



CSE373: Data Structures & Algorithms

Lecture 20: Minimum Spanning Trees

Linda Shapiro Spring 2016

Announcements

- HW 4 due Wednesday, May 18
- HW 5 will be due June 1. Ben Jones is our expert in Ezgi's absence. benjones@cs

Minimum Spanning Trees

The minimum-spanning-tree problem

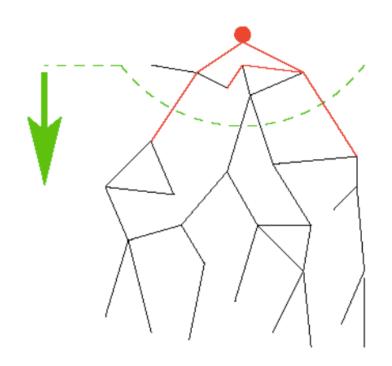
 Given a weighted undirected graph, compute a spanning tree of minimum weight

Given an undirected graph G=(V,E), find a graph G'=(V, E') such that:

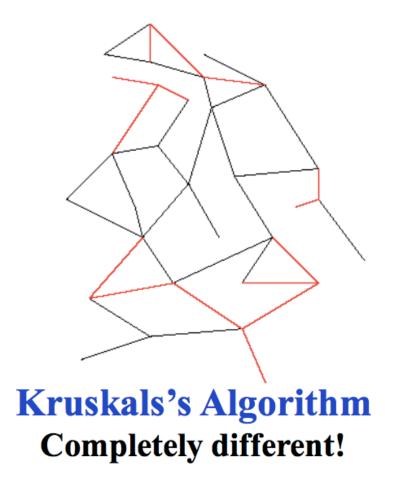
- E' is a subset of E
- |E'| = |V| 1
- G' is connected

G' is a minimum spanning tree.

Two different approaches



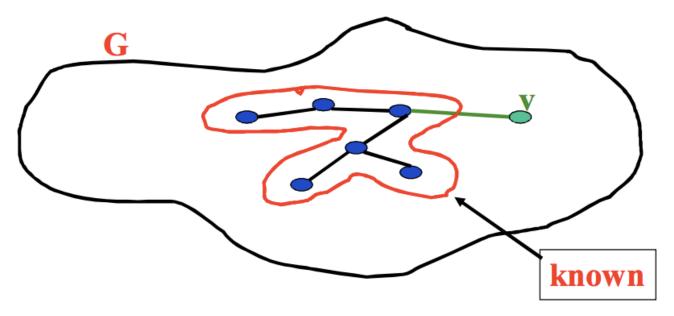
Prim's Algorithm
Almost identical to Dijkstra's



Prim's Algorithm Idea

Idea: Grow a tree by picking a vertex from the unknown set that has the smallest cost. Here cost = cost of the edge that connects that vertex to the known set. Pick the vertex with the smallest cost that connects "known" to "unknown."

A *node-based* greedy algorithm Builds MST by greedily adding nodes



Prim's vs. Dijkstra's

Recall:

Dijkstra picked the unknown vertex with smallest cost where cost = distance to the source.

Prim's pick the unknown vertex with smallest cost where

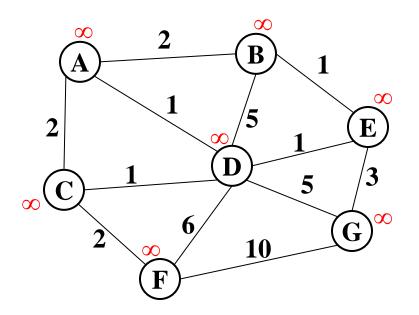
cost = distance from this vertex to the known set

(in other words, the cost of the smallest edge connecting this vertex to the known set)

Otherwise identical ©

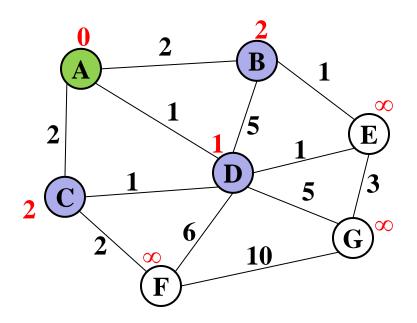
- 1. For each node v, set v.cost = ∞ and v.known = false
- 2. Choose any node v
 - a) Mark v as known
 - b) For each edge (v,u) with weight w, set u.cost=w and u.prev=v
- 3. While there are unknown nodes in the graph
 - a) Select the unknown node v with lowest cost
 - b) Mark v as known and add (v, v.prev) to output
 - c) For each edge (v,u) with weight w,

```
if(w < u.cost) {
   u.cost = w;
   u.prev = v;
}</pre>
```



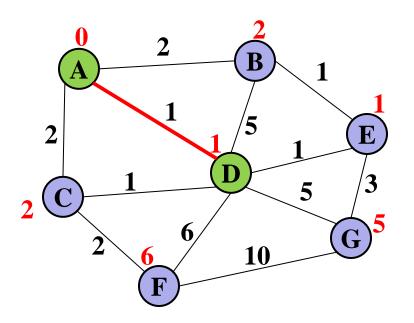
```
if(w < u.cost) {
    u.cost = w;
    u.prev = v;}</pre>
```

vertex	known?	cost	prev
А		??	
В		??	
С		??	
D		??	
Е		??	
F		??	
G		??	

