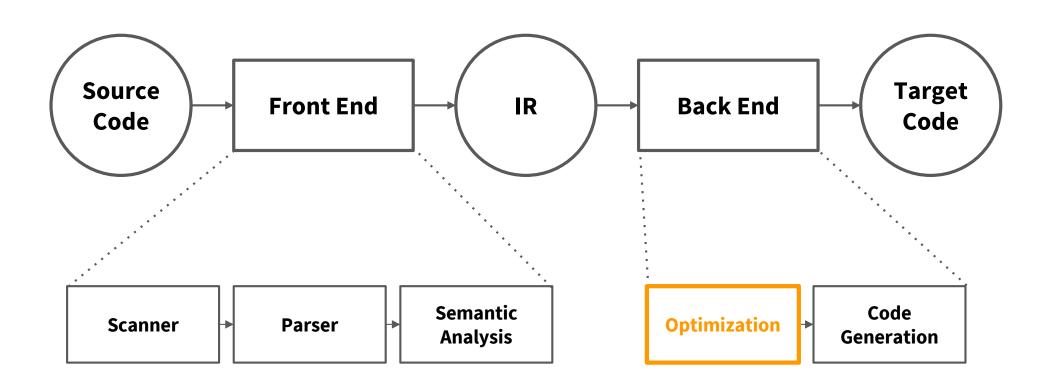
Dataflow Analysis + Intro to SSA

CSE 401/M501

Announcements

- 401 CodeGen due date pushed to Saturday
 - O Contact us if you need more time, but be careful not to spill over to your report/hw4/final review
- 401 report due next Tuesday; M501 project/report due next Weekend.
- HW4 due next Thursday

14:30-15:20 Lecture CSE2 G10	23	16:00-17:00 OH (Larry) 24 Zoom	14:30-15:20 Lecture 2: CSE2 G10	.5	Section WE ARE Dataflow & SSA		14:30-15:20 Lecture 27 CSE2 G10
Dataflow (cond.); start SSA (9.3) SSA slides			SSA 17:00-18:00 OH (Apollo)	١	15:30-16:30 OH (Jack) CSE2 151 and Zoom		SSA (concl.) 23:00 Project: code gen due Saturday 11 pm
18:00-19:00 OH (Robert) CSE2 153 and Zoom			CSE2 153 and Zoom		20:00-21:00 OH (Morel) Zoom		
Memorial Day	30	16:00-17:00 OH (Larry) 31 Zoom	CSE2 G10)1	Section 0 SSA; hw4 last-minute questions; wrapup		14:30-15:20 Lecture 03 CSE2 G10
		23:00 Project: CSE 401 project reports due	Back end overview; instruction selection 17:00-18:00 OH (Apollo)		15:30-16:30 OH (Jack) CSE2 151 and Zoom		Instruction scheduling & register allocation (no new slides); Wrapup
			CSE2 153 and Zoom		20:00-21:00 OH (Morel)		23:00 CSE M 501 project due Saturday 11 pm
					Zoom		23:00 CSE M 501 report due Sunday 11 pm
					23:00 hw4 due (dataflow & SSA) (SSA diagram optional),	-	



Peephole

Local

Intraprocedural / Global

Peephole A few Instructions

Local

Intraprocedural / Global

Peephole A few Instructions

Local A Basic Block

Intraprocedural / Global

Peephole A few Instructions

Local A Basic Block

Intraprocedural / Global A Function/Method

Peephole A few Instructions

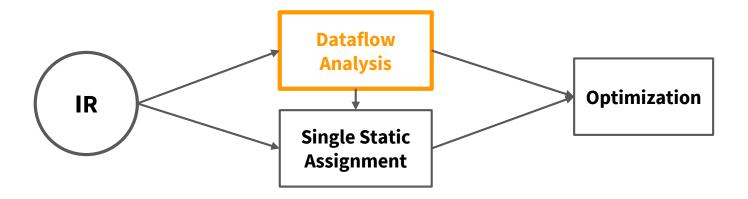
Local A Basic Block

Intraprocedural / Global A Function/Method

Interprocedural A Program

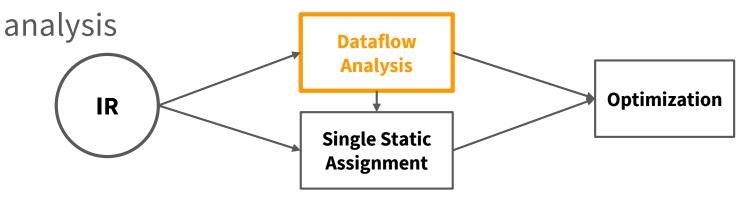
Overview of Dataflow Analysis

- A framework for exposing properties about programs
- Operates using sets of "facts"



