

## Lecture 10: AVL Trees

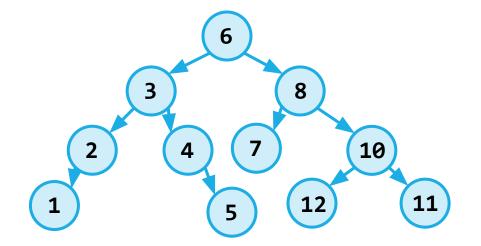
CSE 373: Data Structures and Algorithms

Slido Event #3285614 https://app.sli.do/event/93b XKnWncn1YfXPXVDQXZ7



Binary Tree? Yes BST Invariant? No Balanced? Yes

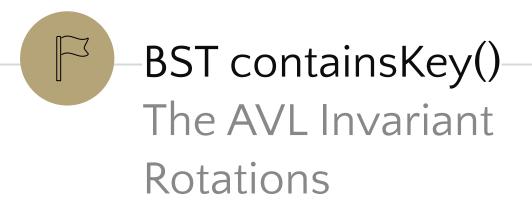
Warm Up



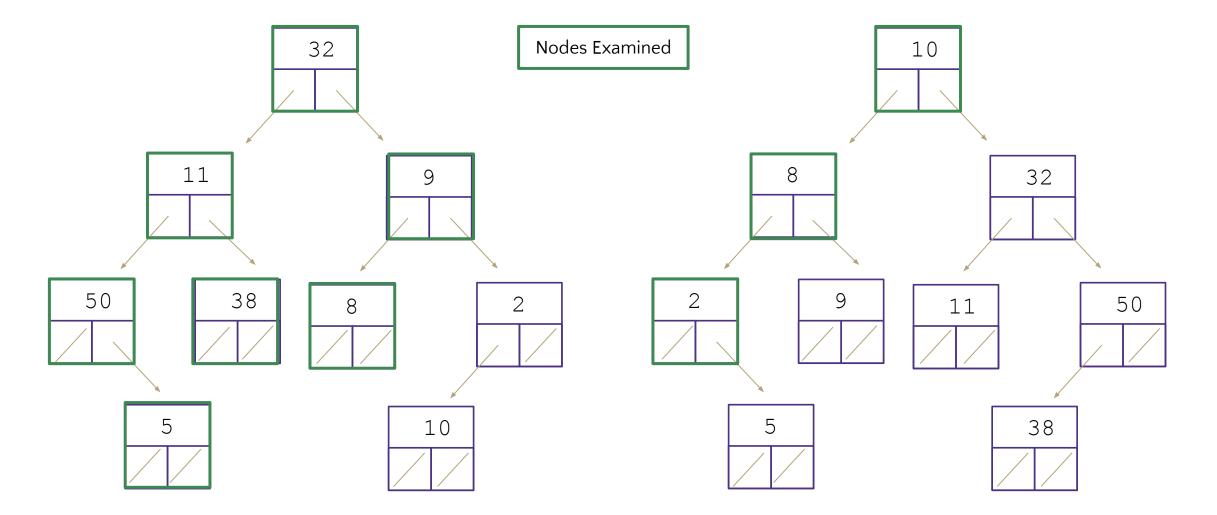
### Announcements

- Exercise 2 Due Tonight
- Exercise 3 releases tonight
- Project 2 out

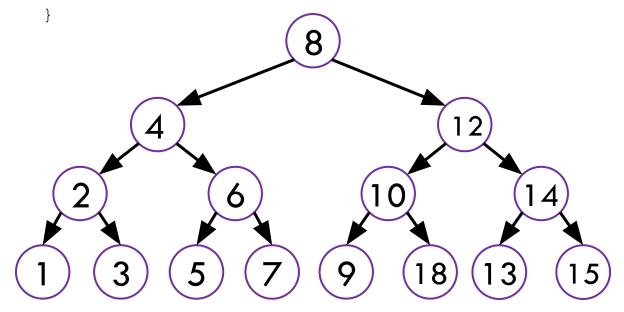




### Binary Trees vs Binary Search Trees: containsKey(2)



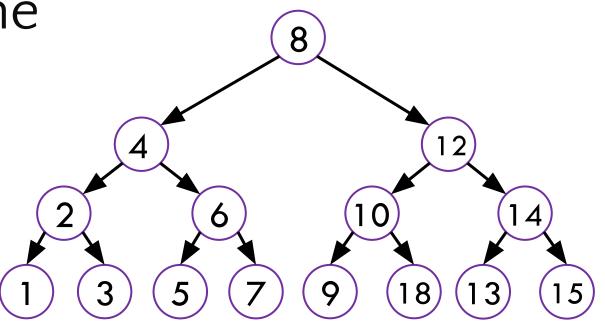
### Binary Trees vs Binary Search Trees: containsKey(2)



```
public boolean containsKeyBST(node, key) {
    if (node == null) {
        return false;
    } else if (node.key == key) {
        return true;
    } else {
        if (key <= node.key) {
            return containsKeyBST(node.left);
        } else {
            return containsKeyBST(node.right);
        }
    }
}</pre>
```

# BST containsKey runtime

```
public boolean containsKeyBST(node, key) {
    if (node == null) {
        return false;
    } else if (node.key == key) {
        return true;
    } else {
        if (key <= node.key) {
            return containsKeyBST(node.left);
        } else {
            return containsKeyBST(node.right);
        }
    }
}</pre>
```