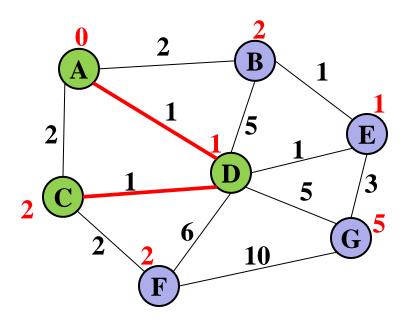


```
if(w < u.cost) {
    u.cost = w;
    u.prev = v;}</pre>
```

vertex	known?	cost	prev
А	Υ	0	
В		2	А
С		2	А
D		1	А
Е		??	
F		??	
G		??	

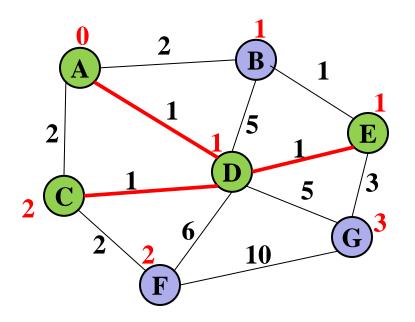


vertex	known?	cost	prev
Α	Υ	0	
В		2	А
С		1	D
D	Υ	1	А
Е		1	D
F		6	D
G		5	D

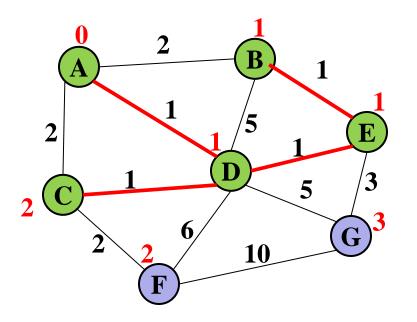


```
if(w < u.cost) {
    u.cost = w;
    u.prev = v;}</pre>
```

vertex	known?	cost	prev
Α	Υ	0	
В		2	А
С	Υ	1	D
D	Υ	1	А
Е		1	D
F		2	С
G		5	D

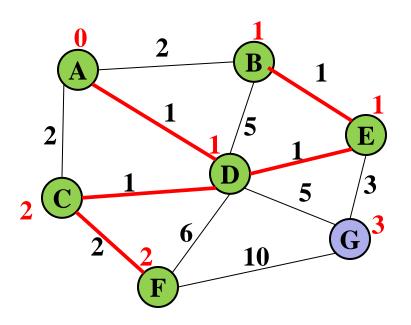


vertex	known?	cost	prev
А	Υ	0	
В		1	Е
С	Υ	1	D
D	Υ	1	А
Е	Υ	1	D
F		2	С
G		3	Е



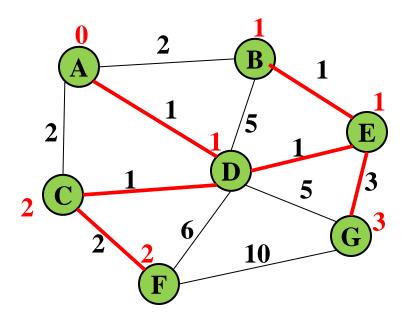
```
if(w < u.cost) {
    u.cost = w;
    u.prev = v;}</pre>
```

vertex	known?	cost	prev
Α	Υ	0	
В	Υ	1	Е
С	Υ	1	D
D	Υ	1	А
Е	Υ	1	D
F		2	С
G		3	E



```
if(w < u.cost) {
    u.cost = w;
    u.prev = v;}</pre>
```

vertex	known?	cost	prev
Α	Υ	0	
В	Υ	1	E
С	Υ	1	D
D	Υ	1	А
Е	Υ	1	D
F	Υ	2	С
G		3	E



```
if(w < u.cost) {
    u.cost = w;
    u.prev = v;}</pre>
```