Overview of Dataflow Analysis

- A framework for exposing properties about programs
- Operates using sets of "facts"
- Just the initial discovery phase
 - Changes can then be made to optimize based on the



Overview of Dataflow Analysis

- Basic Framework of Set Definitions (for a Basic Block b):
 - IN(b): facts true on entry to b
 - OUT(b): facts true on exit from b
 - GEN(b): facts created (and not killed) in b
 - KILL(b): facts killed in b

Reaching Definitions (A Dataflow Problem)

"What definitions of each variable might reach this point"

- Could be used for:
 - Constant Propagation
 - Uninitialized Variables

```
int x;

if (y > 0) {
    x = y;
} else {
    x = 0;
}
System.out.println(x);
```

"x=y", "x=0"

Reaching Definitions (A Dataflow Problem)

"What definitions of each variable might reach this point"

- **Be careful**: Does not involve the *value* of the definition
 - The dataflow problem
 "Available Expressions"
 is designed for that

```
still: "x=y", "x=0"
```

```
int x;

if (y > 0) {
    x = y;
} else {
    x = 0;
}

y = -1;
System.out.println(x);
```

Equations for Reaching Definitions

- IN(b): the definitions reaching upon entering block b
- OUT(b): the definitions reaching upon exiting block b
- GEN(b): the definitions assigned and not killed in block b
- KILL(b): the definitions of variables overwritten in block b

$$IN(b) = \bigcup_{p \in pred(b)} OUT(p)$$

$$OUT(b) = GEN(b) \cup (IN(b) - KILL(b))$$

Another Equivalent Set of Equations (from Lecture):

- Sets:
 - DEFOUT(b): set of definitions in b that reach the end of b (i.e., not subsequently redefined in b)
 - SURVIVED(b): set of all definitions not obscured by a definition in b
 - REACHES(b): set of definitions that reach b
- Equations:

 $U_{p \in preds(b)} DEFOUT(p) U (REACHES(p) \cap SURVIVED(p))$

Problems 1_a and 1_b

L1: b = a + 1

L2: c = c + b

L3: a = b * 2

L4: if a < N goto L1

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
L0	L0					
L1	L1					
L2	L2					
L3	L3					
L4						
L5						

L1: b = a + 1

L2: c = c + b

L3: a = b * 2

L4: if a < N goto L1

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
L0	L0					
L1	L1					
L2	L2					
L3	L3	LO				
L4						
L5						

L1: b = a + 1

L2: c = c + b

L3: a = b * 2

L4: if a < N goto L1

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
L0	L0					
L1	L1		LO			
L2	L2		L0, L1			
L3	L3	L0	L0, L1, L2			
L4			L1, L2, L3			
L5			L1, L2, L3			

L1: b = a + 1

L2: c = c + b

L3: a = b * 2

L4: if a < N goto L1

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
L0	LO			LO		
L1	L1		LO	L0, L1		
L2	L2		L0, L1	L0, L1, L2		
L3	L3	LO	L0, L1, L2	L1, L2, L3		
L4			L1, L2, L3	L1, L2, L3		
L5			L1, L2, L3	L1, L2, L3		

L1: b = a + 1

L2: c = c + b

L3: a = b * 2

L4: if a < N goto L1

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
L0	L0			LO		LO
L1	L1		LO	L0, L1	L0, L1, L2, L3	L0, L1, L2, L3
L2	L2		L0, L1	L0, L1, L2	L0, L1, L2, L3	L0, L1, L2, L3
L3	L3	LO	L0, L1, L2	L1, L2, L3	L0, L1, L2, L3	L1, L2, L3
L4			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3
L5			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3

L1: b = a + 1

L2: c = c + b

L3: a = b * 2

L4: if a < N goto L1

L5: return c

Convergence!

