

# **CSE 373**

**NOVEMBER 1<sup>ST</sup> – EXAM REVIEW**

# EXAM FRIDAY

- **6-8 questions**

- Q1 is short answer, but will have many parts. It may be best to save this for last
- Q2 is algorithm analysis
- AVL
- Hash tables
- Priority Queues/Heaps

# EXAM FRIDAY

- **Topics**

- Definitions
- Stacks and Queues
- Runtime Analysis
- Dictionaries
- BSTs
- Traversals
- AVL Trees
- Hash Tables
- Memory Hierarchy
- B+-trees
- Priority Queues
- Heaps

# DEFINITIONS

- **Important terms**
  - Abstract Data Type
    - Example: Dictionary
      - Supports functions: insert, find, delete
      - Has expected behavior

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- **Important terms**
  - Abstract Data Type
    - Example: Dictionary
      - Supports functions: insert, find, delete
      - Has expected behavior
  - Data Structure
    - Language independent structure which implements an ADT
      - Example: AVL tree
      - Can be analyzed asymptotically

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- **Important terms**
  - Implementation
    - Low-level design decisions
    - Language specific

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- **Example**

- The Queue ADT supports enqueue, dequeue and front.
  - Arrays and Linked Lists are examples of the data structures
  - Implementation: front and back pointers

# STACKS AND QUEUES

- **Our first two ADTs**
  - Stack:
    - Supports: push(), pop(), top()
    - LIFO order



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- **Our first two ADTs**
  - Stack:
    - Supports: push(), pop(), top()
    - LIFO order
  - Queue:
    - Supports: enqueue(), dequeue(), front()
    - FIFO order

# STACKS AND QUEUES

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    - Memory usage
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  - Arrays and Linked Lists
  - Considerations
    - Memory usage
    - Ease of implementation
    - Resizing time
  - Runtimes:
    - $O(1)$  for all functions

# RUNTIME ANALYSIS

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  - Comparisons, mathematical operations, assignments

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- **For loops and while statements**
  - Count the number of times relevant code is executed
- **Important summations**
  - Sum of all numbers from 1 to  $n$
  - Sum of the powers of two

# RUNTIME ANALYSIS

- **Asymptotic Analysis**
  - Best-case, worst-case, average-case
  - Usually we discuss worst-case complexity
  - If we increase the input size, how does the computation time change



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- **BigO notation**
  - Upper bound for a given function
  - $f(n) = O(g(n))$  if there exists a  $c$  and  $n_0$  for which  $f(n) \leq c * g(n)$  for all  $n \geq n_0$

# RUNTIME ANALYSIS

- **Recurrences**
  - Analysis of recursive functions
  - Break the function into recursive and non-recursive
  - Produce the recurrence relation
  - Roll out the recurrence or produce the recurrence tree
  - Find the closed form of the recurrence
  - Upper bound this recurrence with a bigO bound.

# RUNTIME ANALYSIS

- **Amortized analysis**

- Used when an expensive operation occurs with predictable frequency (e.g. resizing an array)
- Describe the state of the data structure
- Indicate the number of operations
- Determine how many are the costly operation and how many are the cheap operations
- $\# \text{ of costly} * \text{costly runtime} + \# \text{ cheap} * \text{cheap runtime}$
- Divide by the number of operations

# RUNTIME ANALYSIS

- **Memory analysis**
  - Calculating how much memory an algorithm needs
  - This is in addition to the data itself
  - Think about any secondary data structures you might use
  - Also, remember that recursive functions consume memory on the call stack

# RUNTIME ANALYSIS

- **Basic ideas**
  - If we increase the size of the input by one, how does our total computation change?

# RUNTIME ANALYSIS

- **Basic ideas**

- $O(1)$ : Input size has no effect on runtime
- $O(\log n)$ : doubling the input increases the runtime by some constant amount
- $O(n)$ : linear time, each additional input increases execution time by a constant amount
- $O(n^2)$ : doubling the input increases the runtime by a factor of 4.
- $O(2^n)$ : exponential, increasing the input by one doubles the runtime

# DICTIONARIES

- **ADT**
  - Supports the following functions
    - Insert(key k, value v)
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  - Supports the following functions
    - Insert(key k, value v)
    - find(key k)
    - delete(key k)
  - Data is stored in key, value pairs
  - In this course, duplicate keys are not allowed
  - Most data structures can implement a dictionary



# BINARY SEARCH TREES

- **Binary trees**
- **Nodes with two children**
- **Maintains search property**
  - All values in the left subtree must be less than the parent
  - All values in the right subtree must be greater than the parent

# BINARY SEARCH TREES

- **Binary trees**
- **Nodes with two children**
- **Maintains search property**
  - All values in the left subtree must be less than the parent
  - All values in the right subtree must be greater than the parent
- **With each increase in height, the number of nodes in a tree roughly doubles**
- **A perfect tree has  $2^{h+1}-1$  nodes**
- **Roughly half of a binary search tree are leaves**

# TRAVERSALS

- **Two main traversal families**
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# TRAVERSALS

- **Two main traversal families**
  - Depth First Search
  - Breadth First Search
- **DFS**
  - Usually implemented recursively
  - Whether the parent is processed before, after or in the middle of its children determines if the traversal is pre-order, post-order or in-order respectively
- **BFS**
  - Put the root into a queue
  - Dequeue a node, process it and enqueue its children
  - Top to bottom left to right traversal
  - Queue is largest at the widest part of the tree