For the tree on the right, what are some possible interesting cases (best/worst/other?) that could come up? Consider what values of key could affect the runtime

- best: containsKey(8), runtime will be
   O(1) since it will end immediately
- worst: containsKey(-1) since it has to traverse all the way down (other values will work for this)

containsKey() is a recursive method -> recurrences!

$$T(n) = \begin{cases} T(n/2) + 1 \text{ if } n > 1\\ 3 & \text{otherwise} \end{cases}$$

\* if tree is balanced we eliminate half the nodes to search at each level ie n/2

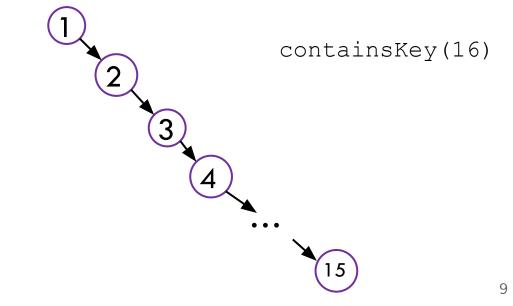
# Is it possible to do worse than O(log n) 😈

We only considered changing the key parameter for that one particular BST in our last thought exercise, but what about if we consider the different possible arrangements of the BST as well?

Let's try to come up with a valid BST with the numbers 1 through 15 (same as previous tree) and key combination that result in a worse runtime for containsKey.

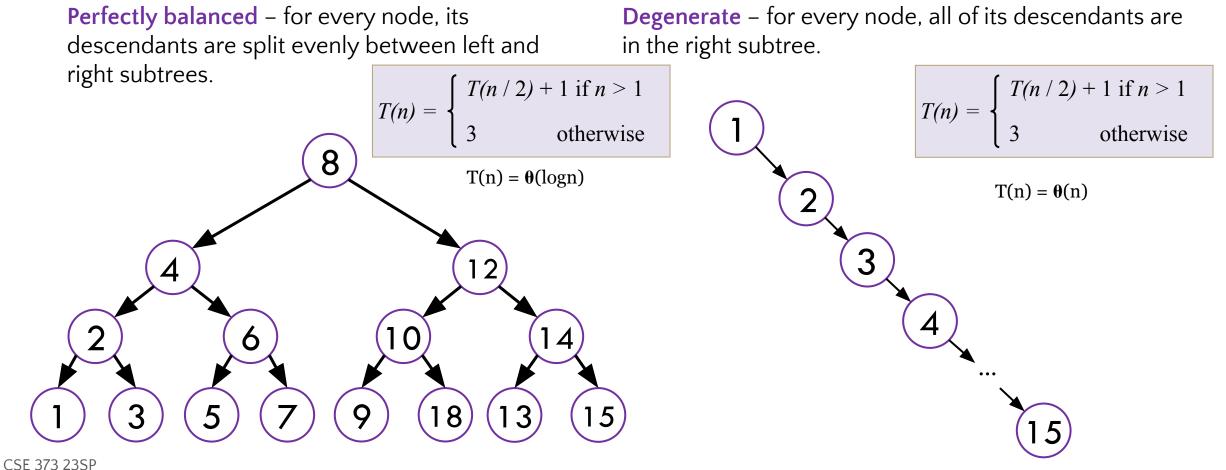
$$T(n) = \begin{cases} T(n/2) + 1 \text{ if } n > 1\\ 3 & \text{otherwise} \end{cases}$$

 $T(n) = \Theta(n)$ 



## **BST** different states

Two different extreme states our BST could be in (there's in-between, but it's easiest to focus on the extremes as a starting point). Try containsKey(15) to see what the difference is.



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# Can we do better?

Key observation: what ended up being important was the *height* of the tree!

- Height: the number of edges contained in the longest path from root node to any leaf node
- In the worst case, this is the number of recursive calls we'll have to make

If we can limit the height of our tree, the BST invariant can take care of quickly finding the target

- How do we limit?
- Let's try to find an invariant that forces the height to be short



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- This *is* technically what we want (would be amazing if true on entry)
- But how do we implement it so it's true on exit?
  - Should the insertBST method rebuild the entire tree balanced every time?
  - This invariant is too broad to have a clear implementation
- Invariants are tools more of an art than a science, but we want to pick one that is specific enough to be maintainable

## Invariant Takeaways

# Need requirements everywhere, not just at root

**NVARIANT** 

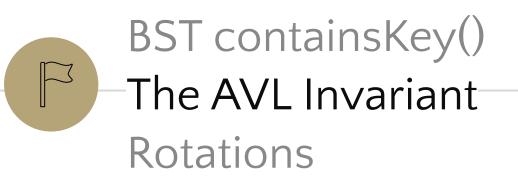
In some ways, this makes sense: only restricting a constant number of nodes won't help us with the asymptotic runtime

# Forcing things to be *exactly* equal is too difficult to maintain

Fortunately, it's a two-way street: from the same intuition, it makes sense that a constant "amount of imbalance" wouldn't affect the runtime 😒

#### **AVL Invariant**

For every node, the height of its left and right subtrees may only differ by at most 1



# The AVL Invariant

INVARIANT

AVL Invariant

For every node, the height of its left and right subtrees may only differ by at most 1

AVL Tree: A Binary Search Tree that also maintains the AVL Invariant

- Named after Adelson-Velsky and Landis
- But also A Very Lovable Tree!

