Control Hazards

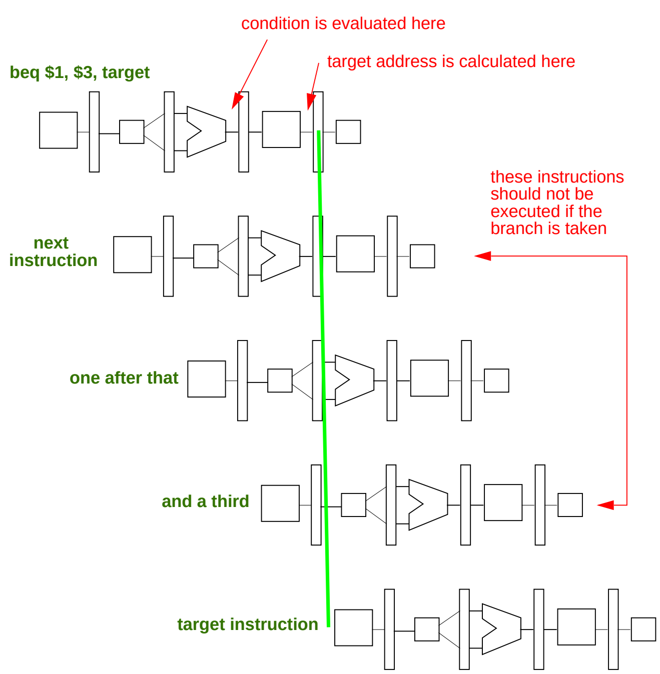
Cause of the hazard:

- evaluation of the branch condition & calculation of the branch target is not completed before the next instruction is fetched
- conflict as to which instruction to fetch next
- called a **delayed branch** if the hazard can't be eliminated

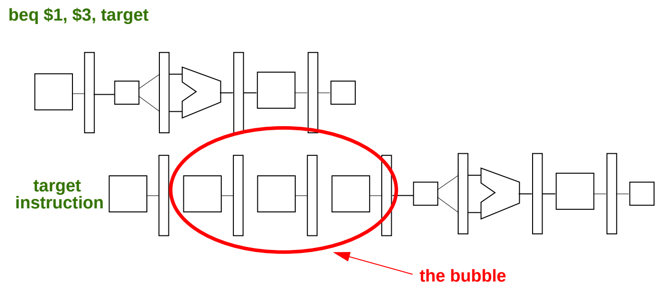
Hardware solutions:

- stall until the result of the condition & target are known (unacceptable delay: no computer does this now)
- assume the branch is not taken
- redesign the pipeline
- dynamic branch prediction

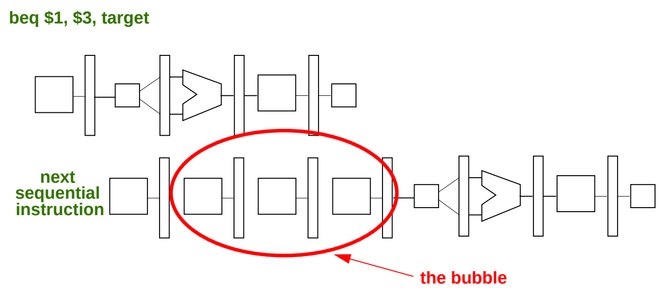
The Problem



Just Stall



Even worse:



Assume a Branch Outcome

Technique:

- assume the branch will not be taken
- continue fetching sequential instructions
- **flush** them if the branch is taken after all
- fetch the target instruction

Performance savings

- no cost if the condition is false & branch isn't taken
  - 40% of conditional branches are not taken
- 3 cycle penalty if the branch is taken

Implementation (for flushing)

- change control signals for EX, MEM & WB stages
  in IF/ID, ID/EX & EX/MEM set pipeline registers to 0
  (similar to what we did for stalling after a load data hazard)

Redesign the Pipeline

Purpose of the redesign:

- determine the branch outcome earlier
- reduce the branch cost of a taken branch

Hardware changes:

- add a **target address shifter & adder** to ID stage

  ⟹ will know where to branch to in ID stage
- add combinational logic in ID stage to determine the outcome of simple comparisons
  - equal/not equal
  - less than 0

    ⟹ know whether to branch in ID stage
  - do the more complicated comparisons in the ALU

    ⟹ know whether to branch in EX stage
  - what architectural design principle is being used here?

How did the branch penalty change?

Branch Prediction

Definition:

- Resolve a branch hazard by predicting which path will be taken
- Proceed under that assumption
- Have a mechanism to back out if wrong

Dynamic branch prediction:

- branch prediction implemented in hardware
  (static branch prediction is done by the compiler)
- the prediction changes as program behavior changes
- common algorithm:
  - predict the branch **taken** if branched the last time
  - predict the branch **not-taken** if didn't branch the last time

Branch Prediction Buffer

Branch prediction buffer

- small memory indexed by the lower bits of the address of a branch instruction
- contains a prediction bit/address
- do what the bit says to do
- if the prediction was wrong
  - toggle the bit
  - flush the pipeline

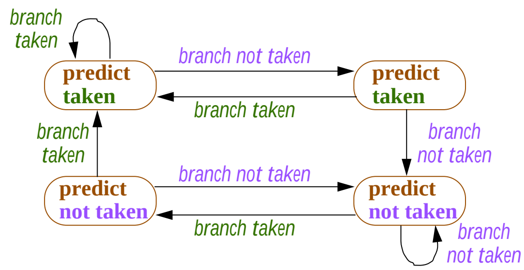
- accessed in IF stage
  - What is the penalty if predict not taken & prediction is correct?
  - What is the penalty if predict taken & prediction is correct?
  - What is the penalty if mispredict?
- branch prediction buffer predicts correctly most of the time

Two-bit Prediction

A single prediction bit does not work well with loops

Two-bit branch prediction for loops

- must be wrong twice to toggle the bit



- What pattern is bad for two-bit branch prediction?

Control Hazards, in Summary

Goals of the solutions to eliminate control hazards:

- assume the common-case outcome
- determine the branch outcome & target address earlier so can branch to the target earlier
- predict the branch direction

Control hazards can occur with all transfers of control:

- jumps
- procedure calls
- returns
- as well as taken conditional branches