# CSE 373: Data Structures and Algorithms Lecture 19: Comparison Sorting Algorithms 

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## Today

- Intro to sorting
- Comparison sorting
- Insertion Sort
- Selection Sort
- Heap Sort
- Merge Sort


## Sorting

Now looking at algorithms instead of data structures!

## Introduction to Sorting

- Stacks, queues, priority queues, and dictionaries all focused on providing one element at a time
- But often we know we want "all the things" in some order
- Humans can sort, but computers can sort fast
- Very common to need data sorted somehow
- Alphabetical list of people
- List of countries ordered by population
- Search engine results by relevance
- List store catalogue by price
- ...
- Algorithms have different asymptotic and constant-factor trade-offs
- No single "best" sort for all scenarios
- Knowing one way to sort just isn't enough


## More Reasons to Sort

General technique in computing:
Preprocess data to make subsequent operations faster

Example: Sort the data so that you can

- Find the $\mathrm{k}^{\text {th }}$ largest in constant time for any k
- Perform binary search to find elements in logarithmic time

Whether the performance of the preprocessing matters depends on

- How often the data will change (and how much it will change)
- How much data there is


## The main problem, stated carefully

For now, assume we have $n$ comparable elements in an array and we want to rearrange them to be in increasing order

Input:

- An array A of data records
- A key value in each data record
- A comparison function

Effect:

- Reorganize the elements of A such that for any i and j, if $i<j$ then
- (Also, A must have exactly the same data it started with)
- Could also sort in reverse order, of course

An algorithm doing this is a comparison sort

## Variations on the Basic Problem

1. Maybe elements are in a linked list (could convert to array and back in linear time, but some algorithms needn't do so)
2. Maybe ties need to be resolved by "original array position"

- Sorts that do this naturally are called

3. Maybe we must not use more than $O(1)$ "auxiliary space"

- Sorts meeting this requirement are called

4. Maybe we can do more with elements than just compare

- Sometimes leads to faster algorithms

5. Maybe we have too much data to fit in memory

- Use an "
" algorithm


## Sorting: The Big Picture

Surprising amount of neat stuff to say about sorting:

| Simple <br> algorithms: <br> $\mathrm{O}\left(n^{2}\right)$ | Fancier <br> algorithms: <br> $\mathrm{O}(n \log n)$ | Comparison <br> lower bound: <br> $\Omega(n \log n)$ | Specialized <br> algorithms: <br> $\mathrm{O}(n)$ |
| :--- | :---: | :---: | :---: | | Handling |
| :---: |
| huge data |
| sets |

(space for notes from demo)

## Insertion Sort

- Idea: At step $k$, put the $k^{\text {th }}$ element in the correct position among the first k elements
- Alternate way of saying this:
- Sort first two elements
- Now insert $3^{\text {rd }}$ element in order
- Now insert $4^{\text {th }}$ element in order
- ...
- "Loop invariant": when loop index is i, first i elements are sorted
- Time?
"Average" case $\qquad$


## Selection sort

- Idea: At step $k$, find the smallest element among the not-yet-sorted elements and put it at position $k$
- Alternate way of saying this:
- Find smallest element, put it $1^{\text {st }}$
- Find next smallest element, put it $2^{\text {nd }}$
- Find next smallest element, put it $3^{\text {rd }}$...
- "Loop invariant": when loop index is i, first i elements are the i smallest elements in sorted order
- Time?

Best-case $\qquad$ Worst-case $\qquad$ "Average" case $\qquad$

## Insertion Sort vs. Selection Sort

- Different algorithms
- Solve the same problem
- Have the same worst-case and average-case asymptotic complexity
- Insertion-sort has better best-case complexity; preferable when input is "mostly sorted"
- Other algorithms are more efficient for large arrays that are not already almost sorted
- Insertion sort may do well on small arrays


## The Big Picture

Surprising amount of juicy computer science: 2-3 lectures...

| Simple <br> algorithms: <br> $\mathrm{O}\left(n^{2}\right)$ | Fancier <br> algorithms: <br> $\mathrm{O}(n \log n)$ | Comparison <br> lower bound: <br> $\Omega(n \log n)$ | Specialized <br> algorithms: <br> $\mathrm{O}(n)$ | Handling <br> huge data <br> sets |
| :---: | :--- | :---: | :---: | :---: |
|  |  |  |  |  |
| Insertion sort | Heap sort |  | Bucket sort | External |
| Selection sort | Merge sort <br> Shell sort | Quick sort (avg) | sorting |  |

## Heap sort

- Sorting with a heap:
- insert each arr[i], or better yet use buildHeap
- for (i=0; $i<a r r . l e n g t h ; ~ i++)$
arr[i] =
- Worst-case running time:
- We have the array-to-sort and the heap
- So this is not an in-place sort
- There's a trick to make it in-place...


## In-place heap sort

But this reverse sorts how would you fix that?

- Treat the initial array as a heap (via buildHeap)
- When you delete the $i^{\text {th }}$ element, put it at arr [n-i]
- That array location isn't needed for the heap anymore!

| 4 | 7 | 5 | 9 | 8 | 6 | 10 | 3 | 2 | 1 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |  |



## "AVL sort"

- We can also use a balanced tree to:
- insert each element: total time $O(n \log n)$
- Repeatedly de letemin: total time $O(n \log n)$
- Better: in-order traversal $O(n)$, but still $O(n \log n)$ overall
- Compared to heap sort
- both are $O(n \log n)$ in worst, best, and average case
- neither parallelizes well
- heap sort is can be done in-place, has better constant factors

Design decision: which would you choose between Heap Sort and AVL Sort?
Why?

