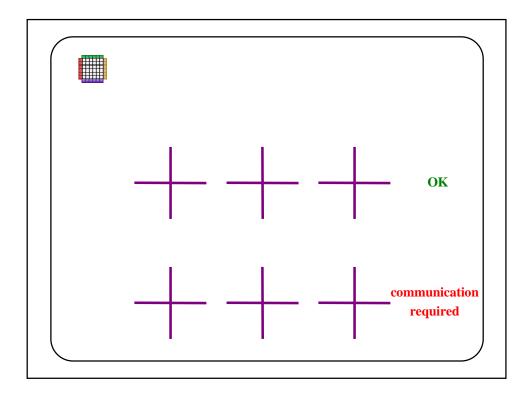
- for trivial problems (stuffing a million envelopes), it probably would go 1,000× faster
- BUT, for more interesting problems, people would require meetings or communications...
  - ...to compare notes
  - ...to exchange data
  - ...to pass a task off from one person to another
- this is *overhead* (wasn't required by a lone worker)
- the same issues apply to parallel programming



# Example of Parallel Overhead

Matrix Addition

• Matrix Multiplication



## III Writing Parallel Programs

Q: How can I write a parallel program?

### A: Lots of ways:

- use a traditional language (C/Fortran) plus a library that supports communication between processors (PVM/MPI) - tedious, painstaking
- use a traditional language and a parallelizing compiler that will "automatically" make your program run in parallel – *hard problem, cross fingers*
- use a new language designed to make parallel programming easier (HPF, NESL, ZPL)

### **What is ZPL?**

- An array programming language
  - atomic operations are supported on arrays
- A data-parallel programming language
  - array operations are executed in parallel
- Targets large-scale scientific applications
- Developed at UW, 1991 present



### **ZPL's Goals**

*Expressiveness*: Allow programmers to express parallel computations elegantly

Portability: The program should run on all modern parallel platforms

*Performance:* The program should run quickly (ideally, as fast as a hand-coded parallel program)



# Outline

- ✓ Introduction to Parallel Programming
- Introduction to ZPL
- The ZPL Compiler
  - Achieving Portability
  - Achieving Performance

# Region Overview

Regions: index sets that...

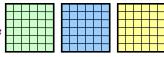
...can be named

```
region
         R = [1..n , 1..n ];
       BigR = [0..n+1,0..n+1];
```



... are used to declare arrays

var A, B, C: [BigR] integer;



... specify indices for a statement's array references

[R] A := B + C;









# Array Operators

Array Operators: applied to array expressions to modify the statement's region indices

- *e.g.*, the @-operator translates indices by an offset [R] A := B@east + C@west;

```
[R] A := (A@east + A@west)/2;
```

# Regions vs. Indexing

Compare:

```
C:
      for (i=1; i<=n; i++) {
        for (j=1; j<=n; j++) {
          A[i,j] = B[i,j] + C[i,j];
          A[i,j] = B[i,j+1] + C[i,j-1];
          T[i,j] = (A[i,j+1] + A[i,j-1])/2;
      for (i=1; i<=n; i++) {
        for (j=1; j<=n; j++) {
          A[i,j] = T[i,j];
        }
```



# Challenges to ZPL's Portability

- Unlike sequential machines, parallel architectures aren't well-understood
- As a result, they change rapidly
  - since entering grad school, I've seen about a dozen different parallel architectures
  - about half of these are no longer in use
  - each architecture has its own unique characteristics, quirks
- Thus, writing a compiler to work on all of them could present quite a challenge



# Achieving Portability

ZPL achieves platform-independence in two ways:

- posits an abstract parallel architecture
- uses ANSI C as its back-end "assembly language"



### **ZPL's Machine Model**

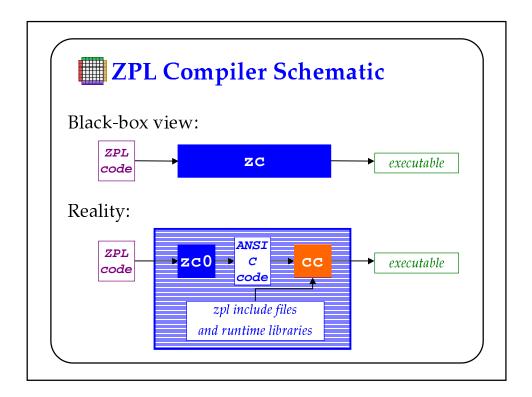
- ZPL relies on a *machine model* called the CTA
- The CTA provides an abstract view of parallel computers:
  - referring to data on another processor takes longer than referring to your own local data
  - the way that processors are interconnected is not terribly important
- When compiling ZPL, we focus on the CTA rather than each machine's particular characteristics



## Compiling to ANSI C

The ZPL compiler doesn't translate ZPL into assembly code, but rather into ANSI C

- don't need to learn each machine's instruction set
- don't have to write a new back-end for every new machine that emerges
- knowing how C translates to assembly allows us to generate efficient code
- don't have to worry about traditional scalar optimizations, register allocation, etc.