vertex	known?	cost	prev
Α	Υ	0	
В	Υ	1	E
С	Υ	1	D
D	Υ	1	А
Е	Υ	1	D
F	Y	2	С
G	Y	3	Е

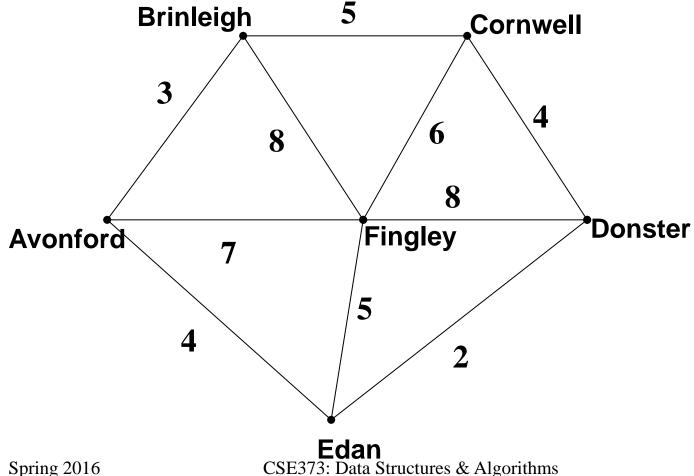
Analysis

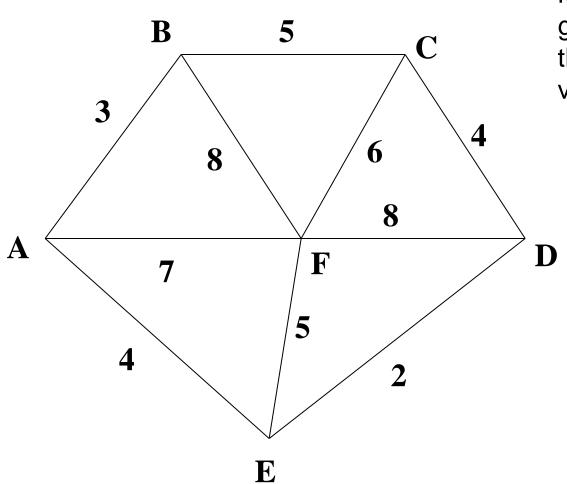
- Correctness
 - A bit tricky
 - Intuitively similar to Dijkstra

- Run-time
 - Same as Dijkstra
 - O(|E|log|V|) using a priority queue
 - Costs/priorities are just edge-costs, not path-costs

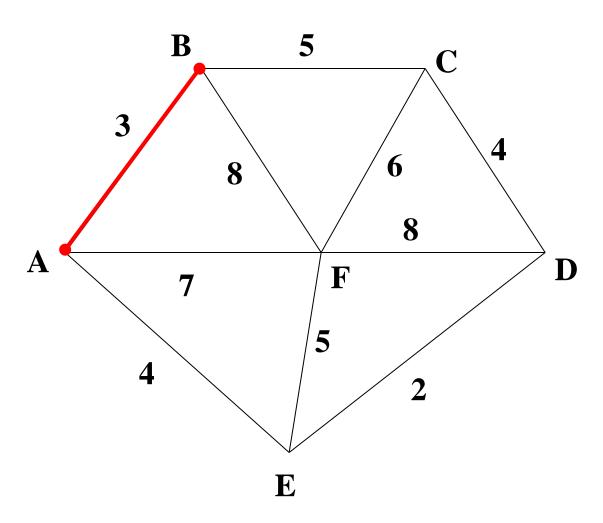
Another Example

A cable company wants to connect five villages to their network which currently extends to the town of Avonford. What is the minimum length of cable needed?





Model the situation as a graph and find the MST that connects all the villages (nodes).

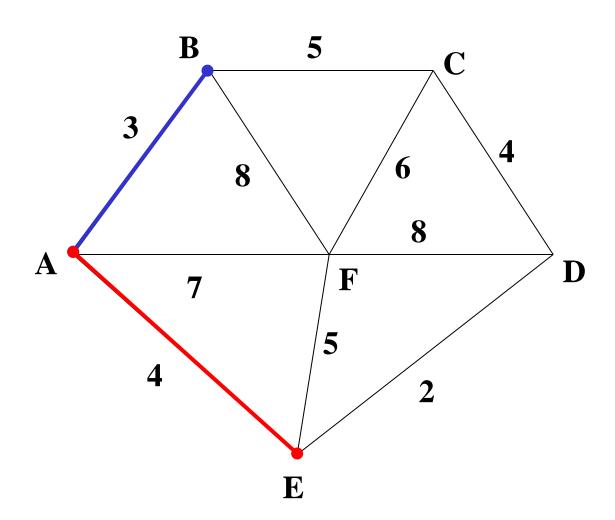


Select any vertex

Α

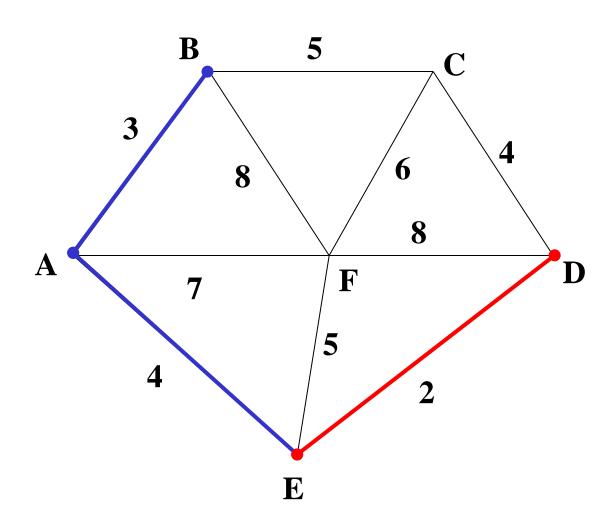
Select the shortest edge connected to that vertex (since it's the only known one)