Will this have the effect we want?

- If maintained, our tree will have height Θ(log n)
- Fantastic! Limiting the height avoids the  $\Theta(n)$  worst case

Can we maintain this? We'll need a way to fix this property when violated in insert and delete

# AVL Trees

#### **AVL Trees** must satisfy the following properties:

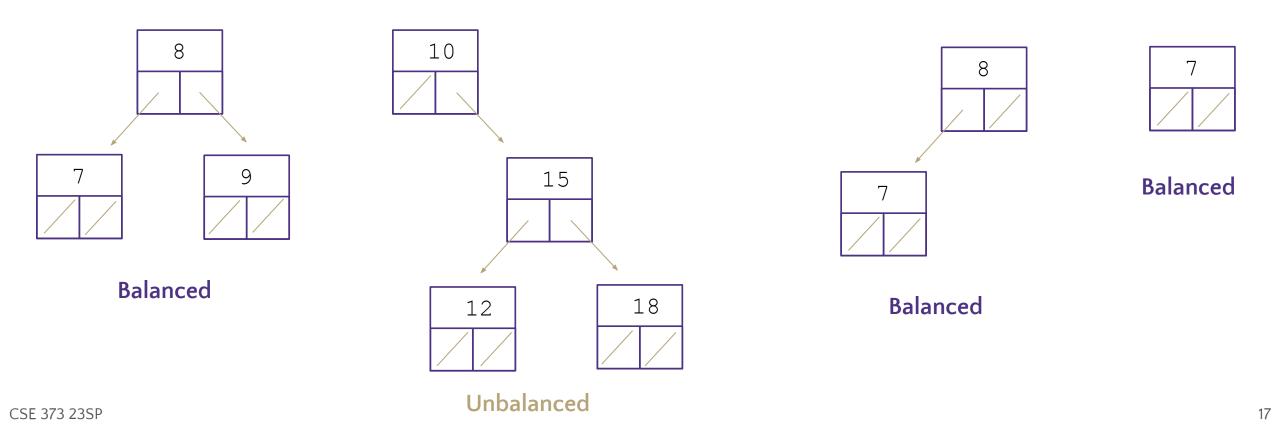
- o binary trees: all nodes must have between 0 and 2 children
- binary search tree: for all nodes, all keys in the left subtree must be smaller and all keys in the right subtree must be larger than the root node
- balanced: for all nodes, there can be no more than a difference of 1 in the height of the left subtree from the right. Math.abs(height(left subtree) – height(right subtree)) ≤ 1

AVL stands for Adelson-Velsky and Landis (the inventors of the data structure)