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
LO	L0			LO		LO
L1	L1		LO	L0, L1	L0, L1, L2, L3	L0, L1, L2, L3
L2	L2		L0, L1	L0, L1, L2	L0, L1, L2, L3	L0, L1, L2, L3
L3	L3	LO	L0, L1, L2	L1, L2, L3	L0, L1, L2, L3	L1, L2, L3
L4			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3
L5			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3

L1: b = a + 1

L2: c = c + bL3: a = b * 2

L4: if a < N goto L1

L5: return c

Is it possible to replace the use of *a* in block L1 with the constant 0?

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
L0	L0			LO		LO
L1	L1		LO	L0, L1	L0, L1, L2, L3	L0, L1, L2, L3
L2	L2		L0, L1	L0, L1, L2	L0, L1, L2, L3	L0, L1, L2, L3
L3	L3	LO	L0, L1, L2	L1, L2, L3	L0, L1, L2, L3	L1, L2, L3
L4			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3
L5			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3

L1: b = a + 1

L2: c = c + b

L3: a = b * 2

L4: if a < N goto L1

L5: return c

Is it possible to replace the use of *a* in block L1 with the constant 0?

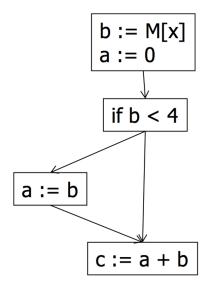
No. To determine this, we would look at the IN set for block L1 -- the fact that the IN set contains two definitions of 'a' (L0 and L3) means we cannot perform this constant propagation. In other words, more than one definition of 'a' is a reaching definition to block L1, and therefore performing constant propagation would only preserve one possible value of 'a' and the generated code would not be equivalent.

Block	GEN	KILL	IN (1)	OUT (1)	IN (2)	OUT (2)
L0	LO			LO		LO
L1	L1		LO	L0, L1	L0, L1, L2, L3	L0, L1, L2, L3
L2	L2		L0, L1	L0, L1, L2	L0, L1, L2, L3	L0, L1, L2, L3
L3	L3	LO	L0, L1, L2	L1, L2, L3	L0, L1, L2, L3	L1, L2, L3
L4			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3
L5			L1, L2, L3	L1, L2, L3	L1, L2, L3	L1, L2, L3

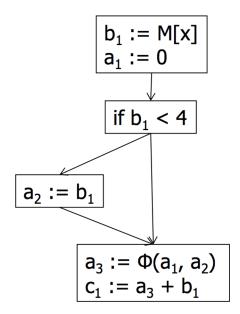
Phi-Functions

- A way to represent <u>multiple possible values</u> for a certain definition
 - o Not a "real" instruction just a form of bookkeeping needed for SSA



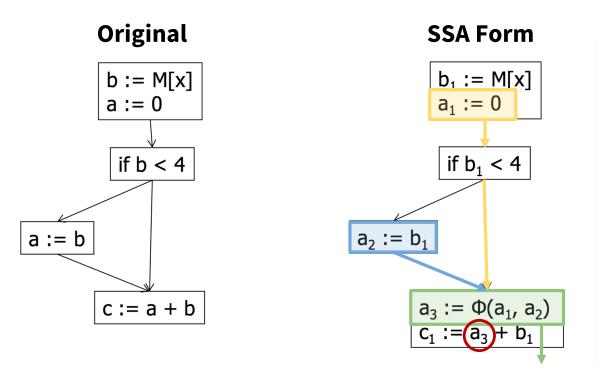


SSA Form

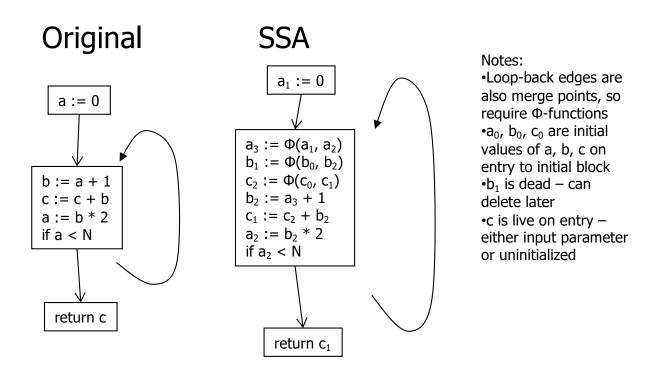


Where to place Phi-Functions?

