BEFORE WE START

Head to PollEverywhere to let us know what you thought of the exam and the online format!

1. How many hours did you spend?
2. Compared to your expectations, how difficult was the exam?
3. Compared to other classes, how clear was the link between course content and what we tested you on?
4. What did you think of the logistics?
You did it!
EXAM I out of the way!

- I know there can be a lot of anxiety surrounding exams!
  - Hopefully the take-home format helped reduce time pressure, learning objectives helped clarify our expectations, and group work helped you bounce your ideas off someone!
- This class has a LOT of difficult content, so pat yourself on the back for reviewing so much material
- **Next steps:**
  - We’re hard at work grading your responses, expect feedback published by early next week
  - If there are concepts you felt shaky on, schedule a 1:1 to review!
Announcements

• P2 late cutoff tonight at 11:59pm
  - Exam days “free late days”, so submitting today will use up 3 total late days
• P3 due in 1.5 weeks on Wednesday, 8/05
  - Start early!
  - Remember that changePriority and contains aren’t efficient on a heap alone – you should use an extra data structure!
  - Recommendation: just get it working first, then analyze where inefficiencies are – what data structure could help?
• EX3 published this Friday, 7/31
  - Focusing on post-Exam I content, especially this week
Announcements

- If you’re at all interested in careers in tech, now’s a great time to start thinking about applying for internships or jobs!
  - A+ Advice for Getting a Job (**373-specific lecture recording**!): Linked on calendar now, along with some other fantastic resources (Job Guide & Resume Guide)!

- I’ve doubled available 1:1 slots this week! Come chat if you’re interested in talking about how you might apply this class in industry (or grad school!) 😊

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PREPARATION

- Putting together your resume
- Personal projects/other experience to help you stand out
- Identifying where to apply, and when

CSE 373 MATERIAL

- Practicing with interview problems & design decisions
- Identifying common patterns in interview questions

PROCESS

1. Applying
   - Online Apps
   - Career Fairs

2. Interviewing
   - Technical
   - Behavioral

Job/Internship Offer
Learning Objectives

After this lecture, you should be able to...

1. Categorize graph data structures based on which properties they exhibit

2. Select which properties of a graph would be most appropriate to model a scenario (e.g. Directed/Undirected, Cyclic/Acyclic, etc.)

3. Compare the runtimes of Adjacency Matrix and Adjacency List graph implementations, and select the most appropriate one for a particular problem

4. Describe the high-level algorithm for solving the s-t Connectivity Problem, and be prepared to expand on it going forward
Lecture Outline

• Graphs
  - Definitions
  - Choosing Graph Types

• Graph Implementations

• s-t Connectivity Problem
**Review Trees**

- A **tree** is a collection of nodes where each node has at most 1 parent and at least 0 children
  - A **binary tree** is a tree where each node has at most 2 children

- **Root node**: the single node with no parent, “top” of the tree
- **Leaf node**: a node with no children
- **Subtree**: a node and all its descendants
- **Edge**: connection between parent and a child
**Review** Trees We’ve Seen So Far

**Binary Search Trees**
- And variant: **AVL Trees**

**B+ Trees**

**Binary Min-Heaps**
Inter-data Relationships

Arrays

- Elements only store pure data, no connection info
- Only relationship between data is order

Trees

- Elements store data and connection info
- Directional relationships between nodes; limited connections

Graphs

- Elements AND connections can store data
- Relationships dictate structure; huge freedom with connections
Everything is Graphs

• **Everything** is graphs.

• Most things we’ve studied this quarter can be represented by graphs.
  - BSTs are graphs
  - Linked lists? Graphs.
  - Heaps? Also can be represented as graphs.
  - Those trees we drew in the tree method? Graphs.

• But it’s not just data structures that we’ve discussed...
  - Google Maps database? Graph.
  - Facebook? They have a “graph search” team. Because it’s a graph
  - Gitlab’s history of a repository? Graph.
  - Those pictures of prerequisites in your program? Graphs.
  - Family tree? That’s a graph
Applications

- Physical Maps
  - Airline maps
    - Vertices are airports, edges are flight paths
  - Traffic
    - Vertices are addresses, edges are streets

- Relationships
  - Social media graphs
    - Vertices are accounts, edges are follower relationships
  - Code bases
    - Vertices are classes, edges are usage

- Influence
  - Biology
    - Vertices are cancer cell destinations, edges are paths

- Related topics
  - Web Page Ranking
    - Vertices are web pages, edges are hyperlinks
  - Wikipedia
    - Vertices are articles, edges are links