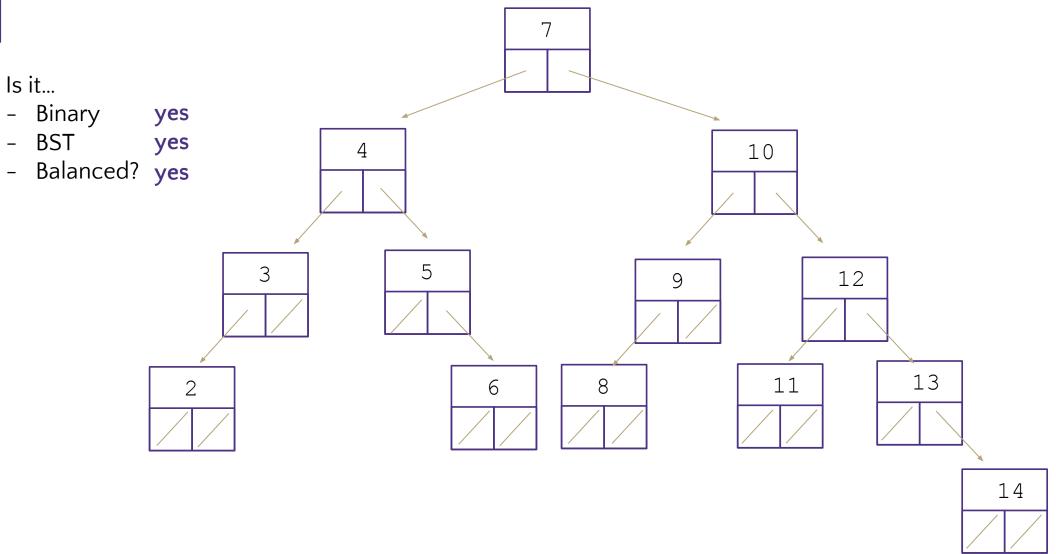
# Measuring Balance

### Measuring balance:

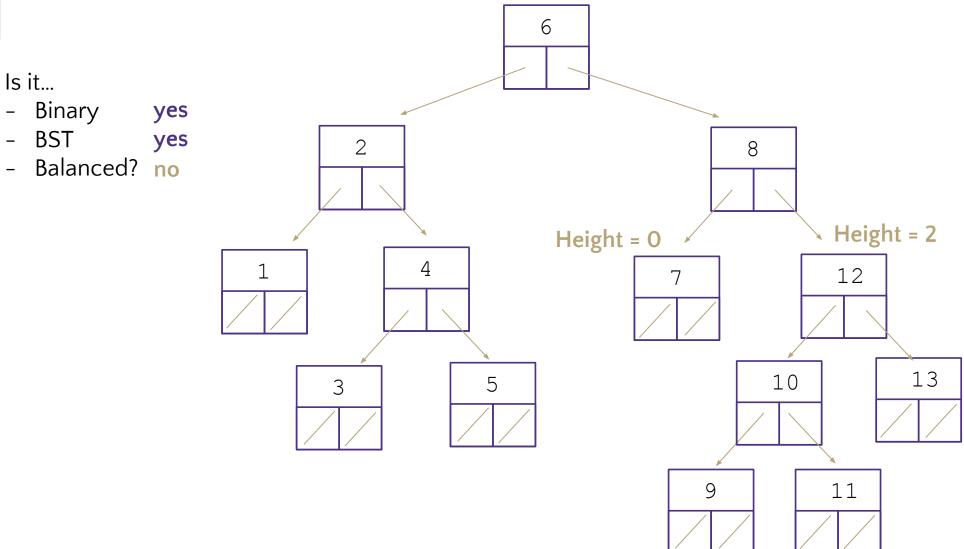
- For each node, compare the heights of its two sub trees
- Balanced when the difference in height between sub trees is no greater than 1



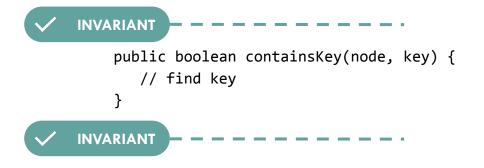
## Is this a valid AVL tree?



## Is this a valid AVL tree?



# Maintaining the Invariant



**containsKey** benefits from invariant: at worst  $\Theta(\log n)$  time

**containsKey** doesn't modify anything, so the invariant holds after being called

**insert** benefits from invariant: at worst  $\Theta(\log n)$  time to find location for key

public boolean insert(node, key) {

// find where key would go

But needs to maintain the invariant

How?

**INVARIANT** 

INVARIANT

??

- Track heights of subtrees
- Detect any imbalance

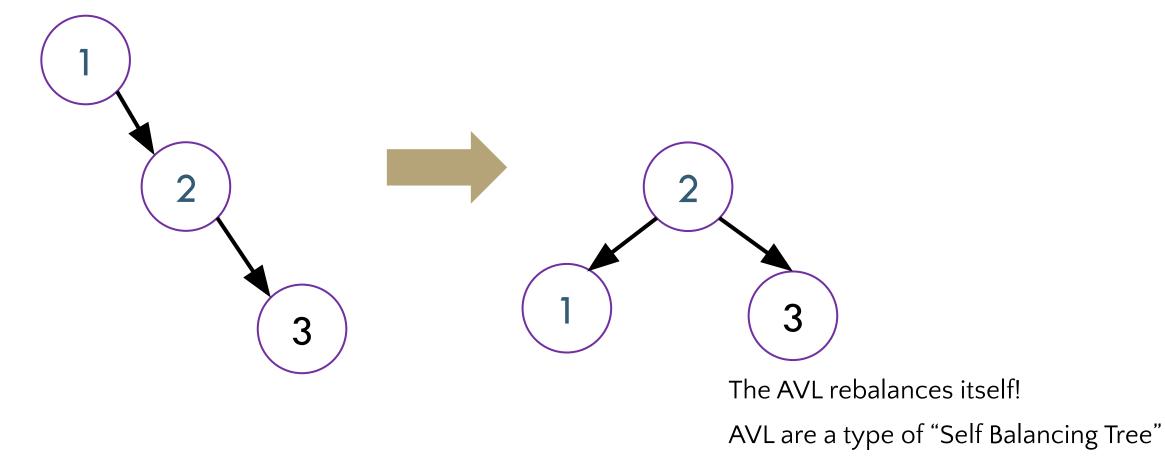
// insert

• Restore balance

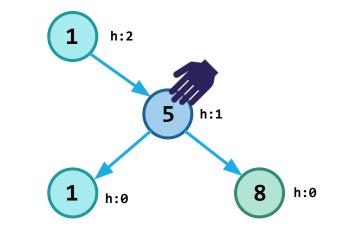
### BST containsKey() The AVL Invariant Rotations

### Insertion

What happens if when we do an insertion, we break the AVL condition?



## Fixing AVL Invariant

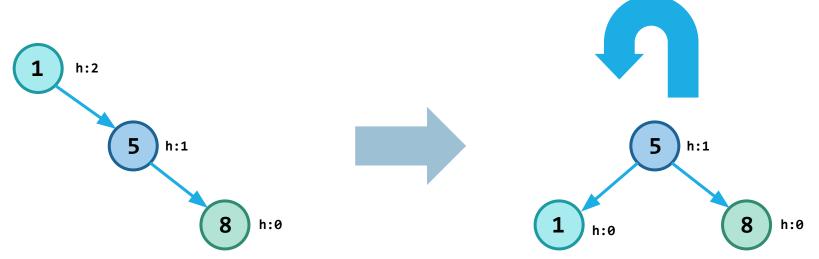


# Fixing AVL Invariant: Left Rotation

In general, we can fix the AVL invariant by performing rotations wherever an imbalance was created

### Left Rotation

- Find the node that is violating the invariant (here, 1) Let it "fall" left to become a left child