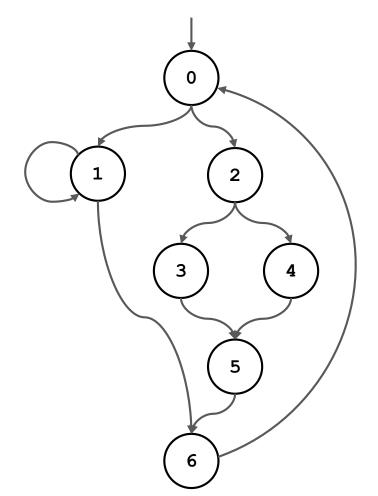
- Wherever a variable has multiple possible definitions entering a block
 - Inefficient (and unnecessary!) to consider all possible phi-functions at the start of each block



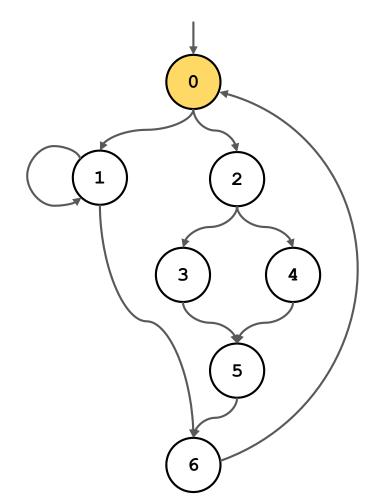
Example With a Loop



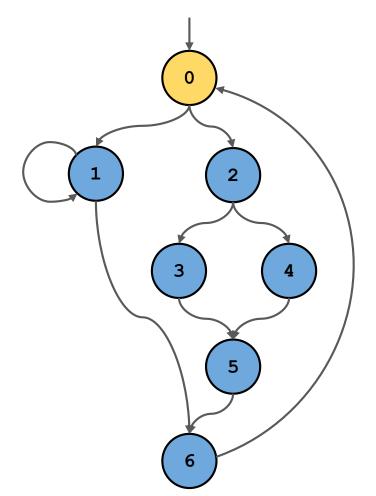
Problem 2(a)



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0		
1		
2		
3		
4		
5		
6		



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0		
1		
2		
3		
4		
5		
6		

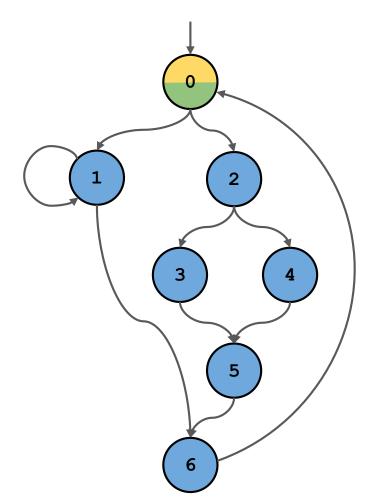


NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	
1		
2		
3		
4		
5		
6		

A node \mathbf{x} dominates a node \mathbf{Y} iff every path from the entry point of the control flow graph to \mathbf{Y} includes \mathbf{x} .

A node \mathbf{X} strictly dominates \mathbf{Y} and $\mathbf{X} \neq \mathbf{Y}$

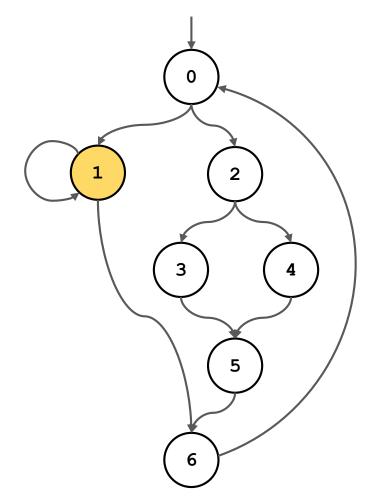
Need to go through 0 to get through 1, 2, 3, 4, 5, 6 and 0 cannot strictly dominate itself



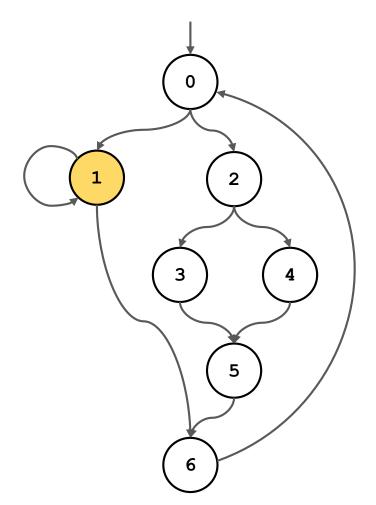
NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1		
2		
3		
4		
5		
6		

