Before we start

If removeMin() always returns the root node, why do we still care about keeping the heap's height small?

- a) To maintain a quick runtime for percolateDown() when restoring the invariants
- b) To run contains() and look up an arbitrary key
- c) To minimize the amount of space the heap takes up
Announcements

• P2 due TONIGHT 11:59pm PDT
  - Don’t forget to fill out the P2 Project Survey! Worth 1 point, due tonight as well
• EX1 & P1 Grades released
  - If you think we made a mistake, 2 weeks for submitting a regrade request on Gradescope
• Exam I Review Materials were released Monday
  - Find under “Exams” on the website sidebar
  - Resources available to you:
    - 373 20su-specific Practice Problems Set (w/ Solutions)
    - Section Exam Review handout
    - Post-lecture review questions
    - Previous section worksheets (problems we didn’t get to)
    - 20wi Midterm & Practice Midterm (both w/ Solutions, less specific)
• Section tomorrow will emphasize Exam I review
  - Come prepared with your questions for maximum effectiveness
# Exam I Logistics

- Lecture on Friday is extra OH for the exam! Join the same Zoom call.

- Released Friday morning (7/24 12:01am PDT), due Saturday night (7/25 11:59pm PDT). Total: 48 hour window, work whenever!
  - No late submissions accepted. You cannot use late days on Exam I!
  - Written for 1-2 hours

- You’ll submit on Gradescope, just like the exercises. You can add up to 8 total people to your submission.

- During those 48 hours, we will only help with clarification questions during office hours – no review of course concepts.

- Email cse373-staff@cs or post on Piazza ASAP with any technical problems

- Don’t forget to BREATHE – you have plenty of time, no need to panic

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<thead>
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<th>WED</th>
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Learning Objectives

After this lecture, you should be able to...

1. (Continued) Trace the removeMin(), and add() methods, including percolateDown() and percolateUp()

2. Describe how a heap can be stored using an array, and compare that implementation to one using linked nodes

3. Recall the runtime to build a heap with Floyd’s buildHeap algorithm, and describe how the algorithm proceeds
Lecture Outline

• Heaps II
  - Operations & Implementation
  - Building a Heap

• Technical Interviews
Review Priority Queue ADT

- If a Queue is “First-In-First-Out” (FIFO), Priority Queues are “Most-Important-Out-First”

- Items in Priority Queue must be **comparable** – The data structure will maintain some amount of internal sorting, in a sort of similar way to BSTs/AVLs

- We’ll talk about “Min Priority Queues” (lowest priority is most important), but “Max Priority Queues” are almost identical

## MIN PRIORITY QUEUE ADT

**State**
- Set of comparable values (**ordered based on** “priority”)

**Behavior**
- **add(value)** – add a new element to the collection
- **removeMin()** – returns the element with the smallest priority, removes it from the collection
- **peekMin()** – find, but do not remove the element with the smallest priority

## MAX PRIORITY QUEUE ADT

**State**
- Set of comparable values (**ordered based on** “priority”)

**Behavior**
- **add(value)** – add a new element to the collection
- **removeMin()** – returns the element with the largest priority, removes it from the collection
- **peekMin()** – find, but do not remove the element with the largest priority
**Review** Binary Heap Invariants Summary

- One flavor of heap is a **binary heap**, which is a Binary Tree with the heap invariants *(NOT a Binary Search Tree)*

---

**Heap Invariant**
Every node is less than or equal to all of its children.

**Heap Structure Invariant**
A heap is always a *complete* tree.

---

**Binary Tree**
Every node has at most 2 children

```
INVENTORY
8
 /   \
9    10
```

```
INVENTORY
2
 / \
9   4
 /   \
6   7
```

```
INVENTORY
22
 / \
36   47
 /   \
8   9
 /   \
8   9
```
**Review**  Implementing `peekMin()`

**Runtime:** Θ(1)

Simply return the value at the root! That’s a constant-time operation if we’ve ever seen one 😊
Review  Implement `removeMin()`

1) Remove min to return
2) Structure Invariant broken: replace with bottom level right-most node (the only one that can be moved)

Heap Structure Invariant
A heap is always a complete tree.

Heap Invariant
Every node is less than or equal to all of its children.