## "Hash sort"???

Finding min item in a hashtable is $O(\mathrm{n})$, so this would be a slower, more complicated selection sort

## Divide and conquer

Very important technique in algorithm design

1. Divide problem into smaller parts
2. Independently solve the simpler parts

- Think recursion
- Or parallelism

3. Combine solution of parts to produce overall solution

Two great sorting methods are fundamentally divide-and-conquer (Merge Sort \& Quicksort)

## Merge Sort

Merge Sort: recursively...

- Sort the left half of the elements
- Sort the right half of the elements
- Merge the two sorted halves into a sorted whole
(space for notes from demo)


## Merge sort



- To sort array from position lo to position hi:
- If range is 1 element long, it is already sorted!
- Else:
- Sort from lo to (hi+lo)/2
- Sort from (hi+lo)/2 to hi
- Merge the two halves together
- Merging takes two sorted parts and sorts everything
- $O(n)$ but requires auxiliary space...


## Merge Sort: Example focused on merging

Start with:

| 8 | 2 | 9 | 4 | 5 | 3 | 1 | 6 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

After recursion:
(not magic ©)


Main array

Merge:
Use 3 "fingers"
and 1 more array


Auxiliary array
(After merge, copy back to
original array)


Main array

## Merge Sort: Example showing recursion



## One way to practice on your own time:

- Make yourself an unsorted array
- Try using one of the sorting algorithms on it
- You know you got the right end result if it comes out sorted
- Can use the same example for merge sort as the previous slide to double check in-between steps


## Some details: saving a little time

- What if the final steps of our merge looked like this:



## Main array



Auxiliary array

- Wasteful to copy to the auxiliary array just to copy back...


## Some details: saving a little time

- If left-side finishes first, just stop the merge and copy back:

- If right-side finishes first, copy dregs into right then copy back


Auxiliary array

## Some details: saving space and copying

Simplest / Worst:
Use a new auxiliary array of size (hi-lo) for every merge

Better:
Use a new auxiliary array of size n for every merging stage

Better:
Reuse same auxiliary array of size $n$ for every merging stage

Best (but a little tricky):
Don't copy back - at $2^{\text {nd }}, 4^{\text {th }}, 6^{\text {th }}, \ldots$ merging stages, use the original array as the auxiliary array and vice-versa

- Need one copy at end if number of stages is odd


## Swapping Original / Auxiliary Array ("best")

- First recurse down to lists of size 1
- As we return from the recursion, swap between arrays

(Arguably easier to code up without recursion at all)


## Linked lists and big data

We defined sorting over an array, but sometimes you want to sort linked lists
One approach:

- Convert to array:
- Sort:
- Convert back to list:

Merge sort works very nicely on linked lists directly

- Heapsort and quicksort do not
- Insertion sort and selection sort do but they're slower

Merge sort is also the sort of choice for external sorting

- Linear merges minimize disk accesses
- And can leverage multiple disks to get streaming accesses


## Analysis

Having defined an algorithm and argued it is correct, we should analyze its running time and space:

To sort $n$ elements, we:

- Return immediately if $n=1$
- Else do 2 subproblems of size
and then an
merge

Recurrence relation:

## Analysis intuitively

This recurrence is common, you just "know" it's $O(n \log n)$

Merge sort is relatively easy to intuit (best, worst, and average):

- The recursion "tree" will have height
- At each level we do a total amount of merging equal to



## Analysis more formally

(One of the recurrence classics)
For simplicity, ignore constants (let constants be )

$$
\begin{aligned}
T(1) & =1 \\
T(n) & =2 T(n / 2)+n \\
& =2(2 T(n / 4)+n / 2)+n \\
& =4 T(n / 4)+2 n \\
& =4(2 T(n / 8)+n / 4)+2 n \\
& =8 T(n / 8)+3 n \\
& \ldots \\
& =2^{k} T\left(n / 2^{k}\right)+k n
\end{aligned}
$$

We will continue to recurse until we reach the base case, i.e. $T(1)$ for $T(1), n / 2^{k}=1$, i.e., $\log n=k$
So the total amount of work is

$$
2^{k} T\left(n / 2^{k}\right)+k n=2^{\log n} T(1)+n \log n=n+n \log n=O(n \log n)
$$

## Divide-and-Conquer Sorting

Two great sorting methods are fundamentally divide-and-conquer

1. Merge Sort:

- Sort the left half of the elements (recursively)
- Sort the right half of the elements (recursively)
- Merge the two sorted halves into a sorted whole

2. Quicksort:

- Pick a "pivot" element
- Divide elements into "less-than pivot" and "greater-than pivot"
- Sort the two divisions (recursively on each)
- Answer is "sorted-less-than", followed by "pivot", followed by "sorted-greater-than"


## Quicksort Overview (sneak preview)

1. Pick a pivot element
2. Partition all the data into:
A. The elements less than the pivot
B. The pivot
C. The elements greater than the pivot
3. Recursively sort A and C
4. The final answer is "as simple as $\mathrm{A}, \mathrm{B}, \mathrm{C}$ " (also is an American saying)

## Cool Resources

- http://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html
- http://www.sorting-algorithms.com/
- https://www.youtube.com/watch?v=t8g-iYGHpEA

Seriously, check them out!