A node **Y** is in the *dominance frontier* of node **X** iff **X** dominates an immediate predecessor of **Y** but **X** does not strictly dominate **Y**. A node **0** is in the *dominance frontier* of node **0** iff **0** dominates an immediate predecessor **(6)** of **0** but **0** does not strictly dominate **0**

0 dominates 6, 6 is an immediate predecessor of 0, 0 does not strictly dominate 0



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1		
2		
3		
4		
5		
6		

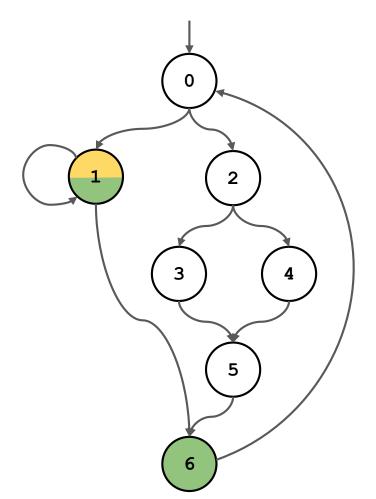


NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	
2		
3		
4		
5		
6		

A node \mathbf{x} dominates a node \mathbf{Y} iff every path from the entry point of the control flow graph to \mathbf{Y} includes \mathbf{x} .

A node x strictly dominates a node y iff x dominates y and $x \neq y$

1 does not dominate 6 because there is a path from 5 that doesn't include 1. 1 does not strictly dominate itself

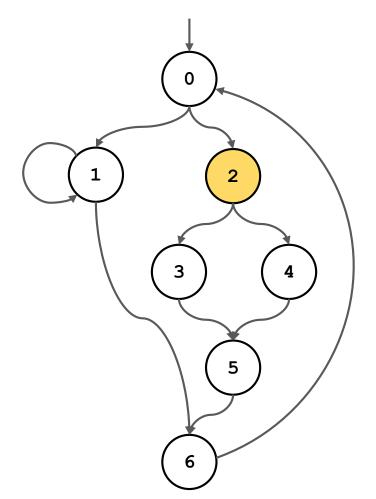


NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1, 6
2		
3		
4		
5		
6		

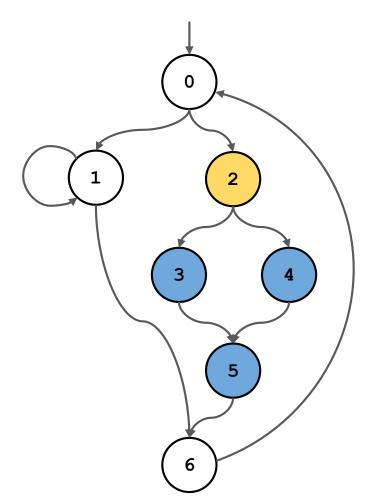
A node \mathbf{Y} is in the *dominance frontier* of node \mathbf{X} iff \mathbf{X} dominates an immediate predecessor of \mathbf{Y} but \mathbf{X} does not strictly dominate \mathbf{Y} .

X = 1, Y = 6, 1 dominates 1, 1 is an immediate predecessor of 6, 1 does not strictly dominate 6

X = 1, Y = 1, 1 dominates 1, 1 is an immediate predecessor of 1, 1 does not strictly dominate 1



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1,6
2		
3		
4		
5		
6		

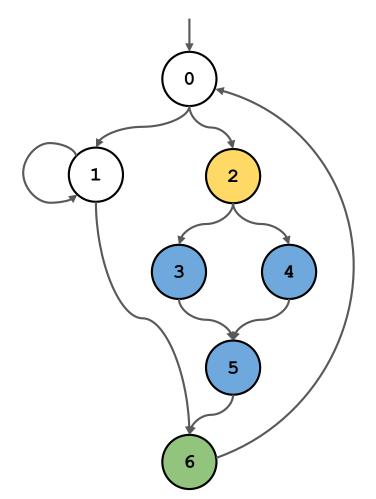


NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1,6
2	3, 4, 5	
3		
4		
5		
6		

A node \mathbf{x} dominates a node \mathbf{Y} iff every path from the entry point of the control flow graph to \mathbf{Y} includes \mathbf{x} .

