

CSE 373: Data Structures and Algorithms

# Floyd's buildHeap, Sorting

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# Today

- Heap review and Array implementation of Heap
- Floyd's buildHeap algorithm
- Intro to Sorting
- Insertion sort
- Heap sort

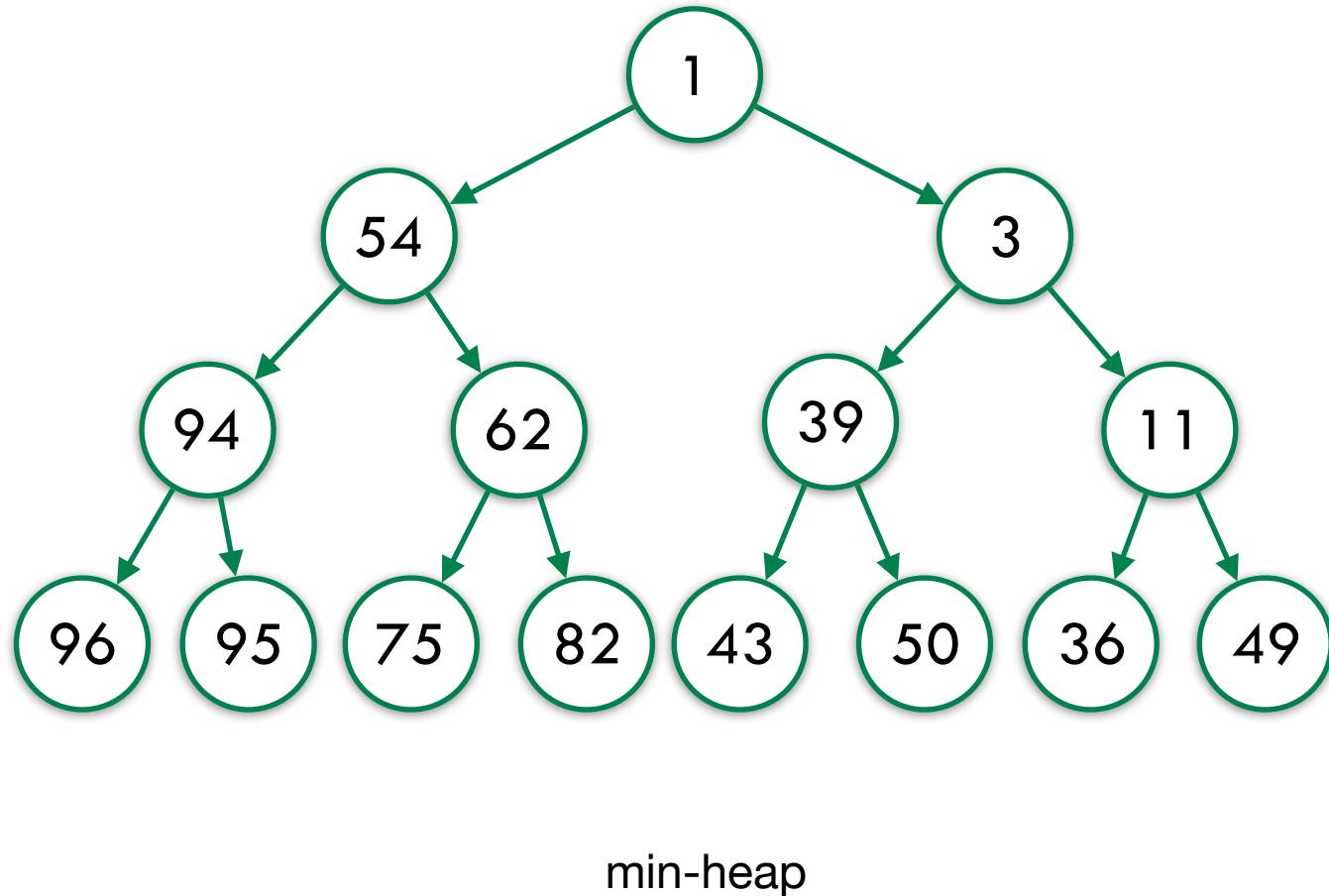
# Heap review

Heap is a tree-based data structure that satisfies

- (a) structure property: it's a complete tree
- (b) heap property, which states:
  - for min-heap:  $\text{parent} \leq \text{children}$
  - for max-heap:  $\text{parent} \geq \text{children}$
- Operations (for min-heap):
  - `removeMin()`
  - `peekMin()`
  - `insert()`
- Applications: priority queue, sorting, ..

# removeMin()

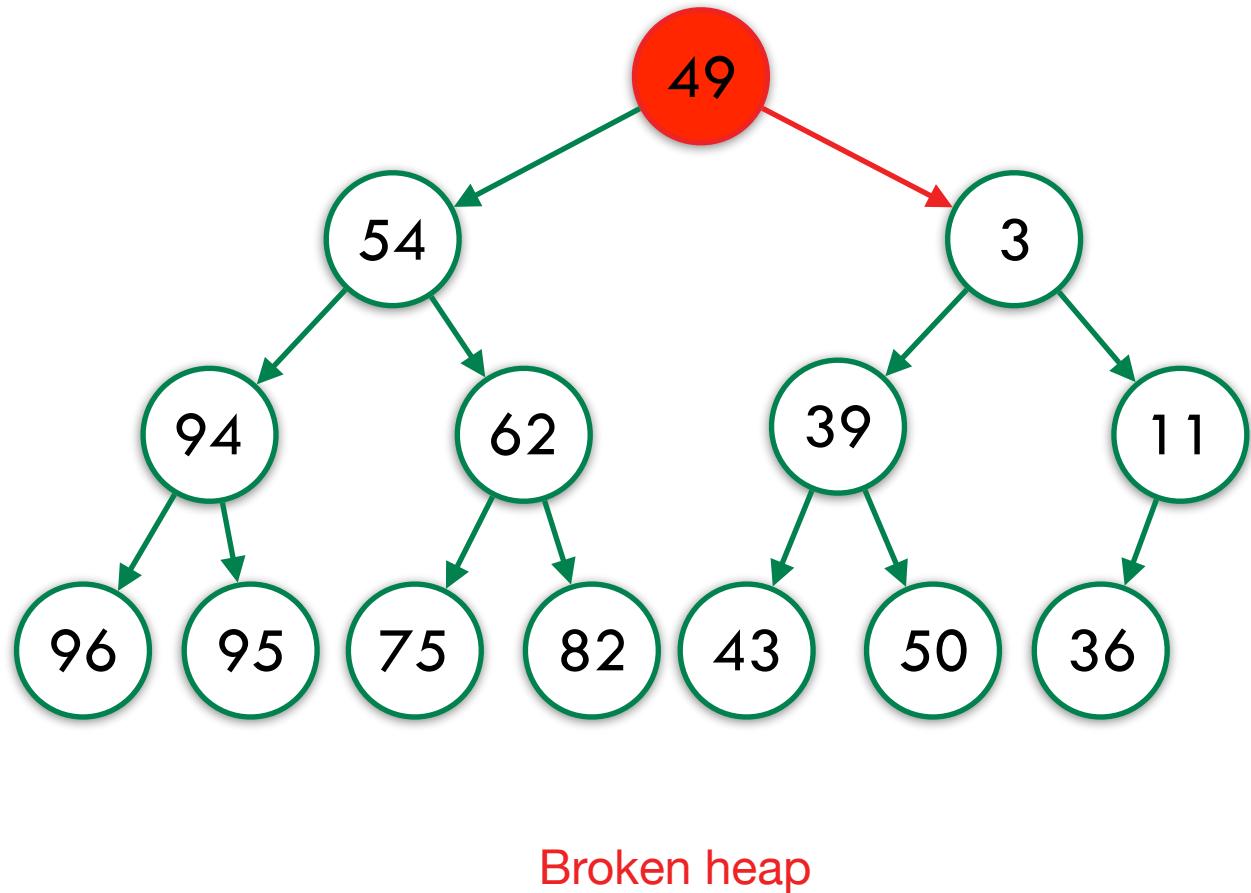
Calls:  
removeMin()