AB 3



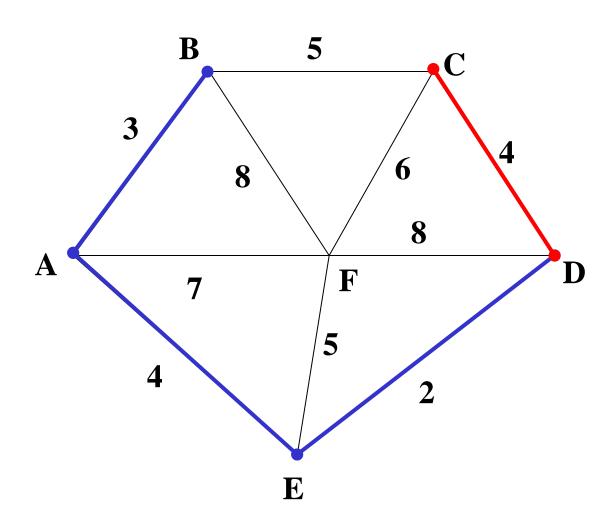
Select the shortest edge that connects an unknown vertex to any known vertex.

AE 4



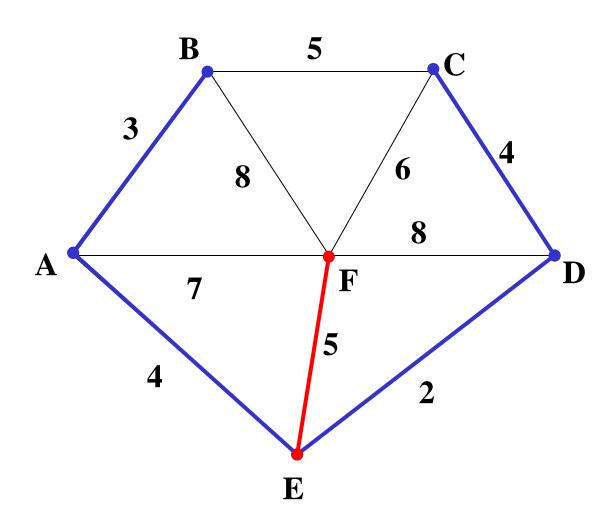
Select the shortest edge that connects an unknown vertex to any known vertex.

ED 2



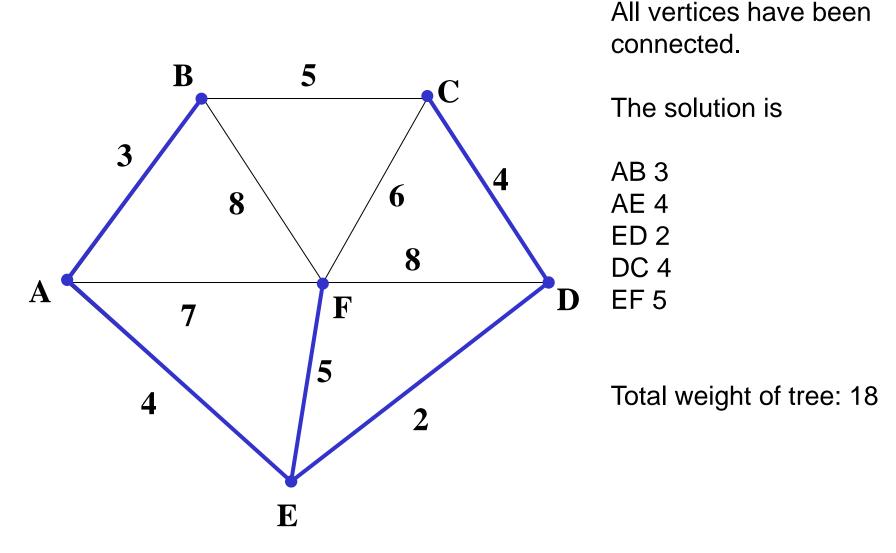
Select the shortest edge that connects an unknown vertex to any known vertex.

DC 4

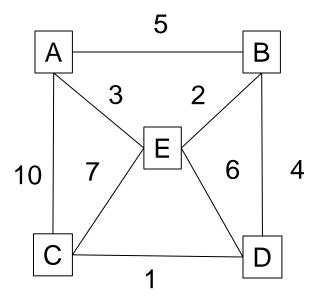


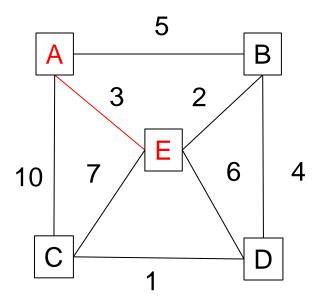
Select the shortest edge that connects an unknown vertex to any known vertex.