A node \mathbf{X} strictly dominates \mathbf{Y} and $\mathbf{X} \neq \mathbf{Y}$

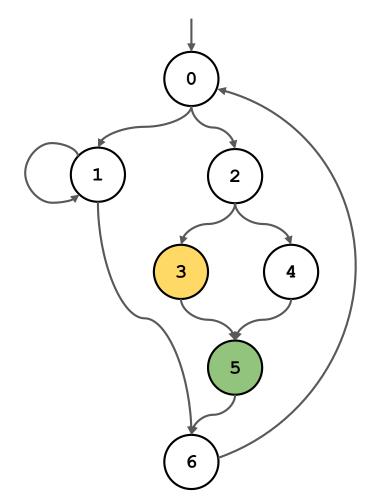
Need to go through 2 to get through 3, 4, 5 and 2 cannot strictly dominate itself



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	ø	1,6
2	3, 4, 5	6
3		
4		
5		
6		

A node \mathbf{Y} is in the *dominance frontier* of node \mathbf{X} iff \mathbf{X} dominates an immediate predecessor of \mathbf{Y} but \mathbf{X} does not strictly dominate \mathbf{Y} .

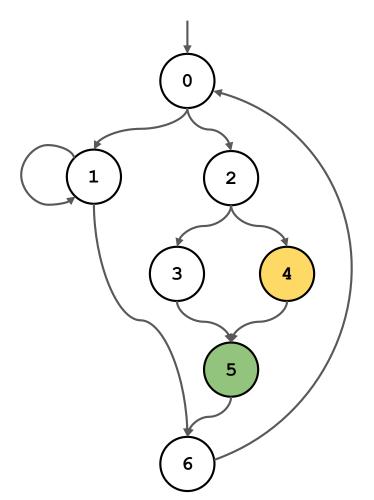
X = 2, Y = 6, 2 dominates 5, 5 is an immediate predecessor of 6, 2 does not strictly dominate 6



MODE		
NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1,6
2	3, 4, 5	6
3	Ø	5
4		
5		
6		

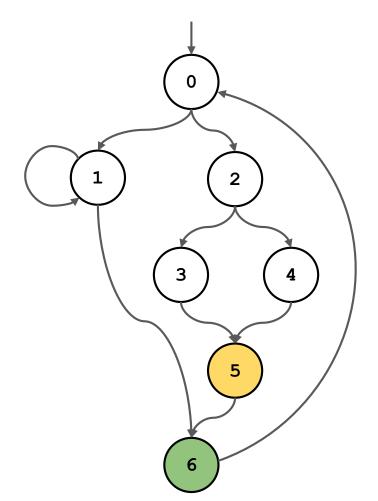
3 does not strictly dominate 5 (path through 4) and therefore does not strictly dominate anything else

3 dominates 3, 3 is an immediate predecessor of 5, 3 does not strictly dominate 5



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1,6
2	3, 4, 5	6
3	Ø	5
4	Ø	5
5		
6		

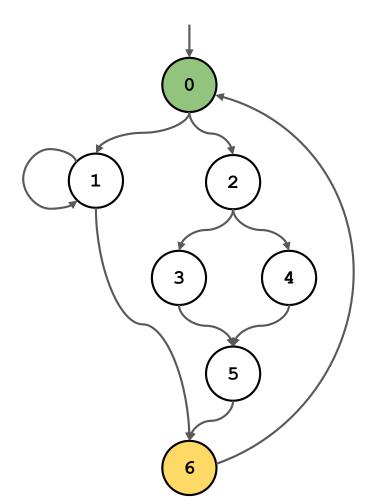
Same as previous slide but with 4 instead of 3



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1,6
2	3, 4, 5	6
3	Ø	5
4	Ø	5
5	Ø	6
6		

5 does not strictly dominate 6 (path through 1) and therefore does not strictly dominate anything else

5 dominates 5, 5 is an immediate predecessor of 6, 5 does not strictly dominate 6



NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1,6
2	3, 4, 5	6
3	Ø	5
4	Ø	5
5	Ø	6
6	Ø	0