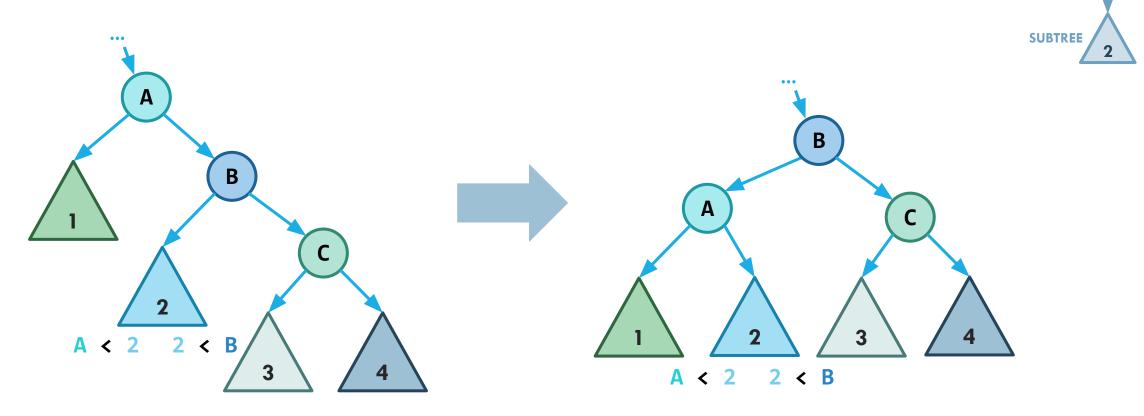


Apply a left rotation whenever the newly inserted node is located under the right child of the right child CSF 373 23SP

# Left Rotation: More Precisely

Subtrees are okay! They just come along for the ride.

• Only subtree 2 needs to hop – but notice that its relationship with nodes A and B doesn't change in the new position!

