

## Optimizations

Identify inefficiencies in target or intermediate code

- usually IR
- machine-independent optimizations

Goal: replace with equivalent but better sequences

- fewer instructions
- cheaper instructions
- different instructions
- fewer registers

“Optimize” overly optimistic; “usually improve”

Must reproduce the same results

## Optimizations

Scope of study for optimizations:

- **peephole:**  
look at single instruction/adjacent instructions
- **local:**  
look at straight-line sequence of statements
- **global (intraprocedural):**  
look at whole procedure
- **interprocedural:**  
look across procedures

Larger scope  $\Rightarrow$  better optimization, more complexity

## Peephole optimization

**After** code generation, look at adjacent instructions  
(a “**peephole**” on the code stream)

- try to replace:
    - single instruction
    - adjacent instructions
- with a shorter, faster sequence of code

## Algebraic simplifications

**Eliminate redundant code**

```
x := x + 0
x := x * 1
x := (x + Y) - Y
```

## Algebraic simplifications

### Strength reduction

- replace expensive operation with a cheaper one

```
a := b * 8;
```

```
mult $5, $4, #8
```

$\Rightarrow$

```
sll $5, $4, 3
```

## Algebraic simplifications

### Constant folding: evaluate constant expressions

```
x := 3 + 4
```

```
li $4, #7
```

```
sw $4, 0(addr of x)
```

## Redundant instruction elimination

Eliminate redundant **loads & stores**

```
a := b + b
c := a
...
lw $4, 0(addr of b)
lw $5, 0(addr of b)
add $6, $4, $5
sw $6, 0(addr of a)

lw $4, 0(addr of a)
sw $4, 0(addr of c)
...
⇒
lw $4, 0(addr of b)
add $6, $4, $4
sw $6, 0(addr of a)

sw $6, 0(addr of c)
...
```

## Redundant instruction elimination

**Unreachable code**

Unlabeled instructions after a `goto` can be eliminated

```
#define debug 0
...
if (debug) {...}
⇒
if 0 <> 1 goto L2
debug stmts
L2: ...

⇒
goto L2
debug stmts (the peephole opt)
L2: ...

⇒
L2: ...
```

## Flow of control optimizations

“Adjacent” instructions = “adjacent in control flow”

Eliminate **jumps to jumps**

```
goto L1
...
L1: goto L2
⇒
```

```
goto L2
...
L1: goto L2
```

## Flow of control optimizations

Eliminate **jumps after conditional branches**

```
if a < b then
  if c < d then
    do nothing
  else
    stmt1;
  end;
else
  stmt2;
end;
```

assume a in \$1, b in \$2, c in \$3, d in \$4

```
slt $5, $1, $2
beq $5, $0, L2
slt $5, $3, $4
beq $5, $0, L1 ⇒ bne $5, $0, L3
br L3 ⇒
L1: stmt1 ⇒ stmt1
    br L3
L2: stmt2
L3: ...
```

## Instruction selection

```
sub sp, 4, sp  
mov r1, 0(sp)
```

⇒

```
mov r1, -(sp)
```

```
mov 12(fp), r1  
add r1, 1, r1  
mov r1, 12(fp)
```

⇒

```
inc 12(fp)
```

(68000 code)

## Local optimization

Analysis and optimizations within a basic block

**Basic block:** straight-line sequence of statements

- no control flow into or out of sequence
- start of basic blocks
  - beginning of program
  - target of conditional or conditional goto
  - statement immediately following conditional or conditional goto

Better than peephole

Not too hard to implement

Machine-independent, if done on intermediate code

## Local constant folding & constant propagation

**Constant folding:** evaluate constant expressions

**Constant propagation:**

- if a variable is assigned a constant, replace downstream uses of the variable with that constant
- why do we want the compiler, not the programmer to do constant propagation?