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**function** removeMin  
    *last* = last node in the tree  
    *minvalue* = *root*  
    swap *root* with *last*  
    percolateDown(*root*)  
    return *minvalue*  
**end function**

# removeMin()



Calls:

removeMin()

1

---

**function** removeMin

*last* = last node in the tree

*minvalue* = *root*

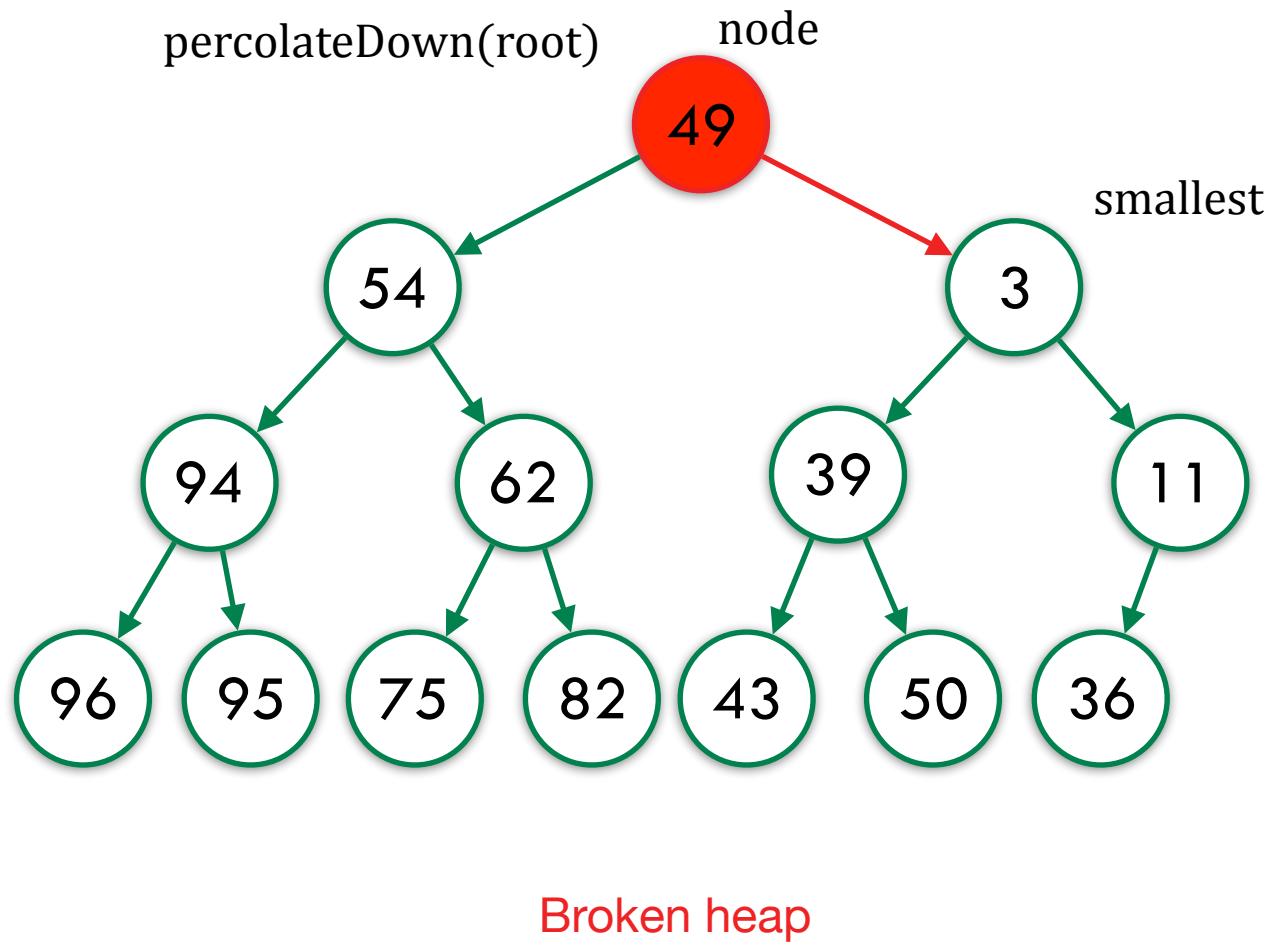
swap *root* with *last*

percolateDown(*root*)

return *minvalue*

**end function**

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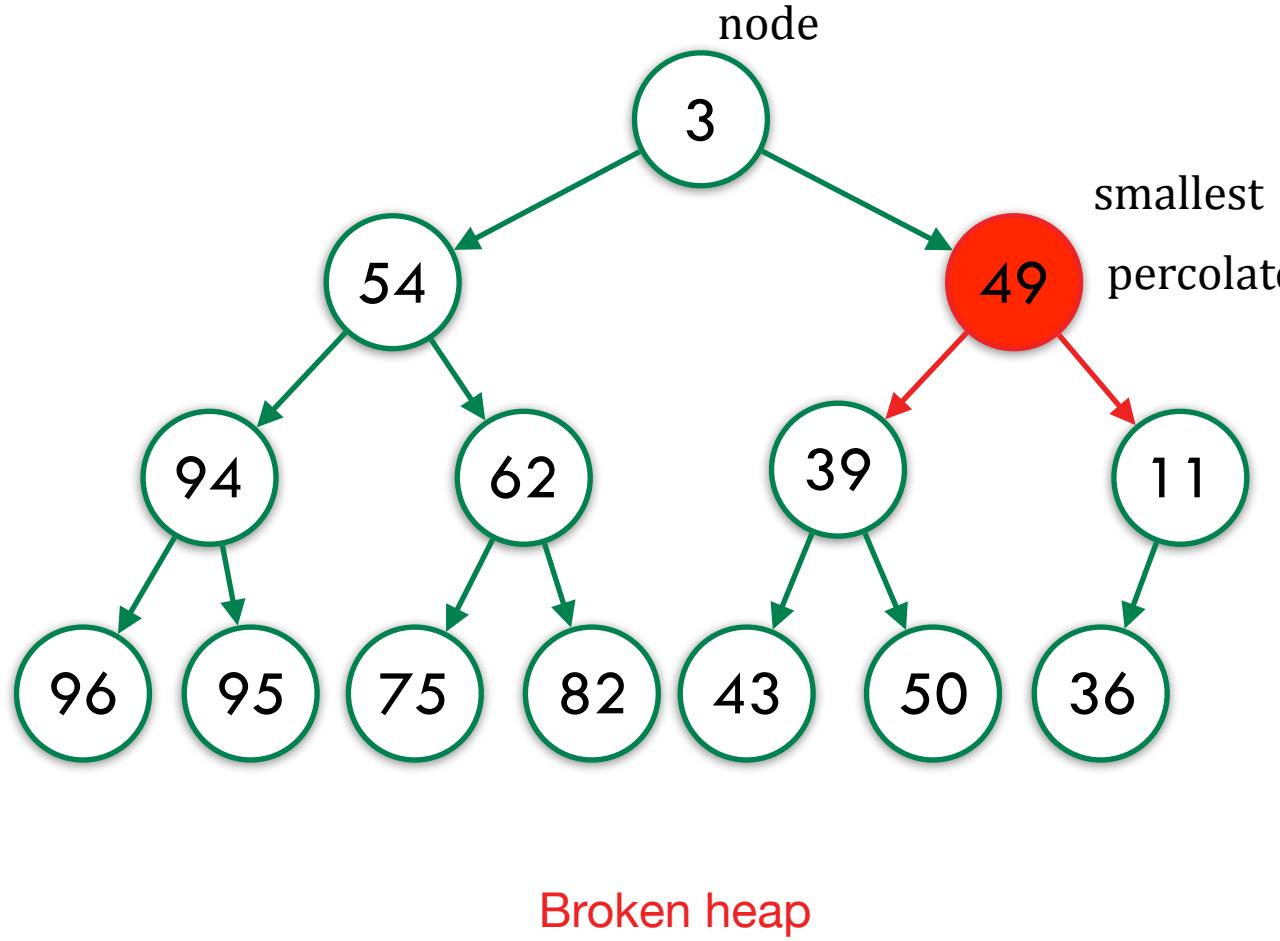