EF 5

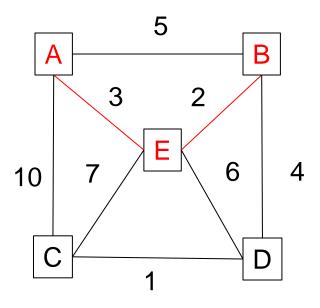


Start with A. Make it Known. HINT: Choose the least cost edge out of it. Add that node to the Known.



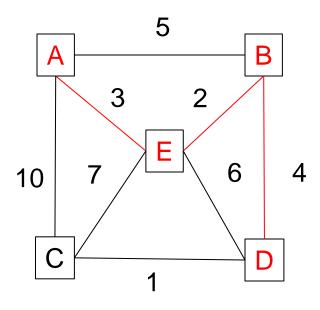


A connects to B, C, E Lowest cost is to E



Now we consider anything connected to A or E.

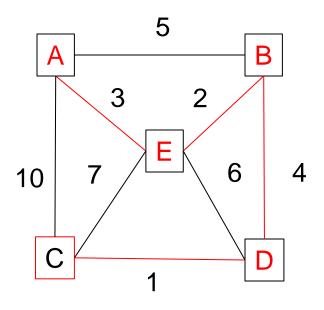
Nodes considered are B, C, D. Lowest cost to B.



Now we consider anything connected to A, B, or E.

Nodes considered are C, D.

Lowest cost to D.



Now we consider anything connected to A, B, D, or E.

Nodes considered are C.

Lowest cost is from D to C.

DONE

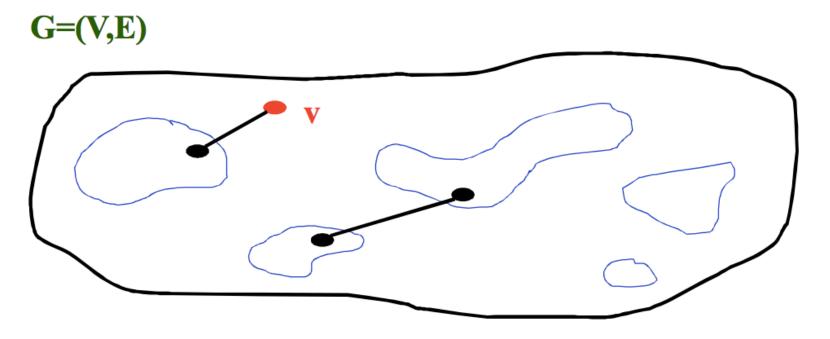
Minimum Spanning Tree Algorithms

- Prim's Algorithm for Minimum Spanning Tree
 - Similar idea to Dijkstra's Algorithm but for MSTs.
 - Both based on expanding cloud of known vertices
 (basically using a priority queue instead of a DFS stack)
- Kruskal's Algorithm for Minimum Spanning Tree
 - Another, but different, greedy MST algorithm.
 - Uses the Union-Find data structure.

Kruskal's Algorithm

Idea: Grow a forest out of edges that do not create a cycle. Pick an edge with the smallest weight.

An edge-based greedy algorithm Builds MST by greedily adding edges

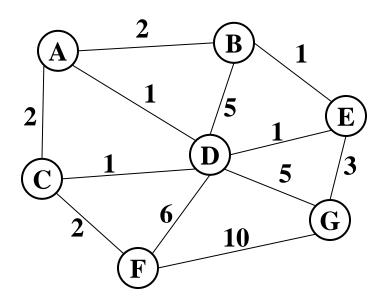


Kruskal's Algorithm Pseudocode

- 1. Sort **edges** by weight (min-heap)
- 2. Each **node** in its own set (up-trees)
- 3. While output size < |V|-1
 - Consider next smallest edge (u,v)
 - if find(u) and find(v) indicate u and v are in different sets
 - output (u,v)
 - union(find(u),find(v))

Recall invariant:

u and **v** in same set if and only if connected in output-so-far



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

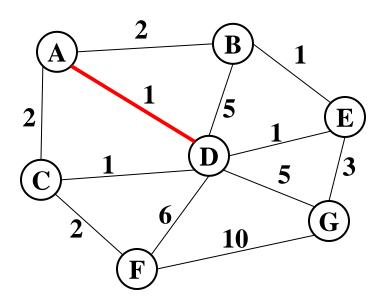
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output:



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

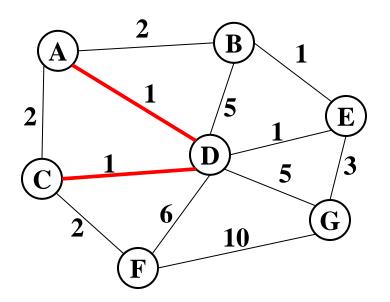
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