Structure Invariant restored, but Heap Invariant now broken
3) percolateDown

Recursively swap parent with smallest child until parent is smaller than both children (or at a leaf).

What’s the worst-case running time?
• Find last element
• Move it to top spot
• Swap until invariant restored

This is why we want to keep the height of the tree small! The height of these tree structures (BST, AVL, heaps) directly correlates with the worst-case runtimes.

Structure invariant restored, heap invariant restored
percolateDown: Why Smallest Child?

• Why does percolateDown swap with the smallest child instead of just any child?

• If we swap 13 and 7, the heap invariant isn’t restored!
• 7 is greater than 4 (it’s not the smallest child!) so it will violate the invariant.
Implement add(key): percolateUp!

**ADD ALGORITHM**

- Insert node on the bottom level to ensure no gaps (*Heap Structure Invariant*).
- Fix *Heap Invariant* with new technique: *percolateUp*.
  - Swap with parent, until your parent is smaller than you (or you’re the root).

Worst case runtime similar to removeMin and percolateDown:
- might have to do log(n) swaps, so the worst-case runtime is $\Theta(\log(n))$.
MinHeap Runtimes

**removeMin()**: 
1. Remove root node
2. Find last node in tree and swap to top level
3. Percolate down to fix heap invariant

**add(key)**: 
1. Find next available spot and insert new node
2. Percolate up to fix heap invariant

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- **Finding the “end” of the heap is hard!**
  - Can do it in \(\Theta(\log n)\) time on complete trees with extra class variables by walking down
  - Fortunately, there’s a better way 😊
Implementing Heaps with an Array

- Map our binary tree heap representation into an array
  - Fill in the array in level order from left to right
  - Remember, heaps are complete trees – very predictable number of nodes on each level!

- Note: array implementation is how people almost always implement a heap
  - But tree drawing is good way to think of it conceptually!
  - Everything we’ve discussed about the tree is still true – these are just different ways of looking at the same thing

Fill array in **level-order** from left to right

<table>
<thead>
<tr>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
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<tr>
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</table>
Implementing Heaps with an Array

Calculations to navigate array:

How do we find the minimum node?

\[
\text{peekMin}() = \text{arr}[0]
\]

How do we find the last node?

\[
\text{lastNode}() = \text{arr}[\text{size} - 1]
\]

How do we find the next open space?

\[
\text{openSpace}() = \text{arr}[\text{size}]
\]

How do we find a node’s left child?

\[
\text{leftChild}(i) = 2i + 1
\]

How do we find a node’s right child?

\[
\text{rightChild}(i) = 2i + 2
\]

How do we find a node’s parent?

\[
\text{parent}(i) = \frac{(i - 1)}{2}
\]

Fill array in **level-order** from left to right

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Implementing Heaps with an Array

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**Simplified calculations to navigate array, if we skip index 0:**

How do we find the minimum node?

\[
\text{peekMin}() = \text{arr}[1]
\]

How do we find the last node?

\[
\text{lastNode}() = \text{arr}[\text{size}]
\]

How do we find the next open space?

\[
\text{openSpace}() = \text{arr}[\text{size} + 1]
\]

How do we find a node’s left child?

\[
\text{leftChild}(i) = 2i
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How do we find a node’s right child?

\[
\text{rightChild}(i) = 2i + 1
\]

How do we find a node’s parent?

\[
\text{parent}(i) = \frac{i}{2}
\]
Array-Implemented MinHeap Runtimes

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- With array implementation, heaps match runtime of finding min in AVL trees
- But better in many ways!
  - Constant factors: array accesses give contiguous memory/spatial locality, tree constant factor shorter due to stricter height invariant
  - In practice, add doesn’t require many swaps
  - WAY simpler to implement!
AVL vs Heaps: Good For Different Situations

**HEAPS**
- `removeMin`: much better constant factors than AVL Trees, though asymptotically the same
- `add`: in-practice, sweet sweet $O(1)$ (few swaps usually required)

 PriorityQueue

**AVL TREES**
- `get`, `containsKey`: worst-case ($\log n$) time (unlike Heap, which has to do a linear scan of the array)

 Map/Set
Lecture Outline

• Heaps II
  - Operations & Implementation
  - Building a Heap

• Design Decisions

• Technical Interviews
Building a Heap

- **buildHeap**\(\text{elements } e_1, \ldots, e_n\) – Given \(n\) elements, create a heap containing exactly those \(n\) elements.

