## Set and Map ADTs: B-Trees

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## Announcements

* Asymptotic Analysis: handout coming soon
: Workshops 解
- Student-centered study groups; bring your questions!
- Friday 11:30-12:30 @ CSE 203

- Saturday morning: 10:30am-12pm @ Odegaard 117E
* "tl;dr" slides are your per-topic learning objectives

Questions from Reading Quiz
*Why is the reading quiz borkened $\$$ ? We will regrade!

* Why is BST height in $O\left(N^{2}\right)$ ? Best structured tie: $h \in \Theta(\log N)$ Wurst structured tree: $h \in \Theta(N)$
: Why is BST height NOT in $\Theta(N)$ ? $\therefore$ No $\theta$-bound for the overall case!
* How do you calculate average depth? Why do we care about depth? How does it relate to height?

| Node attributes | Tree attributes |
| :--- | :--- |
| depth | avg depth <br> height |

## Lecture Outline

* BST Remove (cont.)
* BST Tree Height
* 2-3 Trees
* B-Trees


## Binary Search Trees: Remove

* 3 cases based on the number of children

1. Key has no children
2. Key has one child
3. Key has two children


* In each case, we must maintain the Binary Search Tree Invariant!


## BST Remove: Case \#1: Leaf

* Remove the node with the value hippo

```
BSTNode remove(BSTNode n) {
```


\}

## BST Remove: Case \#2: One Child

* Remove the node with the value ears
- What does the BST invariant say about the descendant's values?

```
BSTNode remove(BSTNode n) {
```


\}

## BST Remove: Case \#3: Two Children

* Remove the node with the value dog
* The replacement node:
- Must be $>$ than all keys in left subtree
- Must be < than all keys in right
 subtree


## BST Remove: Case \#3: Two Children

* Remove the node with the value dog
* The replacement node:
- Must be $>$ than all keys in left subtree: predecessor (cat)
- Must be < than all keys in right subtree: successor (ears)


$$
a, b, c, d(e, f, g, h
$$

* The predecessor or successor have either 0 or 1 children


## BST Remove: Case \#3: Two Children



## Aside: Finding the largest (or smallest) node

* The predecessor is the largest node in the left subtree
* The successor is the smallest node in the right subtree
* How do you find the largest (and smallest) node in a tree?
- Remember that subtrees are trees too

```
BSTNode largest(BSTNode n)
    while (n.right != null) {
        n = n.right;
    }
    return n;
}
```



## tl;dr

* Binary Search Trees implement both the Set and Map ADTs
* Binary Search Trees are recursively defined
* Binary Search Trees can be an efficient Map/Set ADT

|  | LinkedList Map, <br> Worst Case | BST Map, <br> Worst Case |
| :---: | :---: | :---: |
| Find | $\Theta(\mathrm{N})$ | $\Theta(\mathrm{h})$ |
| Add | $\Theta(\mathrm{N})$ | $\Theta(\mathrm{h})$ |
| Remove | $\Theta(\mathrm{N})$ | $\Theta(\mathrm{h})$ |

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## Binary Search Tree: Height

* Suppose we want to build a BST out of $\{1,2,3,4,5,6,7\}$
* Give a sequence of add operations that result in:
- a spindly tree ("worst case") : sorted order
- a bushy tree ("best case") :? any non-sorted order?



## Randomization: Mathematical Analysis

* Binary search tree height is in O(N)
- Worst case height: $\Theta(\mathrm{N})$
- Best case height: $\Theta(\log \mathrm{N})$
- $\Theta(\log N)$ via randomized insertion
- Randomized insertion with randomized deletion is still $\Theta$ (log $N$ ) height
* BSTs are frequently concerned with best- and worst-case tree structure


## Average Depth of a Randomized BST

If N distinct keys are inserted in
random order, the expected average
depth is
$\sim 2 \ln N=\Theta(\log N)$.

## Total Height of a Randomized BST

If N distinct keys are inserted in random order, the expected height is
$\sim 4.311 \ln \mathrm{~N}=\Theta(\log \mathrm{N})$.

The Height of a Randomized Binary Search Tree (Reed/STOC 2000)

## What About "Real World" BSTs?

* These examples are contrived! What about real-world workloads?
* An approximation of the real-world: inserting random numbers


Random Insertion into a BST (Kevin Wayne/Princeton) https://www.youtube.com/watch?v=5dGkblzqdmc

## Randomization is Pretty Good!

* BSTs have great runtime if we insert keys randomly
- $\Theta(\log N)$ per insertion
* But:

- We can’t always insert our keys in a random order. Why?
- What if we need guaranteed $\Theta(\log \mathrm{N})$ runtime?

$$
\begin{aligned}
& \text { plain BUTs are pretty } \\
& \text { good unless you need } \\
& \text { a guarantee against sorted input }
\end{aligned}
$$

## Bounding the Height (ie, protecting against sorted input)

* Recall that a Binary Search Tree's invariant is:
- The left subtree only contains values $<k$
- The right subtree only contains values $>k$
*What invariants could we add, to bound the height to $\log \mathrm{N}$ ?



## Bounding the Height: Example Invariant

* Hypothesis: Every node has either 0 or 2 children
* Analysis: What is the worst-case height for this tree?



## (II) Poll Everywhere

What is the worst-case height of a BST where every node must have either 0 or 2 children?

| A. | $\Theta(1)$ |
| :--- | :--- |
| B. | $\Theta\left(\log _{2} N\right)$ |
| C | $\Theta(N)$ |
| D. | $\Theta\left(N \log _{2} N\right)$ |
| E. | $\Theta\left(N^{2}\right)$ |



How do you add a node to this tree?