Can enable more constant folding

## Local constant folding & constant propagation

Source:

```
const count:int = 10;  
...  
x := count * 5;  
y := x ^ 3;
```

Unoptimized intermediate code:

```
t1 := 10  
t2 := 5  
t3 := t1 * t2  
x := t3  
  
t4 := x  
t5 := 3  
t6 := exp(t4, t5)  
y := t6
```

## Local copy propagation

### Copy propagation:

- if have an assignment, use RHS in downstream references to LHS
- can lead to **dead code elimination**

```
x := t3
y := z + x
⇒
x := t3
y := z + t3
```

## Local dead assignment elimination

Eliminate when result is never referenced again

- define: assign to
- use: reference
- **live**: variable is live at some program point if used later on otherwise dead

```
x := y + z;
a := y + x;
```



## Local common subexpression elimination (CSE)

### Common subexpression:

- previously computed
- none of its variables have changed

a := b + c

b := a - d

c := b + c

d := a - d

Use the previously computed value instead of repeating the same calculation

Keep track of available expressions

## Local common subexpression elimination (CSE)

Source:

```
... a[i] + b[i] ...
```

Unoptimized intermediate code:

```
t2 := i * 4
```

```
t3 := t2 + &a
```

```
t4 := *(t3)
```

```
t6 := i * 4
```

```
t7 := t6 + &b
```

```
t8 := *(t7)
```

```
t9 := t4 + t8
```

## Intraprocedural (“global”) optimizations

Enlarge scope of analysis to whole procedure

- more opportunities for optimization
- have to deal with splits, merges, and loops

Can do constant propagation,  
common subexpression elimination, etc.  
at global level

Can do new optimizations, e.g., **loop optimizations**

Optimizing compilers usually work at this level

## Loop-invariant code motion

Goal: hoist **loop-invariant calculations** out of loops

- result does not change as execute the iterations

Source:

```
for i := 1 to 10 do
  a[i] := a[i] + b[j];
  z := z + 100000;
end;
```

Transformed source:

```
var1 := b[j];
var2 := 100000;
for i := 1 to 10 do
  a[i] := a[i] + var1;
  z := z + var2;
end;
```

## Code motion at intermediate code level

Source:

```
for i := 1 to 10 do
  a[i] := b[j];
end;
```

Unoptimized intermediate code:

```
*(fp + offseti) := 1
_top:
  if *(fp + offseti) > 10 goto _done
  t1 := *(fp + offsetj)
  t2 := t1 * 4
  t4 := *(t2 + &b)
  t5 := *(fp + offseti)
  t6 := t5 * 4
  *(t6 + &a) := t4
  t9 := *(fp + offseti)
  t10 := t9 + 1
  *(fp + offseti) := t10
  goto _top
_done:
```

## Loop induction variable elimination

For-loop index is **induction variable**

If used only to index arrays, can rewrite with pointers

Source:

```
for i := 1 to 10 do
  a[i] := a[i] + x;
end;
```

Transformed source:

```
for p := &a[1] to &a[10] do
  *p := *p + x;
end;
```

## Global register allocation

Try to allocate global variables to registers

- avoid stores and reloading at basic block boundaries

Make sure a globally used variable doesn't conflict with a local

Example:

```
procedure foo(n:int, x:int):int;
  var sum:int, i:int;
  begin
    sum := x;
    for i := 1 to n do
      sum := sum + i;
    end;
    q := 17;
    output q;
    return sum;
  end foo;
```

## How to do global optimizations?

Represent procedure by a **control flow graph**

Each **basic block** is a node in graph

Branches become edges in graph

Example:

```
procedure foo(n:int);
  var a:array[10] of int;
  var i:int, j:int;
  begin
    j := 10;
    for i := 0 to 9 do
      a[i] := a[i] + (n - j * 2);
    end;
  end foo;
```