So many more:
www.allthingsgraphed.com
Graphs

• A **Graph** consists of two sets, V and E:
  - V: Set of **vertices** (aka **nodes**)
  - E: Set of **edges** (pairs of vertices)
  - |V|: Size of V (also called n)
  - |E|: Size of E (also called m)
Directed vs Undirected; Acyclic vs Cyclic

**Directed:**

- **Acyclic:**
  - Graph with no cycles.
  - Example: a → b → c → d

- **Cyclic:**
  - Graph contains at least one cycle.
  - Example: a → b → d → a

**Undirected:**

- **Acyclic:**
  - Graph with no cycles.
  - Example: a - b - c

- **Cyclic:**
  - Graph contains at least one cycle.
  - Example: a - b - d - a
Labeled and Weighted Graphs

**Vertex Labels**

```
  a  b  d  c  e
```

**Edge Labels**

```
a  b  c  d
```

**Vertex & Edge Labels**

```
  a  b  c  d  e
```

**Numeric Edge Labels**

```
1  2  3  4  5
```
More Graph Terminology

• A **Simple Graph** has no **self-loops** or **parallel edges**
  - In a simple graph, $|E| = O(|V|^2)$
  - Unless otherwise stated, all graphs in this course are simple

• Vertices with an edge between them are **adjacent**
  - Vertices or edges may have optional **labels**
    - Numeric edge labels are sometimes called **weights**
More More Graph Terminology

• Two vertices are **connected** if there is a path between them
  - If all the vertices are connected, we say the graph is **connected**
  - The number of edges leaving a vertex is its **degree**

• A **path** is a sequence of vertices connected by edges
  - A **simple path** is a path without repeated vertices
  - A **cycle** is a path whose first and last edges are the same
    - A graph with a cycle is **cyclic**
Lecture Outline

• **Graphs**
  - Definitions
  - Choosing Graph Types

• Graph Implementations

• s-t Connectivity Problem
This schematic map of the Paris Métro is a graph. Which of the following characteristics make sense here?

A. Undirected / Connected / Cyclic / Vertex-labeled
B. Directed / Connected / Cyclic / Vertex-labeled
C. Undirected / Connected / Cyclic / Edge-labeled
D. Directed / Connected / Cyclic / Edge-labeled
E. I’m not sure …
Some examples

• For each of the following: what should you choose for vertices and edges? Directed?
  
  • Webpages on the Internet
  
  • Ways to walk between UW buildings
  
  • Course Prerequisites
Some examples

• For each of the following: what should you choose for vertices and edges? Directed?

• Webpages on the Internet
  - Vertices: webpages. Edges from a to b if a has a hyperlink to b.
  - Directed, since hyperlinks go in one direction

• Ways to walk between UW buildings
  - Vertices: buildings. Edges: from parent to child, maybe for marriages too?
  - Undirected, since each route can be walked both ways

• Course Prerequisites
  - Vertices: courses. Edge: from a to b if a is a prereq for b.
  - Directed, since one course comes before the other
Lecture Outline

• Graphs
  - Definitions
  - Choosing Graph Types

• Graph Implementations

• s-t Connectivity Problem
Multi-Variable Analysis

• So far, we thought of everything as being in terms of some single argument “n” (sometimes its own parameter, other times a size)
  - But there’s no reason we can’t do reasoning in terms of multiple inputs!
• Why multi-variable?
  - Remember, algorithmic analysis is just a tool to help us understand code. Sometimes, it helps our understanding more to build a Oh/Omega/Theta bound for multiple factors, rather than handling those factors in case analysis.

• With graphs, we usually do our reasoning in terms of:
  - n (or |V|): total number of vertices (sometimes just call it V)
  - m (or |E|): total number of edges (sometimes just call it E)
  - deg(u): degree of node u (how many outgoing edges it has)
Multi-Variable Analysis

Sources of Variation:
- n (size of list 1)
- m (size of list 2)
- k (position of element)

Only difference: let multiple sources of variation be represented as variables in runtime functions, instead of wrapping them up into cases!
Adjacency Matrix

- Create a 2D matrix that is $|V| \times |V|$
- In an adjacency matrix, $a[u][v]$ is 1 if there is an edge $(u,v)$, and 0 otherwise.
- Symmetric for undirected graphs