6 does not strictly dominate 0 (path through 0) and therefore does not strictly dominate anything else

6 dominates 6, 6 is an immediate predecessor of 0, 6 does not strictly dominate 0

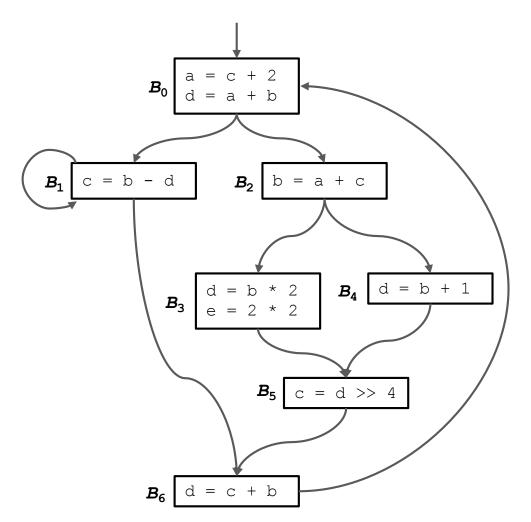
Problem 2(b)

Converting to SSA





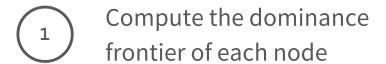
- Determine which variables need merging in each node
- Assign numbers to definitions and add phi functions



Step 1: Dominance Frontiers

NODE	STRICTLY DOMINATES	DOMINANCE FRONTIER
0	1, 2, 3, 4, 5, 6	0
1	Ø	1, 6
2	3, 4, 5	6
3	Ø	5
4	Ø	5
5	Ø	6
6	Ø	0

Converting to SSA



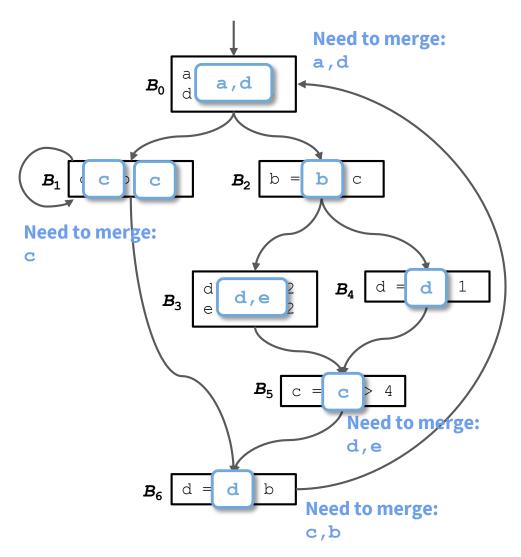


Determine which variables need merging in each node



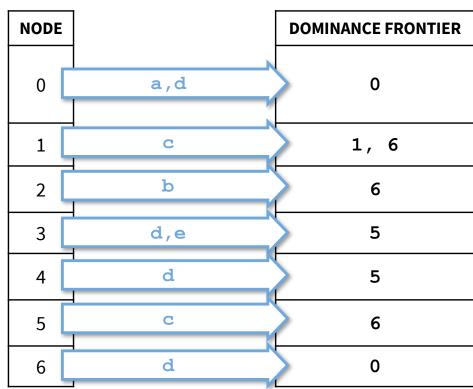
We will compute using the dominance frontiers

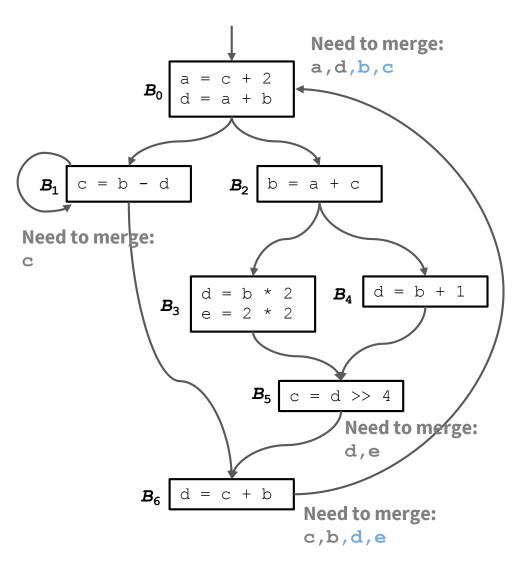
Assign numbers to definitions and add phi functions



Step 2: Determine Necessary Merges

ITERATION 1: Each node in the dominance frontier of node X will merge any definitions created in node X.