## Adding Nodes Creates Worst-case Height Trees

* Unbalanced growth leads to worst-case height trees

* When does adding a new node affect the height of a tree?
- Can you explain in terms of the subtrees (ie, recursively)?


Your Turn: Generate Some Invariants

* Generate an invariant that might balance your tree
- Is it strong enough to roughly-balance the tree?
- Is it flexible enough to be maintainable?
- Root balanced: not strong enough

- Recursively balance di strong, but "complete" trees ae unmaintainable



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## Bounding the Height: Overstuff the leaves

Results in a non-biracy search tree!

* If we never add new leaves, the tree can never get unbalanced
- Instead: Overstuff existing leaves to avoid adding new leaves



## Overstuffed Leaves: Promote the Keys

* Set a limit L on number of keys
- e.g. L=3
* If any node has more than L

keys, give ("promote") a key to the parent
- e.g. the left-middle key
- Why not the leftmost or rightmost?



## Promoting Keys Splits the Leaf Node

* Set a limit L on number of keys
- e.g. L=3
* If any node has more than L keys, give ("promote") a key to the parent
- e.g. the left-middle key
- Why not the leftmost or rightmost?
- Promoting a key splits the old
 overstuffed node into two new parts: left and right.



## Practice: Adding More Keys

* Suppose we add the keys 20 and 21.
* If our cap is at most $\mathrm{L}=3$ keys per node, draw the post-split tree.



## Promoting Keys Can Cascade Into Ancestors

* Add 25 and 26



## Overstuffing the Root Node

* If promotions can cascade up the tree, we may eventually need to split the root.
$*$ Splitting the root is the only time a tree grows in height!



## 2-3, 2-3-4, and B-Trees

* We chose limit L=3 keys in each node. Formally, this is called a 2-3-4 Tree: each non-leaf node can have 2,3 , or 4 children
* 2-3 Tree. Choose L=2 keys. Each non-leaf node can have 2 or 3 children
* B-Trees are the generalization of this idea for any choice of $L$


Max 3 keys and 4 non-null children per node.

2-3 Tree

Max 2 keys and 3 non-null children per node.

## 2-3 Tree Practice

* Give an insertion order for the keys $\{1,2,3,4,5,6,7\}$ that results in:
- a max-height 2-3 Tree
- a min-height 2-3 Tree


Demo: https://www.cs.usfca.edu/~galles/visualization/BTree.htm|

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## B-Tree Invariants

* B-Tree's invariants guarantee "bushy" trees (ie, $\mathrm{H}(\mathrm{N}) \in \Theta\left(\log _{2} \mathrm{~N}\right)$ )

1. All leaves must be the same depth from the root

- Achieved because the tree's height only grows from the root

2. A non-leaf node with $k$ keys must have exactly $k+1$ non-null children

- Achieved because we remove two keys from an overstuffed child: one is promoted to the parent and the other becomes the new child of the newlypromoted parent key

3. A non-leaf non-root node must have at least ceil(L/2) children

- (A non-leaf root node must have >=2 children)
* Why are these invalid B-Trees?



## B-Tree Invariants Bound Its Height

* Smallest possible height ("shortest tree") is when all nodes have $L$ keys
- $H(N) \sim \log _{L+1} N \in \Theta(\log N)$
* Largest possible height ("tallest tree") is when all non-leaf nodes have just 1 key
- H(N) ~ $\log _{2} N \in \Theta(\log N)$




## Search Runtime

* Shortest-case number of nodes to inspect: $\log _{\mathrm{L}+1} \mathrm{~N}$
* Shortest-case number of keys to inspect per node: L
* Runtime: $\mathrm{L} \log _{\mathrm{L}+1} \mathrm{~N} \in \Theta(\log \mathrm{~N})$
* Tallest-case number of nodes to inspect: $\log _{2} \mathrm{~N}+1$
* Tallest-case number of keys to inspect per node: 1
* Runtime: $\log _{2} \mathrm{~N}+1 \in \Theta(\log \mathrm{~N})$




## Insertion Runtime

* Shortest-case number of nodes to inspect: $\log _{\mathrm{L}+1} \mathrm{~N}$
* Shortest-case number of keys to inspect per node: L
* Shortest-case number of splits: $\log _{\mathrm{L}+1} \mathrm{~N}$
* Runtime: $2 \mathrm{~L} \log _{\mathrm{L}+1} \mathrm{~N} \in \Theta(\log \mathrm{~N})$
* Tallest-case number of nodes to inspect: $\log _{2} \mathrm{~N}+1$
* Tallest-case number of keys to inspect per node: 1
* Tallest-case number of splits: $\log _{2} \mathrm{~N}+1$
* Runtime: $2 \log _{2} \mathrm{~N}+2 \in \Theta(\log \mathrm{~N})$



## tl;dr

* Search Trees have great runtimes most of the time
- But they struggle with sorted (or mostly-sorted) input
- Must bound the height if we need runtime guarantees
* Plain BSTs: simple to reason about/implement. A good starting point
* B-Trees are a Search Tree variant that binds the height to $\Theta(\log N)$ by only allowing the tree to grow from its root
- A good choice for a Map and/or Set implementation

|  | LinkedList <br> Map, Worst <br> Case | BST Map, <br> Worst Case | B-Tree Map, <br> Worst Case |
| :---: | :---: | :---: | :---: |
| Find | $\Theta(N)$ | $h=\Theta(N)$ | $\Theta(\log N)$ |
| Add | $\Theta(N)$ | $h=\Theta(N)$ | $\Theta(\log N)$ |
| Remove | $\Theta(N)$ | $h=\Theta(N)$ | $\Theta(\log N)$ |