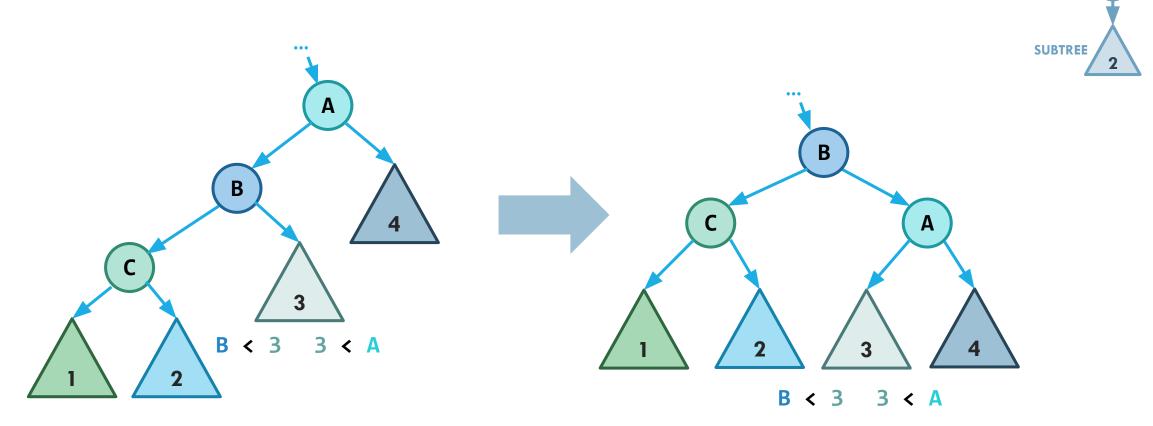


NODE

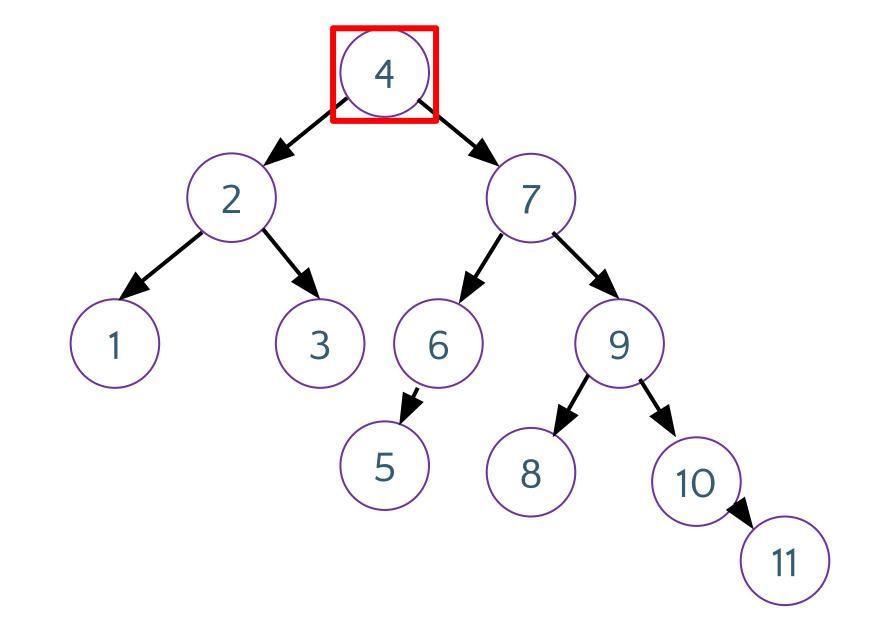
# **Right Rotation**

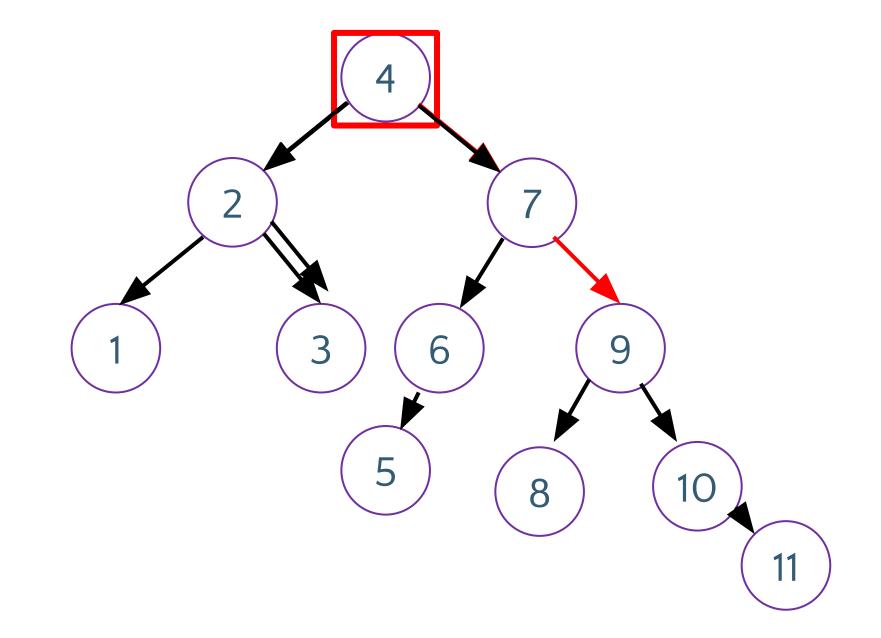
### **Right Rotation**

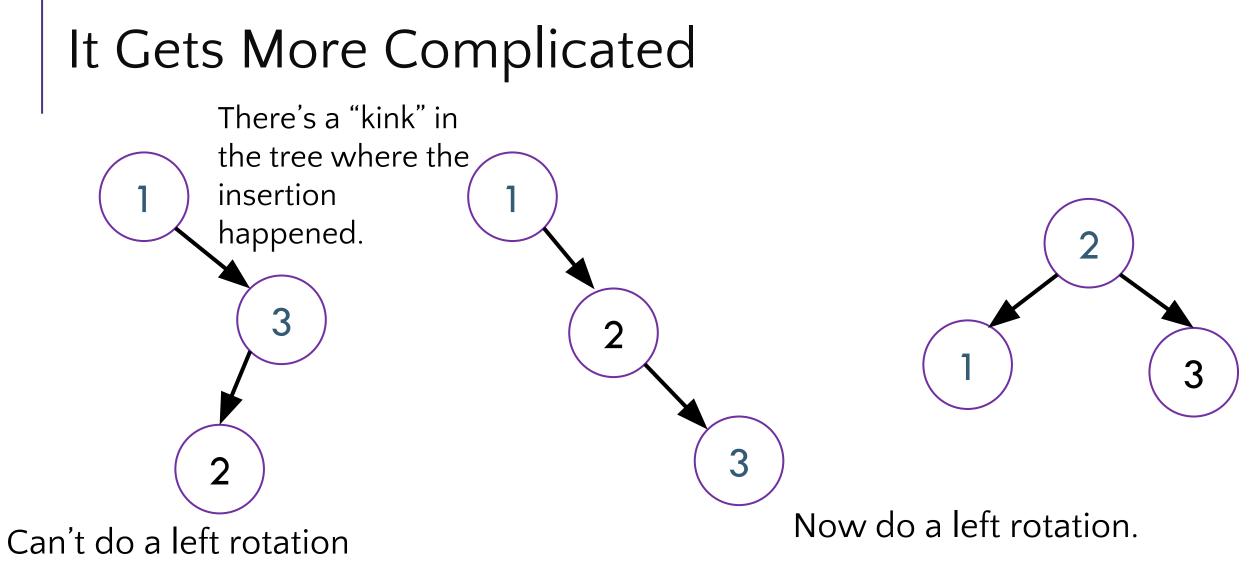
• Mirror image of Left Rotation!



NODE







Do a "right" rotation around 3 first.

# Not Quite as Straightforward

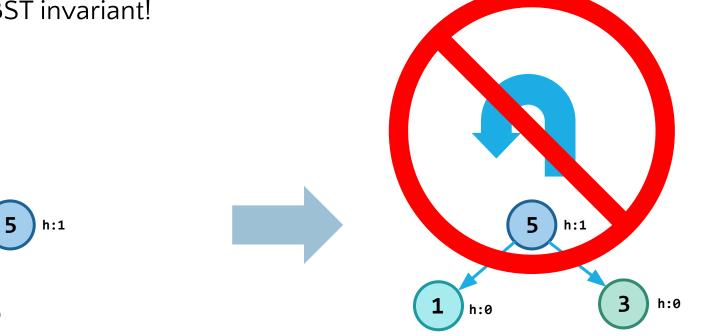
What if there's a "kink" in the tree where the insertion happened?

