Drawbacks of Single-Cycle Implementation

All instructions must complete in 1 cycle (CPI = 1)

- different instructions do different amounts of work, for example:
  - **`add`** uses instruction memory, register file, ALU, register file again
  - **`lw`** uses instruction memory, register file, ALU, data memory, register file again
- clock cycle set to the longest instruction

Hardware units can only be used once in the cycle

- some must be replicated (ALU, memory)
- increased hardware costs

Alternative to Single-Cycle Implementation

Have a shorter cycle

- Length of the shorter cycle is determined by the delay of individual functional units
- Each instruction executes in multiple shorter cycles

Fewer resources if some can be reused in different cycles

Hardware Changes

Add some **temporary registers** (not visible in the ISA) since some information that is calculated in one cycle is needed in subsequent cycles

- instruction register (IR)
- memory data register (MDR)
- ALU source registers, A and B
- ALUOut

Data that is calculated in 1 instruction & needed by subsequent instructions is stored in ISA-visible state (PC, registers, memory)

Larger or more MUXes

- MUX to memory address
- MUX to ALU source 1
- larger MUX to ALU source 2

Multiple-cycle Implementation

Break up the execution cycle into steps:

- want each step to contain work that takes about the same amount of time
- instructions only use the steps they need

(1) instruction fetch

(2) instruction decode & source register(s) read

(3) ALU execution

(4) memory access (read/write) or ALU completion (write the result register)

(5) write back register for a load

Instruction Fetch

Actions:

IR <-- Memory[PC]

PC <-- PC + 4

Implementation registers:

- instruction register: information will be needed in subsequent cycles

Hardware that is shared in different cycles

- memory (data memory later)
- ALU to increment the PC

Instruction Decode & Source Register(s) Read

Actions:

A <-- Register[IR[25:21]] (read rs)

B<-- Register[IR[20:16]] (read rt)

ALUOut <-- PC + sign-extend IR[15:0] << 2
(performed early in case this instructions is a branch)

Implementation registers:

- register A
- register B
  both needed as operation source operands in the next cycle
- ALUOut for the target address

Hardware that is shared in different cycles

- ALU to calculate branch target

ALU Execution

Actions:

- if R-type instruction

  ALUOut <-- A op B
- if data transfer instruction

  ALUOut <-- A + sign-extend (IR[15:0])
- if branch instruction (& successful)

  if (A == B) PC <-- ALUOut
  (this is the value of ALUOut computed on the last cycle;
  the previous datapath picture doesn't illustrate this)

Implementation registers:

- ALUOut passes the target address from the last step

Hardware that is shared in different cycles

- ALU

Memory Access or Write an ALU Result

Actions:

- if load instruction

  memory data register (MDR) <-- Memory[ALUOut]
- if store instruction

  Memory[ALUOut] <-- B
- if R-type instruction

  Register[IR[15:11]] <-- ALUOut

Implementation registers:

- MDR
- ALUOut

Hardware that is shared in different cycles

- ALU
- Memory

Load Completion

Actions:

Register[IR[20:16]] <-- Memory data register (MDR)

Performance Example

Multiple-cycle implementation has better performance because each instruction takes only as many cycles as it needs

Example:

- cycles per instruction
  - loads: 5, stores: 4, R-type: 4, branches: 3
- percentage in total instructions
  - loads: 22%, stores: 11%, R-type: 50%, branches: 17%
- both implementations have the same number of instructions
- $CPI_{single} = 5$
- $CPI_{multi} = 5*.22 + 4*.11 + 4*.50 + 3*.17 = 4.05$
- speedup = 5/4.05 = 1.2

Multiple-cycle Implementation: Control

Control is more complex than in a single-cycle implementation

- need to define control signals for each step
- need to know which step we're on

Two implementations for the control unit

- **hardwired control**
    - specified as a finite state machine (FSM)
- **microprogramming**
    - expressed as a "micro" programming language

Both specifications can be synthesized into hardware

Instruction Fetch

Set the MUX so that the PC is the memory address:
    IorD = 0

Set ***MemRead*** signal

Set ***IRWrite*** signal

Set the MUX for ALU source 1 to be from the PC:
    ALUSrcA = 0

Set the MUX for ALU source 2 to be from the constant 4:
    ALUSrcB = 01

Set ALUcontrol to "+":
    ALUOp = 00

Set the MUX for input to the PC to be from the ALU:
    PCSource = 00

Set ***PCWrite***

Why do we need a signal to write the IR?

The ALU result is also stored in ALUout: why does this not matter?

The PC can be incremented & the memory accessed for an instruction during the same cycle: why can this be done?

Instruction Decode & Read Source Register(s)

Set the MUX for ALU source 1 to be from the PC:
 ALUSrcA = 0

Set the MUX for ALU source 2 to be from the sign-extended, shifted immediate:
 ALUSrcB = 11

Set ALUcontrol to “+”:
 ALUOp = 00

When are temporary registers A and B written?

What if this turns out not to be a branch instruction?

Execute

Which control signals are generated depends on the opcode

- data transfer
  - Set the MUX for ALU source 1 to be from register A:
    ALUSrcA = 1
  - Set the MUX for ALU source 2 to be from the sign-extended immediate:
    ALUSrcB = 10
  - Set ALUcontrol to “+”:
    ALUOp = 00
- R-type
  - Set the MUX for ALU source 1 to be from register A:
    ALUSrcA = 1
  - Set the MUX for ALU source 2 to be from register B:
    ALUSrcB = 00
  - Set ALUcontrol to the func field operation:
    ALUOp = 10

Execute

- conditional branch
  - Set the MUX for ALU source 1 to be from register A:
    ALUSrcA = 1
  - Set the MUX for ALU source 2 to be from register B:
    ALUSrcB = 00
  - Set ALUcontrol to “-”:
    ALUOp = 01
  - Set ***PCCondWrite*** signal to update the PC if Zero is asserted
  - Set the MUX for input to the PC to be from ALUOut (holds the target address that was computed in the last cycle):
    PCSource = 01

    (note that the PC is written twice for taken conditional branches)
- jump
  - Set the MUX for input to the PC to be from the jump address:
    PCSource = 10
  - Set ***PCWrite***

Data Memory Access & Register Write

Which control signals are generated depends on the opcode

- load
  - Set ***MemRead***
  - Set the MUX so that the memory address comes from the ALU:
    IorD = 1
- store
  - Set ***MemWrite***
  - Set the MUX so that the memory address comes from the ALU:
    IorD = 1

  Where is the value that is to be written?
- R-type
  - Set the MUX to choose the rd field as the write register:
    RegDst= 1
  - Set ***RegWrite***
  - Set the MUX to choose the ALU output as the data to write:
    MemtoReg= 0

Register Write from a Load

Which control signals are generated depends on the opcode

- load
  - Set the MUX to choose the rt field as the write register: ***RegDst***= 0
  - Set ***RegWrite***
  - Set the MUX to choose the MDR as the data to write: ***MemtoReg***= 1