<table>
<thead>
<tr>
<th>Add Edge</th>
<th>$\Theta(1)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Remove Edge</td>
<td>$\Theta(1)$</td>
</tr>
<tr>
<td>Check if edge $(u,v)$ exists</td>
<td>$\Theta(1)$</td>
</tr>
<tr>
<td>Get out-neighbors of $u$</td>
<td>$\Theta(n)$</td>
</tr>
<tr>
<td>Get out-neighbors of $v$</td>
<td>$\Theta(n)$</td>
</tr>
<tr>
<td>(Space Complexity)</td>
<td>$\Theta(n^2)$</td>
</tr>
</tbody>
</table>

($|V| = n, |E| = m$)

<table>
<thead>
<tr>
<th></th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
</tr>
</thead>
<tbody>
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<td>0</td>
</tr>
</tbody>
</table>
Adjacency List

- Create a Map from V to some Collection of E
- In an adjacency list, if \((u,v) \in E\), then \(v\) is found in the collection under key \(u\)
- Since each node maps to a list of its neighbors, in undirected graph every edge will be included twice
  - In directed graph, every edge from \(u\) is in list associated with key \(u\).

Add Edge \(\Theta(1)\)
Remove Edge \(\Theta(\text{deg}(u))\)
Check if edge \((u, v)\) exists \(\Theta(\text{deg}(u))\)
Get out-neighbors of \(u\) \(\Theta(\text{deg}(u))\)
Get out-neighbors of \(v\) \(\Theta(n + m)\)
(Space Complexity) \(\Theta(n + m)\)

\(|V| = n, |E| = m\)

Linked Lists
Adjacency List

- Create a Map from V to some Collection of E
- In an adjacency list, if (u,v) ∈ E, then v is found in the collection under key u
- Since each node maps to a list of its neighbors, in undirected graph every edge will be included twice
  - In directed graph, every edge from u is in list associated with key u.

<table>
<thead>
<tr>
<th>Operation</th>
<th>Complexity</th>
</tr>
</thead>
<tbody>
<tr>
<td>Add Edge</td>
<td>Θ(1)</td>
</tr>
<tr>
<td>Remove Edge</td>
<td>Θ(1)</td>
</tr>
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</tr>
<tr>
<td>Get out-neighbors of u</td>
<td>Θ(deg(u))</td>
</tr>
<tr>
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<td>Θ(n)</td>
</tr>
<tr>
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<td>Θ(n + m)</td>
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</tbody>
</table>

(|V| = n, |E| = m)
Tradeoffs

• Adjacency Matrices take more space, and have slower $\Theta()$ bounds, why would you use them?
  - For dense graphs (where $m$ is close to $n^2$), the running times will be close
  - And the constant factors can be much better for matrices than for lists.
  - Sometimes the matrix itself is useful (“spectral graph theory”)

• What’s the tradeoff between using linked lists and hash tables for the list of neighbors?
  - A hash table still might hit a worst-case
  - And the linked list might not
    - Graph algorithms often just need to iterate over all the neighbors, so you might get a better guarantee with the linked list.
373: Graph Implementations

• For this class, unless we say otherwise, we’ll assume the hash tables operations on graphs are all $O(1)$.
  - Because you can probably control the keys.

• Unless we say otherwise, assume we’re using an adjacency list with hash tables for each list.
Lecture Outline

• Graphs
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• Graph Implementations

• s-t Connectivity Problem
s-t Connectivity Problem

• s-t connectivity problem

  - Given source vertex \( s \) and a target vertex \( t \), does there exist a path between \( s \) and \( t \)?

• Try to come up with an algorithm for \( \text{connected}(s, t) \)
s-t Connectivity Problem: Proposed Solution

```java
connected(Node s, Node t) {
    if (s == t) {
        return true;
    } else {
        for (Node n : s.neighbors) {
            if (connected(n, t)) {
                return true;
            }
        }
        return false;
    }
}
```
What's wrong with this proposal?

```java
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    if (s == t) {
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                return true;
            }
        }
        return false;
    }
}
```

Does 0 == 7?  No; if(connected(1, 7) return true;
Does 1 == 7?  No; if(connected(0, 7) return true;
Does 0 == 7?
s-t Connectivity Problem: Better Solution

• Solution: Mark each node as visited!

```java
connected(Node s, Node t) {
    if (s == t) {
        return true;
    } else {
        s.visited = true;
        for (Node n : s.neighbors) {
            if (n.visited) {
                continue;
            }
            if (connected(n, t)) {
                return true;
            }
        }
        return false;
    }
}
```

• This general approach to crawl through everything in a graph is going to be the basis for a LOT of algorithms

• Come back Wednesday to see an application