Can we apply a Left Rotation?

h:2

h:0

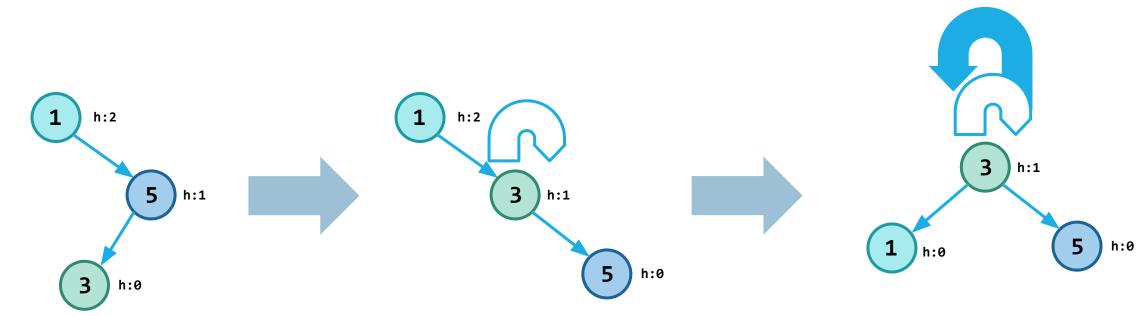
• No, violates the BST invariant!



# Right/Left Rotation

### Solution: Right/Left Rotation

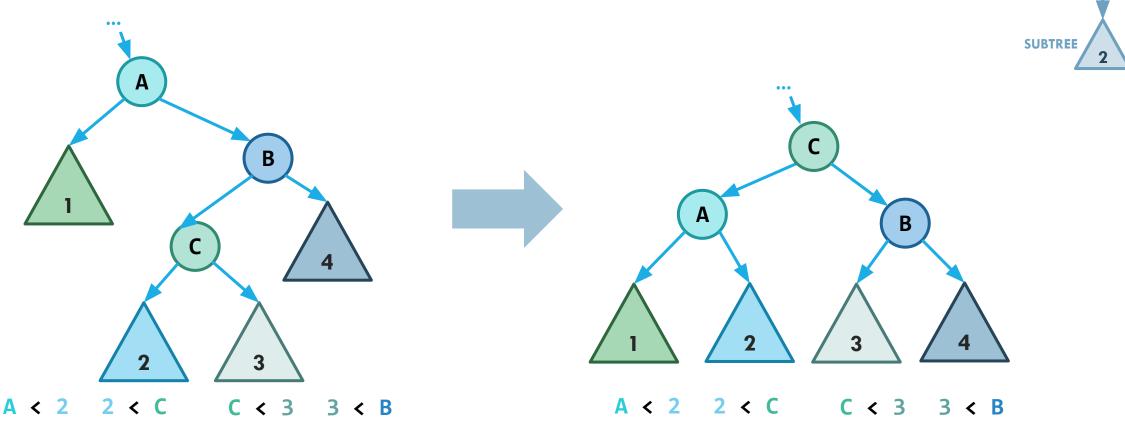
- First rotate the bottom to the right, then rotate the whole thing to the left
- Easiest to think of as two steps
- Preserves BST invariant!



# Right/Left Rotation: More Precisely

Again, subtrees are invited to come with

 Now 2 and 3 both have to hop, but all BST ordering properties are still preserved (see below)



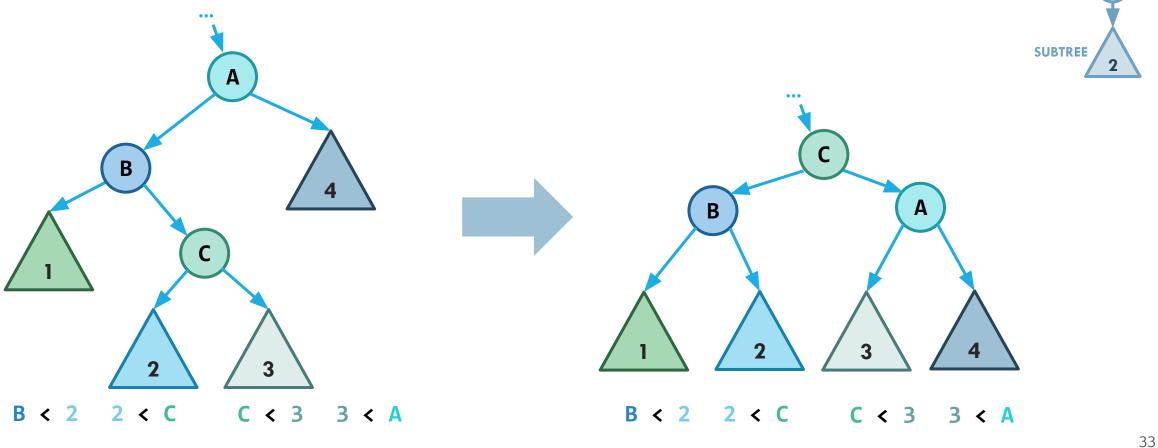
NODE

# Left/Right Rotation

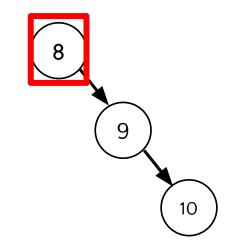
### Left/Right Rotation

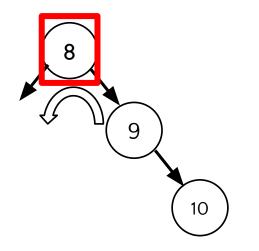
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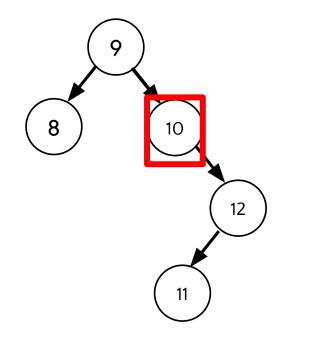
• Mirror image of Right/Left Rotation!