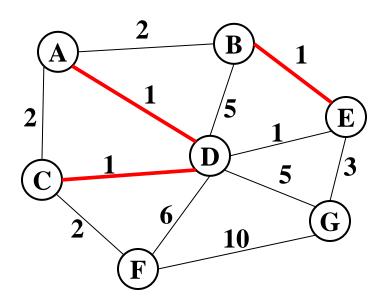
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

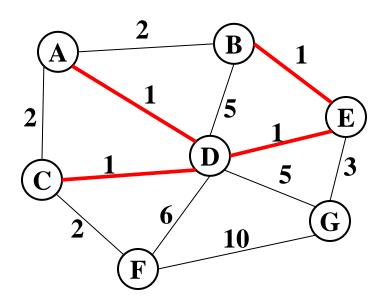
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

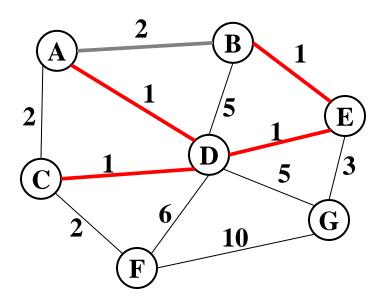
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

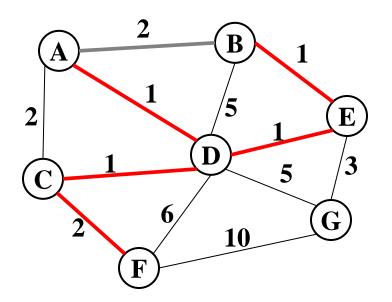
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

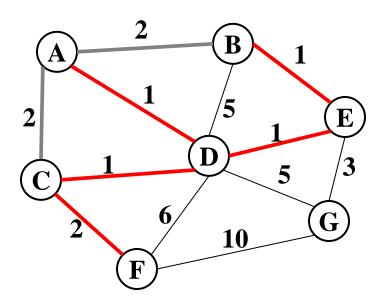
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

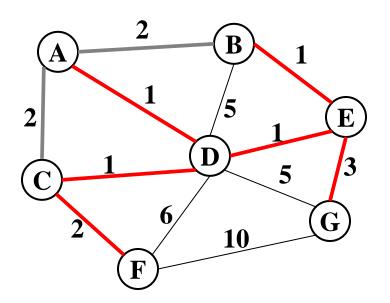
3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F)



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F), (E,G)

Kruskal's Algorithm Analysis

Idea: Grow a forest out of edges that do not grow a cycle, just like for the spanning tree problem.

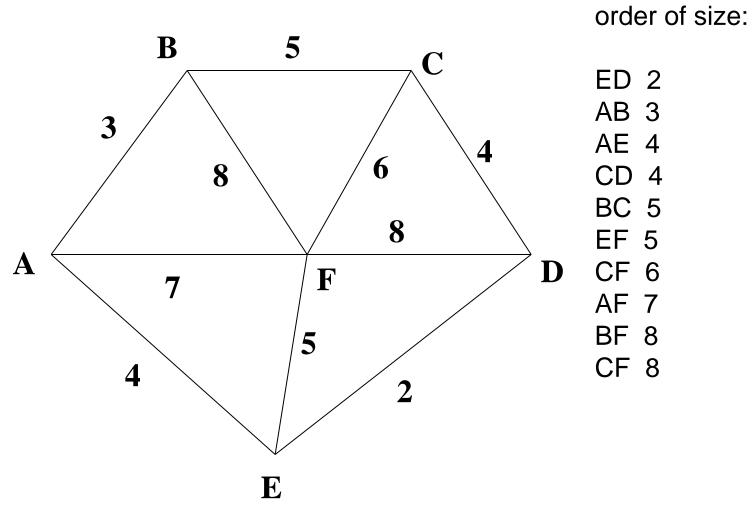
But now consider the edges in order by weight

So:

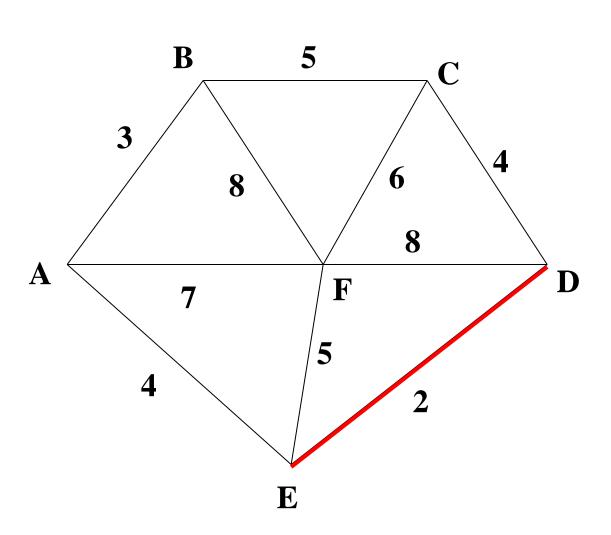
- Sort edges: O(|E|log |E|) (next course topic)
- Iterate through edges using union-find for cycle detection almost O(|E|)

Somewhat better:

- Floyd's algorithm to build min-heap with edges O(|E|)
- Iterate through edges using union-find for cycle detection and deleteMin to get next edge O(|E|log|E|)
- Not better worst-case asymptotically, but often stop long before considering all edges.