# Runtime Library Overview

- Runtime libraries implement all machinespecific behavior:
  - interprocessor communication
  - memory allocation
  - allocating processors
  - coordinated I/O
- Porting the compiler to a new machine is as simple as porting the libraries
  - often no work at all, thanks to communication libraries like PVM and MPI

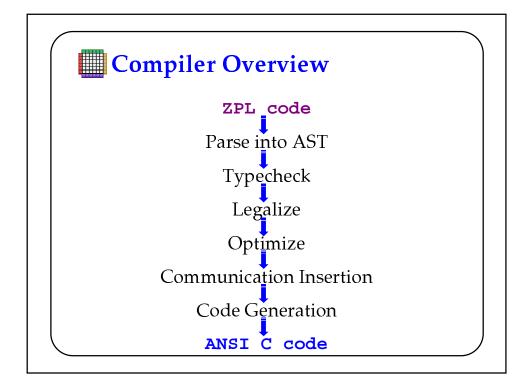


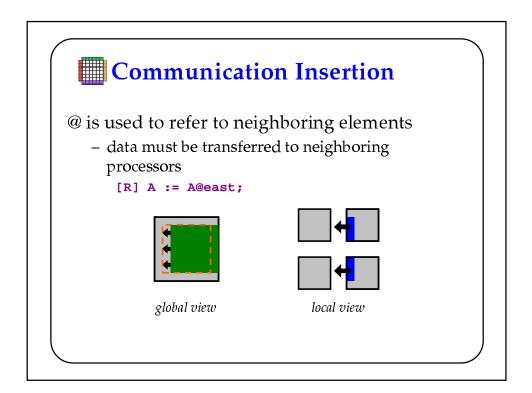
# Compiler Output

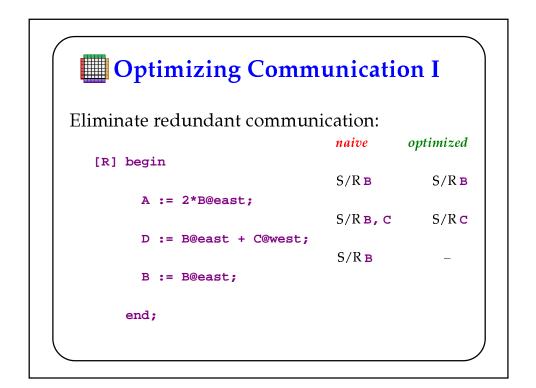
Compiler produces a Single Program, Multiple Data (SPMD) C program

- run one copy of the program on each processor
- each processor given unique index
- based on its index, each processor performs a fraction of the total work:

```
for (i=_MYLO(R,0); i<=_MYHI(R,0); i++) {</pre>
  for (j=_MYLO(R,1); j<=_MYHI(R,1); j++) {</pre>
    \_ACCESS(A,i,j) = \_ACCESS(B,i,j) +
                       _ACCESS(C,i,j);
  }
}
```









# Optimizing Communication II

Overlap Communication and Computation

```
naive
                                          optimized
[R] begin
                                S/RB
                                         S/RB; SC
      A := 2*B@east;
                               S/Rc
                                             RС
      D := B@east + C@west;
      B := B@east;
    end;
```



# Achieving Good Performance

- High-level optimizations
  - communication optimizations
  - array elimination (contraction)
- Low-level optimizations
  - efficient array access
  - dealing with C's quirks



## Implementing ZPL Arrays

- C doesn't support 2D dynamic arrays
- We need them because the number of processors is unknown at compile time
- Thus, we implement them by hand:

```
A = malloc((\_MYHI(R,0)-\_MYLO(R,0)+1) *
             (\underline{MYHI}(R,1)-\underline{MYLO}(R,1)+1) *
             sizeof(element));
ACCESS(A,i,j) = A + ((i-MYLO(R,0))*numcols) +
                       (j-_MYLO(R,1));
```



# Optimizing ZPL Arrays

- This method requires 2 subtractions, 2 additions, and 1 multiplication per array, per iteration
- But all we're doing is iterating over a solid block of memory!!
- Instead we can walk a pointer over memory:

```
Walker = A;
for (i=...) {
  for (j=...) {
                                            row offset
    *Walker = *Walker + 1;
    *Walker += Col_Offset;
  *Walker += Row_Offset;
```



### Conclusions

- For portably compiling a high-level language like ZPL, using C as a back-end is great
  - + compiles on all machines
  - + saves us from implementing traditional optimizations
  - + instead, can focus on issues unique to ZPL and parallel programming
    - communication insertion
    - · communication optimizations
    - array semantics
  - though similar to assembly, C is still not perfect



# **ZPL Summary**

- Performance competitive with hand-coded C + MPI/PVM
- Released to the public July 1997 via web
- User community spans many disciplines
- Continual improvements to language and compiler

http://www.cs.washington.edu/research/zpl mailto:zpl-info@cs.washington.edu