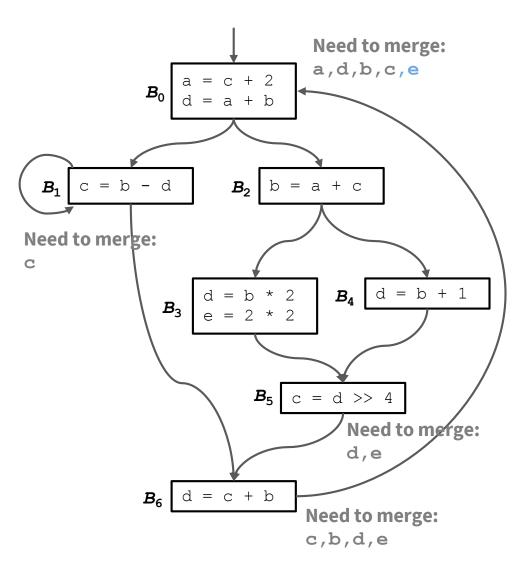




Step 2: Determine Necessary Merges

ITERATION 2: Each merge will create a new definition, which may need merging again.

NODE		DOMINANCE FRONTIER
0		0
1		1, 6
2		6
3		5
4		5
5	d,e	6
6	b,c	0

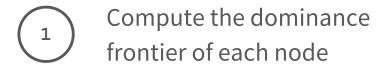


Step 2: Determine Necessary Merges

ITERATION 3: Each merge will create a new definition, which may need merging again.

NODE		DOMINANCE FRONTIER
0		0
1		1, 6
2		6
3		5
4		5
5		6
6	d,e	0

Converting to SSA





Determine which variables need merging in each node



Assign numbers to definitions and add phi functions



Place phi functions first, then increment subscripts

Merges go first, and each successive definition of a variable should increment its index by 1.

$$\mathbf{B_0}$$
 $\begin{bmatrix} a = c + 2 \\ d = a + b \end{bmatrix}$

Need to merge:

Note: these subscripts determined after doing the rest of the CFG!

Merges go first, and each successive definition of a variable should increment its index by 1.

$$\mathbf{B_1}$$
 c = b - d

 $\qquad \qquad \Longrightarrow$

$$c_2 = \Phi(c_1, c_3)$$
 $c_3 = b_1 - d_2$

Need to merge:

С

Note: must merge its own (later) definition because of the back-edge!

Merges go first, and each successive definition of a variable should increment its index by 1.

$$\mathbf{B_2} \mid \mathbf{b} = \mathbf{a} + \mathbf{c}$$



$$\mathbf{B_2} \mid \mathbf{b_2} = \mathbf{a_2} + \mathbf{c_1}$$

Nothing to merge

Merges go first, and each successive definition of a variable should increment its index by 1.

$$\mathbf{B_3} = \begin{bmatrix} d = b & * & 2 \\ e = 2 & * & 2 \end{bmatrix}$$



$$\mathbf{B_3} \begin{vmatrix} d_3 &= b_2 * 2 \\ e_2 &= 2 * 2 \end{vmatrix}$$

Nothing to merge

Merges go first, and each successive definition of a variable should increment its index by 1.

$$\mathbf{B_4}$$
 d = b + 1



$$\mathbf{B_4} \mid d_4 = b_2 + 1$$

Nothing to merge

Merges go first, and each successive definition of a variable should increment its index by 1.



$$\mathbf{B_5} \begin{vmatrix} d_5 &= \Phi(d_3, d_4) \\ e_3 &= \Phi(e_1, e_2) \\ c_4 &= d_5 >> 4 \end{vmatrix}$$

Need to merge:

Merges go first, and each successive definition of a variable should increment its index by 1.

$$B_6 \left[d = c + b \right]$$

Need to merge:

$$\mathbf{B_6} \begin{vmatrix} b_3 &= \Phi(b_1, b_2) \\ c_5 &= \Phi(c_3, c_4) \\ d_6 &= \Phi(d_2, d_5) \\ e_4 &= \Phi(e_1, e_3) \\ d_7 &= c_5 + b_3 \end{vmatrix}$$