Calls:  
removeMin() 1

---

```
1: function percolateDown(node)
2:   l = left child of node
3:   r = right child of node
4:   smallest = smallest in {l, r, node}
5:   if smallest ≠ node then
6:     exchange node with smallest
7:     percolate(smallest)
8:   end if
9: end function
```

# removeMin()

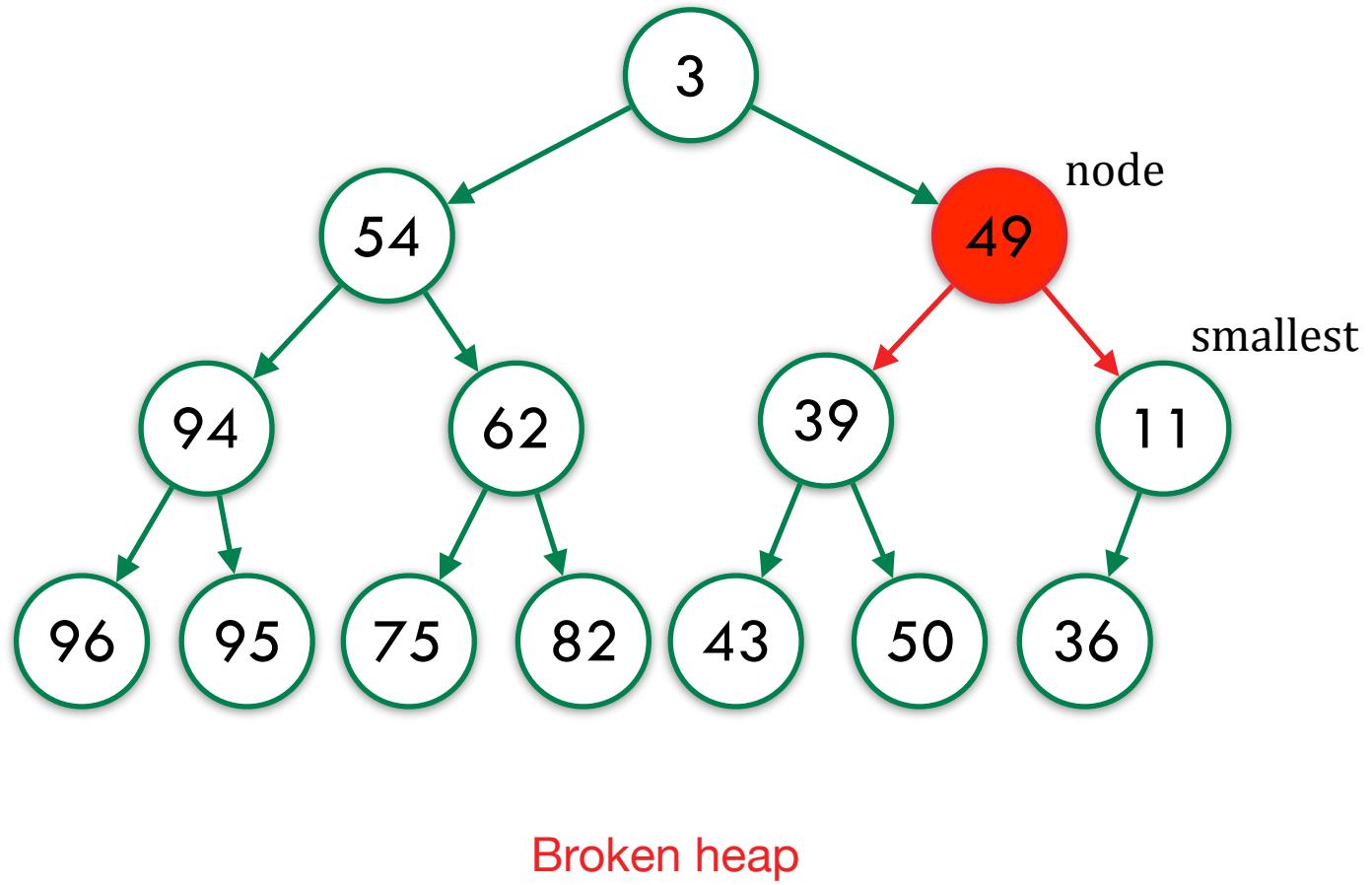


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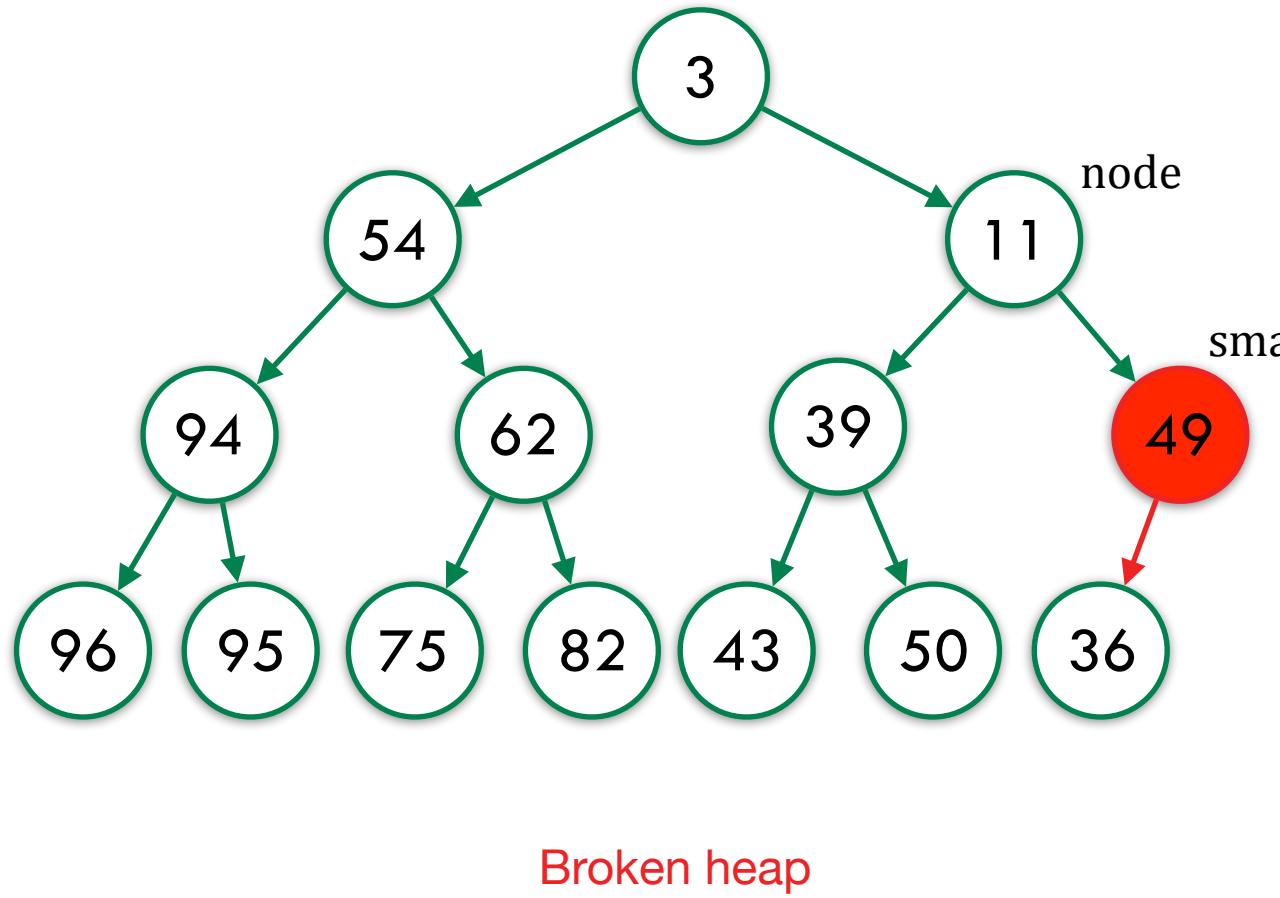