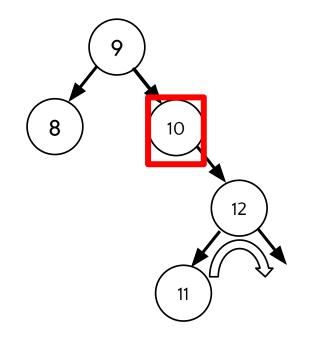


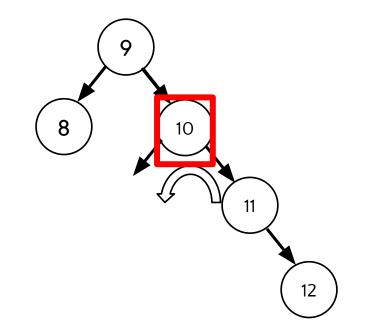
NODE

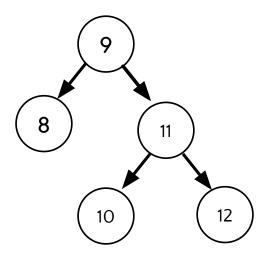












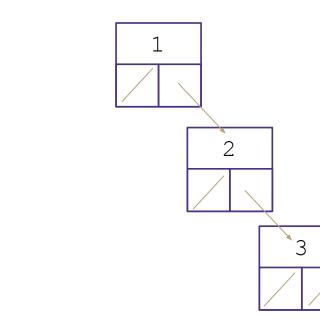
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### Two AVL Cases

#### Line Case Solve with 1 rotation

2

3



#### **Rotate Right**

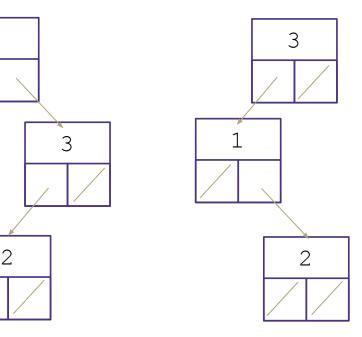
# Child's right becomes its parent

#### Rotate Left

Parent's left becomes child's right Parent's right becomes child's left Child's left becomes its parent

**Right Kink Resolution** Rotate subtree left Rotate root tree right

#### Kink Case Solve with 2 rotations



#### Left Kink Resolution Rotate subtree right Rotate root tree left

# How Long Does Rebalancing Take?

• Assume we store in each node the height of its subtree.

- How do we find an unbalanced node?
- Just go back up the tree from where we inserted.
- How many rotations might we have to do?
  - Just a single or double rotation on the lowest unbalanced node.
  - A rotation will cause the subtree rooted where the rotation happens to have the same height it had before insertion
  - log(n) time to traverse to a leaf of the tree
  - log(n) time to find the imbalanced node
  - constant time to do the rotation(s)
  - <u>Theta(log(n)) time for put</u> (the worst case for all interesting + common AVL methods (get/containsKey/put is logarithmic time)

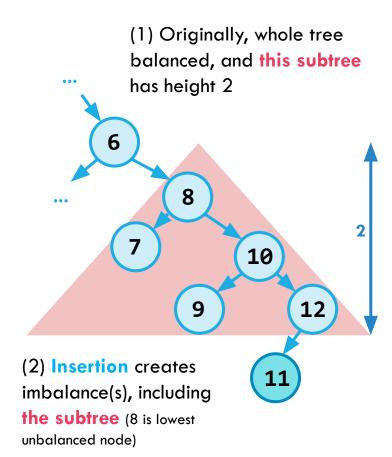
# AVL insert(): Approach

Our overall algorithm:

- 1. Insert the new node as in a BST (a new leaf)
- 2. For each node on the path from the root to the new leaf:
  - The insertion may (or may not) have changed the node's height
  - Detect height imbalance and perform a *rotation* to restore balance

### Facts that make this easier:

- Imbalances can only occur along the path from the new leaf to the root
- We only have to address the lowest unbalanced node
- Applying a rotation (or double rotation), restores the height of the subtree before the insertion -- when everything was balanced!
- Therefore, we need *at most one rebalancing operation*



### AVL delete()

- Unfortunately, deletions in an AVL tree are more complicated
- There's a similar set of rotations that let you rebalance an AVL tree after deleting an element
  - Beyond the scope of this class
  - You can research on your own if you're curious!
- In the worst case, takes  $\Theta(\log n)$  time to rebalance after a deletion
  - But finding the node to delete is also  $\Theta(\log n)$ , and  $\Theta(2\log n)$  is just a constant factor. Asymptotically the same time
- We won't ask you to perform an AVL deletion

## AVL Trees

### PROS

- All operations on an AVL Tree have a logarithmic worst case
  - Because these trees are always balanced!
- The act of rebalancing adds no more than a constant factor to insert and delete
- Asymptotically, just better than a normal BST!

### CONS

- Relatively difficult to program and debug (so many moving parts during a rotation)
- Additional space for the height field
- Though asymptotically faster, rebalancing does take some time
  - Depends how important every little bit of performance is to you