# AVL TREES

- **Specific type of binary search tree**
- **Still must implement binary search**
- **Nodes in AVL trees have two extra fields, height and balance**
- **Balance =  $| \text{height}(\text{left}) - \text{height}(\text{right}) |$**
- **Balance for each node must be less than or equal to 1**
- **Trees with this condition still have  $O(\log n)$  height**
- **No covering delete in this course**
- **Find:  $O(\log n)$ : Insert  $O(\log n)$**

# AVL ROTATIONS

- **AVL Rotations occur when an insertion makes a node out of balance**
  - Relative to the node that is unbalanced, there are four rotations depending on which grandchild received the new node.
  - Left-left and right right rotations involve the child of the affected node being rotated up into position
  - Left-right and right-left rotations involve the grandchild being rotated up into position. The grandparent and parent become the two children
  - It is important that these rotations preserve BST property

# HASH TABLES

- A large data set  $M$  with a smaller set that should be saved,  $D$
- A hash function maps  $M$  onto  $D$ 
  - It should run in  $O(1)$  time
  - It should distribute into all of the available spots evenly
- **Hashtables provide  $O(1)$  runtime IF**
  - Collisions are not a problem
  - Decrease the chance of collisions by increasing the amount of memory (**load factor**)
    - Resizing is costly



# COLLISIONS

- **Probing**

- Linear probing

- Try the appropriate hash table row first
    - Increase the index by one until a spot is found
    - Guaranteed to find a spot if it is available
    - If the array is too full, its operations reach  $O(n)$  time. **Primary clustering**

# COLLISIONS

- **Probing**

- Quadratic Probing

- Rather than increasing by one each time, we increase by the squares
    - $k+1, k+4, k+9, k+16, k+25$
    - Certain tables can cause **secondary clustering**
    - Can fail to insert if the table is over half full

# COLLISIONS

- **Probing**

- **Secondary Hashing**

- If two keys collide in the hash table, then a secondary hash indicates the probing size
    - Need to be careful, possible for infinite loops with a very empty array
    - If the secondary hash value and the table size are coprime (they share no factors), then secondary hashing will succeed if there is an open space
    - If table size is prime, only need to check if hash is a multiple

# COLLISIONS

- **Chaining**

- Rather than probing for an open position, we could just save multiple objects in the same position
- Some data structure is necessary here
- Commonly: a linked list, AVL tree or secondary hash table.
- Resizing isn't **necessary**, but if you don't, you will get  $O(n)$  runtime.

# MEMORY HIERARCHY

- **Memory is not uniformly accessible**
  - OS manages access to computer resources
  - Some memory is on disk and some is in cache
  - Dictated by two types of behavior
    - Spatial locality – Items near each other are moved together (memory pages)
    - Temporal locality – memory used recently will be used again

# B-TREES

- **To reduce disk accesses we introduce the B-tree**
  - Two types of nodes
    - Signposts: Have  $M$  pointers and  $M-1$  keys
    - Leaves: Have  $L$   $\langle K, V \rangle$  Pairs and a pointer to the next leaf
  - Signposts must have at least  $M/2$  pointers and leaves must have at least  $L/2$  data points, unless it is the root
  - Keys in signposts are the smallest item in the next pointer

# B-TREES

- **Insertion**

- Find the leaf that should hold the inserted element
- Insert the new  $k,v$  pair in sorted order in the leaf node
- If it overflows (i.e. the leaf is full when inserted)
  - Split the leaf into two nodes and add the new leaf to the parent
- If the signpost overflows, split the signpost into two signposts and try to add the new signpost to the parent
- Split back up to the root and create a new root if necessary

# HEAPS

- **Priority Queue ADT**

- Supports: insert(), findMin(), deleteMin(), changePriority()
- Data is stored in priority, value pairs
- In this class, we use the min-heap, where a lower value means it should dequeue first



# HEAPS

- **Data Structure**
  - Heap
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- Implementation

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- **Data Structure**

- Heap
  - Complete binary tree
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- Implementation
  - Array
  - Find parents/children arithmetically
- Runtimes
  - Insert:  $O(\log n)$ , findMin:  $O(1)$ , deleteMin  $O(\log n)$
  - ChangePriority:  $O(\log n)$

# HEAPS

- **Data Structure**

- Heap

- Complete binary tree
    - Heap property

- Implementation

- Array
    - Find parents/children arithmetically

- Runtimes

- Insert:  $O(\log n)$ , findMin:  $O(1)$ , deleteMin  $O(\log n)$
    - ChangePriority:  $O(\log n)$
    - buildHeap,  $O(n)$

# HEAPS

- **Percolate up**

- After you've inserted an element in the next location in order to preserve completeness
- Compare the current element against its parent
- Swap if the child is less than the parent
- Repeat until the child is greater than the parent or the new element is swapped up to the root

# HEAPS

- **Percolate down**

- After deleting an element, move the last element (from completeness) up to the root
- Compare the current node against both of its children
- Swap the node with the smaller child provided the child is still smaller than the parent
- Continue until the node is smaller than both children, or it is a leaf.

# HEAPS

- **Floyd's method**

- For each element in the array from  $\text{size}/2$  to the first element
- Percolate that element down as much as necessary
- Because most elements are near the bottom, they do not need to percolate down very far, this results in  $O(n)$  overall runtime

# **GOOD LUCK!**

- **Practice Exam solution tomorrow**
- **Review in section tomorrow**
- **Email/Piazza any questions**
- **No office hours Friday or next Monday**
- **Grades back in class on Monday**