- **Idea 1:** Call add \(n\) times.
  - **Worst case runtime?**
    - Each call takes logarithmic time, and there are \(n\) calls
    - \(\Theta(n \log n)\)
    - (Technically, the worst case is not this simple – you're not always going to hit logarithmic runtime because many insertions happen in a pretty empty tree – but this intuition is good enough)
  - **Could we do better?**

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Can We Do Better?

• What’s causing the $n$ add strategy to take so long?
  - Most nodes are near the bottom, and might need to percolate all the way up.

• Idea 2: Dump everything in the array, and percolate things down until the heap invariant is satisfied
  - Intuition: this could be faster!
  - The bottom two levels of the tree have $\Omega(n)$ nodes, the top two have 3 nodes
  - Maybe we can make “most of the nodes” go only a constant distance
Floyd’s buildHeap algorithm

Build a tree with the values:
12, 5, 11, 3, 10, 2, 9, 4, 8, 15, 7, 6

1. Add all values to back of array
2. percolateDown(parent) starting at last index
Floyd’s buildHeap algorithm

Build a tree with the values:
12, 5, 11, 3, 10, 2, 9, 4, 8, 15, 7, 6

1. Add all values to back of array
2. percolateDown(parent) starting at last index
   1. percolateDown level 4
   2. percolateDown level 3
Floyd’s buildHeap algorithm

Build a tree with the values: 12, 5, 11, 3, 10, 2, 9, 4, 8, 15, 7, 6

1. Add all values to back of array
2. percolateDown(parent) starting at last index
   1. percolateDown level 4
   2. percolateDown level 3
   3. percolateDown level 2

keep percolating down like normal here and swap 5 and 4
Floyd’s buildHeap algorithm

Build a tree with the values:
12, 5, 11, 3, 10, 2, 9, 4, 8, 15, 7, 6

1. Add all values to back of array
2. percolateDown(parent) starting at last index
   1. percolateDown level 4
   2. percolateDown level 3
   3. percolateDown level 2
   4. percolateDown level 1
Floyd’s buildHeap algorithm

Build a tree with the values:
12, 5, 11, 3, 10, 2, 9, 4, 8, 15, 7, 6

1. Add all values to back of array
2. percolateDown(parent) starting at last index
   1. percolateDown level 4
   2. percolateDown level 3
   3. percolateDown level 2
   4. percolateDown level 1
Is It Really Faster?

Floyd’s buildHeap runs in O(n) time!

• percolateDown() has worst case log n in general, but for most of these nodes, it has a much smaller worst case!
  - n/2 nodes in the tree are leaves, have 0 levels to travel
  - n/4 nodes have at most 1 level to travel
  - n/8 nodes have at most 2 levels to travel
  - etc...

• worst-case-work(n) ≈ \( \frac{n}{2} \cdot 1 + \frac{n}{4} \cdot 2 + \frac{n}{8} \cdot 3 + \cdots + 1 \cdot (\log n) \)

  much of the work + a little less + a little less + barely anything

• Intuition: Even though there are \( \log n \) levels, each level does a smaller and smaller amount of work. Even with infinite levels, as we sum smaller and smaller values (think \( \frac{1}{2^i} \)) we converge to a constant factor of n.
Floyd’s buildHeap Summation

- \( n/2 \cdot 1 + n/4 \cdot 2 + n/8 \cdot 3 + \cdots + 1 \cdot (\log n) \)

factor out \( n \)

work(\( n \)) \( \approx n \left( \frac{1}{2} + \frac{3}{4} + \frac{\log n}{8} + \cdots \right) \) find a pattern -> powers of 2

work(\( n \)) \( \approx n \left( \frac{1}{2^1} + \frac{3}{2^3} + \cdots + \frac{\log n}{2^{\log n}} \right) \) Summation!

\[
\text{work}(n) \approx n \sum_{i=0}^{?} \frac{i}{2^i} \quad ? = \text{upper limit should give last term}
\]

We don’t have a summation for this! Let’s make it look more like a summation we do know.

