

CSE401: Optimization

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Optimization

- Identify inefficiencies in target or intermediate code
- Replace with equivalent but “better” sequences
- Should really be “improvement” instead of “optimize”
- And remember, the source program is the first place to look for improvements in performance

Example

```
x := a[i] + b[2];  
c[i] := x - 5;
```

```
t1 := *(fp + ioffset)  
t2 := t1 * 4  
t3 := fp + t2  
t4 := *(t3 + aoffset)  
t5 := 2  
t6 := t5 * 4  
t7 := fp + t6  
t8 := *(t7 + boffset)  
t9 := t4 + t8  
*(fp + xoffset) := t9  
t10 := *(fp + xoffset)  
t11 := 5  
t12 := t10 - t11  
t13 := *(fp + ioffset)  
t14 := t3 * 4  
t15 := fp + t14  
*(t15 + coffset) := t15
```

Kinds of optimizations

- Scope of study is central to what optimizations can be performed
 - That is, a large scope means you can perform better optimizations, but it requires more complexity
- *Peephole*: look at adjacent instructions
- *Local*: look at straight-line sequences of instructions
- *Global (intraprocedural)*: look at whole procedure
- *Interprocedural*: look across procedures

Peephole

- After codegen, look at adjacent instructions
 - Try to replace them with something better
- If you have
 - `sw $8, 12($fp)`
 `lw $12, 12($fp)`
- You can replace it with
 - `sw $8, 12($fp)`
 `mv $12, $8`

Peephole examples: 68k

- A. If you have
 - `sub sp, 4, sp`
 `mov r1, 0(sp)`
- You can replace it with
 - `mov r1, -(sp)`
- B. If you have
 - `mov 12(fp), r1`
 `add r1, 1, r1`
 `mov r1, 12(fp)`
- You can replace it with
 - `mov r1, -(sp)`

A view

- You could consider peephole optimization, in some situations, as increasing the sophistication of the instruction selection algorithm

Peephole optimization of jumps

- Eliminate jumps to jumps
- Eliminate jumps after conditional branches
- “adjacent” instructions in this case means “adjacent in the control flow” of the program

```

if a < b then
  if c < d then
    # do nothing
  else
    stmt1;
end;
else
  stmt2;
end;

```

Algebraic simplifications

by peephole or codegen

- “constant folding” and “strength reduction” are common names for this kind of optimization
- $z := 3 + 4$
 - $z := x + 0$
 - $z := x * 1$
 - $z := x * 2$
 - $z := x * 8$
 - $z := x / 8$
 - float x, y ;
 - $z := (x + y) - y$;

Local optimization

- Analysis and optimizations within a *basic block*
- A basic block is a straight-line sequence of statements
 - No control flow into or out of middle of sequence
- Local optimizations are more powerful than peephole
 - Not too hard to implement
 - Can in fact be machine-independent, if done on intermediate code

Local constant propagation

- If a variable is assigned to a constant, replace downstream uses of the variable with the constant
 - May enable further constant folding

Example

```

const count : int = 10;
..
x := count * 5;
y := x ^ 3;

t1 := 10
t2 := 5
t3 := t1 * t2
x := t3

t4 := x
t5 := 3
t6 := exp(t4, t5)
y := t6

```

Local dead assignment elimination

- If the lefthand side of assignment is never referenced again before being overwritten
 - Then remove the assignment
 - This sometimes happens as cleaning up from other optimizations

Example

```
const count : int = 10;
..
x := count * 5;
y := x ^ 3;
x := input
```

```
x := 50
t6 := exp(50,3)
y := t6
x := input()
```



Intermediate code after constant propagation

Local common subexpression elimination

- Avoid repeating the same calculation
- Requires keeping track of available expressions

Example

```
...a[i] + b[i]...
```

```
t1 := *(fp + ioffset)
t2 := t1 * 4
t3 := fp + t2
t4 := *(t3 + aoffset)

t5 := *(fp + ioffset)
t6 := t5 * 4
t7 := fp + t6
t8 := *(t7 + boffset)

t9 := t4 + t8
```

Lecture++

- Intraprocedural optimizations
 - Code motion
 - Loop induction variable elimination
 - Global register allocation
- Interprocedural optimizations
 - Inlining
- After that...how to implement these optimizations