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Calls:

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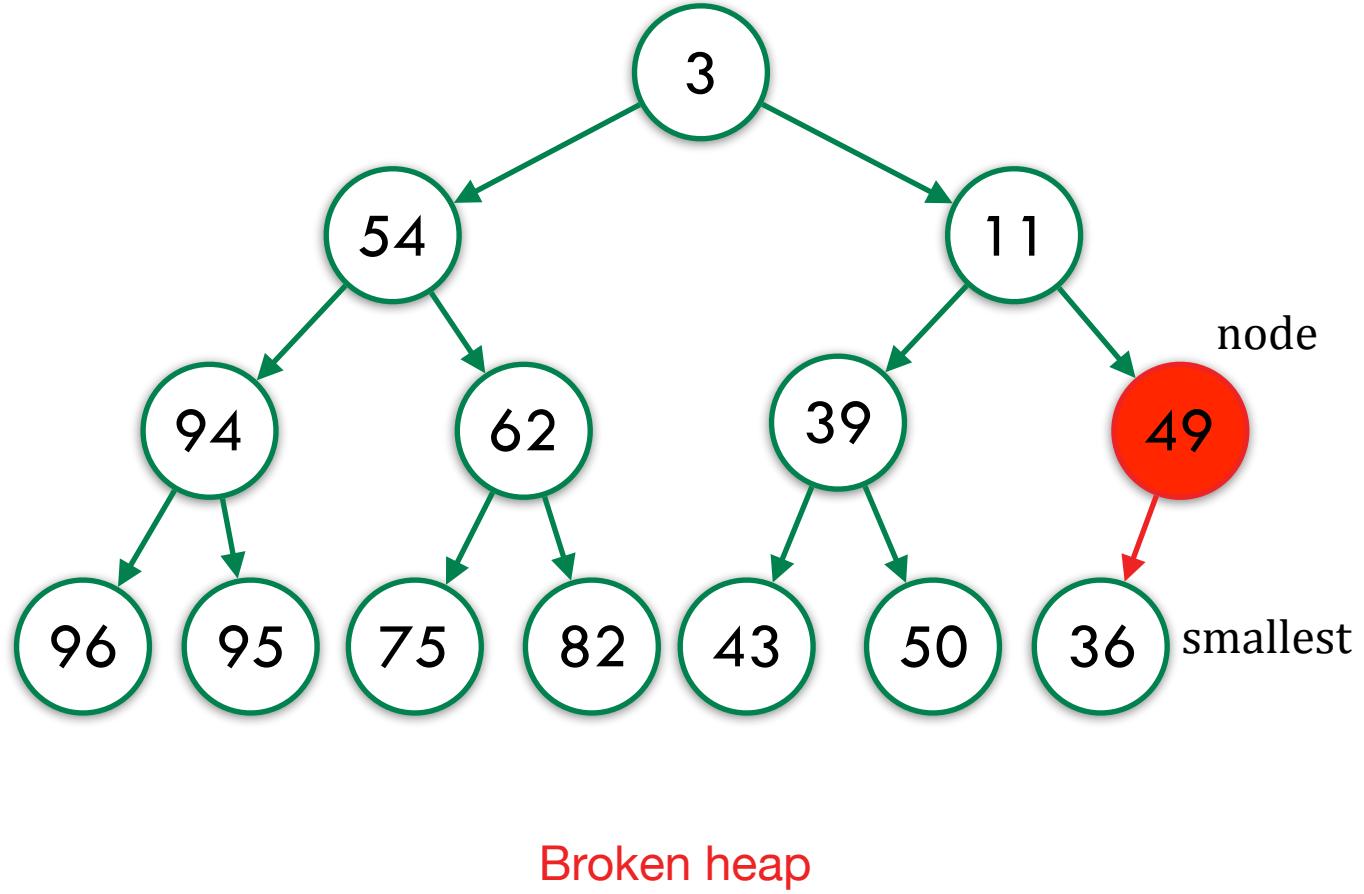
1

percolateDown(smallest)

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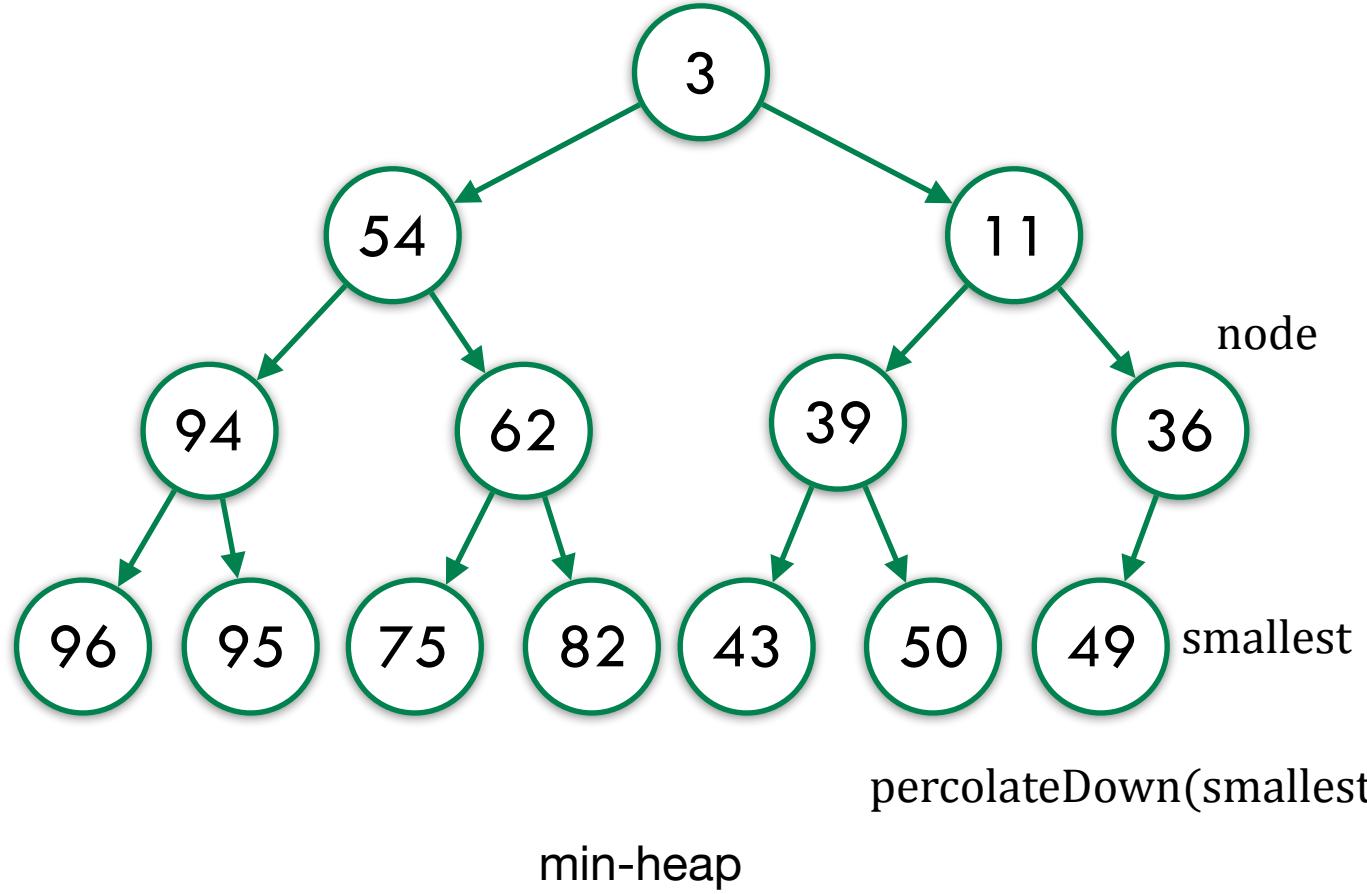