## Analysis of control flow graphs

To do optimization,  
first analyze important info, then do transformations

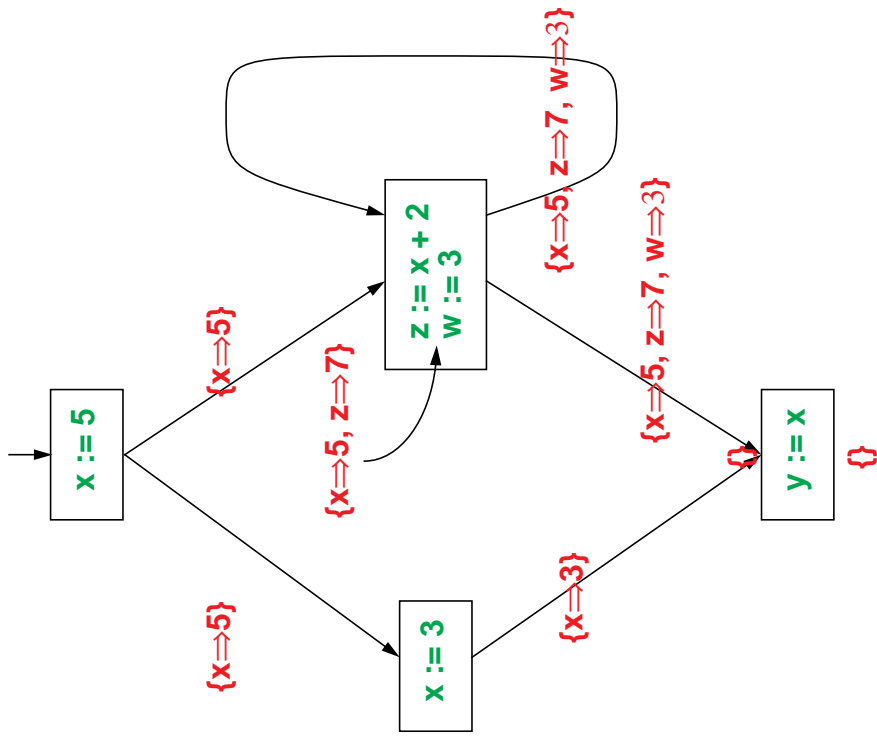
Propagate info through graph

- At branches: copy info along both branches
- At merges: combine info, being conservative
  - constant propagation, CSE: intersection
  - live variable analysis: union

At loops: iterate until annotations do not change (**fixpoint**)

E.g., global constant propagation:  
propagate *name* → *constant* mappings through graph

## Global constant propagation



## Interprocedural optimizations

Expand scope of analysis to procedures calling each other

Can do local, intraprocedural optimizations at larger scope

Can do new optimizations, e.g., **inlining**

## Inlining

Replace procedure call with body of called procedure

Source:

```
const pi:real := 3.1415927;
proc circle_area(radius:int):int;
begin
  return pi * (radius ^ 2);
end circle_area;
...
r := 5;
...
output := circle_area(r);
```

After inlining:

```
const pi:real := 3.1415927;
...
r := 5;
...
output := pi * (r ^ 2);
```

## Summary

Optimizations lead to more efficient code

Enlarging scope of analysis yields better results

- today, most optimizing compilers work at the global/intraprocedural level

Optimizations organized as collections of passes

Some optimizations enable others

- e.g., CSE or constant propagation -> dead assignment elimination
- e.g., constant propagation -> constant folding

Presence of optimizations makes other parts of compiler easier

- register allocation has fewer temporaries
- target code generation only has to generate code

## Optimization summary

	Peep hole	Local	Intra-procedural	Inter-procedural
algebraic simplification	x			
strength reduction	x			
constant folding & propagation	x	x	x	x?
redundant ld/st	x	x	x	x?
dead code elimination	x	x		
jumps to jumps/cond. jumps	x			
CSE	x	x	x	x?
copy propagation	x	x	x	x?
loop invariant code motion			x	
induction variable elimination			x	
instruction selection	x	x		
register allocation	x	x	x	x?
code scheduling		x	x	
inlining				x