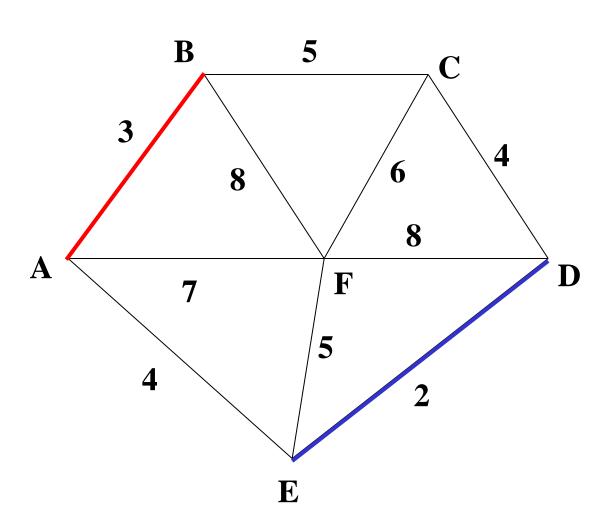


List the edges in



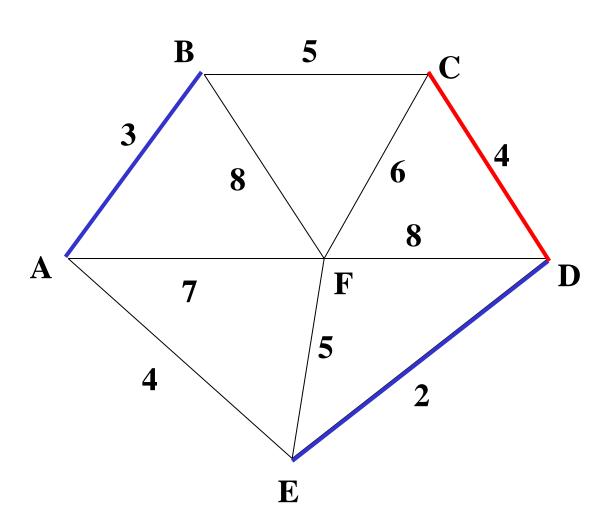
Select the edge with min cost

ED 2



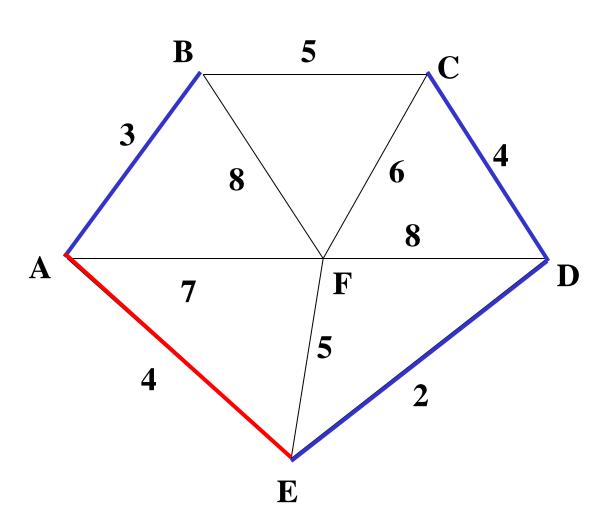
Select the next minimum cost edge that does not create a cycle

ED 2 AB 3



Select the next minimum cost edge that does not create a cycle

ED 2 AB 3 CD 4 (or AE 4)



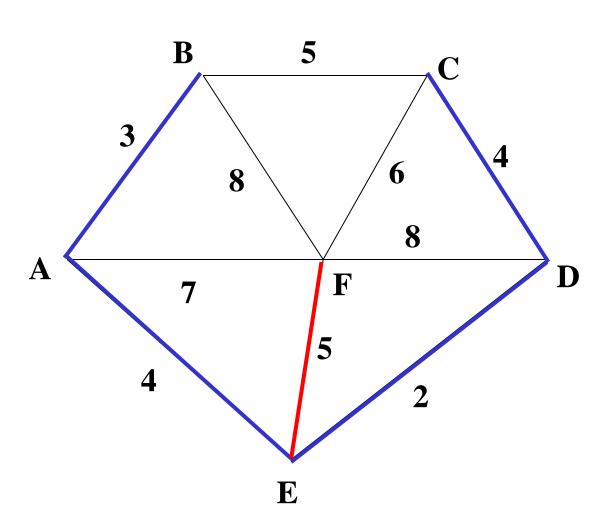
Select the next minimum cost edge that does not create a cycle