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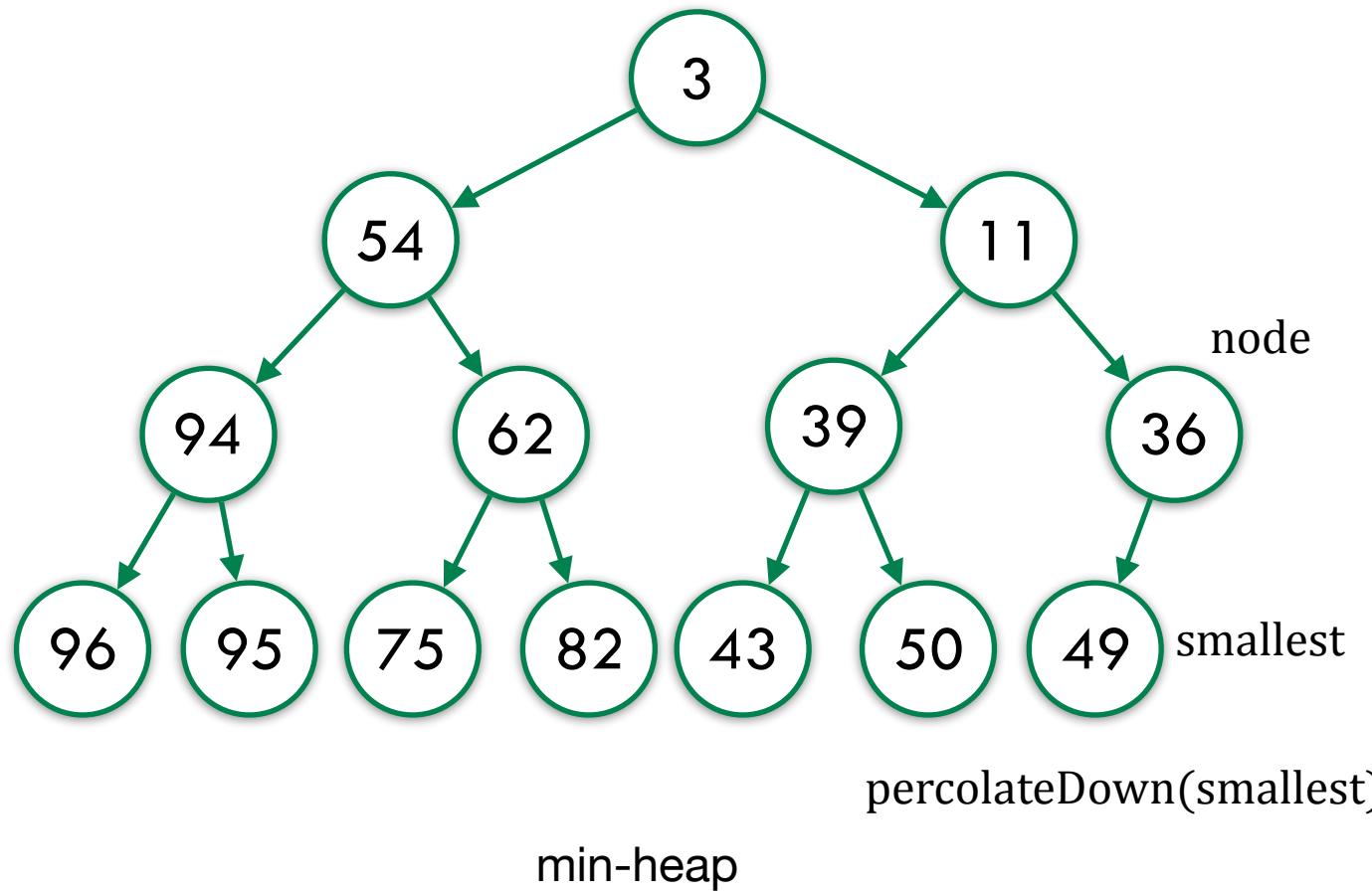


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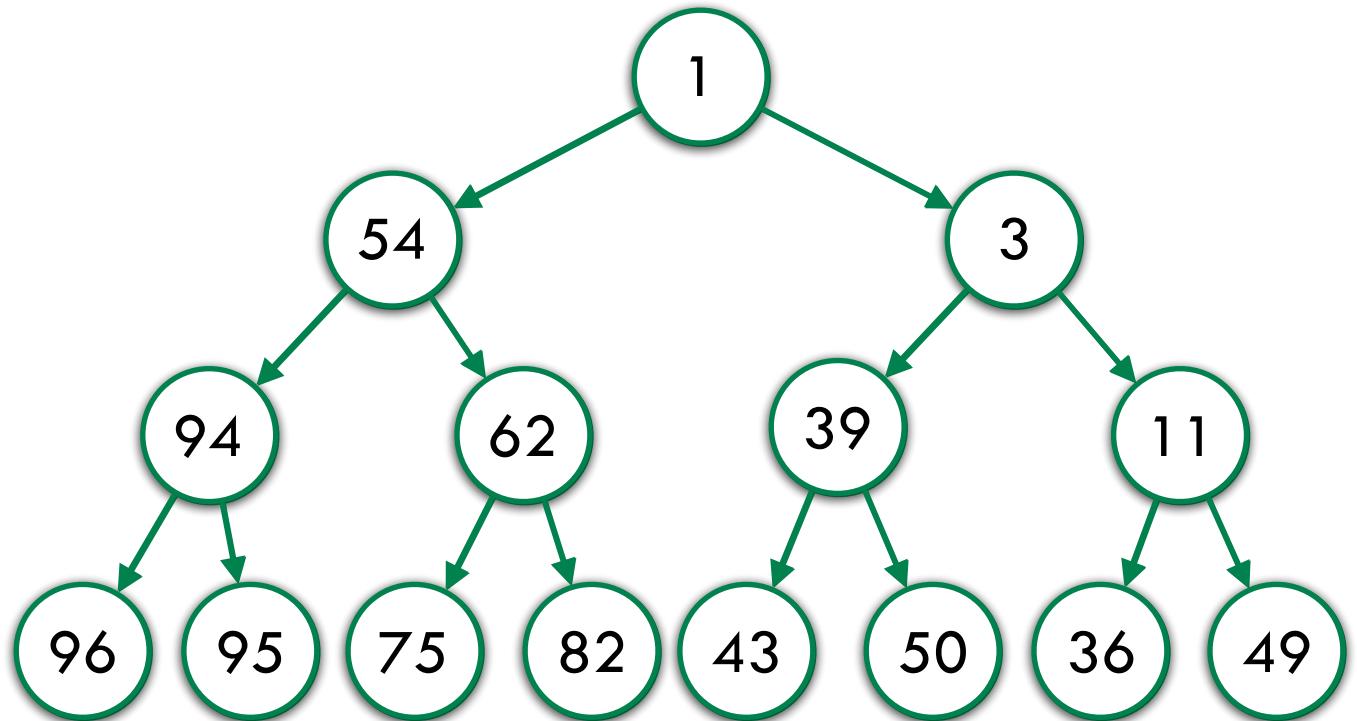
```
function removeMin
    last = last node in the tree
    minValue = root
    swap root with last
    percolateDown(root)
    return minValue
end function
```

Runtime of removeMin():

$$O(n) + c_1 + O(n \log n) = O(n)$$

How can we do better?