Infinite geometric series

work(\( n \)) \( \leq n \sum_{i=1}^{\log n} \frac{3^i}{2^i} \quad \text{if } -1 < x < 1 \text{ then } \sum_{i=0}^{\infty} x^i = \frac{1}{1-x} = x \quad \text{work}(n) \approx n \sum_{i=1}^{\log n} \frac{i}{2^i} \leq n \sum_{i=0}^{\infty} \left( \frac{3}{4} \right)^i = n \times 4
\]

Floyd’s buildHeap runs in \( O(n) \) time!
Project 3

• Build a heap! Alongside hash maps, heaps are one of the most useful data structures to know – and pop up many more times this quarter!
  - You’ll also get practice using multiple data structures together to implement an ADT!
  - Directly apply the invariants we’ve talked so much about in lecture! Even has an invariant checker to verify this (a great defensive programming technique!)

MIN PRIORITY QUEUE ADT

State
Set of comparable values (ordered based on “priority”)

Behavior
add(value) – add a new element to the collection
removeMin() – returns the element with the smallest priority, removes it from the collection
peekMin() – find, but do not remove the element with the smallest priority
changePriority(item, priority) – update the priority of an element
contains(item) – check if an element exists in the priority queue
Project 3 Tips

• Project 3 adds changePriority and contains to the PriorityQueue ADT, which aren’t efficient on a heap alone

• You should utilize an extra data structure for changePriority!
  - Doesn’t affect correctness of PQ, just runtime. Please use a built-in Java collection instead of implementing your own (although you could in theory).

• changePriority Implementation Strategy:
  - implement without regards to efficiency (without the extra data structure) at first
  - analyze your code’s runtime and figure out which parts are inefficient
  - reflect on the data structures we’ve learned and see how any of them could be useful in improving the slow parts in your code

MIN PRIORITY QUEUE ADT

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Lecture Outline

• Heaps II
  - Operations & Implementation
  - Building a Heap

• Technical Interviews
Beyond CSE 373: Industry

• Many people take CSE 373 because they’re interested in a career related to software engineering or more broadly CS
  - If not, that’s totally okay too! There are so many good reasons to take this class and ways to apply it; you don’t have to be interested in software engineering specifically
  - Perhaps you’ve become more interested over the course of the quarter

• If this sounds like you, it’s never too early to start thinking about preparing for a job/internship hunt!
  - We’ll send an announcement after the exam with a ton of resources for you to get started with
  - We’ll talk about this a few more times throughout the course
  - But a few highlights now to get you thinking!
The Technical Interview Process

**PREPARATION**

- Putting together your resume
- Personal projects/other experience to help you stand out
- Identifying where to apply, and when

**PROCESS**

1. **Applying**
   - Online Apps
   - Career Fairs

2. **Interviewing**
   - Technical
   - Behavioral

**CSE 373 MATERIAL**

- Practicing with interview problems & design decisions
- Identifying common patterns in interview questions

**Job/Internship Offer**
Applying


• [UW Career & Internship Center](http://bit.ly/csestorycrafting) – tons of helpful articles, especially for online job hunting!

• [College of Engineering Career Center](http://bit.ly/csestorycrafting) – schedule an appointment to talk to a career counselor
Interviewing

This is where CSE 373 comes in!

• Technical interviews love to ask about maps, trees, heaps, recursive algorithms, and especially algorithmic analysis!
• Making design decisions and determining tradeoffs between data structures is a crucial skill! Fortunately, you’ve been practicing all quarter 😊

• Leetcode and Hackerrank – tons of practice interview questions. If you’re feeling nervous, it always helps to practice 😊
  - Check out #career-prep on Discord! Your amazing TA Joyce has been highlighting example interview problems, and more and more options available as we learn more this quarter!

• The Secrets No One Told You About Technical Interviews – fantastic article (& by previous 373 instructor Kasey Champion!)

• Approaching Technical Interview Questions – when you get asked a question that stumps you, what should you do?
A+ Advice for Getting a Software Job

• A guest lecture by the amazing Kim Nguyen, former Career Coach for UW CSE, specifically for 373 students!
  - Back when a “lecture” was something that happened in person...
  - Look for an announcement with the recording! If you’re overwhelmed with all these resources, highly recommend you start here