ED 2

AB 3

CD 4

AE 4



Select the next minimum cost edge that does not create a cycle

ED 2

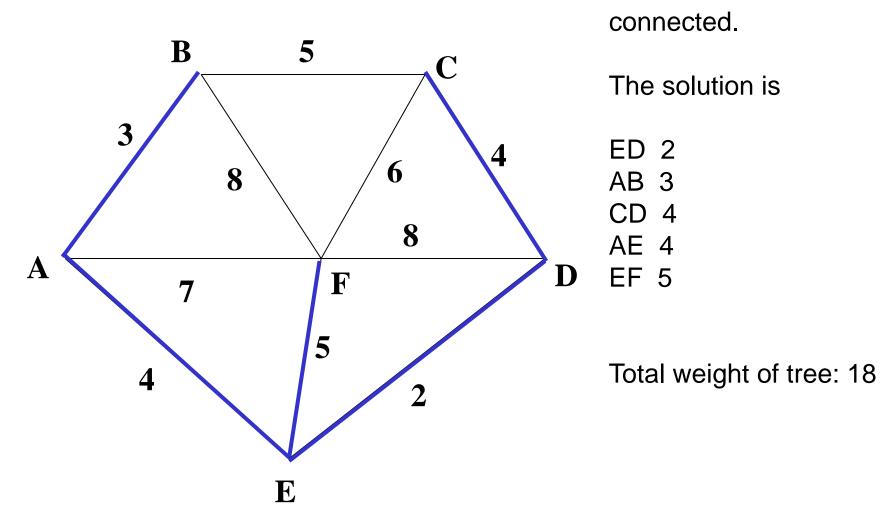
AB 3

CD 4

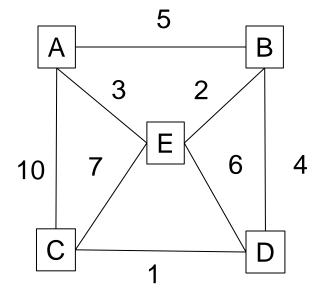
AE 4

BC 5 – forms a cycle

EF 5

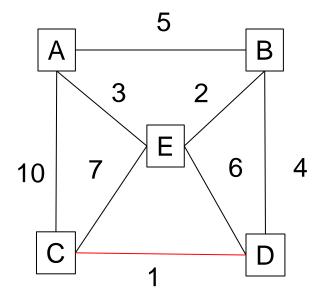


All vertices have been



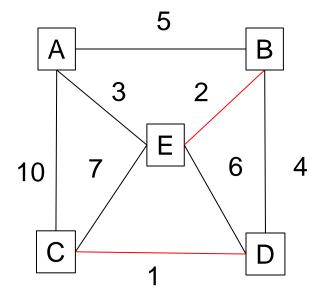
Order the edges.

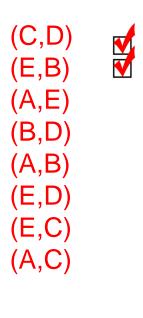
(C,D) (E,B) (A,E) (B,D) (A,B) (E,D) (E,C) (A,C)

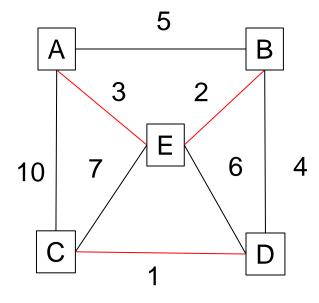


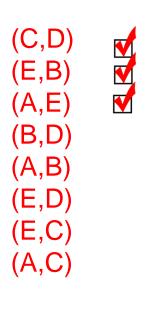
Order the edges.

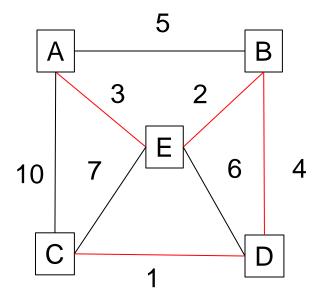
(C,D) (E,B) (A,E) (B,D) (A,B) (E,D) (E,C) (A,C)

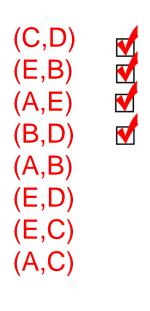


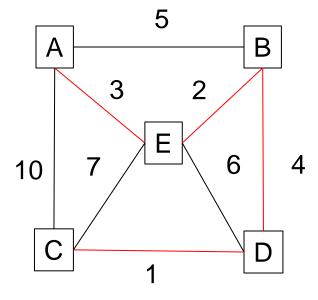


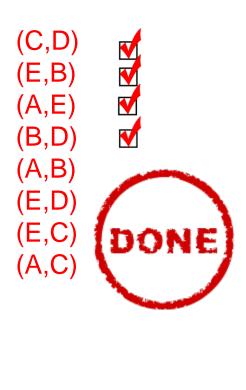












Done with graph algorithms!

Next lecture...

Sorting