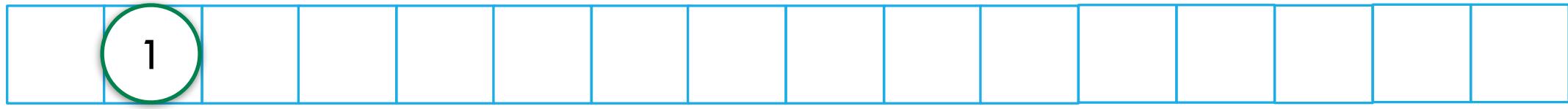
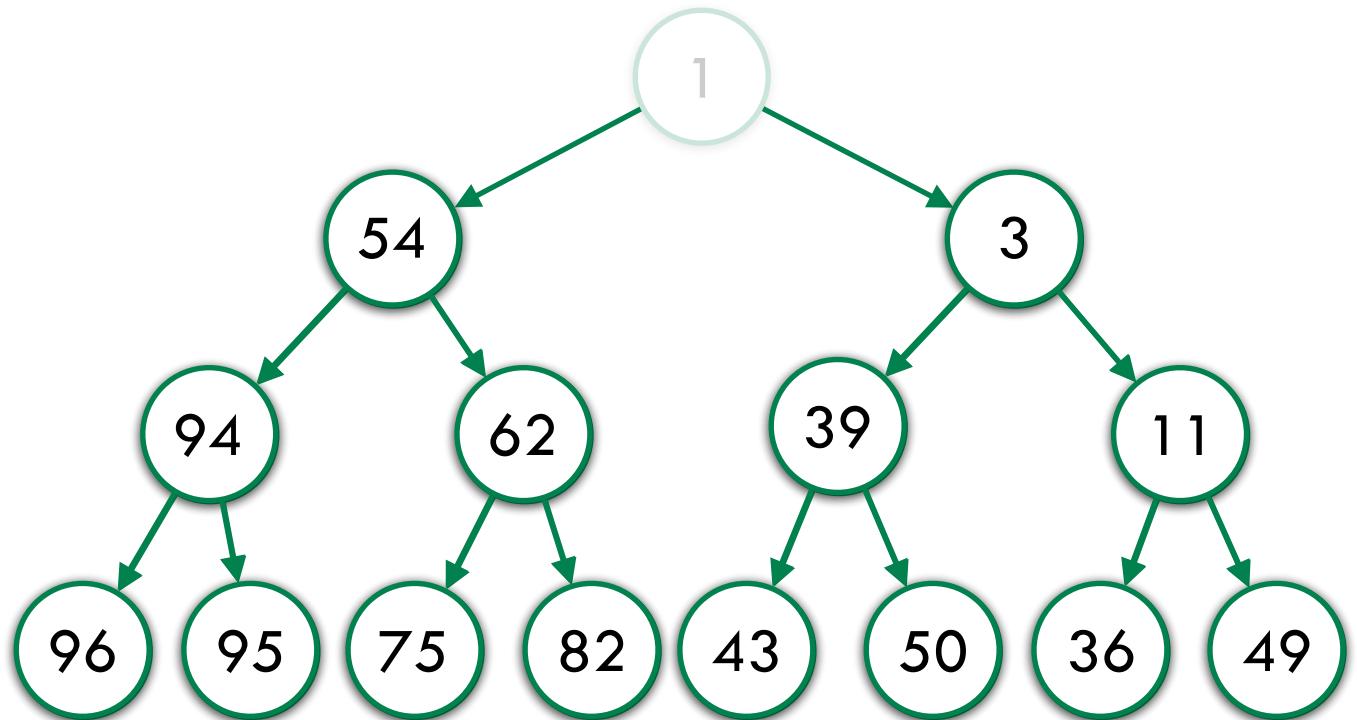
# Binary heap: Array implementation



