Evolution in Memory Management

Programs used all physical memory & executed one at a time.

Programmers divided up their programs into overlays

- memory-size (or less) partitions of program and data that would not be used at the same time
- · loaded into memory under user control
 - \Rightarrow programs larger than physical memory could execute

Multiprogramming

- · several programs were memory-resident at the same time
- one executed while another waited for I/O

 \Rightarrow better utilization of the CPU

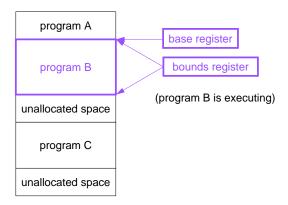
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Evolution in Memory Management

Relocation

- programs are compiled & linked wrt address 0
- · relocated to some other address in physical memory
 - base register: contains the first location of the program
 - bounds register: contains the size of the program
- relocating to physical memory
 - physical address = base register + program address
 - check if physical address is within the bounds (physical address ≤ base address + bounds value)
 - if not, an exception occurs



Evolution in Memory Management

Relocation, cont'd.

- · advantages of relocation
 - · allows multiple programs to reside in memory
 - allows a program to reside anywhere in memory by
 - separating program addresses & physical addresses
- · problems with relocation
 - memory fragmentation
 - unallocated space between programs
 - fragmentation get worse as over time (smaller & more numerous "holes" in memory)
 - requires copying to remove the fragments
 - still requires overlays for large programs

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Virtual Memory

A model (a memory abstraction) to the programmer that:

- a program starts in location 0
- a program extends contiguously in memory
- a program has available to it the entire architectural memory space (2^{wordsize} bytes): called the virtual address space

Paging

- · implementation for virtual memory
- divide the virtual address space into fixed-size chunks, called pages
- divide physical memory into chunks of the same size, called page frames
- provide a mapping between addresses in pages & address in page frames, called address translation
- if no mapping exists

 (i.e., if a virtual address is on a page that does not have a page frame in physical memory),
 it is on disk and has to be paged into memory

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Address Translation

Address translation:

- maps addresses in the virtual address space (virtual addresses) to locations in physical memory (physical addresses)
 - CPU emits a virtual (program-generated) address
 - · memory has physical addresses
- · relocation mechanism is fully associative
 - a page can reside in any page frame
- mapping techniques in:
 - software data structure (page tables) &
 - hardware cache (translation lookaside buffer) (we'll cover them both later)

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Address Translation Using Page Tables

Operating systems data structure

- page tables are built & maintained by the OS
- · one page table per process
 - process A's virtual addresses will map to different physical locations than process B's
- one entry in the page table per (virtual) page:
- called page table entry (PTE)
- PTE fields:
 - valid bit: whether the page is mapped into memory or still resides on disk
 - page frame number or disk location
 - dirty bit: indicates whether any address on the page has been written
 - reference or use bit: set if this page was used recently
 - protection bits: access privilege (read/write/execute) for user or kernel mode

Page Table Size

Calculating page table size:

number of page table entries =
$$\frac{\text{virtual address space}}{\text{page size}}$$

size of page table = number of page table entries × size of a PTE

• there are several techniques to reduce the size of the page tables

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Design Trade-offs for Page Size

Choosing a page size:

- big pages
 - + better throughput from disk
 - + smaller page tables
 - (internal) fragmentation
- small pages
 - + lower latency to fetch a page
 - larger page tables (but can use techniques to reduce page table size)

Current page sizes:

- 8KB
- some machines have larger ones too