Indices

0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

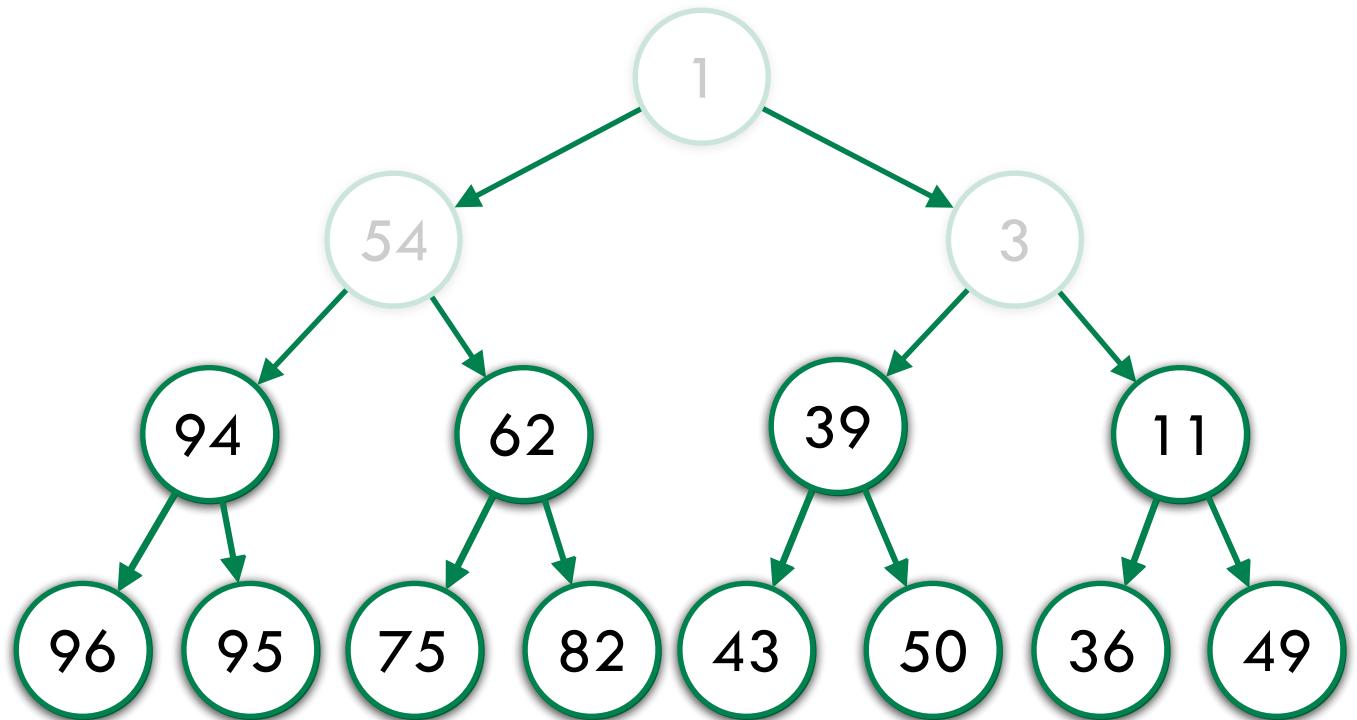
# Binary heap: Array implementation



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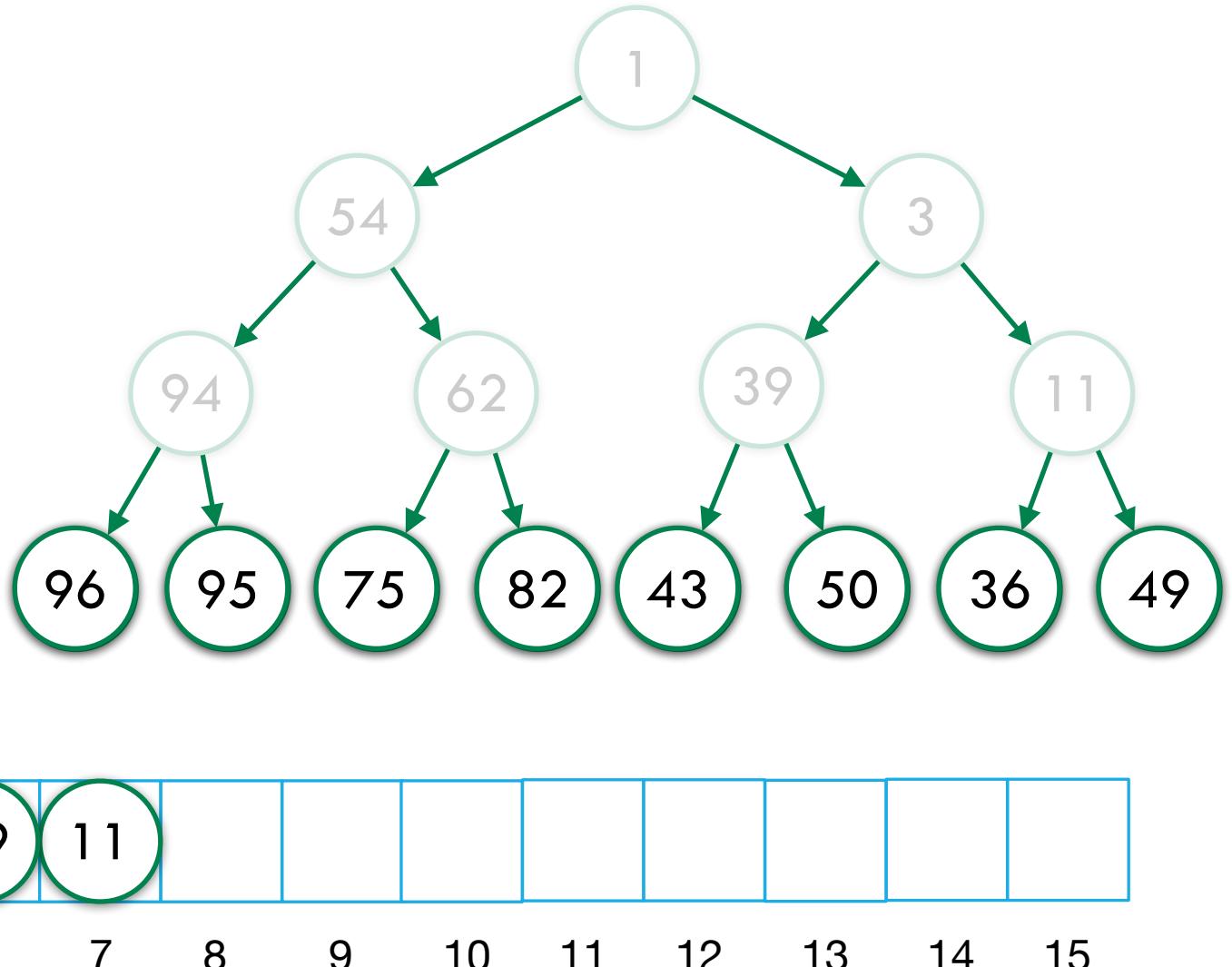
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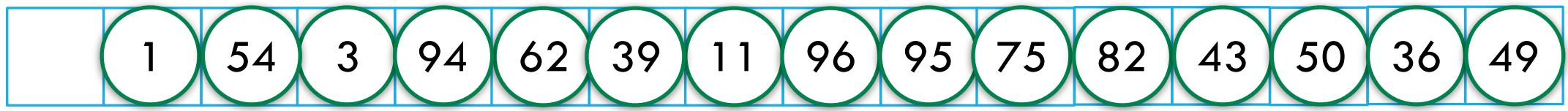
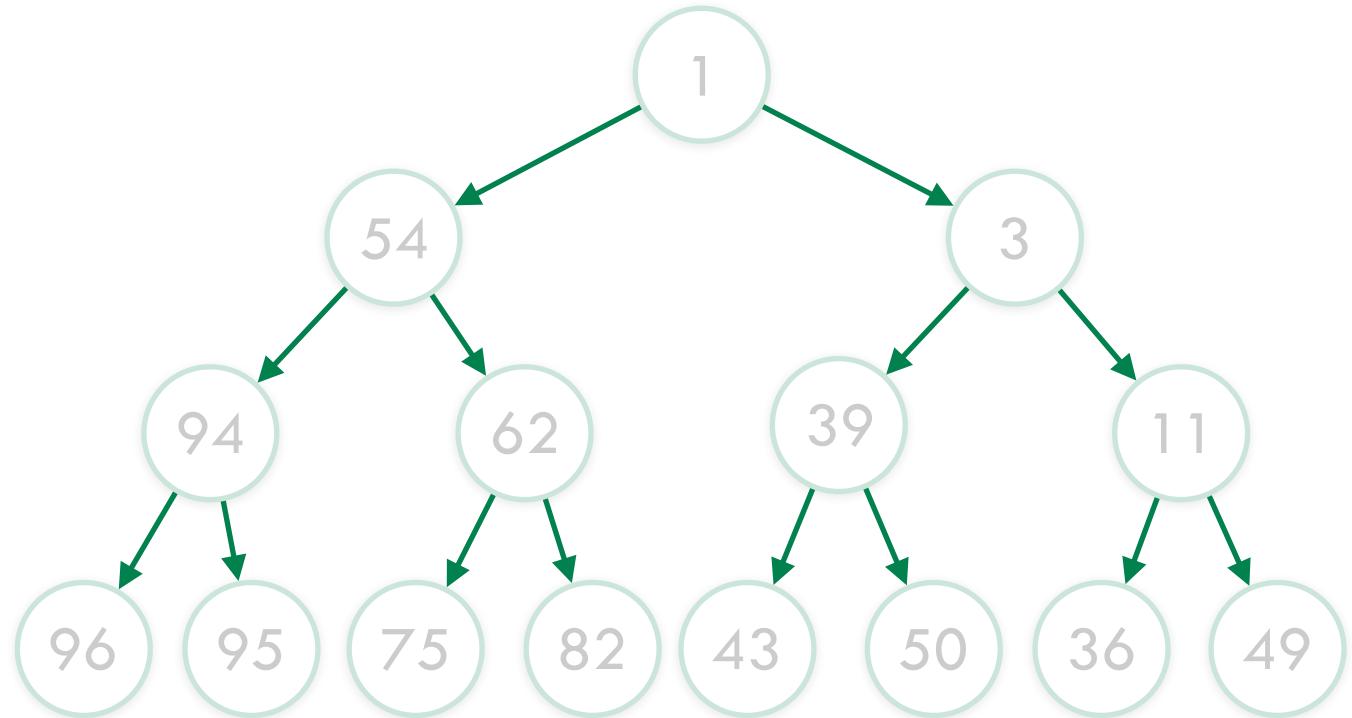
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# Binary heap: Array implementation



# Binary heap: Array implementation



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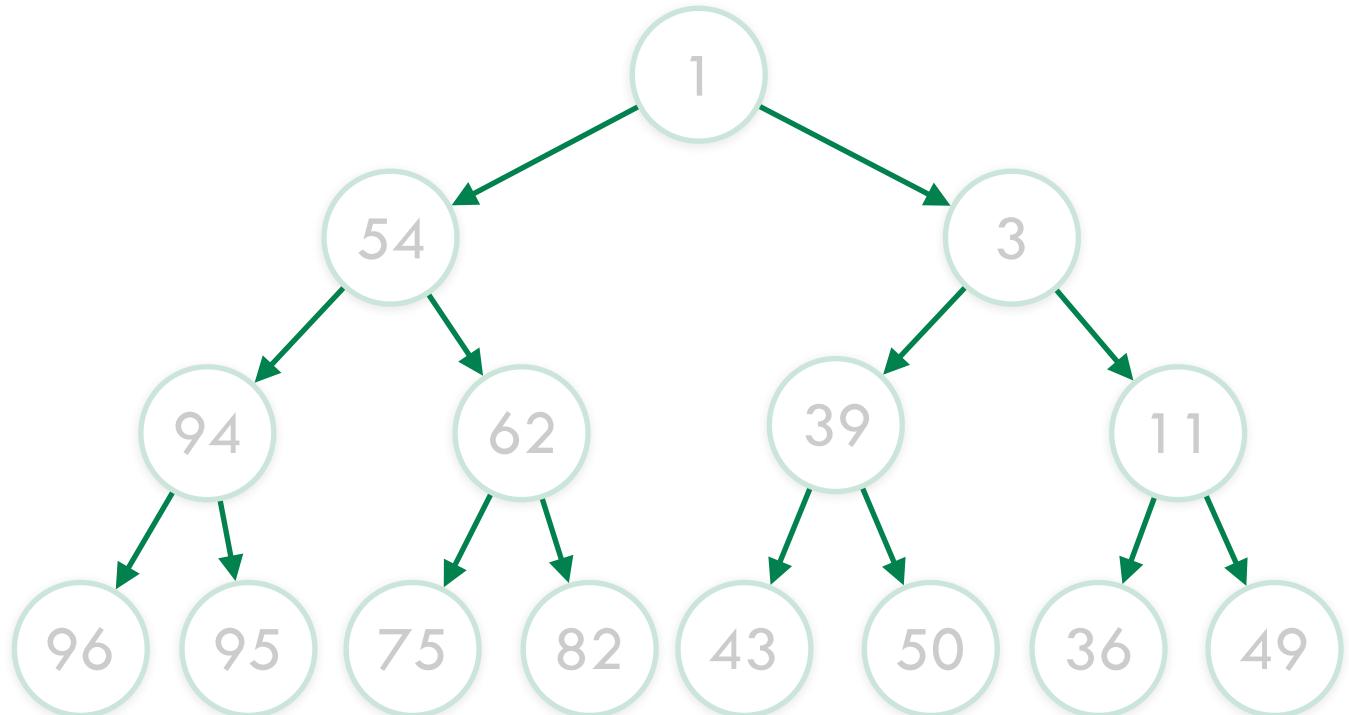
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# Binary heap: Array implementation

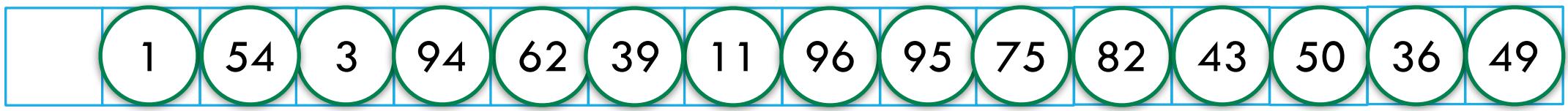
$$\text{leftChild}(i) = 2i$$

$$\text{rightChild}(i) = 2i + 1$$

$$\text{parent}(i) = \left\lfloor \frac{i}{2} \right\rfloor$$



With array starting at index 1



Indices

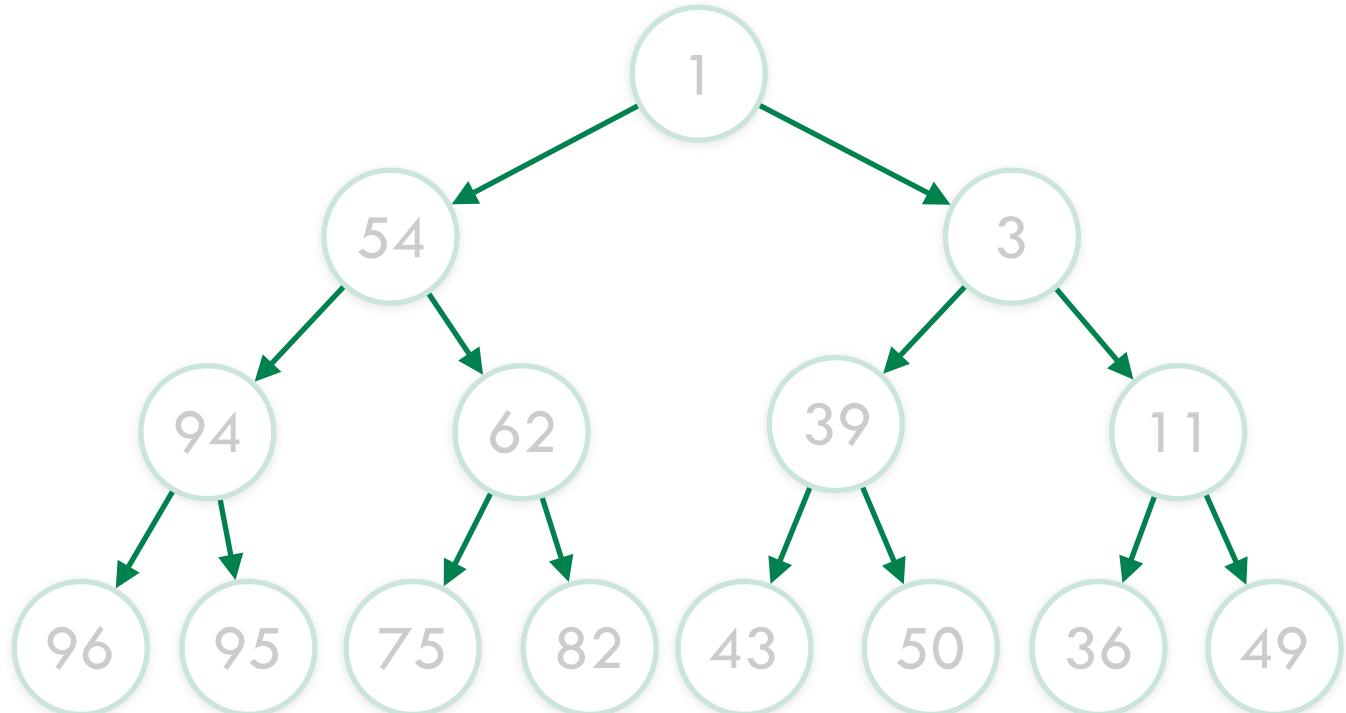
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15

# Binary heap: Array implementation

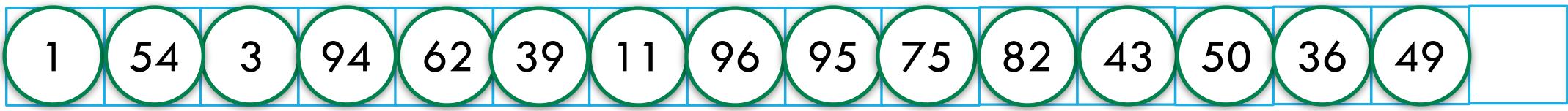
$$\text{leftChild}(i) = 2i + 1$$

$$\text{rightChild}(i) = 2i + 2$$

$$\text{parent}(i) = \left\lfloor \frac{i - 1}{2} \right\rfloor$$

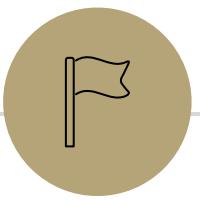


With array starting at index 0



Indices

0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15



# Sorting

# Sorting

- - Problem: Arrange items in a collection in a specified order.
- - Lots of applications:
  - lookup / search
  - merging sequences
  - data processing
- Lots of sorting algorithms out there
- Why study sorting?

# Types of sorting algorithms

## 1. Comparison Sorts

- Order of elements determined by comparing them
- Fastest comparison sort:
- Elements should support `compareTo`

$$O(n \log n)$$

## 2. Non-comparison Sorts

- Order of elements determined by leveraging properties of input
- Typical runtime:
- Also called as Niche Sorts aka “linear sorts”

$$O(n)$$

In this class we'll focus on comparison sorts

# Insertion sort

0	1	2	3	4	5	6	7	8	9
2	3	6	7	5	1	4	10	2	8

<https://visualgo.net/en/sorting>

# Insertion sort

0	1	2	3	4	5	6	7	8	9
2	3	6	7	5	1	4	10	2	8

- Runtime:
- Stable:
- In-place:

---

```
for i = 0 to n do
    current = A[i]
    j = findNewIndex(current, i)
    shift elements from j to i - 1 by 1
    A[j] = current
end for
```

---

# Heap sort

- 1. Run Floyd's buildHeap
- 2. removeMin() n times